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Homework 3:

Exercise 1

$$\begin{aligned} 1) \quad q(y, z, \theta) &= \pi(y|z, \theta) \pi(z|\theta) \pi(\theta) \\ &= \pi(\theta) \pi(z_{\text{pop}}|\theta) \prod_{i=1}^N \left(\prod_{j=1}^{k_i} \pi(y_{ij}|z_i, \theta) \right) \pi(z_i|\theta) \end{aligned}$$

by independence

$$\begin{aligned} \text{then } \pi(\theta) &= \pi(\theta_{\text{pop}}) \times \pi(\theta_i) \\ &= \phi(\bar{t}_0; \bar{t}_0, \sigma_{t_0}^2) \phi(\bar{z}_0; \bar{z}_0, \sigma_{z_0}^2) \\ &\quad \times f_{W_1}(\sigma_1^2) f_{W_1}(\sigma_2^2) f_{W_1}(\sigma^2) \end{aligned}$$

$$\pi(z_{\text{pop}}|\theta) = \phi(\bar{t}_0; \bar{t}_0, \sigma_{t_0}^2) \phi(\bar{z}_0; \bar{z}_0, \sigma_{z_0}^2)$$

$$\pi(z_i|\theta) = \phi(\log(d_i); 0, \sigma_1^2) \phi(\tau_i; 0, \sigma_2^2)$$

$$\text{and } \pi(y_{ij}|z_i, \theta) = \phi(y_{ij} - d_i(\tau_{ij}^2); 0, \sigma^2)$$

where $\phi(\cdot; \mu, \sigma^2)$ is the density of gaussian distribution with mean μ and variance σ^2 .

$$\begin{aligned} \log q(y, z|\theta) &= \log(\pi(z_{\text{pop}}|\theta)) \prod_{i=1}^N \left(\prod_{j=1}^{k_i} \pi(y_{ij}|z_i, \theta) \right) \pi(z_i|\theta) \\ &= c(y, z) - \frac{\bar{t}_0^2}{2\sigma_{t_0}^2} - \frac{2\bar{t}_0\bar{z}_0}{2\sigma_{t_0}\sigma_{z_0}} - \frac{\bar{z}_0^2}{2\sigma_{z_0}^2} \\ &\quad - \frac{N}{2} \left[\frac{\log(d_i)^2}{2\sigma_1^2} + \frac{\tau_i^2}{2\sigma_2^2} + \sum_{j=1}^{k_i} \frac{(y_{ij} - d_i(\tau_{ij}^2))^2}{2\sigma^2} \right] \\ &\quad - \frac{N}{2} [\log(\sigma_1^2) + \log(\sigma_2^2)] - \left(\frac{\sum_{i=1}^N k_i}{2} \right) \log(\sigma^2) \end{aligned}$$

which can be rewritten as:

$$\log q(y, g | \theta) = c(y, g) - \phi(\theta) + \langle S(y, g)^T, \Psi(\theta) \rangle$$

where $c(y, g)$ does not depend on θ ,

$$S(y, g) = \begin{pmatrix} \sum_{i=1}^N \sum_{j=1}^{B_i} (y_{ij} - \mu_0(t_{ij}))^2 \\ \sum_{i=1}^N \log(\sigma_0^2) \\ \sum_{i=1}^N \tau_i^2 \\ \sigma_0 \\ \sigma_0^2 \\ \tau_0 \\ \sigma_0^2 \end{pmatrix} \text{ and } \Psi(\theta) = \begin{pmatrix} -\frac{1}{2\sigma_0^2} \\ -\frac{1}{2\sigma_0^2} \\ -\frac{1}{2\sigma_0^2} \\ \frac{\sigma_0}{\sigma_0^2} \\ \frac{1}{\sigma_0^2} \\ \frac{\tau_0}{\sigma_0^2} \\ \frac{1}{\sigma_0^2} \end{pmatrix}$$

$$\text{and } \phi(\theta) = \frac{\tau_0^2}{2\sigma_0^2} + \frac{\sigma_0^2}{2\sigma_0^2} + \frac{N}{2} \log(\sigma_0^2) + \frac{N}{2} \log(\sigma_0^2) + \frac{1}{2} \sum_{i=1}^N B_i \log(\sigma_0^2)$$

3) We want to sample from $\Pi(g) = \int q(y, g | \theta)$.
The problem lies in the fact that this distribution is too complicated to compute the ratios

$$\begin{aligned} \text{but } \frac{r(g^* | y, \theta)}{r(g^{(0)} | y, \theta)} &= \frac{r(y | g^*, \theta) r(g^*, \theta)}{r(y | \theta) r(g^{(0)}, \theta)} \\ &\quad \times \frac{r(y | \theta)}{r(y | g^{(0)}, \theta) r(g^{(0)}, \theta)} \\ &= \frac{r(y | g^*, \theta)}{r(y | g^{(0)}, \theta)} \times \frac{r(g^* | \theta) r(\theta)}{r(g^{(0)} | \theta) r(\theta)} \\ &= \frac{r(y | g^*, \theta) r(g^* | \theta)}{r(y | g^{(0)}, \theta) r(g^{(0)} | \theta)} \end{aligned}$$

which is easy to compute.

