
Algorithmic Game Theory

COMP6207

Lecture 14: **Stable Roommates**

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Learning Outcomes

- By the end of this session, you should be able to
 - ***Describe*** the stable roommate problem and its objective.
 - ***Identify*** blocking pairs in an instance of SR
 - ***Compute*** a stable matching using Irving's algorithm
 - ***Describe*** the extensions of SR and their corresponding results

Stable Roommates

- School starts, find your roommate (even number of students)
- Each of you have a strict preference list
- Same notion of stability as stable marriage
- Not a bipartite graph anymore
- Stable matching (a.k.a. stable marriage) is special case

Stable Roommates problem (**SR**)

- **Participants**
 - **2n** students or agents
- **Preferences**
 - Each agent has **strict preferences** over all other (**2n-1**) agents
- **Matching**
 - A set of **n** disjoint pairs of agents
- **Stable Matching**
 - A matching **M** with **no blocking pair**
 - That is, **no** $\{p, q\} \notin M$ such that **p** prefers **q** to her partner in **M**, and **q** prefers **p** to her partner in **M**

Example

Example SR instance I_1 :

A:	C	B	D
B:	D	C	A
C:	B	A	D
D:	A	C	B

The matching is not stable as $\{A, C\}$ blocks.

Stable matching in I_1 :

A:	C	B	D
B:	D	C	A
C:	B	A	D
D:	A	C	B

A stable matching not always exists

- Consider the following instance:
 - A: $B > C > D$
 - B: $C > A > D$
 - C: $A > B > D$
 - D: $A > B > C$
- No stable matching in this case, why?

Irving's Algorithm

Knuth (1976): is there an efficient algorithm for deciding whether there exists a stable matching, given an instance of **SR**?

Irving (1985): ``An efficient algorithm for the Stable Roommates problem'', *Journal of Algorithms*.

- Given an instance of SR, decides whether a stable matching exists
- If so, finds one.

Irving's algorithm runs in $O(n^2)$ time and works in two phases

- **Phase 1:** similar to GS algorithm for the Stable Matching problem
- **Phase 2:** elimination of "rotations"

Irving's Algorithm for SR

Semiengagement!

- Engagement is **not a symmetric relation** (unlike in SM)
 - If **x** is engaged to **y**, it is not necessarily the case that **y** is engaged to **x**
- So we use the term semiengage and say that ``**x** is ***semiengaged*** to **y**''
- **y** could be free, semiengaged to another agent **z**, or semiengaged to **x**

Free or not free

- All agents **start out free**
- A semiengaged agent **x** **becomes free** when her semi-fiancé rejects **x**
- **x** becomes **semiengaged** when she **proposes to someone**
 - The algorithm is designed so that when **x** proposes to **y** it must be the case that **y** is either free or finds **x** preferable to the current proposal she is holding

Irving's algorithm: Phase 1

Similar to Gale-Shapley

Phase 1 (agents, preferences)

```
1   Assign all agents to be free; //initial state
2   While (some free agent x has a nonempty list)
3       y = first agent on x's list
      // next: x proposes to y
4       If (some person z is semiengaged to y)
5           assign z to be free; // y rejects z
6       Assign x to be semiengaged to y;
7       For (each successor w of x on y's list)
8           delete w from y's list;
9           delete y from w's list;
```

Example

- A: $C > D > B > F > E$
- B: $F > E > D > A > C$
- C: $B > D > E > A > F$
- D: $E > B > C > F > A$
- E: $C > A > B > D > F$
- F: $E > A > C > D > B$

Phase 1:

- Every agent proposes to others in order.
- Recipients hold their best proposers.

From now on we use the following convention:

X means X is semiengaged

Y means there is a X that is semiengaged to Y

Example: Phase 1

- A: ~~C~~ > D > B > F > ~~E~~
- B: F > E > D > A > C
- C: B > D > E > ~~A~~ > ~~F~~
- D: E > B > C > F > A
- E: C > ~~A~~ > B > D > ~~F~~
- F: ~~E~~ > A > ~~C~~ > D > B

Phase 1:

- Every agent proposes to others in order.
- Recipients hold their best proposers.

