(a)

因为

$$egin{aligned} \langle u,v
angle &= u^*v \ &= (\mathfrak{R}u - i\mathfrak{I}u)^T(\mathfrak{R}v + i\mathfrak{I}v) \ &= (\mathfrak{R}u)^T\mathfrak{R}v + (\mathfrak{I}u)^T\mathfrak{I}v + ((\mathfrak{R}u)^T\mathfrak{I}v - (\mathfrak{R}v)^T\mathfrak{I}u)i \end{aligned} \ \langle ilde{u}, ilde{v}
angle &= \begin{bmatrix} \mathfrak{R}u \ \mathfrak{I}u \end{bmatrix}^T \begin{bmatrix} \mathfrak{R}v \ \mathfrak{I}v \end{bmatrix} \ &= (\mathfrak{R}u)^T\mathfrak{R}v + (\mathfrak{I}u)^T\mathfrak{I}v \end{aligned}$$

所以

$$\langle \tilde{u}, \tilde{v} \rangle = \Re \langle u, v \rangle$$
 (1)

(b)

$$||u|| = (|u_1|^2 + \dots + |u_n|^2)^{1/2}$$

$$= (|\Re u_1|^2 + |\Im u_1|^2 + \dots + |\Re u_n|^2 + |\Im u_n|^2)^{1/2}$$

$$= (|\Re u|^2 + |\Im u|^2)^{1/2}$$

$$= ||\tilde{u}||$$
(2)

另解:对(1)中取

$$u = v$$

那么由于

$$(\mathfrak{R}u)^T\mathfrak{I}v - (\mathfrak{R}v)^T\mathfrak{I}u = (\mathfrak{R}u)^T\mathfrak{I}u - (\mathfrak{R}u)^T\mathfrak{I}u = 0$$

即虚部为0,所以

$$\| ilde{u}\|^2 = \langle ilde{u}, ilde{u}
angle = \langle u, u
angle = \|u\|^2$$

(c)

$$Au = (\Re A + i\Im A) (\Re u + i\Im u)$$

$$= \Re A\Re u - \Im A\Im u + (\Re A\Im u + \Im A\Re u) i$$

$$\tilde{A}\tilde{u} = \begin{bmatrix} \Re A & -\Im A \\ \Im A & \Re A \end{bmatrix} \begin{bmatrix} \Re u \\ \Im u \end{bmatrix}$$

$$= \begin{bmatrix} \Re A\Re u - \Im A\Im u \\ \Re A\Im u + \Im A\Re u \end{bmatrix}$$

$$= \widetilde{(Au)}$$
(3)

(d)

$$\tilde{A}^{T} = \begin{bmatrix} \Re A^{T} & \Im A^{T} \\ -\Im A^{T} & \Re A^{T} \end{bmatrix}
A^{*} = \Re A^{T} - i\Im A^{T}
\tilde{A}^{*} = \begin{bmatrix} \Re A^{T} & \Im A^{T} \\ -\Im A^{T} & \Re A^{T} \end{bmatrix}
= \tilde{A}^{T}$$
(4)

(e)补充证明如下结论:

$$(\widetilde{A^{-1}}) = (\tilde{A})^{-1} \tag{5}$$

首先, 我们有

$$egin{aligned} I_n &= A^{-1}A \ &= \left(\mathfrak{R}(A^{-1}) + i\mathfrak{I}(A^{-1})\right)\left(\mathfrak{R}A + i\mathfrak{I}A\right) \ &= \left(\mathfrak{R}(A^{-1})\mathfrak{R}A - \mathfrak{I}(A^{-1})\mathfrak{I}A\right) + i\left(\mathfrak{I}(A^{-1})\mathfrak{R}A + \mathfrak{R}(A^{-1})\mathfrak{I}A\right) \end{aligned}$$

