# PHYS 301 Formula Sheet

## **Differential Maxwell's Equations**

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0} \qquad \nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \cdot \mathbf{B} = 0 \qquad \nabla \times \mathbf{B} = \mu_0 \mathbf{J} + \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}$$

## **Integral Maxwell's Equations**

$$\oint \mathbf{E} \cdot d\mathbf{a} = \frac{Q_{\text{enc}}}{\epsilon_0} \qquad \oint \mathbf{B} \cdot d\mathbf{a} = 0$$

$$\oint \mathbf{E} \cdot d\mathbf{l} = -\frac{d\Phi_B}{dt} \qquad \oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 I_{\text{enc}} + \epsilon_0 \mu_0 \frac{d\Phi_E}{dt}$$

#### **Electrostatics**

#### The Electric Field

Coulomb's Law:  $\mathbf{F} = \frac{1}{4\pi\epsilon_0} \frac{qQ}{r} \hat{\mathbf{z}}$ 

The Electric Field:

$$\mathbf{F} = O\mathbf{E}$$
  $\mathbf{E} = -\nabla V$ 

Electric Field due to discrete point charges:

$$\mathbf{E}(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \sum_{i=1}^n \frac{q_i}{v_i^2} \hat{\boldsymbol{\lambda}}_i$$

Electric Field due to a continuous charge distribution:

$$\mathbf{E}(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\mathbf{\hat{\lambda}}}{2^2} dq$$

## **Electric Potential**

$$V(b) - V(a) = -\int_{a}^{b} \mathbf{E} \cdot d\mathbf{l}$$

Poisson's Equation:

$$\nabla^2 V = \rho/\epsilon_0$$

Potential due to a localized charge distribution:

$$V(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\mathbf{r}')}{2} dV$$

## **Work and Energy in Electrostatics**

Energy stored in a point charge distribution:

$$W = \frac{1}{2} \sum_{i=1}^{n} q_i V(\mathbf{r}_i)$$

Energy of a continuous charge distribution:

$$W = \frac{1}{2} \int \rho V \, d\tau$$

Total energy of a continuous charge distribution:

$$W = \frac{\epsilon_0}{2} \int E^2 d\tau \quad \text{(all space)}$$

#### **Conductors**

 $\mathbf{E} = \mathbf{0}$  inside a conductor.

Electric Field immediately outside a conductor:

$$\mathbf{E} = \frac{\sigma}{\epsilon_0} \mathbf{\hat{n}}$$

Surface charge:

$$\sigma = -\epsilon_0 \frac{\partial V}{\partial n}$$

Capacitors:

$$Q = CV$$
  
 $W = \frac{1}{2}CV^2 = \frac{1}{2}\frac{Q^2}{C} = \frac{1}{2}QV$ 

#### **Potentials**

Laplace's Equation:

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = 0$$

## **Separation of Variables**

$$\int_0^a \sin\left(\frac{n\pi x}{a}\right) \sin\left(\frac{m\pi x}{a}\right) dx = \begin{cases} 0 & \text{if } n \neq m \\ a/2 & \text{if } n = m \end{cases}$$

Legendre Polynomials:

• 
$$P_0(x) = 1$$

• 
$$P_1(x) = x$$

• 
$$P_2(x) = (3x^2 - 1)/2$$

• 
$$P_3(x) = (5x^3 - 3x)/2$$

Solution to Laplace in spherical ( $\phi$  independent):

$$V(r,\theta) = \sum_{l=0}^{\infty} \left( A_l r^l + \frac{B_l}{r^{l+1}} \right) P_l(\cos \theta)$$

Solution to Laplace in cylindrical (*z* independent):

$$V(s,\phi) = A_0 \ln(s) + B_0 +$$

$$\sum_{n=1}^{\infty} (A_n s^{-n} + B_n s^{-n}) (C_n \cos(n\phi) + D_n \sin(n\phi))$$

## **Multipole Expansion**

Potential at large distances ( $\alpha$  is between **r** and **r**'):

$$V(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \sum_{n=0}^{\infty} \frac{1}{r^{n+1}} \int (r')^n P_n(\cos\alpha) \rho(\mathbf{r}') d\tau$$

