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Abstract

Keywords

- 1. Introduction
- 2. The estimation problem and the estimator
- 3. Convergence of the estimator
- 4. Conclusion
- 5. Summary

References

Vitae



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Gaussian mixture parameter estimation with known means and unknown class-dependent variances

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Abstract

This paper develops a recursive, convergent estimator for some parameters of Gaussian mixtures. The *M* class conditional (component) densities of the mixture random variable are Gaussian with known and distinct means and unknown and possibly different variances. A joint estimator of *M* prior (mixing) probabilities and *M* class conditional variances is derived. Sufficient conditions on the data and control parameters are derived for the estimator to converge. Convergence of the estimator follows from the use of a stochastic approximation theorem. Techniques to extend the estimators for the case of successive class labels forming a

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Markov chain are mentioned. The estimator has applications in blind parameter estimation in digital communication with symbol dependent noise variance and in image compression.

Keywords

Symbol-dependent variances; Class-dependent additive Gaussian noise; Blind parameter estimation; Adaptive receivers; Nonuniform image quantization

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