

# MA2252 Introduction to computing

lectures 23-24

Interpolation

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# Interpolation Problem Statement

Suppose we have a data set containing  $n$  data points  $(x_i, y_i), i = 1, 2, \dots, n$ .

Goal: To find an estimation function  $\hat{y}(x)$  with domain  $x \in [x_1, x_n]$  such that  $\hat{y}(x_i) = y_i$ .

The function  $\hat{y}(x)$  is called **interpolation function**.

**Note:** The choice of interpolation function depends on other factors such as accuracy, underlying physics etc. Depending on this choice, there are different interpolation methods.

# Some Interpolation methods

- Linear Interpolation
- Cubic Spline Interpolation
- Lagrange Polynomial Interpolation

# Linear interpolation

Here, the interpolation function  $\hat{y}(x)$  is defined piecewise by linear polynomials (or straight lines). So,

$$\hat{y}_i(x) = y_i + \frac{(y_{i+1} - y_i)(x - x_i)}{x_{i+1} - x_i}, \quad x_i \leq x \leq x_{i+1} \quad (i = 1, 2, \dots, n-1) \quad (1)$$

MATLAB's `interp1()` function can be used to make life easier.

# Cubic spline interpolation

A cubic spline is a function defined piecewise by cubic polynomials.

In cubic spline interpolation, the interpolating function is a cubic spline defined as

$$S_i(x) = a_i x^3 + b_i x^2 + c_i x + d_i, \quad x_i \leq x \leq x_{i+1} \quad (i = 1, 2, \dots, n) \quad (2)$$

Again, MATLAB's `interp1` function can be used by giving 'cubic' as argument.

## Cubic spline interpolation (contd.)

The unknown parameters  $a_i$ ,  $b_i$ ,  $c_i$  and  $d_i$  are found using these conditions:

$$S_i(x_i) = y_i \quad (i = 1, 2, \dots, n-1) \quad (3a)$$

$$S_i(x_{i+1}) = y_{i+1} \quad (i = 1, 2, \dots, n-1) \quad (3b)$$

$$S'_i(x_{i+1}) = S'_{i+1}(x_{i+1}) \quad (i = 1, 2, \dots, n-2) \quad (3c)$$

$$S''_i(x_{i+1}) = S''_{i+1}(x_{i+1}) \quad (i = 1, 2, \dots, n-2) \quad (3d)$$

$$S''_1(x_1) = 0 \quad (3e)$$

$$S''_{n-1}(x_n) = 0 \quad (3f)$$

# Lagrange Polynomial Interpolation

Here, the interpolation function is a **Lagrange polynomial** defined as

$$L(x) = \sum_{i=1}^n y_i P_i(x) \quad (4)$$

where

$$P_i(x) = \prod_{j=1, j \neq i}^n \frac{x - x_j}{x_i - x_j}. \quad (5)$$

The Lagrange polynomial  $L(x)$  of degree  $n - 1$  passes through  $n$  data points i.e. it satisfies  $L(x_i) = y_i$  ( $i = 1, 2, \dots, n$ ).