

# Exercise Session 1

*Learning at Scale: Supervised, Self-Supervised, and Beyond*

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**Additional Reading Materials.** We recommend following three papers:

- [1] Oord, Aaron van den, Yazhe Li, and Oriol Vinyals. “**Representation Learning with Contrastive Predictive Coding.**” arXiv preprint arXiv:1807.03748 (2018).
- [2] Chen, Ting, et al. “**A Simple Framework for Contrastive Learning of Visual Representations.**” International Conference on Machine Learning (ICML). PMLR, 2020.
- [3] Radford, Alec, et al. “**Learning Transferable Visual Models from Natural Language Supervision.**” International Conference on Machine Learning. PMLR, 2021.

## Task 1. InfoNCE in Contrastive Learning.

In contrastive learning, the goal is to learn useful representations without labels. For each condition  $c$ , the model is trained to identify the single positive sample among  $K$  distractors. For example, in instance discrimination for images,  $c$  is one augmented view of an image,  $x^+$  is another independent augmentation of the same image, and the negatives  $\{x_i^-\}$  are views of other images (e.g., from the same minibatch or from a memory queue). In vision language tasks,  $c$  is an image,  $x$  denotes captions,  $x^+$  is the matched caption, and the negatives are captions of other images. A common objective for this is the InfoNCE loss. We will investigate it from a probabilistic perspective in this task.

Suppose that, given a condition  $c$ , we form a candidate set  $X = \{x_0, \dots, x_K\}$  where  $x_0 = x^+$  is the positive sample and  $x_1, \dots, x_K$  are  $K$  negative samples drawn i.i.d. from  $q_{\text{noise}}(x)$ . The InfoNCE objective is defined as

$$\mathcal{L}_{\text{InfoNCE}} = - \sum_{(X,c) \in D} \left[ \log \frac{\frac{p_{\text{data}}(x^+ | c)}{q_{\text{noise}}(x^+)}}{\sum_{j=0}^K \frac{p_{\text{data}}(x_j | c)}{q_{\text{noise}}(x_j)}} \right],$$

where the term inside the logarithm represents the probability of correctly identifying  $x^+$  as the positive sample among all candidates.

In practice, we typically set  $q_{\text{noise}}(x) = p_{\text{data}}(x)$ , so the numerator simplifies to  $\frac{p_{\text{data}}(x^+ | c)}{p_{\text{data}}(x^+)}$ , whose logarithm equals the pointwise mutual information. Then, we can encode  $x$  and  $c$  with

neural networks to obtain embeddings, define a score to approximate this density ratio. Consequently, the InfoNCE loss encourages the model to learn effective representations that captures mutual information between  $x$  and  $c$ , by learning a higher estimated ratio (or score) for true positive pairs than for negative samples.

- (a) **Connection to cross-entropy loss.** Choose logits whose exponentials match the relative weights of candidates in the InfoNCE numerator/denominator; then build connection between InfoNCE and cross-entropy loss.
- (b) **Relation to NCE.** The local NCE loss is defined as

$$\mathcal{L}_{\text{NCE}} = \sum_{(X,c) \in D} \left[ -\log \frac{p_{\text{data}}(x^+ | c)}{p_{\text{data}}(x^+ | c) + K q_{\text{noise}}(x^+)} - \sum_{j=1}^K \log \frac{K q_{\text{noise}}(x_j^-)}{p_{\text{data}}(x_j^- | c) + K q_{\text{noise}}(x_j^-)} \right].$$

Show that this objective can be seen as optimizing the same logits as the InfoNCE but with a binary cross-entropy loss.

- (c) **Effect of K.** In the case  $q_{\text{noise}}(x) = p_{\text{data}}(x)$ , analyze the effect of the number of negative samples  $K$  on the InfoNCE loss.

**Hint:** In this case, the logarithm of the numerator equals the pointwise mutual information. Optimizing the InfoNCE loss corresponds to maximizing a lower bound on the mutual information.

