# Distributed robust statistical learning: A Byzantine mirror descent algorithm

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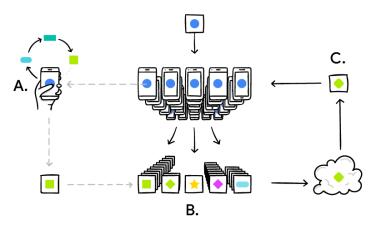
work of
Dongsheng Ding and Xiaohan Wei



58th IEEE Conference on Decision and Control

## **Motivating application**

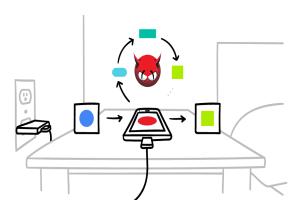
FEDERATED LEARNING



A. Worker machine B. Master machine C. Shared model

Google AI, Blog '17

## **Byzantine fault**



#### • FAULT SOURCES

- \* Machine failures
- \* Communication errors
- \* Malicious users

## Byzantine failure model

STOCHASTIC LEARNING PROBLEM

$$\begin{array}{ll}
\text{minimize} & F(w) := \mathbb{E}_{z \sim \mathcal{D}} \left( f(w; z) \right) \\
\text{subject to} & w \in \mathcal{W} \subset \mathbb{R}^d
\end{array}$$

# Byzantine failure model

STOCHASTIC LEARNING PROBLEM

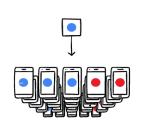
$$\begin{array}{ll}
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\text{subject to} & w \in \mathcal{W} \subset \mathbb{R}^d
\end{array}$$

#### 1 master and m workers

$$\star \ z_t^i \sim \mathcal{D}, i \in \{1, \dots, m\}$$

## m gradients at time t

$$abla_t^i \,:=\, \left\{ egin{array}{ll} 
abla f(w_t; z_t^i) & ext{normal machine} \ & ext{arbitrary} & ext{Byzantine machine} \end{array} 
ight.$$



# Identification of "good" workers

- MEDIAN AGGREGATION
  - \* robust to outliers

sequence							median
1,	3,	3,	6,	7,	8,	10	6
$10^{-10}$ ,	3,	3,	6,	7,	8,	$10^{10}$	6

## **Euclidean setting**

#### BYZANTINE SGD

$$w_{t+1} := \underset{w \in \mathcal{W}}{\operatorname{argmin}} F(w_t) + \eta \langle \xi_t, w - w_t \rangle + \frac{1}{2} \|w - w_t\|_2^2$$

 $\xi_t$  - stochastic estimate of the gradient  $\nabla F(w_t)$ 

$$\xi_t = \frac{1}{m} \sum_{i \in \Omega_t} \nabla_t^i$$

 $\Omega_t$  – set of "good" workers

## Convergence

Convex smooth objective function

$$F(\bar{w}) - F(w^{\star}) \leq \tilde{O}\left(\frac{C}{\sqrt{mT}} + \frac{\alpha}{\sqrt{T}}\right)$$
 w.h.p.

$$\star \ \bar{w} := \frac{1}{T} \sum_{t=1}^{T} w_{t+1}$$

- $\star$  T total number of iterations
- $\star \|w w'\|_2 \leq W \text{ for all } w, w' \in \mathcal{W} \subset \mathbb{R}^d$
- $\star \| \nabla_t^i \nabla_t \|_2 \leq C$  gradient norm bound for "good" workers

Alistarh, Allen-Zhu, Li, NeurIPS '18

## **Example**

#### LINEAR REGRESSION

$$f(w;z) = \frac{1}{2} (x^T w - y)^2, \ w \in \mathcal{W} \subset \mathbb{R}^d$$

\* 
$$z:=(x,y)$$
 - data generated by  $y=x^Tw^*+\xi$  
$$x(i) \sim \{-1,1\}, \;\; \xi \sim \mathcal{N}(0,\sigma^2)$$

### dimension-dependent gradient norm bound

$$\mathbb{E}\left(\|\nabla_t^i - \nabla_t\|_2\right) \, \leq \, \sqrt{\left(d-1\right)W^2 \, + \, d\,\sigma^2}$$

