

Dynamics of Mechanical Systems

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Assignment of Project n°2

The system consists of a beam on two supports located at both ends at coordinates P2 and P11 respectively. A steel cylinder of mass M_1 is mounted at location P10 as illustrated in Figure 1.

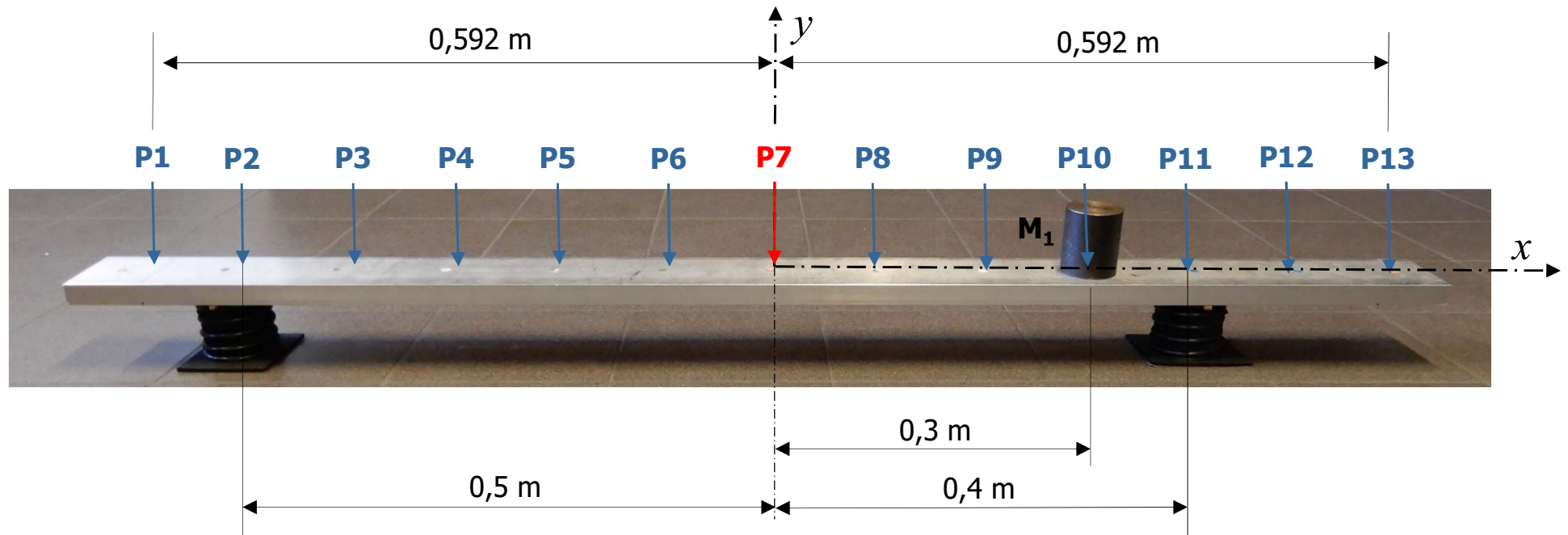


Figure 1.- Beam supporting one mass M_1

Point P7 is located at the centre of the beam, P1 and P13 at a distance of 0,592 m from P7. The distance between two consecutive points (from P2 to P12) is equal to 0,1 m.

The beam has a rectangular cross-section and is made of aluminium.

Geometry of the beam

Length = 1,25 *m*

Width = 80 *mm*

Height = 20 *mm*

Material (aluminium)

Density = 2 690 *kg/m³*

Elasticity modulus $\sim 6,45 \cdot 10^{10}$ *N/m²*

Poisson ratio = 0,39

Steel cylinder

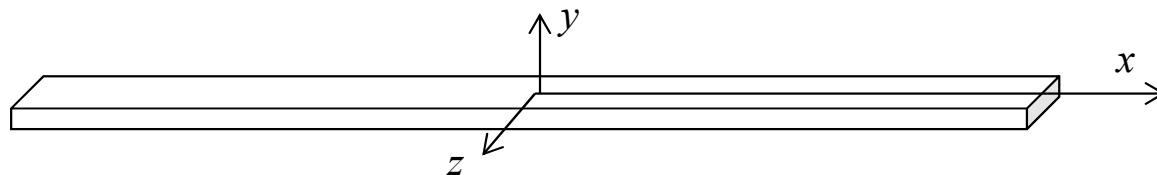
Mass (M_1) = 1 *kg*; height = 61 *mm*; diameter = 51 *mm*

Supports

Each support will be modelled by a single stiffness element with the following characteristic:

$$k_{support} = 10\,500 \text{ N/m}$$

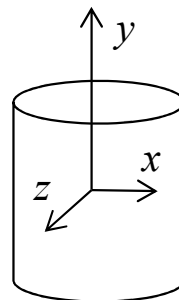
Moment of inertia of a beam about the z -axis passing through its centre of gravity



$$J_{beam} = \frac{M L^2}{12}$$

where M and L are the mass and the length of the beam respectively.

Moment of inertia of a cylinder about the z -axis passing through its centre of gravity



$$J_{cylinder} = \frac{M_1 (3 R^2 + h^2)}{12}$$

where M_1 is the mass, R the radius and h the height of the cylinder.

Project 2 (Part 1)

Build a 2 DOF model of the system with the assumption that the beam is rigid; calculate the natural frequencies and the associated mode-shapes; calculate the coordinate of the nodal node for the second mode.

The results will be summarized on the form provided in the file Project 2_part1_form.pdf to be sent by e-mail at the following address: JC.Golinval@uliege.be. The form will be renamed as follows:

DSM2_part 1_LAST NAME_first name.pdf

The deadline for the submission of the form is fixed to

November 22, 2018.

Project 2 (Part 2)

1. Relaxing the assumption of a rigid beam, compute the first 5 natural frequencies and mode-shapes of the system using the Rayleigh-Ritz method; to this purpose, at least 10 polynomial functions will be chosen as approximation functions.
2. The FRF are measured by accelerometers at coordinates P4 and P10. The excitation consists of an impact produced successively every 0,1 m from points P1 to P13 using the so-called «roving hammer technique». The responses are measured in the frequency range from 0 to 400 Hz with a frequency resolution of 0,1 Hz. The results of the experimental modal identification in terms of natural frequencies and mode-shapes are available on MyULg website in the files 'Project_2018_freq.txt' and 'Project_2018_modes.txt' as explained hereafter.
3. Compare the theoretical predictions of the different models with the experimental results in terms of frequencies and mode-shapes.

Experimental data available on MyULg

- The file 'Project_2018_freq.txt' contains 5 identified frequencies (1st column) and modal damping factors (2nd column).
- The file 'Project_2018_modes.txt' contains the amplitudes of the corresponding identified mode-shapes (columns 1 to 5) under the format:

Mode 1	Mode 2	Mode 3	Mode 4	Mode 5
...
...
...

13 lines
corresponding to
locations P1 to P13

- 1) The report must be concise (max 3 pages according to the template given in the file Project 2_part2_form.pdf).
- 2) Figures must be clear (legend, readability).
- 3) The text must be well structured and should be free of spelling and grammatical mistakes.
- 4) Penalty for late report: -1 point/24h

A PDF version of the report will be sent by e-mail at the following address:
JC.Golinval@uliege.be and will be named as follows:

DSM2_Part 2_LAST NAME_first name.pdf

The deadline for the submission of the report is fixed to

December 13, 2018.