### Solution

- (a) **Connection to cross-entropy loss.** Define logits  $s_j = \log p_{\text{data}}(x_j | c) - \log q_{\text{noise}}(x_j)$ . Then

$$\mathcal{L}_{\text{InfoNCE}} = - \sum_{(X,c) \in D} \log \frac{\exp(s^+)}{\sum_{j=0}^K \exp(s_j)} = - \sum_{(X,c) \in D} \sum_{j=0}^K y_j \log \text{softmax}(s)_j,$$

where  $y$  is the one-hot label for the true sample  $x^+$  (i.e., for  $s^+$ ). Thus this is exactly the multi-class softmax cross-entropy between  $y$  and the model distribution  $P(\cdot | X, c)$ .

In practice for contrastive learning, one example is  $s_j = \langle f(x_j), f(c) \rangle / \tau$  (with temperature  $\tau$ , network  $f$ ), giving

$$- \sum_{(X,c) \in D} \log \frac{\exp(\langle f(x^+), f(c) \rangle / \tau)}{\sum_{j=0}^K \exp(\langle f(x_j), f(c) \rangle / \tau)}.$$

- (b) **Relation to NCE.** In (local) NCE, each pair  $(x, c)$  is classified as *data* vs. *noise*. With  $K$  noises per positive and using the logits  $s_j$  defined in (a), we have:

$$\frac{p_{\text{data}}(x^+ | c)}{p_{\text{data}}(x^+ | c) + K q_{\text{noise}}(x^+)} = \sigma(s^+ - \log K), \quad (1)$$

$$\frac{K q_{\text{noise}}(x^-)}{p_{\text{data}}(x^- | c) + K q_{\text{noise}}(x^-)} = \sigma(-s^- + \log K) = 1 - \sigma(s^- - \log K), \quad (2)$$

with  $\sigma$  as the sigmoid function. Then, we have

$$\mathcal{L}_{\text{NCE}} = - \log \sigma(s^+ - \log K) - \sum_{j=1}^K \log (1 - \sigma(s_j^- - \log K)) \quad (3)$$

$$= -(y \log \sigma(z) + (1-y) \log(1 - \sigma(z))), \quad (4)$$

with  $z = s - \log K$ ,  $y \in \{0, 1\}$  denote the binary label ( $y = 1$  for positive,  $y = 0$  for negative). Thus, NCE and InfoNCE optimize the same logits  $s_j$ ; they differ only in how the likelihood is factored (sum of binary log-losses vs. one multi-class log-loss).

- (c) **Effect of  $K$ .** For the case where  $q_{\text{noise}}(x) = p_{\text{data}}(x)$ , the mutual information is

$$I(x^+; c) = \sum_{x^+, c} p(x^+, c) \log \frac{p(x^+ | c)}{p(x^+)}. \quad (5)$$

If the labels are fully reliable, the InfoNCE estimator yields the lower bound (see Oord et al., 2018, Appendix A for proof)

$$I(x^+; c) \geq \log(K+1) - \mathcal{L}_{\text{InfoNCE}}.$$

By plugging the loss in the right-hand side, we can see that as  $K$  increases, the lower bound becomes tighter, which can often lead to better performance for models trained with the InfoNCE loss. However, in practice a very large  $K$  may introduce too much noise in the negatives and increases compute/memory cost, so  $K$  should be balanced with its temperature factor and batch design.

## Task 2. Masked Language Modeling as Pseudo-Likelihood and -Perplexity.

Consider a sequence  $x = (x_1, \dots, x_T)$  from a data distribution  $\mathcal{D}$ . For masked language modeling (MLM), let us draw a random mask set  $M \subseteq \{1, \dots, T\}$  by sampling each position independently with probability  $q \in (0, 1)$ . Let  $x_{\setminus t}$  denote  $x$  with the token in position  $t$  hidden (or replaced) and other tokens visible. Let  $x_t$  be an actual token in the position  $t$ . The MLM training objective is

$$\mathcal{L}_{\text{MLM}}(\theta) = -\mathbb{E}_{x \sim \mathcal{D}} \mathbb{E}_M \left[ \sum_{t \in M} \log p_\theta(x_t | x_{\setminus t}) \right]. \quad (5)$$