Yin, Chen, Kannan, Bartlett, ICML '18

# **Exploiting problem geometry** to improve the dimension dependence

## **Bregman divergence**

$$D(x,y) \; := \; \Phi(x) \; - \; \Phi(y) \; - \; \nabla \Phi(y)^T (x \, - \, y)$$

 $\star$   $\Phi$  - differentiable, 1-strongly convex w.r.t.  $\|\cdot\|$ 

## **Bregman divergence**

$$D(x,y) := \Phi(x) - \Phi(y) - \nabla \Phi(y)^{T}(x - y)$$

- $\star$   $\Phi$  differentiable, 1-strongly convex w.r.t.  $\|\cdot\|$
- EXAMPLES

$$\star \Phi(x) = \frac{1}{2} \|x\|_2^2$$

strongly convex w.r.t.  $\|\cdot\|_2$ 

$$D(x,y) = \frac{1}{2} \|x - y\|_2^2$$

## **Bregman divergence**

$$D(x,y) := \Phi(x) - \Phi(y) - \nabla \Phi(y)^{T}(x - y)$$

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#### EXAMPLES

$$\star \ \Phi(x) = \frac{1}{2} \|x\|_2^2$$

$$D(x,y) = \frac{1}{2} \|x - y\|_2^2$$

$$\star \Phi(x) = \sum_{i} x(i) \log x(i)$$

strongly convex w.r.t.  $\|\cdot\|_1$ 

strongly convex w.r.t.  $\|\cdot\|_2$ 

$$D(x,y) = \sum_{i} x(i) \log \frac{x(i)}{y(i)}$$
 KL divergence

Bubeck, Found. Trends Mach. Learn. '15

## Non-Euclidean setting

BYZANTINE MIRROR DESCENT

$$w_{t+1} := \underset{w \in \mathcal{W}}{\operatorname{argmin}} F(w_t) + \eta \langle \xi_t, w - w_t \rangle + D(w, w_t)$$

 $\xi_t$  - stochastic estimate of the gradient  $\nabla F(w_t)$ 

$$\xi_t = \frac{1}{m} \sum_{i \in \Omega_t} \nabla_t^i$$

 $\Omega_t$  – set of "good" workers

#### IMPORTANT QUANTITIES

- $\star \ \nabla_t^1, \dots, \nabla_t^m \ \ \text{gradients (normal or Byzantine)}$
- $\star A_t^1, \ldots, A_t^m$  gradient related values

$$A_t^i := \sum_{k=1}^t \left\langle \nabla_k^i, w_k - w_1 \right\rangle$$

 $\star B_t^1, \ldots, B_t^m$  - accumulated gradients

$$B_t^i := \sum_{k=1}^t \nabla_k^i$$

used to update the set of "good" workers

## Convergence result

Convex and L-smooth objective function

$$\begin{split} F(\bar{w}) \,-\, F(w^\star) \,\, \leq \,\, \frac{2R^2}{\eta T} \,\,+\,\, \frac{8\sqrt{2}W C \Delta (1 + 4\alpha \sqrt{m})}{\sqrt{mT}} \\ \,\, + \,\, \eta \left(\frac{32C^2\Delta^2}{m} + 64\alpha^2C^2\right) \quad \text{w.h.p.} \end{split}$$

$$\sup_{w \in \mathcal{W}} D(w, w_1) \le R^2$$

$$\Delta = \Theta\left(\sqrt{\log \frac{mT}{\delta}}\right)$$

$$\stackrel{\sim}{=} 2L$$

$$\eta \leq \tfrac{1}{2L}$$
 matches standard mirror descent for  $C=0$ 

## **Optimal rate**

#### OPTIMAL STEPSIZE

$$\eta \ = \ \left\{ \begin{array}{ll} \min\left(\frac{1}{\alpha C \sqrt{T}}, \frac{1}{2L}\right), & \alpha \ \geq \ \frac{1}{\sqrt{m}} \\ \min\left(\frac{1}{C} \sqrt{\frac{m}{T}}, \frac{1}{2L}\right), & \alpha \ < \ \frac{1}{\sqrt{m}} \end{array} \right.$$

$$F(\bar{w}) - F(w^\star) \le \tilde{O}\left(C\left(\frac{R^2}{T} + \frac{1}{\sqrt{mT}} + \frac{\alpha}{\sqrt{T}}\right)\right)$$
 w.h.p.