4) Recalling that $\theta = (\tau_0, \sigma_0, \sigma_0^2, \sigma_0^2, \sigma_0^2)$,
 $\forall \theta \log q(g | \theta) = 0$ is equivalent to:

$$\begin{aligned} \frac{-\tau_0 + \tau_0}{\sigma_0^2} &= 0 \\ \frac{-\sigma_0 + \sigma_0}{\sigma_0^2} &= 0 \\ \frac{\log(\sigma_0^2)}{2\sigma_0^2} - \frac{N}{2\sigma_0^2} &= 0 \\ \frac{\tau_0^2}{2\sigma_0^2} - \frac{N}{2\sigma_0^2} &= 0 \end{aligned}$$

$$\text{and } \sum_{i=1}^N \sum_{j=1}^{B_i} \frac{(y_{ij} - d_i(b_{ij}))^2}{2\sigma^4} - \left(\sum_{i=1}^N B_i \right) \times \frac{1}{\sigma^2} = 0$$

$$\text{so } \overline{b_0^{(R+1)}} = \overline{b_0} = S_0$$

$$\overline{\sigma_0^{(R+1)}} = \overline{\sigma_0} = S_4$$

$$\sigma_3^2 = \frac{1}{N} \sum_{i=1}^N \log(b_i)^2 = \frac{1}{N} S_2$$

$$\sigma_4^2 = \frac{1}{N} \sum_{i=1}^N \tau_i^2 = \frac{1}{N} S_3$$

$$\sigma^2(R+1) = \frac{1}{\sum_{i=1}^N B_i} \sum_{i=1}^N \sum_{j=1}^{B_i} (y_{ij} - d_i(b_{ij}))^2 = \frac{1}{\sum_{i=1}^N B_i} S_1$$

$$5) \text{ Given } \mathbf{z}_i^{(R)} = (\xi_i^{(R)}, \tau_i^{(R)})$$

$$\xi_i^{(R+1)} \sim p(\xi_i | \tau_i^{(R)}, \mathbf{z}_{-i}^{(R)}, y, \theta)$$

$$\tau_i^{(R+1)} \sim p(\tau_i | \xi_i^{(R+1)}, \mathbf{z}_{-i}^{(R)}, y, \theta)$$

where $p(\xi_i | \tau_i^{(R)}, \mathbf{z}_{-i}^{(R)}, y, \theta)$ can be sampled using Hastings - Metropolis method with

$$\frac{p(\xi_i^* | \tau_i, \mathbf{z}_{-i}^{(R)}, y, \theta)}{p(\xi_i^{(R)} | \tau_i, \mathbf{z}_{-i}^{(R)}, y, \theta)} = \frac{p(y | \xi_i^*, \mathbf{z}_{-i}^{(R)}, \theta) p(\xi_i^* | \theta)}{p(\tau_i, \mathbf{z}_{-i}^{(R)}, y, \theta)}$$

$$\times \frac{p(\tau_i | \mathbf{z}_{-i}^{(R)}, y, \theta)}{p(y | \xi_i^{(R)}, \mathbf{z}_{-i}^{(R)}, \theta) p(\xi_i^{(R)} | \theta)}$$

$$= \frac{p(y_i | \xi_i^*, \mathbf{z}_{-i}^{(R)}, \theta) p(\xi_i^* | \theta)}{p(y_i | \xi_i^{(R)}, \mathbf{z}_{-i}^{(R)}, \theta) p(\xi_i^{(R)} | \theta)}$$

(the derivatives on y_{ij} disappear in the ratio thanks to independence up and down) and because they do not depend on \mathbf{z}_i which can be easily computed.

