10.2

(a)

特征值:

$$\det(\lambda I - A) = \lambda^2 + w^2 = 0 \Rightarrow \lambda = \pm iw$$

resolvent:

$$egin{aligned} (sI-A)^{-1} &= egin{bmatrix} s & -\omega \ \omega & s \end{bmatrix} \ &= egin{bmatrix} rac{s}{s^2+w^2} & rac{\omega}{s^2+w^2} \ -rac{\omega}{s^2+w^2} & rac{s}{s^2+w^2} \end{bmatrix} \end{aligned}$$

状态转移矩阵:

$$\Phi(t) = \mathcal{L}^{-1} \left( (sI - A)^{-1} \right) \ = \begin{bmatrix} \cos wt & \sin wt \\ -\sin wt & \cos wt \end{bmatrix}$$

所以

$$x(t) = \begin{bmatrix} \cos wt & \sin wt \\ -\sin wt & \cos wt \end{bmatrix} x(0)$$

(b)略过

$$(c)$$
因为 $\begin{bmatrix} \cos wt & \sin wt \\ -\sin wt & \cos wt \end{bmatrix}$ 是正交矩阵,所以结论成立。

(d)

$$egin{aligned} rac{d}{dt} \|x(t)\|^2 &= rac{d}{dt} ig(x(t)^T x(t)ig) \ &= 2 \dot{x}(t)^T x(t) \ &= x(t)^T egin{bmatrix} 0 & -\omega \ \omega & 0 \end{bmatrix} x(t) \ &= 0 \end{aligned}$$

所以

$$\dot{x}(t)^T x(t) = 0$$

结论成立。

(a)

$$e^{A}e^{B} = \left(\sum_{i=0}^{\infty} \frac{A^{i}}{i!}\right) \left(\sum_{j=0}^{\infty} \frac{B^{j}}{j!}\right)$$

$$= \sum_{k=0}^{\infty} \sum_{i+j=k} \frac{1}{i!j!} A^{i} B^{j}$$

$$= \sum_{k=0}^{\infty} \frac{1}{k!} \sum_{i+j=k} \frac{k!}{i!j!} A^{i} B^{j}$$

$$= \sum_{k=0}^{\infty} \frac{1}{k!} (A+B)^{k} \qquad \text{for } AB = BA$$

$$= e^{(A+B)}$$

(b)

$$egin{aligned} rac{d}{dt}e^{At} &= rac{d}{dt}\left(\sum_{i=0}^{\infty}rac{(At)^i}{i!}
ight) \ &= \sum_{i=1}^{\infty}rac{A^it^{i-1}}{(i-1)!} \ &= A\sum_{i=1}^{\infty}rac{(At)^{i-1}}{(i-1)!} \ &= Ae^{At} \ &= \left(\sum_{i=1}^{\infty}rac{(At)^{i-1}}{(i-1)!}
ight)A \ &= e^{At}A \end{aligned}$$

10.4

(a)因为

$$A^2 = egin{bmatrix} -1 & 1 \ -1 & 1 \end{bmatrix} egin{bmatrix} -1 & 1 \ -1 & 1 \end{bmatrix} = 0$$

所以

$$e^{tA} = \sum_{i=0}^{\infty} \frac{(tA)^i}{i!}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} -1 & 1 \\ -1 & 1 \end{bmatrix} t$$

$$= \begin{bmatrix} 1-t & t \\ -t & 1+t \end{bmatrix}$$

取t = 1得到

$$e^A = egin{bmatrix} 0 & 1 \ -1 & 2 \end{bmatrix}$$

(b)由结论可得

$$egin{aligned} x(t) &= e^{tA}x(0) \ &= egin{bmatrix} 1-t & t \ -t & 1+t \end{bmatrix} egin{bmatrix} 1 \ a \end{bmatrix} \end{aligned}$$

令t = 1得到

$$x(1) = \begin{bmatrix} 0 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ a \end{bmatrix}$$
$$= \begin{bmatrix} a \\ 2a - 1 \end{bmatrix}$$

由题意可得

$$2a - 1 = 2 \Rightarrow a = \frac{3}{2}$$

因此

$$egin{aligned} x(t) &= egin{bmatrix} 1-t & t \ -t & 1+t \end{bmatrix} egin{bmatrix} 1 \ rac{3}{2} \end{bmatrix} \ &= egin{bmatrix} 1+rac{1}{2}t \ rac{3}{2}+rac{1}{2}t \end{bmatrix} \ x(2) &= egin{bmatrix} 2 \ rac{5}{2} \end{bmatrix} \end{aligned}$$

## 补充题

1

求导可得

$$\dot{x}(t) = a(t) \exp\left(\int_0^t a(\tau)d\tau\right) x(0)$$

$$= a(t)x(t)$$

作为反例,考虑(参考自解答)

$$A(t) = \left\{egin{array}{ll} A_1 & 0 \leq t < 1 \ A_2 & t \geq 1 \end{array}
ight.$$

那么

$$A_1 = \left[egin{matrix} 0 & 1 \ 0 & 0 \end{matrix}
ight], \qquad A_2 = \left[egin{matrix} 0 & 0 \ 1 & 0 \end{matrix}
ight]$$

那么

$$egin{aligned} x(2) &= (\exp A_2) \left( \exp A_1 
ight) x(0) \ &= egin{bmatrix} 1 & 1 \ 0 & 1 \end{bmatrix} egin{bmatrix} 1 & 0 \ 1 & 1 \end{bmatrix} x(0) \ &= egin{bmatrix} 1 & 1 \ 1 & 2 \end{bmatrix} x(0) \end{aligned}$$

但是,在上述公式中

$$egin{aligned} \int_0^2 A(t)dt &= \int_0^1 A_1 dt + \int_1^2 A_2 dt \ &= egin{bmatrix} 0 & 1 \ 1 & 0 \end{bmatrix} \ & riangleq B \end{aligned}$$

不难验证

$$B^{2k} = I, B^{2k+1} = B$$

所以

$$\exp(tB) = \sum_{i=0}^{\infty} \frac{B^i}{i!}$$

$$= \sum_{k=0}^{\infty} \frac{B^{2k}}{(2k)!} + \sum_{k=0}^{\infty} \frac{B^{2k+1}}{(2k+1)!}$$

$$= I \sum_{k=0}^{\infty} \frac{1}{(2k)!} + B \sum_{k=0}^{\infty} \frac{1}{(2k+1)!}$$

$$= I \frac{e+e^{-1}}{2} + B \frac{e-e^{-1}}{2}$$

$$= \begin{bmatrix} 1.5431 & 1.1752 \\ 1.1752 & 1.5431 \end{bmatrix}$$

因此

$$x(2) = egin{bmatrix} 1.5431 & 1.1752 \ 1.1752 & 1.5431 \end{bmatrix} x(0)$$

所以上述事实对高维情形不成立。