

RISC-V Assembly Programming

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Info

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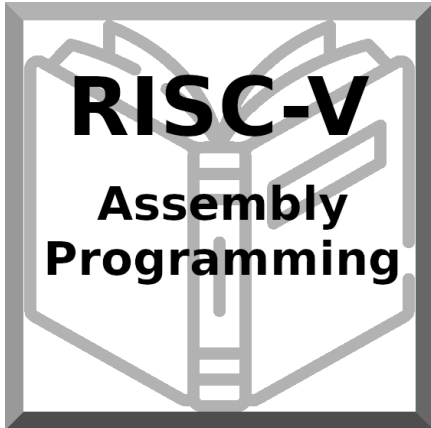
If you're interested in contacting me regarding RISC-V tutoring or any other business request related to the book, you can reach me at books@robertwinkler.com.

Dedication

This book is dedicated to all its [supporters](#) and all the students I've helped with RISC-V over the years who inspired me to create it.

Thank you.

An extra thank you goes to the corporate level sponsors below:



Chapter 0: Hello World

In which we lay the groundwork for the rest of the book...

Prereqs

While someone with no programming experience could probably learn RISC-V from this book, it is definitely preferable to have at least some experience in a higher level imperative programming language. I say imperative, because programming in assembly is the antithesis of functional programming; everything is about state, with each line changing the state of the CPU and sometimes memory. Given that, experience in functional languages like Lisp, Scheme etc. are less helpful than experience in C/C++, Java, Python, Javascript etc.

Of all of the latter, C is the best, with C++ being a close second because at least all of C exists in C++. There are many reasons C is the best prior experience when learning assembly (any assembly, not just RISC-V), including the following:

- pointers, concepts and symmetry of "address of" and "dereference" operators
- pointer/array syntax equivalence
- stack allocation as the default
- manual memory management, no garbage collector
- global data
- rough equivalence in structure of a C program and an assembly program (vs. say Java)
- pass by value

There is some overlap between those and there are probably more, but you can see that most other languages that are commonly taught as first languages are missing most, if not all of those things.

Even C++, which technically has all of them being a superset of C, is usually taught in a way that mostly ignores all of those things. They teach C++ as if it's Java, never teaching the fundamentals. In any case this is getting into my problems with CS pedagogy of the last 20 years based on my experience as a CS major myself ('12) and as a programming tutor helping college students across the country since 2016, and I should save it for a proper essay/rant sometime.

Long story short, I use C code and C syntax to help explain and teach RISC-V. I'll try to provide enough explanation regardless of past experience as best I can.

System Setup

As I tell all of my tutoring students, if you're majoring in CS or anything related I highly recommend you use Linux. It's easier in every way to do dev work on Linux vs Windows or Mac. Many assignments require it, which often necessitates using a virtual machine (which is painful, especially on laptops) and/or ssh-ing into a school Linux server, which is also less than ideal. In general, you'll have to learn how to use the Unix terminal eventually and will probably use it to some extent in your career so it also makes sense to get used to it asap.

That being said, Windows does now have WSL so you can get the full Ubuntu or Debian or Fedora etc. terminal based system on Windows without having to setup a real virtual machine (or dealing with the slowdown that would cause). I've even heard that they'll get support for Linux GUI programs soon.

MacOS on the other hand, is technically a Unix based system and you can use their terminal and install virtually any program from there using Macports or Homebrew or similar.

There are a few RISC-V simulators that I know of and have used:

- RARS is a RISC-V port of MARS, a Java GUI based simulator with dozens of extra environment calls, syntactic sugar and features like graphics, memory mapped I/O, etc.
- Venus, a web based simulator used by Berkeley (also has a downloadable jar)
- Ripes, a graphical processor simulator and assembly editor for bare bones assembly programming

Of those three, RARS is by far the most full featured and user friendly for learning since it forked from the venerable MARS MIPS simulator. It is also the most commonly used by students outside of Berkeley. Given that, this book will focus primarily on RARS, though most of it applies equally well to Venus. [Appendix A: Venus](#) covers the differences between RARS and Venus.