In a similar way

$p(\tau_i^{(k)} | \xi_i^{(k)}, z_{1:n}, y, \theta)$ can be sampled with the ratio:

$$\frac{p(\tau_i^* | \xi_i^*, z_{1:n}, y, \theta)}{p(\tau_i^{(k)} | \xi_i^{(k)}, z_{1:n}, y, \theta)} = \frac{p(y_i | \xi_i^*, z_{1:n}, \theta) p(\tau_i^* | \theta)}{p(y_i | \xi_i^{(k)}, z_{1:n}, \theta) p(\tau_i^{(k)} | \theta)}$$

c) The same way:
"given $z_{1:n}$ "

$$t_0^{(k)} \sim p(t_0^{(k)} | z_0^{(k)}, \xi_i, y, \theta)$$

$$z_0^{(k)} \sim p(z_0^{(k)} | t_0^{(k)}, \xi_i, y, \theta)$$

where the first can be sampled with the ratio

$$\frac{p(t_0^* | z_0^*, \xi_i, y, \theta)}{p(t_0^{(k)} | z_0^{(k)}, \xi_i, y, \theta)} = \frac{p(y | z_{1:n}^*, \xi_i, \theta) p(t_0^* | \theta)}{p(y | z_{1:n}^{(k)}, \xi_i, \theta) p(t_0^{(k)} | \theta)}$$

and the second with

$$\frac{p(z_0^* | t_0^*, \xi_i, y, \theta)}{p(z_0^{(k)} | t_0^{(k)}, \xi_i, y, \theta)} = \frac{p(y | z_{1:n}^*, \xi_i, \theta) p(z_0^* | \theta)}{p(y | z_{1:n}^{(k)}, \xi_i, \theta) p(z_0^{(k)} | \theta)}$$

8) A Block HMC is less costly: sampling one d -multivariate gaussian is less costly than sampling d univariate and independent gaussian for example (and the same applies to whatever the proposal distribution chosen).

Exercise 2)

1) Let $t \in \mathbb{R}$.

$$\begin{aligned} P(Y \leq t) &= P(\varepsilon X \leq t) P(B=1) + P\left(\frac{X}{\varepsilon} \leq t\right) P(B=0) \\ &= \frac{1}{2} \left[P(\varepsilon X \leq t) + P\left(\frac{X}{\varepsilon} \leq t\right) \right] \end{aligned}$$

If $X \geq 0$:

* if $t \geq 0$:

$$\begin{aligned} P(Y \leq t) &= \frac{1}{2} \left[P\left(\varepsilon \leq \frac{t}{X}\right) + P\left(\frac{X}{\varepsilon} \leq t \mid \varepsilon > 0\right) P(\varepsilon > 0) \right. \\ &\quad \left. + P\left(\frac{X}{\varepsilon} \leq t \mid \varepsilon < 0\right) P(\varepsilon < 0) \right] \\ &= \frac{1}{2} \left[P\left(\varepsilon \leq \frac{t}{X}\right) + P\left(\varepsilon \geq \frac{X}{t} \mid \varepsilon > 0\right) P(\varepsilon > 0) \right. \\ &\quad \left. + P(\varepsilon < 0) \right] \end{aligned}$$

- If $\frac{t}{X} \leq 1$:

$$P(Y \leq t) = \frac{1}{2} \left[P\left(\varepsilon \leq \frac{t}{X}\right) + 0 + P(\varepsilon < 0) \right]$$

$$\text{and } f_Y(t) = \frac{dP(Y \leq t)}{dt} = \frac{1}{2X} f\left(\frac{t}{X}\right)$$

- If $\frac{t}{X} \geq 1$:

$$P(Y \leq t) = \frac{1}{2} \left[1 + P\left(\varepsilon \geq \frac{X}{t} \mid \varepsilon > 0\right) P(\varepsilon > 0) + P(\varepsilon < 0) \right]$$

$$\text{and } \frac{dP(Y \leq t)}{dt} = \frac{X}{2t^2} f\left(\frac{X}{t}\right)$$

* If $t \leq 0$,

$$\begin{aligned} P(Y \leq t) &= \frac{1}{2} \left[P(E \leq \frac{t}{x}) + \overbrace{P(E \leq \frac{x}{t} | E \geq 0)}^{=0} P(E \geq 0) \right. \\ &\quad \left. + P(E \geq \frac{x}{t} | E \leq 0) P(E \leq 0) \right] \\ &= \frac{1}{2} \left[P(E \leq \frac{t}{x}) + P(E \geq \frac{x}{t} | E \leq 0) P(E \leq 0) \right] \end{aligned}$$

- If $\frac{t}{x} \leq -1$,

$$P(Y \leq t) = \frac{1}{2} \left[0 + P(E \geq \frac{x}{t} | E \leq 0) P(E \leq 0) \right]$$

$$\text{and } f_Y(t) = \frac{dP(Y \leq t)}{dt} = \frac{x}{2t^2} f\left(\frac{x}{t}\right)$$

