

## Problem 1

(a)  $E_1$  测量  $f$  和  $f_0$  的误差,  $E_2$  测量  $f$  的光滑性。

(b) 该式表示关于  $g$  的相对变化率。

(c)

$$\begin{aligned} dE_1(f, g) &= \frac{d}{d\epsilon} \int_0^1 (f(t) + \epsilon g(t) - f_0(t))^2 dt \Big|_{\epsilon=0} \\ &= \int_0^1 2(f(t) + \epsilon g(t) - f_0(t)) g(t) dt \Big|_{\epsilon=0} \\ &= 2 \int_0^1 (f(t) - f_0(t)) g(t) dt \\ dE_2(f, g) &= \frac{d}{d\epsilon} \int_0^1 (f'(t) + \epsilon g'(t))^2 dt \Big|_{\epsilon=0} \\ &= \int_0^1 2(f'(t) + \epsilon g'(t)) g'(t) dt \Big|_{\epsilon=0} \\ &= 2 \int_0^1 f'(t) g'(t) dt \\ &= 2 \int_0^1 f'(t) d(g(t)) \\ &= 2 \left( f'(t) g(t) \Big|_{t=0}^{t=1} - \int_0^1 f''(t) g(t) dt \right) \\ &= -2 \int_0^1 f''(t) g(t) dt \end{aligned}$$

(d) 由(c)可得

$$dE(f) = 2 \int_0^1 (f(t) - f_0(t) - \alpha f''(t)) g(t) dt = 0$$

所以可以近似认为

$$f(t) - f_0(t) = \alpha f''(t)$$

(e) 这部分感觉有点问题, 这里略过。

## Problem 2

假设  $a_i$  存在数组  $a$  中, 那么利用如下算法即可在  $O(k)$  时间内计算出  $f(x)$ :

```

res = 0
s = 1
for i in a:
    res += i * s
    s *= x

```

### Problem 3

(a)设

$$g(x) = p \left( x - \frac{a+b}{2} \right)^2 + q \left( x - \frac{a+b}{2} \right) + r$$

那么

$$g'(x) = 2p \left( x - \frac{a+b}{2} \right) + q$$

因为

$$\begin{aligned} f'(a) &= g'(a) \\ f'(b) &= g'(b) \\ g\left(\frac{a+b}{2}\right) &= f\left(\frac{a+b}{2}\right) \end{aligned}$$

所以

$$\begin{aligned} f\left(\frac{a+b}{2}\right) &= r \\ f'(a) &= 2p \left( a - \frac{a+b}{2} \right) + q \\ f'(b) &= 2p \left( b - \frac{a+b}{2} \right) + q \end{aligned}$$

解得

$$\begin{cases} p = \frac{f'(a) - f'(b)}{2(a-b)} \\ q = \frac{f'(a) + f'(b)}{2} \\ r = f\left(\frac{a+b}{2}\right) \end{cases}$$

因此

$$g(x) = \frac{f'(a) - f'(b)}{2(a-b)} \left( x - \frac{a+b}{2} \right)^2 + \frac{f'(a) + f'(b)}{2} \left( x - \frac{a+b}{2} \right) + f\left(\frac{a+b}{2}\right)$$

(b)对 $g(x)$ 积分可得

$$\begin{aligned}
\int_a^b g(x)dx &= \frac{f'(a) - f'(b)}{2(a-b)} \int_a^b \left(x - \frac{a+b}{2}\right)^2 dx + \frac{f'(a) + f'(b)}{2} \int_a^b \left(x - \frac{a+b}{2}\right) dx + f\left(\frac{a+b}{2}\right) \int_a^b dx \\
&= -\frac{f'(a) - f'(b)}{2(a-b)} \times \frac{2}{3} \times \left(\frac{a-b}{2}\right)^3 + f\left(\frac{a+b}{2}\right) (b-a) \\
&= (b-a) \left(f\left(\frac{a+b}{2}\right) + \frac{1}{24}(f'(b) - f'(a))(b-a)\right)
\end{aligned}$$

(c)为方便叙述, 记

$$c = \frac{1}{2}(a+b)$$

那么 $f$ 在 $c$ 处的泰勒展开为

$$f(x) = f(c) + f'(c)(x-c) + \frac{1}{2}f''(c)(x-c)^2 + \frac{1}{6}f'''(c)(x-c)^3 + \frac{1}{24}f''''(c)(x-c)^4 + \cdots \quad (1)$$