所以

$$\mathfrak{R}(A^{-1})\mathfrak{R}A - \mathfrak{I}(A^{-1})\mathfrak{I}A = I_n$$

 $\mathfrak{I}(A^{-1})\mathfrak{R}A + \mathfrak{R}(A^{-1})\mathfrak{R}A = 0$

其次我们有

$$\widetilde{(A^{-1})} = egin{bmatrix} \mathfrak{R}(A^{-1}) & -\mathfrak{I}(A^{-1}) \ \mathfrak{I}(A^{-1}) & \mathfrak{R}(A^{-1}) \end{bmatrix}$$

所以

$$\widetilde{(A^{-1})}\widetilde{A} = \begin{bmatrix} \Re(A^{-1}) & -\Im(A^{-1}) \\ \Im(A^{-1}) & \Re(A^{-1}) \end{bmatrix} \begin{bmatrix} \Re A & -\Im A \\ \Im A & \Re A \end{bmatrix} \\
= \begin{bmatrix} \Re(A^{-1})\Re A - \Im(A^{-1})\Im A & -\Re(A^{-1})\Im A - \Im(A^{-1})\Re A \\ \Re(A^{-1})\Im A + \Im(A^{-1})\Re A & \Re(A^{-1})\Re A - \Im(A^{-1})\Im A \end{bmatrix} \\
= \begin{bmatrix} I_n & 0 \\ 0 & I_n \end{bmatrix} \\
= I_{2n}$$

因此结论成立。

由之前的记号可得

$$||Ax - y||^2 = ||\widetilde{Ax - y}||^2 \qquad \text{th}(2)$$

$$= \langle \widetilde{Ax - y}, \widetilde{Ax - y} \rangle$$

$$= \langle \widetilde{Ax} - \widetilde{y}, \widetilde{Ax} - \widetilde{y} \rangle \qquad \text{th}(3)$$

$$= ||\widetilde{Ax} - \widetilde{y}||^2$$

由最小二乘法, 我们知道该问题的解为

$$ilde{x} = (ilde{A}^T ilde{A})^{-1} ilde{A}^T ilde{y}$$

下面证明

$$\tilde{x}_{1s} = \tilde{x}$$

即

$$(A^*\widetilde{A)}^{-1}A^*y=(\widetilde{A}^T\widetilde{A})^{-1}\widetilde{A}^T\widetilde{y}$$

证明如下:

$$(A^* \widetilde{A})^{-1} A^* y = (\widetilde{A^* A})^{-1} \widetilde{A}^* \widetilde{y} \qquad \text{ th } (3)$$

$$= (\widetilde{A^* A})^{-1} \widetilde{A}^* \widetilde{y} \qquad \text{ th } (5)$$

$$= (\widetilde{A}^* \widetilde{A})^{-1} \widetilde{A}^* \widetilde{y} \qquad \text{ th } (3)$$

$$= (\widetilde{A}^T \widetilde{A})^{-1} \widetilde{A}^T \widetilde{y} \qquad \text{ th } (4)$$

6.2

(a)首先目标函数为

$$\int_{t=0}^{10} f(t)^2 dt = \sum_{i=1}^{10} \int_{i-1}^{i} f(t)^2 dt$$

$$= \sum_{i=1}^{10} \int_{i-1}^{i} x_i^2 dt$$

$$= \sum_{i=1}^{10} x_i^2$$

$$= ||x||^2$$

 $\forall k, j-1 < k \leq j$, 那么由牛顿第二定律可得,

$$egin{aligned} \dot{p}(k) &= \int_0^k f(t) dt \ &= \sum_{i=1}^{j-1} \int_{i-1}^i f(t) dt + \int_{j-1}^k f(t) dt \ &= \sum_{i=1}^{j-1} \int_{i-1}^i x_i dt + \int_{j-1}^k x_j dt \ &= \sum_{i=1}^{j-1} x_i + (k-j+1) x_j \end{aligned}$$