- If $\frac{t}{x} \geq -1$,

$$P(Y \leq t) = \frac{1}{2} \left[P(E \leq \frac{t}{x}) + P(E \leq 0) \right]$$

$$\text{and } f_Y(t) = \frac{1}{2x} f\left(\frac{t}{x}\right)$$

So if $x \geq 0$,

$$f_Y(t) = \begin{cases} \frac{1}{2x} f\left(\frac{t}{x}\right) & \text{if } \left|\frac{t}{x}\right| \leq 1 \\ \frac{x}{2t^2} f\left(\frac{x}{t}\right) & \text{if } \left|\frac{t}{x}\right| \geq 1 \end{cases}$$

Then if $x < 0$,

$$P(Y \leq t) = P(-Y \geq -t)$$

$$= 1 - P(-Y \leq -t)$$

and $-Y$ follows the same distribution as if we

had $|X|$ instead of $X \in \mathbb{O}_1$

$$\text{and } f_Y(t) = \frac{dP(Y \leq t)}{dt}$$

$$= \begin{cases} \frac{1}{2|X|} f\left(\frac{-t}{|X|}\right) & \text{if } \left|\frac{t}{X}\right| \leq 1 \\ \frac{|X|}{2t^2} f\left(\frac{|X|}{-t}\right) & \text{if } \left|\frac{t}{X}\right| \geq 1 \end{cases}$$

$$= \begin{cases} \frac{1}{2|X|} f\left(\frac{t}{X}\right) & \text{if } \left|\frac{t}{X}\right| \leq 1 \\ \frac{|X|}{2t^2} f\left(\frac{X}{t}\right) & \text{if } \left|\frac{t}{X}\right| \geq 1 \end{cases}$$

2) The acceptance ratio becomes:

$$\alpha(X|Y) = \min\left(1, \frac{q(Y|X) \pi(Y)}{q(X|Y) \pi(X)}\right)$$

but if $\left|\frac{X}{Y}\right| \leq 1$,

$$\frac{q(Y|X)}{q(X|Y)} = \frac{\frac{1}{2|Y|} f\left(\frac{X}{Y}\right)}{\frac{|X|}{2|Y|^2} f\left(\frac{X}{Y}\right)} = \left|\frac{X}{Y}\right|$$

and if $\left|\frac{X}{Y}\right| \geq 1$,

$$\frac{q(Y|X)}{q(X|Y)} = \frac{\frac{|Y|}{2|X|^2} f\left(\frac{Y}{X}\right)}{\frac{1}{2|X|} f\left(\frac{Y}{X}\right)} = \left|\frac{X}{Y}\right|$$

Exercise 3)

$$1) P((X_n, Y_n) \in A | (X_k, Y_k) \forall k \leq n-1) \\ = P(Y_n \in A_y | X_n \in A_x, (X_k, Y_k) \forall k \leq n-1) P(X_n \in A_x | (X_k, Y_k) \forall k \leq n-1)$$

where $A = A_x \times A_y$

$$= P(Y_n \in A_y | X_n \in A_x) P(X_n \in A_x | Y_{n-1})$$

because $Y_n \sim f_{Y|X}(X_n, \cdot)$ and $X_n \sim f_{X|Y}(\cdot, Y_{n-1})$

$$= P(Y_n \in A_y | X_n \in A_x, Y_{n-1}) P(X_n \in A_x | Y_{n-1})$$

$$= P((X_n, Y_n) \in A | Y_{n-1})$$

$$= P((X_n, Y_n) \in A | (X_{n-1}, Y_{n-1}))$$

This is a Markov chain.
Its transition kernel is;

$$P((x_{n+1}, y_{n+1}) \in A | (x_n, y_n) = (x, y)) \\ = \iint_A f_{X|Y}(x|y_n) f_{Y|X}(x|y) dx dy$$

$$2) P(Y_n \in A | Y_k \forall k \leq n-1)$$

$$= \int_{\mathbb{R}^T} P(Y_n \in A | X_n = x, Y_k \forall k \leq n-1) \pi(X_n = x | Y_k \forall k)$$

$$= \int_{\mathbb{R}^T} P(Y_n \in A | X_n = x) \pi(X_n = x | Y_{n-1})$$

$$= P(Y_n \in A | Y_{n-1})$$

This is a Markov chain.
its transition kernel is,

$$\begin{aligned} P(y_n | A) &= P(Y_{n+1} \in A | Y_n = y) \\ &= \int_{x \in \mathbb{R}^d} \int_{y \in A} f_{X|Y}(x|y) f_{Y|X}(x|y) dx dy \end{aligned}$$