- (a) **Connection to pseudo-likelihood.** Define the (negative) pseudo log-likelihood (NPLL):

$$\text{NPLL}(\theta) = -\mathbb{E}_{x \sim \mathcal{D}} \left[ \sum_{t=1}^T \log p_\theta(x_t | x_{\setminus t}) \right]. \quad (6)$$

Show that under independent Bernoulli masking at rate  $q$ , i.e.,  $M \stackrel{iid}{\sim} \text{Bern}(q)$ :

$$\mathbb{E}_M \left[ \sum_{t \in M} \log p_\theta(x_t | x_{\setminus t}) \right] = q \sum_{t=1}^T \log p_\theta(x_t | x_{\setminus t}), \quad (7)$$

and hence  $\mathcal{L}_{\text{MLM}}(\theta) = q \cdot \text{NPLL}(\theta)$ .

*Hint:* Use indicators  $\mathbf{1}_{\{t \in M\}}$  and linearity of expectation.

- (b) **Pseudo-perplexity and an unbiased estimator.** Define the pseudo-perplexity (PPPL) for a sequence  $x$  by

$$\text{PPPL}(x) = \exp\left(\frac{1}{T} \sum_{t=1}^T -\log p_\theta(x_t | x_{\setminus t})\right). \quad (8)$$

- (i) Show that  $\log \text{PPPL}(x)$  equals the average token-wise NPLL.
  - (ii) Propose a practical *unbiased* single-pass estimator of  $S(x) = \sum_{t=1}^T -\log p_\theta(x_t | x_{\setminus t})$  by sampling one index  $U \sim \text{Unif}\{1, \dots, T\}$  and evaluating only  $-\log p_\theta(x_U | x_{\setminus U})$ . Then, prove that it is indeed unbiased.
- (c) **Relation to autoregressive maximum likelihood.** An autoregressive (AR) model maximizes
- $$\log p_\theta(x) = \sum_{t=1}^T \log p_\theta(x_t | x_{\prec t}). \quad (9)$$
- (i) Explain why AR likelihood can be evaluated exactly, whereas MLM/pseudo-likelihood generally cannot yield a normalized joint  $p_\theta(x)$ .
  - (ii) **Bonus:** State a modeling assumption(s) under which minimizing NPLL( $\theta$ ) is statistically consistent. That is, if  $\theta_n$  denotes the estimator from  $n$  samples, then  $\text{NPLL}(\theta_n) \rightarrow \text{NPLL}(\theta^*)$  and  $\theta_n \rightarrow \theta^*$  as  $n \rightarrow \infty$ . Sketch the proof of consistency.  
**Hint:** Consider applying results from M-estimation theory.
  - (iii) Give one advantage and one limitation of MLM vs. AR for downstream tasks.

**Bonus (BERT 80/10/10).** In BERT, of the selected tokens, 80% are replaced by [MASK], 10% by a random token, and 10% are left unchanged. Argue how this reduces train–test mismatch and prevents over-reliance on [MASK]; predict qualitative effects of using 100% or 0% [MASK].

### Solution

- (a) **Connection to pseudo-likelihood.** Let  $I_t := \mathbf{1}_{\{t \in M\}}$  with  $I_t \stackrel{iid}{\sim} \text{Bern}(q)$ , independent of  $x$ . Then

$$\begin{aligned} \mathbb{E}_M \left[ \sum_{t \in M} \log p_\theta(x_t | x_{\setminus t}) \right] &= \mathbb{E}_M \left[ \sum_{t=1}^T I_t \log p_\theta(x_t | x_{\setminus t}) \right] = \\ &= \sum_{t=1}^T \mathbb{E}[I_t] \log p_\theta(x_t | x_{\setminus t}) = q \sum_{t=1}^T \log p_\theta(x_t | x_{\setminus t}). \end{aligned}$$

