

## Properties

### Definition (Efficiency)

A quasilinear mechanism is **efficient** if in equilibrium selects a choice  $x$  that maximises  $\sum_{i=1}^n v_i(x)$ .

### Definition (Dominant-strategy truthful mechanism)

A direct quasilinear mechanism is **truthful** if for each agent  $i$  and for all  $\hat{v}_i$ , declaring  $\hat{v}_i = v_i$  maximises  $i$ 's utility.

### Definition (Ex post individual rationality)

A mechanism is **ex post individually rational** if in equilibrium, the utility of each agent is at least 0.

### Definition (Budget balance)

A quasilinear mechanism is **budget balance** if in equilibrium the sum of the payments of the agents is equal to 0.

### Definition (Weak Budget balance)

A quasilinear mechanism is **budget balance** if in equilibrium the sum of the payments of the agents is at least 0.

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## Two Assumptions

### Definition (Choice-set monotonicity)

A setting exhibits **choice-set monotonicity** if  $\forall i, X_{-i} \subseteq X$ .

- In other words: removing any agent weakly decreases—that is, never increases—the mechanism's set of possible choices  $X$ .

### Definition (No negative externalities)

A setting exhibits **no negative externalities** if  $\forall i, \forall x \in X_{-i}, v_i(x) \geq 0$ .

- In other words: every agent has zero or positive utility for any choice that can be made without her participation.

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## Vickrey-Clarks-Groves (VCG) mechanism

The **VCG** mechanism is a direct quasilinear mechanism  $(x, p)$  where

$$x(\hat{v}) = \operatorname{argmax}_x \sum_i \hat{v}_i(x)$$

$$p_i(\hat{v}) = \sum_{j \neq i} \hat{v}_j(x(\hat{v}_{-i})) - \sum_{j \neq i} \hat{v}_j(x(\hat{v}))$$

$$p_i = \begin{matrix} \text{Optimal social welfare} \\ \text{(for the other agents)} \\ \text{if } i \text{ is not participating} \end{matrix} - \begin{matrix} \text{Total welfare of the} \\ \text{other agents from} \\ \text{the chosen choice} \end{matrix}$$

- Every agent pays his/her **social cost**.
- VCG is also called **pivotal** mechanism.
- **Question**: What is  $u_i$  in terms of social welfare?

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## Another property

### Definition (No single-agent effect)

A setting exhibits **no single-agent effect** if

$\forall i, \forall v_{-i}, \forall x \in \operatorname{argmax}_y \sum_j v_j(y)$  there exists a choice  $x'$  that is feasible without  $i$  and that has  $\sum_{j \neq i} v_j(x') \geq \sum_{j \neq i} v_j(x)$ .

- In other words, welfare of agents other than  $i$  is weakly increased by dropping  $i$ .

### Example

Consider a single-item auction. Dropping an agent reduces the amount of competition, making the others better off.

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