任取整数k, 我们有

$$egin{aligned} p(k) &= \int_0^k \dot{p}(t) dt \ &= \sum_{i=1}^k \int_{i-1}^i \dot{p}(t) dt \ &= \sum_{i=1}^k \int_{i-1}^i \left(\sum_{k=1}^{i-1} x_k + (t-i+1) x_i
ight) dt \ &= \sum_{i=1}^k \left(\sum_{k=1}^{i-1} x_k + rac{1}{2} x_i
ight) dt \ &= \sum_{i=1}^k \left(k - i + rac{1}{2}
ight) x_i \end{aligned}$$

所以题目中的约束条件为

$$egin{split} \sum_{i=1}^{10} \left(10-i+rac{1}{2}
ight)x_i &= 1 \ \sum_{i=1}^9 x_i + (10-10+1)x_j &= \sum_{i=1}^{10} x_i &= 0 \ \sum_{i=1}^5 \left(5-i+rac{1}{2}
ight)x_i &= 0 \end{split}$$

写成矩阵的形式为

$$Ax = b$$

其中

所以优化问题为

$$\min \quad ||x||^2 = x^T x$$
subject to
$$Ax = b$$

构造拉格朗日乘子:

$$L(x,\lambda) = x^T x - \lambda^T (Ax - b)$$

求梯度并令梯度为0得到:

$$abla_x L(x,\lambda) = 2x - 2A^T \lambda = 0$$
 $abla_\lambda L(x,\lambda) = Ax - b = 0$

解得

$$\lambda = \left(AA^T
ight)^{-1}y \ x = A^T\left(AA^T
ight)^{-1}y$$

matlab中使用如下命令计算即可:

$$x = pinv(A) * b$$

完整代码如下:

```
% (a)
a1 = linspace(9.5, 0.5, 10);
a2 = ones(1,10);
a3 = [linspace(4.5, 0.5, 5), 0 0 0 0 0];

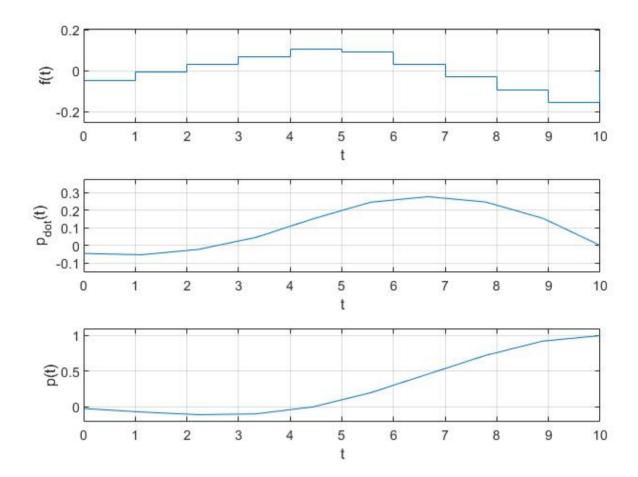
A = [a1; a2; a3];
b = [1; 0; 0];
x = pinv(A) * b
```

```
x =
    -0.0455
    -0.0076
    0.0303
    0.0682
    0.1061
    0.0939
    0.0318
    -0.0303
    -0.0924
    -0.1545
```

作图代码:

```
% 作图
% f(t)
figure(1);
subplot(3,1,1);
stairs(0:10, [x; 0]);
grid on;
xlabel('t');
ylabel('f(t)');
axis([0, 10, min(x) - 0.1, max(x) + 0.1]);
% p_dot(t)
T1 = toeplitz(ones(10,1), [1,zeros(1,9)]);
p_dot = T1 * x;
subplot(3,1,2);
plot(linspace(0, 10, 10), p_dot);
grid on;
xlabel('t');
ylabel('p_{dot}(t)');
axis([0, 10, min(p_dot) - 0.1, max(p_dot) + 0.1]);
% p(t)
T2 = toeplitz(linspace(0.5, 9.5, 10)', [0.5, zeros(1,9)]);
p = T2 * x;
subplot(3,1,3);
plot(linspace(0, 10, 10), p);
grid on;
xlabel('t');
ylabel('p(t)');
axis([0, 10, min(p) - 0.1, max(p) + 0.1]);
```