* Instance of $\int f_Y(y) dy$

$$\int_{y \in \mathbb{R}^d} f_Y(y) P(y | A) dy$$

$$= \int_{y \in \mathbb{R}^d} f_Y(y) \left(\int_{x' \in \mathbb{R}^d} \int_{y' \in A} \underbrace{f_{X|Y}(x'|y) f_{Y|X}(x'|y)}_{\frac{f(x'|y)}{f_Y(y)}} dx' dy' \right) dy$$

$$= \int_{y \in \mathbb{R}^d} \int_{x' \in \mathbb{R}^d} \int_{y' \in A} f(x'|y) f_{Y|X}(x'|y') dx' dy' dy$$

$$= \int_{x' \in \mathbb{R}^d} \int_{y' \in A} \left(\int_y f(x'|y) dy \right) \underbrace{f_{Y|X}(x'|y')}_{\frac{f(x'|y')}{f_X(x')}} dx' dy'$$

$\underbrace{\int_y f(x'|y) dy}_{= f_X(x')} \rightarrow f_X(x')$

$$= \int_{x' \in \mathbb{R}^d} \int_{y' \in A} f(x'|y') dx' dy' = \int_{y' \in A} f_Y(y') dy'$$

It is indeed invariant

3) We can compute $f_X(x)$ and $f_Y(y)$.

$$\begin{aligned} f_X(x) &= \int_{\mathbb{R}} \frac{4}{\sqrt{2\pi}} y^{\frac{3}{2}} \exp\left(-y\left(\frac{x^2}{2} + 2\right)\right) \mathbb{1}_{\mathbb{R}^+(y)} dy \\ &= \int_0^{+\infty} \frac{4}{\sqrt{2\pi}} y^{\frac{3}{2}} \exp\left(-\frac{y}{2}(x^2 + 4)\right) dy \end{aligned}$$

Doing a first integration by part:

$$= 0 + \frac{4 \times 2 \times \frac{3}{2}}{\sqrt{2\pi} (x^2 + 4)} \int_0^{+\infty} y^{\frac{1}{2}} \exp\left(-\frac{y}{2}(x^2 + 4)\right) dy$$

and a second one:

$$= 0 + \frac{12}{\sqrt{2\pi} (x^2 + 4)^2} \int_0^{+\infty} y^{-\frac{1}{2}} \exp\left(-\frac{y}{2}(x^2 + 4)\right) dy$$

Changing variable $u = \sqrt{y(x^2 + 4)}$

$$du = \frac{\sqrt{x^2 + 4}}{2\sqrt{y}} dy$$

$$= \frac{12}{(x^2 + 4)^{5/2}}$$

The same way:

$$\begin{aligned} f_Y(y) &= \int_{\mathbb{R}} \frac{4}{\sqrt{2\pi}} y^{\frac{3}{2}} \exp\left(-y\left(\frac{x^2}{2} + 2\right)\right) \mathbb{1}_{\mathbb{R}^+(y)} dx \\ &= \frac{4 e^{-2y}}{\sqrt{2\pi}} y^{\frac{3}{2}} \mathbb{1}_{\mathbb{R}^+(y)} \int_{\mathbb{R}} \exp\left(-\frac{y x^2}{2}\right) dx \end{aligned}$$

Changing variable $u = \sqrt{y} x$

$$du = \sqrt{y} dx$$

$$f_Y(y) = 4 e^{-2y} y \pi R^+(y)$$

We can then use the following Gibbs sampler, similar to Algorithm 4,

Gibbs (X_0, Y_0)

for $n=1$ to max iter do

$$X_n \sim f_{X|Y}(\cdot | Y_{n-1}) = f(X_n | Y_{n-1})$$

$$Y_n \sim f_{Y|X}(X_n, \cdot) = f(Y_n | X_n)$$

end

return the last couple,

$$4) \int_{\mathbb{R}} \frac{H(x)}{(4+x^2)^{5/2}} dx = \frac{1}{12} \mathbb{E}[H(X) | X \sim f_X]$$

In question 2 we showed that f_Y was a stationary distribution of $\{Y_n, n \geq 0\}$, we can show similarly that f_X is a stationary distribution of $\{X_n, n \geq 0\}$. The previous integral can then be approached using a Monte Carlo method using the samples $(X_n)_{n \geq 0}$.

$$\text{ie } \frac{1}{12} \sum_{n=0}^N H(X_n) \xrightarrow[N \rightarrow \infty]{N=400} \int_{\mathbb{R}} \frac{H(x)}{(4+x^2)^{5/2}} dx$$