You can download/access both at the following links:

- [RARS](#)
- [RARSM](#) RARS iMproved; fork of RARS with fixes/features
- [ThaumicMekanism's Venus](#) Get the jar [here](#)
- [CS 61C's Venus](#) Get the jar [here](#).

Handy Resources

There are a few references that you should bookmark (or download) before you get started. The first is the [RISC-V Greensheet](#). It's possible you already have a physical copy of this as it's actually the tearout from the Patterson and Hennessey textbook *Computer Architecture and Design* that is commonly used in college courses. Berkeley provides a similar [reference sheet](#) with the same information.

There is also a large format of the [greensheet](#).

The second thing is the list of [environment calls](#) (aka ecalls, system calls, syscalls) from the RARS wiki.

I recommend you download/bookmark both and keep them open while working because you'll be referencing them often to remind yourself which instructions and ecalls you have available and how they work.

Hello World

Let's start with the classic hello world program, first in C, then in RISC-V, and go over all the pieces in overview. You can copy paste these into your editor of choice (mine being neovim), or use the files in the associated repo to follow along.

```
1 #include <stdio.h>
2
3 int main()
4 {
5     printf("Hello World!\n");
6     return 0;
7 }
```

It is pretty self explanatory. You have to include `stdio.h` so you can use the function `printf` (though in the real world I'd use `puts` here), the function `main` is the start of any C/C++ program, which is a function that returns an `int`. We call `printf` to display the string `"Hello World!\n"` to the user and then return 0 to exit. Returning 0 indicates success and there were no errors.

You can compile and run it in a linux/unix terminal as shown below. You can substitute `clang` or another compiler for `gcc` if you want.

```
$ gcc -o hello hello.c
$ ./hello
Hello World!
```

Now, the same program in RISC-V:

```
1 .data
2 hello: .asciz "Hello World!\n"
3
4 .text
5 main:
6     li    a7, 4      # load immediate, a7 = 4 (4 is print string system call)
7     la    a0, hello  # load address of string to print into a0
8     ecall
9
10    li    a7, 10     # exit ecalls
11    ecalls
```

The `.data` section is where you declare global variables, which includes string literals as in this case. We'll cover them in more detail later.

The `.text` section is where any code goes. Here we declare a single label `main:`, indicating the start of our main function.

We then put the number 4 in the `a7` register to select the print string system call. The print string

system call takes one argument, the address of the string to print, in the `a0` register. We do that on the next line. On line 8, we call the system call using the `ecall` instruction.

Finally we call the `exit` system call which takes no arguments and exits the program.

Again, we'll cover system calls in a later chapter. This is just an intro/overview so don't worry if some things aren't completely clear. This chapter is about getting you up and running, not really about teaching anything specific yet.

Building and Running

Now that we have our hello world RISC-V program, how do we run it? Well the easiest and quickest^[1] way is of course to do it on the command line, which can be done like this:

```
$ java -jar ~/rars_latest.jar hello.s
RARS 1.5 Copyright 2003-2019 Pete Sanderson and Kenneth Vollmar

Hello World!

Program terminated by calling exit
```

The name of your RARS jar file may be different^[2], so be sure to use the correct name and path. For myself, I keep the jar file in my home directory so I can use tilde to access it no matter where I am. You can also copy it into your working directory (ie wherever you have your source code) so you don't have to specify a path at all. There are lots of useful command line options that you can use^[3], some of which we'll touch on later.

Running the jar directly on the command line works even in the Windows/DOS command line though I've never done it and it's probably not worth it.

Alternatively, you can start up RARS like a normal GUI application and then load your source file. RARS requires you to hit "assemble" and then "run".

Conclusion

Well, there you have it, you have written and run your first RISC-V program. Another few chapters and you will have no trouble with almost anything you would want to do in RISC-V, whether for a class, or on your own for fun.

Exercises

You can support the book and purchase the chapter exercise solutions [here](#).