结果如下:



(b)首先

$$J_2 = \int_{t=0}^{10} f(t)^2 dt$$

$$= \sum_{i=1}^{10} \int_{i-1}^{i} f(t)^2 dt$$

$$= \sum_{i=1}^{10} \int_{i-1}^{i} x_i^2 dt$$

$$= \sum_{i=1}^{10} x_i^2$$

$$= ||x||^2$$

其次 $\forall k, j-1 < k \leq j$,那么由牛顿第二定律可得,

$$egin{align} \dot{p}(k) &= \dot{p}(0) + \int_0^k f(t)dt \ &= 1 + \sum_{i=1}^{j-1} \int_{i-1}^i f(t)dt + \int_{j-1}^k f(t)dt \ &= 1 + \sum_{i=1}^{j-1} \int_{i-1}^i x_i dt + \int_{j-1}^k x_j dt \ &= \sum_{i=1}^{j-1} x_i + (k-j+1)x_j + 1 \ \end{cases}$$

以及任取整数k:

$$egin{aligned} p(k) &= \int_0^k \dot{p}(t) dt \ &= \sum_{i=1}^k \int_{i-1}^i \dot{p}(t) dt \ &= \sum_{i=1}^k \int_{i-1}^i \left(\sum_{k=1}^{i-1} x_k + (t-i+1) x_i + 1
ight) dt \ &= \sum_{i=1}^k \left(\sum_{k=1}^{i-1} x_k + rac{1}{2} x_i + 1
ight) dt \ &= k + \sum_{i=1}^k \left(k - i + rac{1}{2}
ight) x_i \end{aligned}$$

此时的约束条件为

\$ \begin{aligned} p(10)& =0\\ \dot p(10)& =0 \end{aligned} \$

而

记

那么

$$J_1 = p(10)^2 + \dot{p}(10)^2$$

= $||Ax - y||^2$

所以优化函数为

$$J_1 + \mu J_2 = \|Ax - y\|^2 + \mu \|x\|^2$$

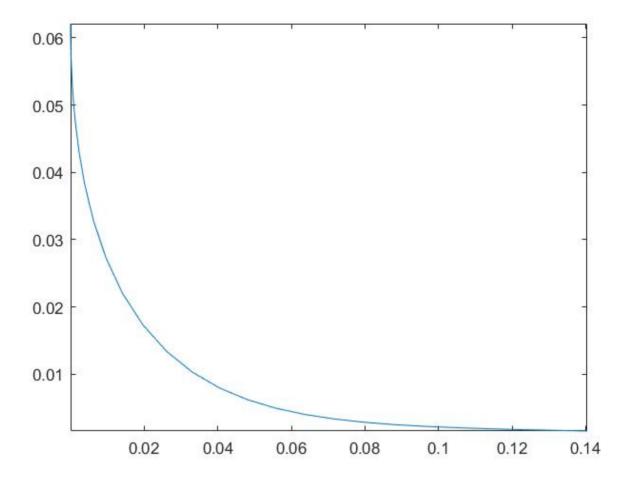
因此

$$x_{\mu} = \left(A^TA + \mu I
ight)^{-1}A^Ty$$

代码如下:

```
% (b)
% 作图
N = 50;
[d, m] = size(A);
Mu = logspace(-5, 2, N);
J1 = zeros(N, 1);
J2 = zeros(N, 1);
for i = 1:N
    mu = Mu(i);
    %x = inv(A' * A + mu * eye(m)) * A' * b;
    x = (A' * A + mu * eye(m)) \setminus (A' * b);
    j1 = norm(A * x - b) \land 2;
    j2 = norm(x) \wedge 2;
    J1(i) = j1;
    J2(i) = j2;
end
figure(2);
plot(J1, J2);
axis tight;
```

结果如下:



6.5 将f(x)的定义代入

 $f(x_i)=y_i$

得到

$$egin{aligned} rac{\sum_{j=0}^m a_j x_i^j}{1 + \sum_{j=1}^m b_j x_i^j} &= y_i \ &\sum_{j=0}^m a_j x_i^j &= y_i \left(1 + \sum_{j=1}^m b_j x_i^j
ight) \ a_0 + \sum_{j=1}^m a_j x_i^j + \sum_{j=1}^m b_j (-y_i x_i^j) &= y_i \end{aligned}$$

$$X_1 = egin{bmatrix} x_1 & x_1^2 & \dots & x_1^m \ dots & dots & \ddots & dots \ x_N & x_N^2 & \dots & x_N^m \end{bmatrix} \ X_2 = egin{bmatrix} -y_1 x_1 & -y_1 x_1^2 & \dots & -y_1 x_1^m \ dots & dots & \ddots & dots \ -y_N x_N & -y_N x_N^2 & \dots & -y_N x_N^m \end{bmatrix} = - ext{diag}(y) X_1 \ X = egin{bmatrix} 1_N & X_1 & X_2 \end{bmatrix} \in \mathbb{R}^{N imes (2m+1)} \ C = egin{bmatrix} a_0 \ dots \ a_m \ b_1 \ dots \ b_m \end{bmatrix} \in \mathbb{R}^{2m+1} \ dots \ b_m \end{bmatrix}$$

所以线性方程组为

$$Xc = y$$

要使得该方程有解,应该找到最小的m,使得

$$\mathrm{rank}(X)=\mathrm{rank}(X,y)$$

代码如下:

```
% 初始化
m = 1;
X1 = x;

while 1
    X1 = [X1, x .* X1(:, m)];
    X2 = - diag(y) * X1;
    X = [ones(N, 1), X1, X2];
    m = m + 1;
    % 判断
    res = (rank(X) == rank([X, y]));

    if res
        break
    end
end
m
```

```
5
```

计算系数:

%计算结果

```
c = X \setminus y;

a = c(1: m + 1)

b = c(m + 2: 2 * m + 1)
```

```
a =

0.2742
1.0291
1.2906
-5.8763
-2.6738
6.6845
b =

-1.2513
-6.5107
3.2754
17.3797
6.6845
```

6.12

记

$$y = egin{bmatrix} y_1 \ dots \ y_n \end{bmatrix}, v = egin{bmatrix} v_1 \ dots \ v_n \end{bmatrix}, w = egin{bmatrix} w_1 \ dots \ w_m \end{bmatrix}, s = egin{bmatrix} 1 \ dots \ m \end{bmatrix}$$

所以

$$v = \alpha 1_n + \beta T s + w$$

所以模型为

$$y = Ax + v = Ax + \alpha 1_m + \beta Ts + w$$

注意 α , β 未知, 所以记

$$ilde{x} = egin{bmatrix} x \ lpha \ eta \end{bmatrix} \in \mathbb{R}^{n+2}, ilde{A} = egin{bmatrix} A & 1_m & Ts \end{bmatrix} \in \mathbb{R}^{m imes (n+2)}$$

模型修改为

$$y = ilde{A} ilde{x} + w$$

利用最小二乘法求解该问题即可, 正规方程为

$${ ilde A}^T { ilde A} { ilde x} = { ilde A}^T w$$

如果 \tilde{A} 满秩,那么该问题的解为

$$ilde{x} = \left(ilde{A}^T ilde{A}
ight)^{-1} ilde{A}^T w$$

6.14

(a)

$$egin{aligned} J &= \sum_{k=1}^{N} \left\| Ax^{(k)} - y^{(k)}
ight\|^2 \ &= \sum_{k=1}^{N} \left(Ax^{(k)} - y^{(k)}
ight)^T \left(Ax^{(k)} - y^{(k)}
ight) \ &= \sum_{k=1}^{N} \left(\left(x^{(k)}
ight)^T A^T Ax^{(k)} + \left(y^{(k)}
ight)^T y^{(k)} - 2 \left(y^{(k)}
ight)^T Ax^{(k)}
ight) \ &= \operatorname{trace} \left(X^T A^T AX + Y^T Y - 2 Y^T AX
ight) \end{aligned}$$