Taking expectation over  $x \sim \mathcal{D}$  yields

$$\begin{aligned} \mathcal{L}_{\text{MLM}}(\theta) &= -\mathbb{E}_{x \sim \mathcal{D}} \mathbb{E}_M \left[ \sum_{t \in M} \log p_\theta(x_t | x_{\setminus t}) \right] \\ &= -q \mathbb{E}_{x \sim \mathcal{D}} \left[ \sum_{t=1}^T \log p_\theta(x_t | x_{\setminus t}) \right] = q \cdot \text{NPLL}(\theta). \end{aligned}$$

- (b) **Pseudo-perplexity and an unbiased estimator.**

(i) By definition,

$$\log \text{PPPL}(x) = \log \exp \left( \frac{1}{T} \sum_{t=1}^T -\log p_\theta(x_t | x_{\setminus t}) \right) = \frac{1}{T} \sum_{t=1}^T -\log p_\theta(x_t | x_{\setminus t}),$$

which is the average token-wise NPLL.

(ii) A single-pass unbiased estimator of  $S(x) = \sum_{t=1}^T -\log p_\theta(x_t | x_{\setminus t})$  is

$$\widehat{S}(x) = T \cdot (-\log p_\theta(x_U | x_{\setminus U})), \quad \text{where } U \sim \text{Unif}\{1, \dots, T\}.$$

**Intuition:** We estimate the sum of  $T$  terms by sampling one uniformly at random and scaling by  $T$ .

Unbiased-ness follows by linearity of expectation:

$$\begin{aligned} \mathbb{E}_U [T \cdot (-\log p_\theta(x_U | x_{\setminus U}))] &= \sum_{t=1}^T \Pr(U=t) T \cdot (-\log p_\theta(x_t | x_{\setminus t})) = \\ &= \sum_{t=1}^T \frac{1}{T} T \cdot (-\log p_\theta(x_t | x_{\setminus t})) = S(x). \end{aligned}$$

### (c) Relation to autoregressive maximum likelihood.

(i) For an autoregressive (AR) model,

$$\log p_\theta(x) = \sum_{t=1}^T \log p_\theta(x_t | x_{\setminus t}) \Rightarrow p_\theta(x) = \prod_{t=1}^T p_\theta(x_t | x_{\setminus t}),$$

where each factor is directly given by the model, so we can compute likelihood exactly.

For the MLM/pseudo-likelihood, if the conditionals came from a joint normalized  $p_\theta(x)$ , they would satisfy:

$$p_\theta(x_t | x_{\setminus t}) = \frac{p_\theta(x)}{\sum_{x'_t} p_\theta(x_1, \dots, x_{t-1}, x'_t, x_{t+1}, \dots, x_T)} \quad (*)$$

(i.e., marginalizing out position  $t$  from the joint). But there is no guarantee that such a joint exists. We model the conditional distributions directly without constraints to ensure compatibility.

Here's a counterexample showing incompatibility. Consider  $T = 2$  with tokens  $u, v$ . Suppose the MLM model defines:

$$p_\theta(x_1 = u | x_2 = v) = 1 \quad (10)$$

$$p_\theta(x_2 = v | x_1 = u) = 0 \quad (11)$$

If these came from a joint  $p_\theta(x_1, x_2)$ , we would need:

$$p_\theta(u, v) = p_\theta(x_1 = u | x_2 = v) \cdot p_\theta(x_2 = v) = 1 \cdot p_\theta(v)$$

and also:

$$p_\theta(u, v) = p_\theta(x_2 = v | x_1 = u) \cdot p_\theta(x_1 = u) = 0 \cdot p_\theta(u) = 0$$

This gives  $p_\theta(v) = 0$ , but then the first conditional wouldn't be well-defined (division by zero in the marginal). Therefore, no joint distribution exists that yields these conditionals.

- (ii) For statistical consistency of minimizing NPLL( $\theta$ ), we need different assumptions than for joint distributions.