1. Modify the hello world program to print something different, perhaps your name.
2. Run it with both RARS and Venus.

purposes of learning and actually using assembly directly, there's no reason to make your life

harder than necessary.]

[1] Starting up the RARS GUI (an old style Java app) is often annoyingly slow

[2] Some schools/professors have their own versions with extra features and other improvements over the official releases

[3] <https://github.com/TheThirdOne/rars/wiki/Using-the-command-line>

Chapter 1: Data

In RISC-V, you can declare global variables in the `.data` section.

At a minimum, this is where you would declare/define any literal strings your program will be printing, since virtually every program has at least 1 or 2 of those.

When declaring something in the `.data` section, the format is

```
variable_name: .directive value(s)
```

where whitespace between the 3 is arbitrary. The possible directives are listed in the following table:

Table 1. RISC-V data types

| Directive | Size | C equivalent |
|----------------------|------|---|
| <code>.byte</code> | 1 | char |
| <code>.half</code> | 2 | short |
| <code>.word</code> | 4 | int, all pointer types |
| <code>.float</code> | 4 | float |
| <code>.double</code> | 8 | double |
| <code>.ascii</code> | NA | char str[5] = "hello"; (no '\0') |
| <code>.asciz</code> | NA | char str[] = "hello"; (includes the '\0') |
| <code>.string</code> | NA | alias for <code>.asciz</code> |
| <code>.space</code> | NA | typeless, uninitialized space, can be used for any type/array |

As you can see it's pretty straightforward, but there are a few more details about actually using them so let's move onto some examples.

Say you wanted to convert the following simple program to RISC-V:

```
1 #include <stdio.h>
2
3 int main()
4 {
5     char name[30];
6     int age;
7     printf("What's your name and age?\n");
8     scanf("%s %d", name, &age);
9     printf("Hello %s, nice to meet you!\n", name);
10    return 0;
11 }
```

The first thing you have to remember when converting from a higher level language to assembly

(any assembly), is that what matters is whether it is functionally the same, not whether everything is done in exactly the same way^{footnote}: [Obviously compilers have to follow stricter rules, but for the. In this instance, that means realizing that your literal strings and your local variables `name` and `age` become globals in RISC-V.

```
1 .data
2 age:      .word 0 # can be initialized to anything
3
4 ask_name:  .asciz "What's your name and age?\n"
5 hello_space: .asciz "Hello "
6 nice_meet: .asciz ", nice to meet you!\n"
7
8 name:      .space 30
9
10 .text
11
12 # main goes here
```

As you can see in the example, we extract all the string literals and the character array `name` and `age` and declare them as globals. One thing to note is the second `printf`. Because it prints a variable, `name`, using the conversion specifier, we break the literal into pieces around that. Since there is no built-in `printf` function in RISC-V, you have to handle printing variables yourself with the appropriate environment calls.

Arrays

Obviously strings are special cases that can be handled with `.ascii` or `.asciz` (or the alias `.string`) for literals, but for other types or user input strings how do we do it?

The first way, which was demonstrated in the snippet above is to use `.space` to declare an array of the necessary byte size. Keep in mind that the size is specified in bytes not elements, so it only matches for character arrays. For arrays of ints/words, floats, doubles etc. you'd have to multiply by the `sizeof(type)`.

"But, `.space` only lets you declare uninitialized arrays, how do I do initialized ones?"

Actually, it appears `.space` initializes everything to 0 similar to global/static data in C and C++, though I can't find that documented anywhere.

Aside from that, there are two ways depending on whether you want to initialize every element to the same value or not.

For different values, the syntax is an extension of declaring a single variable of that type. You specify all the values, comma separated. This actually gives you another way to declare a string or a character array, though I can't really think of a reason you'd want to. You could declare a `.byte` array and list all the characters individually.

However, if you want an array with all elements initialized to the same value there is a more convenient option. After the type you put the value you want, a colon, and then the number of

elements. So `a: .word 123 : 10` would declare a 10 integer array with all elements set to 123. Note, Venus does not support this syntax.