$$\mbox{matches the rate of} \left\{ \begin{array}{ll} \mbox{Byzantine SGD}, & \alpha \neq 0 \\ \mbox{batch SGD}, & \alpha = 0 \end{array} \right.$$

## **Probability simplex**

$$\mathcal{W} := \left\{ w \in \mathbb{R}^d, \|w\|_1 = 1, \ w \ge 0 \right\}$$
$$\|\cdot\| = \|\cdot\|_1, \ \|\cdot\|_* = \|\cdot\|_{\infty}$$

#### KL DIVERGENCE

$$D(x,y) = \sum_{i} x(i) \log \frac{x(i)}{y(i)}$$

- $\star \| \nabla_t^i \nabla_t \|_{\infty} \leq C \text{dimension-independent bound}$
- $\star~w_1 = (\frac{1}{d}, \cdots, \frac{1}{d})~-~$  uniform initialization

$$D(w^*, w_1) \le \log d = R^2$$

#### Convex and L-smooth objective function

$$F(\bar{w}) - F(w^*) \leq \frac{2\log d}{\eta T} + \frac{8C\Delta(\sqrt{mT} + 4\alpha m\sqrt{T})}{mT} + \eta \left(\frac{4C^2\Delta^2}{m} + 32\alpha^2C^2\right) \text{ w.h.p.}$$

C – dimension-independent constant

#### OPTIMAL STEPSIZE $\eta$

$$F(\bar{w}) - F(w^*) \leq \tilde{O}\left(\frac{\log d}{T} + \frac{1}{\sqrt{mT}} + \frac{\alpha}{\sqrt{T}}\right)$$
 w.h.p.

# **Summary**

- RESULTS
  - ⋆ Byzantine mirror descent
  - \* Probability simplex: nearly dimension-free
- ONGOING EFFORT
  - \* Problems with constraints
  - \* Byzantine primal-dual algorithm

# **Extra slides**

## **Concentration bounds**

#### Gradient bias

$$|E_1| = \left| \sum_{t=1}^T \sum_{i \in \Omega_t} \left\langle \nabla_t^i - \nabla_t, w_t - w^\star \right\rangle \right|$$

$$\leq 4WC\Delta\sqrt{2Tm} + 16\alpha mWC\Delta\sqrt{2T} \quad \text{w.h.p.}$$

#### Gradient variance

$$\begin{split} \underline{E_2} &= \frac{1}{T} \sum_{t=1}^T \left\| \frac{1}{m} \sum_{i \in \Omega_t} (\nabla_t^i - \nabla_t) \right\|_*^2 \\ &\leq \frac{16C^2\Delta^2}{2} + 32\alpha^2C^2 \quad \text{w.h.p.} \end{split}$$

$$\star I_A = 4WC\Delta\sqrt{2T}$$

$$\star I_B = 4C\Delta\sqrt{2T}$$

$$\star \ \Delta = R + 2\sqrt{2\log\frac{8\sqrt{2}mT}{\delta}}$$

## **Convergence analysis**

### Convex and L-smooth objective

$$\frac{1}{mT} \sum_{t=1}^{T} \sum_{i \in \Omega_t} (F(w_{t+1}) - F(w^\star)) \leq \eta \underline{E_2} + \frac{R^2}{\eta T} - \frac{\underline{E_1}}{mT}$$

$$\leq \underline{\eta} C^2 \left( \frac{16\Delta^2}{m} + 32\alpha^2 \right) + \underbrace{\frac{R^2}{\eta T}}_{\text{error}} + \underbrace{C \frac{4\sqrt{2}W\Delta}{\sqrt{mT}} + \alpha C \frac{16\sqrt{2}W\Delta}{\sqrt{T}}}_{\text{bias}}$$

$$\star \|w - w'\| \le W \text{ for all } w, w' \in \mathcal{W}$$

$$\star D(w^{\star}, w_1) \leq R^2$$

$$\star \|\nabla_t^i - \nabla_t\|_* < C$$

$$\star \eta \leq \frac{1}{2L}$$