IOT LAB - 5th Sem

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Program No: 14

Program Title: IR based SERVO Motor Controller

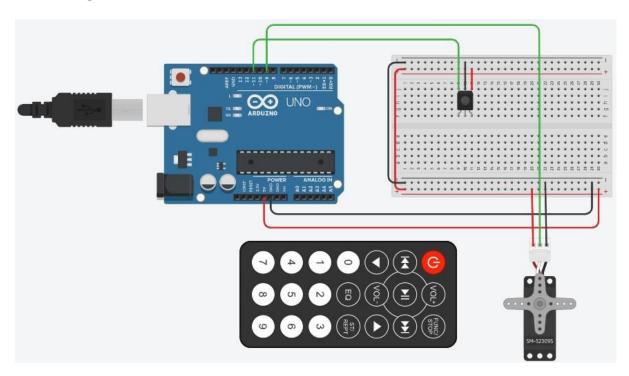
Aim:

To design IR based SERVO motor controller (Clockwise and Counter) using an Arduino Uno board.

Hardware Required:

- · Arduino Uno Board
- IR Sensor
- IR Remote
- Micro Servo

Circuit Diagram:



Written Code:

```
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# include < Seavo. h>
# include < I Remote. h>
 int RECV_PIN = 11;
 IRreco irreco (RECV_PIN).
   decode - results results.
  Servo myservo.
 Void setup ()
   Serial Degin (9600).
     its ecv. enable IRIn ();
 void loop ()
   if (inneve. decode (& nesults))
         Switch ( Aesults. value )
        E case OxFDOOFF:
             myservo attach (q).
              Serial. print ln ("start")
              break.
           case 0xFD 609F:
              nyservo, write (360).
               Social . println (" clockwise")
               break.
```

```
Case Ox FDAOSF:

nysouro. White (-360).

Serial. Phintln ("Counter Clockwise").

break;

Ox FDAOSF!

nysouro. attach (7);

Schial. Phintln ("Stop");

break;

q

insecv. resume ();

q
```

Observation / Output:

The Servo motor turns clockwise and counter clockwise upon detection of IR signal from the remote.