对上式积分可得

$$\int_a^b f(x)dx = (b-a)f(c) + \frac{1}{24}f''(c)(b-a)^3 + \frac{1}{1920}f''''(c)(b-a)^5 + \cdots \quad (2)$$

注意

$$\begin{aligned}
\int_a^b g(x)dx &= (b-a) \left(f\left(\frac{a+b}{2}\right) + \frac{1}{24}(f'(b) - f'(a))(b-a)\right) \\
&= (b-a) \left(f(c) + \frac{1}{24}f''(\xi)(b-a)^2\right) \quad a \leq \xi \leq b \\
&= (b-a)f(c) + \frac{1}{24}f''(\xi)(b-a)^3
\end{aligned}$$

所以(2)可以化为

$$\begin{aligned}
\int_a^b f(x)dx &= (b-a)f(c) + \frac{1}{24}f''(\xi)(b-a)^3 - \frac{1}{24}f''(\xi)(b-a)^3 + \frac{1}{24}f''(c)(b-a)^3 + O((b-a)^5) \\
&= \int_a^b g(x)dx + O((b-a)^3)
\end{aligned}$$

所以精度为3次。

(d)假设

$$\Delta x = \frac{b-a}{k}, x_i = a + i\Delta x, i = 0, \dots, k$$

那么复合求积公式为

$$\int_a^b f(x)dx \approx \sum_{i=0}^{k-1} \Delta x \left(f\left(\frac{x_i + x_{i+1}}{2}\right) + \frac{1}{24}(f'(x_{i+1}) - f'(x_i)) \Delta x\right)$$

## Problem 4

利用范德蒙行列式计算结果：

$$\begin{pmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^{k-1} \\ 1 & x_2 & x_2^2 & \cdots & x_2^{k-1} \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ 1 & x_k & x_k^2 & \cdots & x_k^{k-1} \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \\ \vdots \\ a_{k-1} \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_k \end{pmatrix}$$

对应代码如下：

```
import numpy as np
import matplotlib.pyplot as plt

def Vandermon(X, k):
    #维度
    n = X.shape[0]
    #计算结果
    res = np.ones(n).reshape(-1, 1)
    x = np.copy(X)
    for i in range(k):
        res = np.c_[res, x]
        x *= X

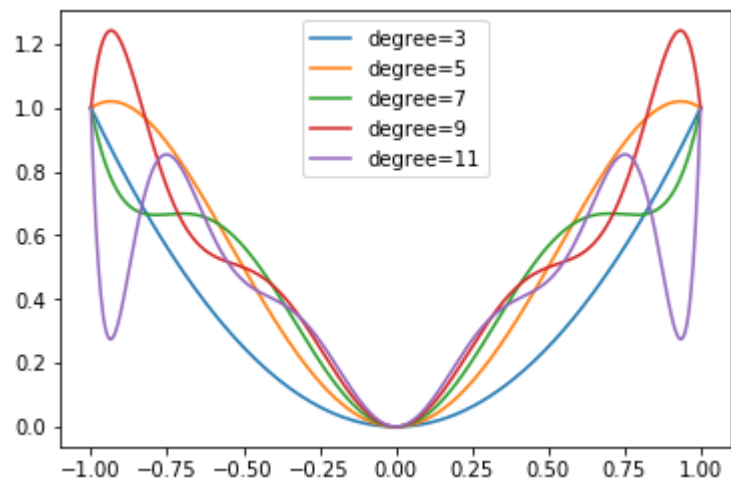
    return res

x1 = np.linspace(-1, 1, 500).reshape(-1, 1)

K = [3, 5, 7, 9, 11]
for k in K:
    x = np.linspace(-1, 1, k).reshape(-1, 1)
    y = np.abs(X)
    Van = Vandermon(X, k-1)
    #计算系数
    a = np.linalg.solve(Van, y)
    #计算结果
    y1 = Vandermon(x1, k-1).dot(a)
    plt.plot(x1, y1, label="degree={}".format(k))

plt.legend()
plt.show()
```

图像结果如下：



不难看出，随着次数增加，曲线变化幅度越来越大。