

XIANGLEI DONG

(+86) 17615868113 | [Dongray1009.github.io](https://github.com/DongRay1009) | xdong@udmercy.edu | github.com/DongRay1009

EDUCATION

Beijing University of Chemical Technology, B.Eng. in Mechanical Engineering <i>Coursework: Signals and Systems, Basic Theory of Mechanical Design</i>	Sep. 2022 – Jul. 2025 GPA: 3.60/4.33
University of Detroit Mercy, B.Eng. in Robotics and Mechatronics Systems <i>Coursework: Embedded Systems, Sensor and Actuator, Robotics Integration</i>	Sep. 2025 – Present GPA: 3.94/4.00

EXPERIENCE

Hardware and Software Engineer <i>STATE GRID INTELLIGENCE TECHNOLOGY CO.,LTD</i>	Jun. 2024 - Sep. 2024 Jinan, China
<ul style="list-style-type: none">Independently responsible for the design and implementation of the hardware and software architecture for robotic projects, including system integration, sensor calibration, and actuator control.Successfully integrated multiple modules within the project, including real-time operating systems (RTOS), communication protocols (based on ROS and RTThread), and embedded systems, enabling efficient task execution and seamless interaction between modules.Demonstrated excellent project management and problem-solving skills by addressing complex hardware-software integration challenges during testing and deployment.	

PROJECTS

*: Equal Contribution

RViz Plugin for Multi-Point Navigation <i>Xianglei Dong</i>	Sep. 2024 - Dec. 2024
<ul style="list-style-type: none">Developed a plugin for RViz within the ROS system to enhance the robot's navigation capabilities.Enabled multi-point navigation for robots, significantly reducing the need for manual input of coordinate points in RViz.	
Reproducing and Training the ACT Neural Network from the LeRobot Project <i>Jiawei Xia*, Xianglei Dong*</i>	Nov. 2024 - Dec. 2024
<ul style="list-style-type: none">The robotic arm was 3D printed and physically assembled to achieve a fully functional prototype.Trained a custom dataset to enable the robotic arm to autonomously organize a desktop environment.	
Developed an intelligent home service robot based on ROS <i>Jiawei Xia, Xianglei Dong, Wengcong Zhang, Boyi Zhang, Yutong Sun</i>	Feb. 2024 – May. 2024
<ul style="list-style-type: none">Developed an intelligent home service robot using Kinova Gen2 and Kinect Azure camera.The robot's functions include guest reception and guidance, voice interaction, object recognition, and room cleaning.Integrated Azure AI Speech SDK for speech recognition and output, implementing simple human-robot voice interaction through a finite state machine.Incorporated YOLOv5 and Kinect DK for object recognition, used Cartographer for 2D indoor mapping, employed IRIS LaMa for robot localization, and implemented local path planning using DWA and global path planning using A*.In 2025, wrote an update to yolov8 3d detection and deployed together with graspnet ROS nodes.	

AWARDS

2025 robocup@home China National <i>First Price</i>	Huairou, Beijing May. 2025
2024 robocup@home China National <i>Second Price</i>	Quanzhou, Fujian May. 2024