

# Dongnan Hu

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## EDUCATION

**East China University of Science and Technology**

*M.S. in Control Engineering*

**Shanghai, China**

*September, 2021-Present*

**Supervisor:** Prof. Yang Tang (IEEE Fellow)

GPA: 84.75/100.00 (9th among 182 students)

**Nanjing Tech University**

*B.S. in Mechanical Engineering*

**Nanjing, China**

*September, 2018-June, 2020*

## PUBLICATIONS

- **IECON2024** "Trajectory Planning and Tracking of Hybrid Flying-Crawling Quadrotors"  
**Dongnan Hu**, Ruihao Xia, Xin Jin, Yang Tang.  
Accepted by The 2024 Annual Conference of the IEEE Industrial Electronics Society  
**Preprint:** <https://arxiv.org/abs/2312.08718>  
**Attached Video:** <https://youtu.be/nxFqLxe14c0>

## RESEARCH EXPERIENCE

**"Trajectory Planning and Tracking of Hybrid Flying-Crawling Quadrotors"**

*Supervised by Prof. Yang Tang*

*June, 2022-November, 2023*

- I proposed a planner that generates hybrid terrestrial-aerial trajectories satisfying the kinematic and dynamic requirements of the multimodal quadrotors.
- Given the processing time on model transition, the quadrotor cannot track the trajectory during transitions between terrestrial and aerial phases. I developed a trajectory-tracking algorithm by avoiding the tracking of terrestrial-aerial junctions and re-planning the trajectory, compensating for the disadvantage of the extended deformation time required by the quadrotor.

## RESEARCH INTEREST

Autonomous Navigation, Motion Planning and Control, Mobile Robotics

## AWARDS AND ACHIEVEMENTS

- Second-class Scholarship for Master's Academic Achievement in the session of 2022-2023.
- First-class Scholarship for Master's Academic Achievement in the session of 2021-2022.
- Second Prize in the 18th "Huawei Cup" Chinese Graduate Mathematical Modeling Competition in December 2021.

## KEY SKILLS

<b>Programming Language</b>	C/C++, Python
<b>Research Tool</b>	Matlab
<b>Robot Tool</b>	ROS, PX4
<b>Mechanical software</b>	Solidworks, Catia, Workbench

## SELF EVALUATION

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- Solid mathematical and physics foundation. I achieved high grades in courses such as Matrix Theory (87/100), and Principle and Application of Pattern Recognition (88/100).
- Proficient in C/C++, Python. Experienced with ROS and PX4. Possess 2 years of development experience in the Linux environment, capable of independently completing robotic task development.
- Strong spatial imagination and mechanical design skills. I adeptly utilize CAD software to transform intricate mechanical designs from conceptualization to reality.
- Proficient in the integration, testing, and maintenance of mechatronic systems. I have created a transformable hybrid flying-crawling quadcopter, completing all tasks independently, including mechanical structure design, manufacturing, electronic unit integration, functionality debugging, motion planning and control, as well as autonomous navigation system integration.