Given what we just covered, this:

```
1 int a[20];
2 double b[20];
3 int c[10] = { 9,8,7,6,5,4,3,2,1,0 };
4 int d[5] = { 42, 42, 42, 42, 42 };
5 char e[3] = { 'a', 'b', 'c' };
```

becomes

```
1 .data
2 a:      .space 80
3 b:      .space 160
4 c:      .word 9,8,7,6,5,4,3,2,1,0
5 d:      .word 42 : 5
6 e:      .byte 'a', 'b', 'c'
```

For more examples of array declarations, see [array_decls.s](#). You don't have to understand the rest of the code, just that it prints out each of the arrays.

Exercises

You can support the book and purchase the chapter exercise solutions [here](#).

1. Create a RISC-V data section that declares variables equivalent to the following. This will not be a runnable program without a main.

```
1 float a;
2 float b = 2.71;
3 int myarray[10] = { 9, 8, 7, 6, 5, 4, 3, 2, 1 };
4 short array2[10];
5
6 char riscv_str[] = "RISC-V assembly is awesome!";
```

2. How would you declare an array of 500 points? The point structure is tightly packed and defined like this:

```
1 struct point {
2     float x;
3     float y;
4     float z;
5 };
```

Chapter 2: Environment Calls

We mentioned environment calls (aka ecalls, though they're also called system calls or syscalls in other languages like MIPS) in chapter 0 when we were going over our "Hello World" program, but what exactly are they?

Essentially, they are the built in functions of an operating system; in this case, the simple operating system of the RARS simulator. They provide access to all the fundamental features, like input and output to/from both the console and files, allocating memory, and exiting. Those are the basics but RARS supports many more, for things ranging from playing MIDI sounds, to getting a random number, to creating GUI dialogs.^[1]

Table 2. Basic RARS supported ecalls

| Name | a7 | Arguments | Result |
|-----------------|------|--|---|
| print integer | 1 | a0 = integer to print | |
| print float | 2 | fa0 = float to print | |
| print double | 3 | fa0 = double to print | |
| print string | 4 | a0 = address of string | |
| read integer | 5 | | a0 = integer read |
| read float | 6 | | fa0 = float read |
| read double | 7 | | fa0 = double read |
| read string | 8 | a0 = address of input buffer a1 = buffer size | works like C's fgets |
| sbrk | 9 | a0 = size in bytes to allocate | a0 = address of allocated memory (sbrk is basically malloc but there is no free) |
| exit | 10 | | program terminates |
| print character | 11 | a0 = character to print (ascii value) | |
| read character | 12 | | a0 = character read |
| open file | 1024 | a0 = address of filename \$a1 = flags | a0 = file descriptor (negative if error) |
| lseek | 62 | a0 = file descriptor, a1 = offset from base, a2 = beginning(0), current(1), or end of the file(2) | a0 = selected position from beginning of the file or -1 if error |
| read from file | 63 | a0 = file descriptor a1 = address of input buffer a2 = max characters to read | a0 = number of characters read, -1 if error |
| write to file | 64 | a0 = file descriptor a1 = address of output buffer a2 = number of characters to write | a0 = number of characters written |

| Name | a7 | Arguments | Result |
|------------|----|-------------------------|---|
| close file | 57 | a0 = file descriptor | |
| exit2 | 93 | a0 = termination result | program terminates, returning number in a0 (only meaningful when run in the terminal, ignored in GUI) |

As you can see, they really only cover the basics. You can read or write the different types, do file I/O using calls identical to POSIX functions (open, read, write, close; see man pages), allocate memory, and exit. Even so, they're sufficient to build anything you want.

So, what does that table mean? How do these actually work?

The process is:

1. Put the number for the ecall you want in **a7**
2. Fill in the appropriate arguments, if any
3. Execute the ecall with **ecall**

```

1    li    a7, 1    # 1 is print integer
2    li    a0, 42   # takes 1 arg in a0, the number to print
3    ecall                # actually execute ecall

```

You can think of the above as **print_integer(42)**;. Let's look at an actual program that uses a few more ecalls next.