Dipole Moment:

$$\mathbf{p} = \sum_{i=1}^{n} q_i \mathbf{r'}_i = \int \mathbf{r'} \rho(\mathbf{r'}) d\tau$$

Electric Dipole Potential:

$$V_{\rm dip}(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \frac{\mathbf{p} \cdot \hat{\mathbf{r}}}{r^2}$$

#### **Electric Fields in Matter**

Bound Charges:

$$\sigma_b = \mathbf{P} \cdot \hat{\mathbf{n}} \qquad \rho_b = -\nabla \cdot \mathbf{P}$$

The Electric Displacement:

$$\mathbf{D} = \epsilon_0 \mathbf{E} + \mathbf{P} \qquad \nabla \cdot \mathbf{D} = \rho_f \qquad \oint \mathbf{D} \cdot d\mathbf{a} = Q_{f,\text{enc}}$$

#### **Linear Dielectrics**

Polarization:

$$\mathbf{P} = \epsilon_0 \chi_e \mathbf{E}$$

Electric Displacement:

$$\mathbf{D} = \epsilon_0 (1 + \chi_e) \mathbf{E} = \epsilon \mathbf{E}$$

Energy in a Dielectric System:

$$W = \frac{1}{2} \int \mathbf{D} \cdot \mathbf{E} \, d\tau$$

## **Boundary Conditions in Electrostatics**

• 
$$\mathbf{D}_{\text{above}}^{\perp} - \mathbf{D}_{\text{below}}^{\perp} = \sigma_f$$

• 
$$\mathbf{D}_{\text{above}}^{\parallel} - \mathbf{D}_{\text{below}}^{\parallel} = \mathbf{P}_{\text{above}}^{\parallel} - \mathbf{P}_{\text{below}}^{\parallel}$$

• 
$$\mathbf{E}_{\text{above}}^{\perp} - \mathbf{E}_{\text{below}}^{\perp} = \sigma/\epsilon_0$$

• 
$$\mathbf{E}_{\text{above}}^{\parallel} - \mathbf{E}_{\text{below}}^{\parallel} = \mathbf{0}$$

• 
$$V_{\text{above}} = V_{\text{below}}$$

• 
$$\epsilon_{\text{above}} \mathbf{E}_{\text{above}}^{\perp} - \epsilon_{\text{below}} \mathbf{E}_{\text{below}}^{\perp} = \sigma_f$$

• 
$$\epsilon_{\text{above}} \frac{\partial V_{\text{above}}}{\partial n} - \epsilon_{\text{below}} \frac{\partial V_{\text{below}}}{\partial n} = \sigma_f$$

## **Magnetostatics**

Lorentz Force Law:

$$\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B})$$

Currents:

$$I = \lambda v$$
  $K = \sigma v$   $J = \rho v$ 

Biot-Savart Law:

$$\mathbf{B}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \frac{\mathbf{I} \times \hat{\boldsymbol{\lambda}}}{v^2} dl' = \frac{\mu_0 I}{4\pi} \int \frac{d\mathbf{l}' \times \hat{\boldsymbol{\lambda}}}{v^2}$$

## **Magnetic Vector Potential**

$$\mathbf{B} = \nabla \times \mathbf{A} \quad \text{where} \quad \nabla \cdot \mathbf{A} = 0$$

Vector Potential Poisson's Equation:

$$\nabla^2 \mathbf{A} = -\mu_0 \mathbf{J}$$

Vector Potential when  $A \rightarrow 0$  at infinity:

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \frac{\mathbf{J}(\mathbf{r}')}{2} d\tau$$

Multipole Expansion of a current loop:

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \sum_{n=0}^{\infty} \frac{1}{r^{n+1}} \oint (r')^n P_n(\cos \alpha) \, d\mathbf{l}'$$
$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \frac{\mathbf{m} \times \hat{\mathbf{r}}}{r^2}$$

Magnetic Dipole Moment for a vector area **a**:

$$\mathbf{m} = I \int d\mathbf{A} = I\mathbf{a}$$

## **Magnetic Fields in Matter**

**Bound Currents:** 

$$\mathbf{J}_B = \nabla \times \mathbf{M} \qquad \mathbf{K}_B = \mathbf{M} \times \mathbf{n}$$

