

20/5/2019

09.30 - 11.30am

CMPU 4031 Games Engines 2

Basement 2, Kevin Street

Programme Code: DT211C, DT228, DT282, DT508

Module Code: CMPU 4031

CRN: 22535, 22425, 31090, 27946

TECHNOLOGICAL UNIVERSITY DUBLIN
KEVIN STREET CAMPUS

BSc. (Honours) Degree in Computer Science (Infrastructure)

BSc. (Honours) Degree in Computer Science

BSc. (Honours) Degree in Computer Science (International)

Year 4

DT508 BA. (Honours) in Game Design

Year 3

SEMESTER 2 EXAMINATIONS 2018/19

Games Engines 2

Dr. Bryan Duggan Rahim

Dr. Deirdre Lillis

Ms. Pauline Martin – DT211C

Mr. Patrick Clarke – DT228/282

INSTRUCTIONS TO CANDIDATES

ANSWER QUESTION 1 (COMPULSORY) AND ANY 2 FROM THE REMAINING QUESTIONS
QUESTION 1 IS WORTH 40 MARKS, THE REMAINING QUESTIONS ARE WORTH 30 MARKS EACH

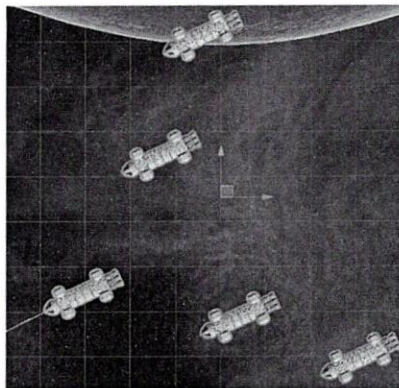
Question 1

- (a) Explain the laws of motion that are used to program a Boid integration function.
- (b) What is banking? How can a Boid implement banking?
- (c) What is damping? How can a Boid implement damping? How does this differ from real-world friction?
- (d) How can a Boid deal with sudden changes in forces, for example due to sensing an obstacle?
- (e) Why would you program a custom integration function for a Boid rather than use a rigid body?
- (f) How can polymorphism be employed in a design of a Boid behaviour framework?
- (g) Explain how behaviours are combined.
- (h) Describe how to program a steering behaviour that takes input from a game controller.

(8 x 5 marks)

Question 2

Figure 1 depicts a formation of Eagle landers moving through a scene in Unity. The leader uses the seek behaviour while the followers employ offset pursue.

**Figure 1**

- (a) Assuming the models were incorrectly rotated and not centred around the origin when imported into Unity, how would you create a prefab for a spawner MonoBehaviour that instantiates Eagle landers?

(5 marks)

- (b) How are the initial positions and rotations of the Eagles calculated?

(5 marks)

- (c) How are the initial offsets calculated?

(5 marks)

- (d) How would you keep the followers moving in formation with the leader?

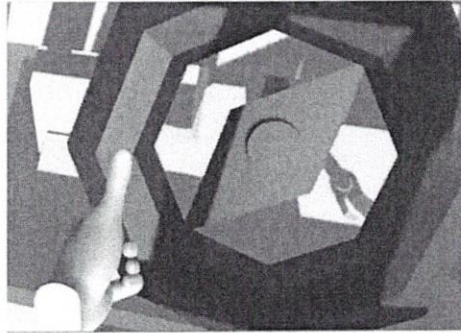
(10 marks)

- (e) Suggest two methods of adding a certain amount of randomness to the ship's movement.

(5 marks)

Question 3

- (a) How do you program Unity to respond to collisions between two objects? What does it mean to assign the static flag on a gameobject? (5 marks)
- (b) Figure 2 shows a screenshot of VR controls for a steering wheel implemented in Unity. In relation to this:

**Figure 2**

- i. Explain in detail how the grab point is calculated. Include a diagram in your answer. (10 marks)
- ii. Explain in detail how to calculate the angle of rotation. (15 marks)

Question 4

In relation to the obstacle avoidance behaviour we developed on the course:

- (a) How are the feelers direction vectors calculated? (5 marks)
- (b) How does the behaviour deal with holes in the geometry of obstacles? (5 marks)
- (c) How are the direction and magnitude of the avoidance force calculated? How does the distance to the obstacle affect the magnitude of the force? (5 marks)
- (d) How is the behaviour programmed to avoid certain objects but ignore others? Include examples in your solution. (5 marks)
- (e) How does the speed of the boid affect the behaviour? (5 marks)
- (f) Is this behaviour efficient? Explain. (5 marks)