接着利用如下公式求梯度:

$$abla_X ext{trace} \left(AXB
ight) = A^T B^T \
abla_X ext{trace} \left(AXX^T B
ight) = A^T B^T X + BAX$$

我们有

$$egin{aligned}
abla_A J &=
abla_A \mathrm{trace} \left(X^T A^T A X
ight) - 2
abla_A \mathrm{trace} \left(Y^T A X
ight) \ &= \left(
abla_{A^T} \mathrm{trace} \left(X^T A^T A X
ight)
ight)^T - 2 Y X^T \ &= \left(X X^T A^T + X X^T A^T
ight)^T - 2 Y X^T \ &= 2 A X X^T - 2 Y X^T \end{aligned}$$

令梯度为0得到

$$AXX^T = YX^T$$

$$A = YX^T (XX^T)^{-1}$$

(b)实现上述算法:

A = Y * X' / (X * X')

```
2.0299
         5.0208
                   5.0104
0.0114
         6.9999
                   1.0106
       -0.0025
                   6.9448
7.0424
6.9977
         3.9759
                   4.0024
9.0130
       1.0449
                   6.9980
4.0119
       3.9649
                   9.0267
       6.9723
4.9871
                   8.0336
7.9425
       6.0875
                  3.0174
0.0094
         8.9722
                  -0.0385
1.0612
         8.0208
                   7.0285
```

(a)题目的意思是利用 q_i, p_i 估计 α, d_i 题目中的记号有些重复,这里假设

$$p_i = a\alpha\cos\varphi_i + v_i$$

其中

$$egin{aligned} \cos arphi_i &= rac{d.\,q_i}{\|d\|.\,\|q_i\|} \ &= q_i^T d \ &= (\cos \phi_i \cos heta_i) d_1 + (\cos \phi_i \sin heta_i) d_2 + (\sin \phi_i) d_3 \end{aligned}$$

假设

$$p = \left[egin{array}{c} p_1 \ dots \ p_m \end{array}
ight] \in \mathbb{R}^m, q = \left[egin{array}{c} q_1^T \ dots \ q_m^T \end{array}
ight] \in \mathbb{R}^{m imes 3}. \, v = \left[egin{array}{c} v_1 \ dots \ v_m \end{array}
ight] \in \mathbb{R}^m$$

S

$$p = \alpha q(ad) + v$$

注意a, d未知, 并且d的模长为1, 所以可以设

$$x = ad$$

那么模型为

$$p = \alpha qx + v$$

估计x后,利用下式计算a,d即可:

$$a = ||x||$$
$$d = \frac{x}{||x||}$$

(b)代码如下:

```
% Data for beam estimation problem
m = 5;
alpha = 0.5;
det_az =[ 3  10  80  150  275];
det_el =[ 88  34  30  20  50];
p =[ 1.58  1.50  2.47  1.10  0.001];

q1 = [cosd(det_el'), cosd(det_el'), sind(det_el')];
q2 = [cosd(det_az'), sind(det_az'), ones(m, 1)];
q = q1  .* q2;

x = (alpha * q) \ p';
a = norm(x)
d = x / a;

elevation = asind(d(3))
azimuth = asind(d(2) / cosd(elevation))
```

```
a =
    5.0107
elevation =
    38.7174
azimuth =
    77.6623
```

(a)首先考虑特殊情形。

如果 $\mu=0$,那么取

$$g = f$$

如果 $\mu o \infty$,那么取

$$g_i = ai + b$$

所以此时的优化问题为

$$\left\|f-A\left[egin{a}{a}{b}
ight]
ight\|$$

其中

$$A = egin{bmatrix} 1 & 1 \ 2 & 1 \ 3 & 1 \ dots & dots \ n & 1 \end{bmatrix}$$

因此

$$\left[egin{aligned} a \ b \end{aligned}
ight] = \left(A^TA
ight)^{-1}A^Tf$$

接着考虑一般情形。

对均方曲率进行处理,令

$$h = egin{bmatrix} g_3 - 2g_2 + g_1 \ dots \ g_n - 2g_{n-1} + g_{n-2} \end{bmatrix} \ = egin{bmatrix} g_3 \ dots \ g_n \end{bmatrix} - 2egin{bmatrix} g_2 \ dots \ g_{n-1} \end{bmatrix} + egin{bmatrix} g_1 \ dots \ g_{n-2} \end{bmatrix}$$