Auxillary Field:

$$\mathbf{H} = \frac{\mathbf{B}}{\mu_0} - \mathbf{M} \qquad \nabla \times \mathbf{H} = \mathbf{J}_f \qquad \oint \mathbf{H} \cdot d\mathbf{l} = I_{\text{free}}$$

#### Linear Media

Magnetization in linear media:

$$\mathbf{M} = \chi_m \mathbf{H}$$

Auxillary Field:

$$\mathbf{B} = \mu_0(\mathbf{H} + \mathbf{M}) = \mu_0(1 + \chi_m)\mathbf{H} = \mu \mathbf{H}$$

Volume bound current:

$$\mathbf{J}_B = \chi_m \mathbf{J}_f$$

## **Boundary Conditions in Magnetostatics**

• 
$$\mathbf{B}_{\text{above}}^{\parallel} - \mathbf{B}_{\text{below}}^{\parallel} = \mu_0 \mathbf{K}$$

• 
$$\mathbf{B}_{\text{above}} - \mathbf{B}_{\text{below}} = \mu_0(\mathbf{K} \times \hat{\mathbf{n}})$$

• 
$$\mathbf{A}_{above} = \mathbf{A}_{below}$$

• 
$$\frac{\partial A_{\text{above}}}{\partial n} - \frac{\partial A_{\text{below}}}{\partial n} = -\mu_0 \mathbf{K}$$

• 
$$\mathbf{H}_{above}^{\perp} - \mathbf{H}_{below}^{\perp} = -(\mathbf{M}_{above}^{\perp} - \mathbf{M}_{below}^{\perp})$$

• 
$$\mathbf{H}_{\text{above}}^{\parallel} - \mathbf{H}_{\text{below}}^{\parallel} = \mathbf{K}_f \times \hat{\mathbf{n}}$$

#### Vector Derivatives

#### Cartesian

$$d\mathbf{l} = dx\,\hat{\mathbf{x}} + dy\,\hat{\mathbf{y}} + dz\,\hat{\mathbf{z}} \qquad d\tau = dx\,dy\,dz$$

$$\nabla f = \frac{\partial f}{\partial x}\hat{\mathbf{x}} + \frac{\partial f}{\partial y}\hat{\mathbf{y}} + \frac{\partial f}{\partial z}\hat{\mathbf{z}}$$

Divergence:

$$\nabla \cdot \mathbf{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$$

$$\nabla \times \mathbf{v} = \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z}\right) \hat{\mathbf{x}} + \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x}\right) \hat{\mathbf{y}} + \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y}\right) \hat{\mathbf{z}}$$
 Spherical Coordinates

## **Spherical**

 $d\tau = r^2 \sin\theta \, dr \, d\theta \, d\phi$ 

$$\nabla f = \frac{\partial f}{\partial r} \hat{\mathbf{r}} + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{\boldsymbol{\theta}} + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi} \hat{\boldsymbol{\phi}}$$

$$\nabla \cdot \mathbf{v} = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 v_r \right) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta v_\theta) + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi}$$

$$\nabla \times \mathbf{v} = \frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial \theta} (\sin \theta \, v_{\phi}) - \frac{\partial v_{\theta}}{\partial \phi} \right] \hat{\mathbf{r}} +$$

$$\frac{1}{r} \left[ \frac{1}{\sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{\partial}{\partial r} (r v_\phi) \right] \hat{\pmb{\theta}} + \frac{1}{r} \left[ \frac{\partial}{\partial r} (r v_\theta) - \frac{\partial v_r}{\partial \theta} \right] \hat{\pmb{\phi}}$$

## **Cylindrical**

 $d\tau = s ds d\phi dz$ 

Gradient: 
$$\nabla f = \frac{\partial f}{\partial s} \hat{\mathbf{s}} + \frac{1}{s} \frac{\partial f}{\partial \phi} \hat{\boldsymbol{\phi}} + \frac{\partial f}{\partial z} \hat{\mathbf{z}}$$

Divergence

$$\nabla \cdot \mathbf{v} = \frac{1}{s} \frac{\partial}{\partial s} (s v_s) + \frac{1}{s} \frac{\partial v_{\phi}}{\partial \phi} + \frac{\partial v_z}{\partial z}$$