From now on we use the following convention:

X means X is semiengaged

Y means there is a X that is semiengaged to Y

Example: Phase 1

- A: $\overline{D} > B > \underline{F}$
- B: $\overline{F} > E > D > A > \underline{C}$
- C: $\overline{B} > D > \underline{E}$
- D: $\overline{E} > B > C > F > \underline{A}$
- E: $\overline{C} > B > \underline{D}$
- F: $\overline{A} > D > \underline{B}$

After Phase 1, there are two possibilities:

1) Exist an **agent who got rejected by everyone else.**
 \Rightarrow **No stable matching**

2) Every agent holds a proposal.
In other words, each row should have one top bar and one bottom bar (could coincide)

- If every row has only one remaining entry (top bar and bottom bar coincide) then we have a unique stable matching.
- \Rightarrow **Phase 2**

Phase 2: intuition

- The reduced preference lists (with deleted agents removed) at the end of phase 1 is referred to as **phase-1 table**

A	D	B	F		
B	F	E	D	A	C
C	B	D	E		
D	E	B	C	F	A
E	C	B	D		
F	A	D	B		

Phase 2: summary

- The reduced preference lists (with deleted agents removed) at the end of phase 1 is referred to as **phase-1 table**
- In **phase 2**, the **preference table is further reduced** until
 - All lists contain just one entry, in which case it constitutes a **stable matching**, or
 - Until **some list becomes empty**, in which case **no stable matching** exists.
- **Reduction** of preference table takes place by eliminating so called **“exposed rotations”**

Phase 2: intuition

- High-level intuition is that ``the existence of a stable matching is preserved by removing exposed rotations''.

That is:

- If the original preference table admits a stable matching, so does all subsequent reduced tables.
- If a reduced table doesn't admit a stable matching, neither does the original preference table.

Exposed Rotation

- A pair of sequences $\rho = ((p_0, \dots, p_{r-1}), (q_0, \dots, q_{r-1}))$ constitute an **exposed rotation** if
 - q_i is the **second entry** on p_i 's list, and
 - p_{i+1} is the **last entry** on q_i 's list

$i+1$ is taken modulo r

- Example**

A	D	B	F
B	F	E	D A C
C	B	D	E
D	E	B	C F A
E	C	B	D
F	A	D	B



Last entry
 Second entry

Eliminating an exposed rotation

- A pair of sequences $\rho = ((p_0, \dots, p_{r-1}), (q_0, \dots, q_{r-1}))$ constitute an *exposed rotation* if
 - q_i is the second entry on p_i 's list, and
 - p_{i+1} is the last entry on q_i 's list
- $i+1$ is taken modulo r
- Exposed rotation $\rho = ((p_0, \dots, p_{r-1}), (q_0, \dots, q_{r-1}))$ is *eliminated* by deleting (q_i, p_{i+1}) from each other's lists, for all i
 - delete q_i from p_{i+1} 's list
 - delete p_{i+1} from q_i 's list

Example: elimination

- Exposed rotation $\rho = ((p_0, \dots, p_{r-1}), (q_0, \dots, q_{r-1}))$ is **eliminated** by deleting (q_i, p_{i+1}) from each other's lists, for all i
 - delete q_i from p_{i+1} 's list
 - delete p_{i+1} from q_i 's list

A	D	B	F
B	F	E	D
C	B	D	E
D	E	B	C
E	C	B	D
F	A	D	B



Last entry
 Second entry

Irving's algorithm: Phase 2

Reducing preference table

Phase 2 (phase-1 Table)

```
1   T = phase-1 table; //initial state
2   While ((some list in T has more than one entry)
and (no list in T is empty))
3       find a rotation  $\rho$  exposed in T
        T = T /  $\rho$  // eliminate  $\rho$ 
4   If (some list in T is empty)
5       return instance unsolvable;
6   Else
7       return T, which is a stable matching;
```

Example: Phase 2

- A: $\overline{D} > B > \underline{F}$
- B: $\overline{F} > E > D > A > \underline{C}$
- C: $\overline{B} > D > \underline{E}$
- D: $\overline{E} > B > C > F > \underline{A}$
- E: $\overline{C} > B > \underline{D}$
- F: $\overline{A} > D > \underline{B}$

First round:

Least: A

2nd:



D will reject A! and B will reject C!