记

$$egin{aligned} D_1 &= egin{bmatrix} I_{n-2} & 0 & 0 \end{bmatrix} \in \mathbb{R}^{(n-2) imes n} \ D_2 &= egin{bmatrix} 0 & I_{n-2} & 0 \end{bmatrix} \in \mathbb{R}^{(n-2) imes n} \ D_3 &= egin{bmatrix} 0 & 0 & I_{n-2} \end{bmatrix} \in \mathbb{R}^{(n-2) imes n} \ D &= D_1 + D_3 - 2D_2 \end{aligned}$$

那么

$$h = Dg$$

所以

$$d = rac{1}{n} \|f - g\|^2$$
 $c = rac{n^4}{n-2} \|h\|^2$
 $= rac{n^4}{n-2} \|Dg\|^2$

所以目标函数为

$$egin{align} d + \mu c &= rac{1}{n} \|f - g\|^2 + \mu rac{n^4}{n-2} \|Dg\|^2 \ &= \left\|rac{1}{\sqrt{n}} g - rac{1}{\sqrt{n}} f
ight\|^2 + \mu \left\|rac{n^2 \sqrt{n}}{\sqrt{n-2}} D rac{1}{\sqrt{n}} g
ight\|^2 \end{split}$$

对比课件中的标准形式:

$$J_1 + \mu J_2 = ||Ax - y||^2 + \mu ||Fx - h||^2$$

我们有

$$x=rac{1}{\sqrt{n}}g$$
 $y=rac{1}{\sqrt{n}}f$ $A=I_n$ $F=rac{n^2\sqrt{n}}{\sqrt{n-2}}D$ $h=0$

所以问题的解为

$$egin{aligned} x &= rac{1}{\sqrt{n}}g \ &= \left(A^TA + \mu F^TF
ight)^{-1}\left(A^Ty + \mu F^Th
ight) \ &= \left(I_n + \mu rac{n^5}{n-2}D^TD
ight)^{-1}\left(rac{1}{\sqrt{n}}f
ight) \end{aligned}$$