Curl:

$$\left[\frac{1}{s}\frac{\nabla \times \mathbf{v}}{\partial \phi} - \frac{\partial v_{\phi}}{\partial z}\right] \hat{\mathbf{s}} + \left[\frac{\partial v_{s}}{\partial z} - \frac{\partial v_{z}}{\partial s}\right] \hat{\boldsymbol{\phi}} + \frac{1}{s} \left[\frac{\partial}{\partial s} (sv_{\phi}) - \frac{\partial v_{s}}{\partial \phi}\right] \hat{\boldsymbol{z}}$$

## **Fundamental Theorems**

Fundamental Theorem of Line Integrals:

$$\int_{-b}^{b} (\nabla f) \cdot d\mathbf{l} = f(\mathbf{b}) - f(\mathbf{a})$$

Divergence Theorem:

$$\int (\nabla \cdot \mathbf{A}) d\tau = \oint \mathbf{A} \cdot d\mathbf{a}$$

Stoke's Theorem:

$$\int (\nabla \times \mathbf{A}) \cdot d\mathbf{a} = \oint \mathbf{A} \cdot d\mathbf{l}$$

#### **Vector Identities**

$$\nabla \cdot \left(\frac{\hat{\mathbf{\lambda}}}{\lambda^2}\right) = 4\pi \delta^3(\mathbf{\lambda})$$

$$\nabla \left(\frac{1}{\lambda}\right) = -\frac{\hat{\mathbf{\lambda}}}{\lambda}$$

$$\delta(kx) = \frac{1}{|k|}\delta(x)$$

 $x = r \sin \theta \cos \phi$  $y = r \sin \theta \sin \phi$  $z = r \cos \theta$ 

 $\hat{\mathbf{x}} = \sin\theta\cos\phi\,\hat{\mathbf{r}} + \cos\theta\cos\phi\,\hat{\boldsymbol{\theta}} - \sin\phi\,\hat{\boldsymbol{\phi}}$  $\hat{\mathbf{y}} = \sin \theta \sin \phi \, \hat{\mathbf{r}} + \cos \theta \sin \phi \, \hat{\boldsymbol{\theta}} + \cos \phi \, \hat{\boldsymbol{\phi}}$  $\hat{\mathbf{z}} = \cos\theta \,\hat{\mathbf{r}} - \sin\theta \,\hat{\boldsymbol{\theta}}$ 

$$r = \sqrt{x^2 + y^2 + z^2}$$
  

$$\theta = \tan^{-1} \left( \sqrt{x^2 + y^2} / z \right)$$
  

$$\phi = \tan^{-1} (y/x)$$

 $\hat{\mathbf{r}} = \sin \theta \cos \phi \, \hat{\mathbf{x}} + \sin \theta \sin \phi \, \hat{\mathbf{y}} + \cos \theta \, \hat{\mathbf{z}}$  $\hat{\boldsymbol{\theta}} = \cos\theta\cos\phi\,\hat{\mathbf{x}} + \cos\theta\sin\phi\,\hat{\mathbf{y}} - \sin\theta\,\hat{\mathbf{z}}$  $\hat{\boldsymbol{\phi}} = -\sin\phi\,\hat{\mathbf{x}} + \cos\phi\,\hat{\mathbf{v}}$ 

## **Cylindrical Coordinates**

 $x = s \cos \phi$  $y = s \sin \phi$ z = z

 $\hat{\mathbf{x}} = \cos\phi\,\hat{\mathbf{s}} - \sin\phi\hat{\boldsymbol{\phi}}$  $\hat{\mathbf{y}} = \sin \phi \, \hat{\mathbf{s}} + \cos \phi \, \hat{\boldsymbol{\phi}}$ 

 $s = \sqrt{x^2 + y^2}$  $\phi = \tan^{-1}(y/x)$ 

 $\hat{\mathbf{s}} = \cos\phi\,\hat{\mathbf{x}} + \sin\phi\,\hat{\mathbf{y}}$  $\hat{\phi} = -\sin\phi \hat{\mathbf{x}} + \cos\phi \hat{\mathbf{y}}$  $\hat{\mathbf{z}} = \hat{\mathbf{z}}$ 

Updated January 14, 2021 https://github.com/DonneyF/formula-sheets