Example: Phase 2

- A: $B > \underline{F}$
- B: $\underline{F} > E > D > A$
- C: $D > \underline{E}$
- D: $\underline{E} > B > C > F$
- E: $\underline{C} > B > \underline{D}$
- F: $\underline{A} > D > \underline{B}$

First round:

Least: A C A
 2nd: B D

D will reject A! and B will reject C!

Second round:

Least: A B D A
 2nd: F E B

Example: Phase 2

- A: F
- B: $E > D$
- C: $D > \underline{E}$
- D: $B > C > F$
- E: $\overline{C} > B$
- F: $\overline{A} > D$

First round:

Least: A C A
 2nd: B D

D will reject A! and B will reject C!

Second round:

Least: A B D A
 2nd: F E B

Example: Phase 2

- A: F
- B: $E > D$
- C: $D > \underline{E}$
- D: $B > C > F$
- E: C $> B$
- F: A $> D$


First round:

Least: A C A
2nd: B D




Second round:

Least: A B D A
2nd: F E B



Third round:

Least: B F F
2nd: D D



Cycle; eliminate (D, F) pair

Example: Phase 2

- A: F
- B: $E > D$
- C: $D > \underline{E}$
- D: $B > C$
- E: C $> B$
- F: A

First round:

Least: A C A
 2nd: B D

Second round:

Least: A B D A
 2nd: F E B

Third round:

Least: B F F
 2nd: D D

Cycle; eliminate (D, F) pair

Example: Phase 2

- A: F
- B: $E > D$
- C: $D > \underline{E}$
- D: $B > C$
- E: C $> B$
- F: A

Fourth round:

Least: B C B
 2nd: D E

First round:

Least: A C A
 2nd: B D

Second round:

Least: A B D A
 2nd: F E B

Third round:

Least: B F F
 2nd: D D

Cycle; eliminate (D, F) pair

Example: Phase 2

- A: F
- B: D
- C: E
- D: B
- E: C
- F: A

Fourth round:

Least: B C B
 2nd: D E




First round:

Least: A C A
 2nd: B D




Second round:

Least: A B D A
 2nd: F E B



Third round:

Least: B F F
 2nd: D D



Cycle; eliminate (D, F) pair

Quiz

- A: $B > D > \textcircled{F} > C > E$
- B: $D > \textcircled{E} > F > A > C$
- C: $\textcircled{D} > E > F > A > B$
- D: $F > \textcircled{C} > A > E > B$
- E: $F > C > D > \textcircled{B} > A$
- F: $\textcircled{A} > B > D > C > E$

Question

- If there is a stable matching, do all executions of Irving's algorithm return the same matching?
 - Phase 1 always returns the same preference table (the same phase-1 table)
 - Depending on the **order of elimination in phase 2**, we may arrive at different stable matchings.
 - So the answer is, **no**.

Question

- Is Irving's algorithm **DS truthful**?
- If not, how to find a best strategy to be matched with a roommate as good as possible?

Extensions of SR

1. Odd number of agents

- We might have odd number of agents, say $2n+1$
- In any matching one agent is unmatched
- Stability defined as before
- Recall that an agent prefers being matched than to remain unmatched

Extending Irving's algorithm

- If after **phase 1** all preference lists are nonempty then there exists no stable matching
 - Coursework 1 Exercise 4: prove the previous statement.
- If at the end of **phase 1** exactly one agent's, say **x**, preference list becomes empty
 - **x** cannot be matched in any stable matching
 - If there exists a stable matching, no other person is unmatched
 - To check whether or not there exists a stable matching, we run **phase 2** (without agent **x**)

After the execution of **phase 1**, at most one agent's preference list can be empty.
Proof: left as an exercise.