**Key point:** We do NOT assume the conditionals come from a joint distribution (which would contradict part (i)).

**Sufficient assumptions for consistency:**

- The data is generated i.i.d. from some true distribution with conditionals  $p^*(x_t | x_{\setminus t})$
- The model class is correctly specified:  $\exists \theta^* \in \Theta$  such that  $p_{\theta^*}(x_t | x_{\setminus t}) = p^*(x_t | x_{\setminus t})$  for all  $t$
- Identifiability: if  $p_\theta(x_t | x_{\setminus t}) = p_{\theta'}(x_t | x_{\setminus t})$  for all  $t$  and almost all  $x$ , then  $\theta = \theta'$
- Standard regularity conditions (e.g., compact parameter space, continuous likelihood)

**Sketch of consistency proof:** Define the empirical estimator from  $n$  samples  $x^{(1)}, \dots, x^{(n)}$ :

$$\theta_n = \arg \max_{\theta \in \Theta} \frac{1}{n} \sum_{i=1}^n \sum_{t=1}^T \log p_\theta(x_t^{(i)} | x_{\setminus t}^{(i)})$$

The population objective is:

$$\mathcal{Q}(\theta) = \mathbb{E}_{x \sim p^*} \left[ \sum_{t=1}^T \log p_\theta(x_t | x_{\setminus t}) \right]$$

For each position  $t$ , by the KL divergence inequality:

$$\mathbb{E}_{x \sim p^*} [\log p_\theta(x_t | x_{\setminus t})] \leq \mathbb{E}_{x \sim p^*} [\log p^*(x_t | x_{\setminus t})]$$

with equality if and only if  $p_\theta(x_t | x_{\setminus t}) = p^*(x_t | x_{\setminus t})$  almost surely.

Therefore  $\mathcal{Q}(\theta) \leq \mathcal{Q}(\theta^*)$  with equality only at  $\theta = \theta^*$  (by identifiability).

By the law of large numbers, the empirical objective converges to the population objective uniformly over  $\Theta$ . Since  $\theta^*$  is the unique maximizer of  $\mathcal{Q}(\theta)$ , standard M-estimation theory gives us  $\theta_n \rightarrow \theta^*$  in probability as  $n \rightarrow \infty$ .

**Remark:** The assumption of correct specification can be relaxed. Even if no  $\theta^*$  exactly matches the true conditionals, consistency still holds for the  $\theta^*$  that minimizes the KL divergence to the true conditionals, making pseudo-likelihood robust to model misspecification.

**Note:** Knowledge of M-estimation theory is not relevant for the exam.

- (iii) *One advantage of MLM:* It supports bidirectional context, making it natural for tasks that require information from both directions (e.g., fill-in-the-blank or fill-in-the-middle). Training with bidirectional context often yields strong representations for fill-in-the-blank and encoder-style downstream tasks. One limitation: to enable generation, an MLM typically needs an encoder-decoder architecture, whereas an autoregressive (AR) model requires only a decoder. Moreover, under a strict MLM objective, only the masked tokens contribute to the loss in each forward pass, so token usage is less efficient than in AR models.

**Bonus (BERT 80/10/10).** Among the tokens chosen for prediction, replacing 80% with [MASK], 10% with a random token, and leaving 10% unchanged reduces train–test mismatch and discourages over-reliance on the [MASK] because:

- The 10% unchanged positions force the model to sometimes predict when the true token is visible, mitigating the fact that [MASK] never appears at test time.
- The 10% random replacements inject noise so the model cannot treat [MASK] as the sole prediction signal.

Qualitatively, using 100% [MASK] increases train–test mismatch and risks overfitting to the special token; using 0% [MASK] makes many targets trivially copyable (identity shortcut), weakening the learning signal, harming generalization, and reducing model understanding of the language.

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### Task 3. Exploring Contrastive Learning with SimCLR.

See Task A in the Jupyter notebook.

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### Task 4. Exploring the Scaling Behaviour of LMs with a Series of Pythia Models.

See Task B in the Jupyter notebook.

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