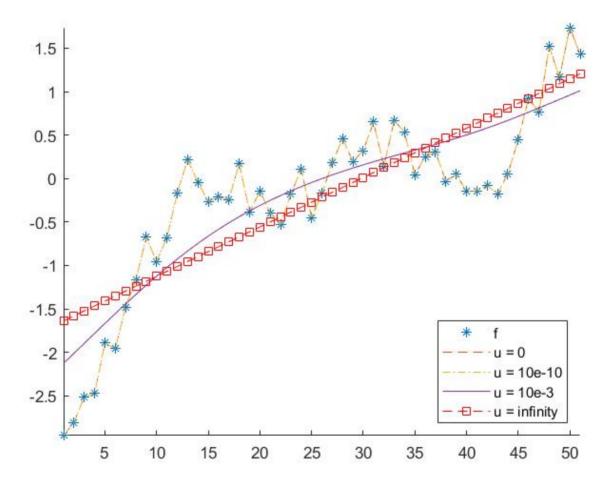
即

$$g = \left(I_n + \mu rac{n^5}{n-2} D^T D
ight)^{-1} f$$

(b)对不同的 μ 作图:

```
% 矩阵D
D1 = [eye(n - 2), zeros(n - 2, 2)];
D2 = [zeros(n - 2, 1), eye(n - 2), zeros(n - 2, 1)];
D3 = [zeros(n - 2, 2), eye(n - 2)];
D = D1 + D3 - 2 * D2;
% 作出不同的mu
% mu = 0
mu = 0;
g1 = (eye(n) + mu * n \wedge 5 / (n - 2) * (D' * D)) \setminus f';
% mu = 1e-10
mu = 1e-10;
g2 = (eye(n) + mu * n \wedge 5 / (n - 2) * (D' * D)) \setminus f';
% mu = 1e-3
mu = 1e-3;
g3 = (eye(n) + mu * n \wedge 5 / (n - 2) * (D' * D)) \setminus f';
% mu = infty
A = [(1:n)', ones(n, 1)];
coef = A \ f';
g4 = A * coef;
```

```
% 作图
figure(1);
hold;
plot(f, '*');
plot(g1, '--');
plot(g2, '--');
plot(g3, '-');
plot(g4, '--rs');
axis tight;
legend('f','u = 0', 'u = 10e-10', 'u = 10e-3', 'u = infinity', 'location', 'SouthEast');
```



作出权衡曲线:

```
% 权衡曲线
m = 30;
Mu = logspace(-8, -3, m);
x = zeros(m+2, 1);
y = zeros(m+2, 1);

x(1) = norm(f' - g1) ^ 2 / n;
y(1) = norm(D * g1) ^ 2 * n ^ 4 / (n - 2);
for i = 1: m
    mu = Mu(i);
    g = (eye(n) + mu * n ^ 5 / (n - 2) * (D' * D)) \ f';
```

```
x(i+1) = norm(f' - g) \land 2 / n;

y(i+1) = norm(D * g) \land 2 * n \land 4 / (n - 2);

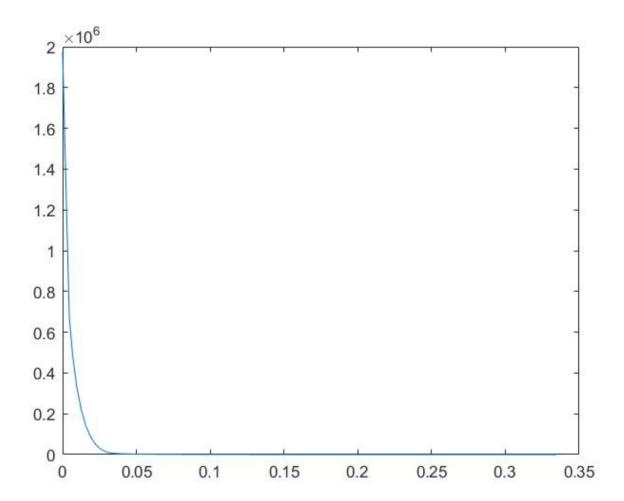
end

x(m+2) = norm(f' - g4) \land 2 / n;

y(m+2) = norm(D * g4) \land 2 * n \land 4 / (n - 2);

figure(2)

plot(x, y);
```



题目的要求等价于求

$$h \left[egin{array}{cc} G & ilde{G}
ight] = \left[egin{array}{cc} I_n & I_n
ight] \end{array}$$

转置后得到

$$egin{bmatrix} G^T \ ilde{G}^T \end{bmatrix} h^T = egin{bmatrix} I_n \ I_n \end{bmatrix}$$

对于例子中的情形, 我们需要求

$$egin{bmatrix} G^T \ ilde{G}^T \end{bmatrix} h^T = egin{bmatrix} I_2 \ I_2 \end{bmatrix}$$

求解该线性方程组即可,由于方程数量大于未知数数量,所以使用左逆即可

$$A^\dagger = \left(A^TA
ight)^{-1}A^T$$

代码如下:

```
G = [2 3; 1 0; 0 4; 1 1; -1 2];
G_tilde = [-3 -1; -1 0; 2 -3; -1 -3; 1 2];
A = [G'; G_tilde'];
b = [eye(2); eye(2)];
X = pinv(A) * b;
h = X';
%验证结果
h * G
h * G_tilde
```

```
ans =

1.0000 -0.0000

-0.0000 1.0000

ans =

1.0000 0

0.0000 1.0000
```