2. Unacceptable partners

- As in the marriage market, some agents might find some other agents **unacceptable**. In this case we get **Stable Roommates with Incomplete lists (SRI)**
- Matching is a pairing of agents
 - One or more agents may remain unmatched
- Stability defined as before
- Recall that an agent prefers being matched to an acceptable partner than to remain unmatched

Extending Irving's algorithm

- After **phase 1** one or more preference lists may become empty.
 - Any agent with empty list cannot be matched in any stable matching.
 - Any person with nonempty list must be matched in every stable matching
 - To check whether or not there exists a stable matching, we run **phase 2** (without those agents whose lists are empty at the end of phase 1)

Stable Pairs

- Any pair (X, Y) removed during **phase 1** cannot be a stable pair
 - i.e. X and Y are not matched in any of the stable matchings
- For each agent, the **first entry** in the **phase-1 table** is their **best achievable roommate** (if there is any achievable roommate)
- For each agent, the **last entry** in the **phase-1 table** is their **worst achievable roommate** (if there is any achievable roommate)

3. Ties

- As in the marriage market, some agents might be **indifferent** between several other agents. In this case we get **Stable Roommates with Ties (SRT)**
- As in SMT, different types of blocking pairs can be defined for SRT. Here we will focus on the straightforward extension of the stability notion we already know
 - A matching is stable if there is **no pair** such that each of whom would **strictly prefer to match with each other** rather than their assigned partner.

SRT

- Can we decide in polynomial time whether an instance of SRT admits a stable matching? And if so, find one?

Theorem (Ronn, 1990)

Deciding whether a stable matching exists, given an instance of SRT, is NP-complete.

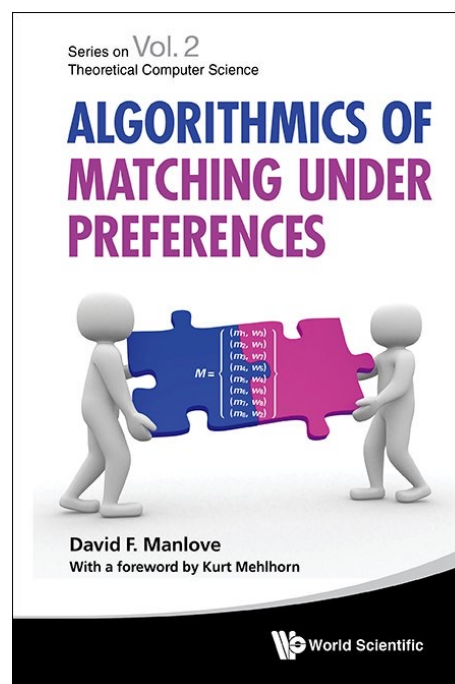
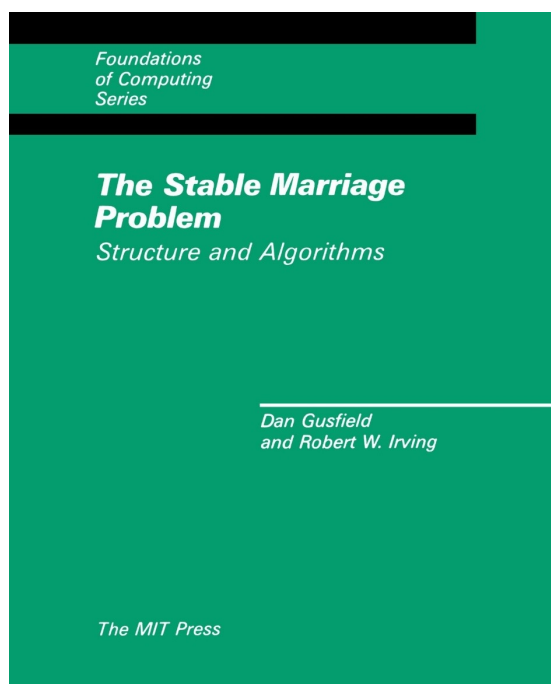
- Even if each preference list is either strictly ordered or contains a tie of length 2 at the head.

Acknowledgement

Some of the slides in this lecture were based on the slides by **David Manlove** and **Jie Zhang**.

Books

- **The Stable Marriage Problem - Structure and Algorithms** by Dan Gusfield and Robert W. Irving



- **Algorithmics of Matching under Preferences** by David F. Manlove.

Optional additional reading

- Chapter 4 of **The Stable Marriage Problem - Structure and Algorithms** by Dan Gusfield and Robert W. Irving