Examples

```

1  #include <stdio.h>
2
3  int main()
4  {
5      int age;
6      int height;
7      char name[50];
8      printf("What's your name? ");
9      fgets(name, 50, stdin);
10
11     printf("Hello %s", name);
12
13     printf("How old are you? ");
14     scanf("%d", &age);
15
16     printf("Enter your height in inches: ");
17     scanf("%d", &height);
18

```

```

19     printf("Your age + height = %d\n", age + height);
20
21     return 0;
22 }

```

I'm using `fgets()` instead of `scanf("%s", name)` because `fgets` works the same as the read string `ecall` (8).

```

1 .data
2
3 name:      .space 50
4
5 nameprompt: .asciz "What's your name? "
6 hello_space: .asciz "Hello "
7 how_old:    .asciz "How old are you? "
8 ask_height: .asciz "Enter your height in inches: "
9 ageplusheight: .asciz "Your age + height = "
10
11
12 .text
13 main:
14     li    a7, 4      # print string
15     la    a0, nameprompt # load address of string to print into a7
16     ecall
17
18     li    a7, 8      # read string
19     la    a0, name
20     li    a1, 50
21     ecall
22
23     li    a7, 4
24     la    a0, hello_space
25     ecall
26
27     la    a0, name # note 4 is still in a7
28     ecall
29
30     # don't print a newline here because
31     # one will be part of name unless they typed >48 characters
32
33     li    a7, 4
34     la    a0, how_old
35     ecall
36
37     li    a7, 5      # read integer
38     ecall
39     mv    t0, a0     # save age in t0
40
41     li    a7, 4
42     la    a0, ask_height

```



```

43     ecall
44
45     li    a7, 5    # read integer
46     ecall
47     add   t0, t0, a0 # t0 += height
48
49     li    a7, 4
50     la    a0, ageplusheight
51     ecall
52
53     li    a7, 1    # print int
54     mv    a0, t0   # a0 = age + height
55     ecall
56
57     # print newline
58     li    a7, 11   # print char
59     li    a0, 10   # ascii value of '\n'
60     ecall
61
62     li    a7, 10    # exit ecall
63     ecall

```

There are a few things to note from the example.

We don't declare global variables for age or height. We could, but there's no reason to since we need them in registers to perform the addition anyway. Instead, we copy/save age to `t0` so we can use `a0` for 2 more ecalls, then add height to `t0`.

This is generally how it works. Use registers for local variables unless required to do otherwise. We'll cover [more about](#) register use when we cover the RISC-V calling convention.

Another thing is when we print their name, we don't put 4 in `a7` again because it is still/already 4 from the lines above.

Lastly, many people will declare a string `"\n"` and use `print string` to print a newline, but it's easier to use the `print char` `ecall` as we do right before exiting.

Exercises

You can support the book and purchase the chapter exercise solutions [here](#).

1. Convert the following C code to RISC-V

```

1 #include <stdio.h>
2
3 int main()
4 {
5     float price;
6     double golden = 1.618;

```

```
7   int ret;
8
9   printf("Enter what the price of gas was last time you filled up: ");
10  scanf("%f", &price);
11
12  printf("%f is too expensive!\n", price);
13
14  printf("The golden ratio is roughly %f\n", golden);
15
16
17  printf("Enter an integer for the program to return: ");
18  scanf("%d", &ret);
19  return ret;
20 }
```

2. Write a program that asks the user for their name, reads it in, and then prints "Hello [user's name]!"

Chapter 3: Branches and Logic

We can't go much further in our RISC-V programming journey without covering branching. Almost every non-trivial program requires some logic, even if it's only a few **if** or **if-else** statements. In other words, almost every program requires branching, a way to do a instead of b, or to do a only if certain conditions are met.

You already know how to do this in higher level languages, the aforementioned **if** statement. In assembly it's more complicated. Your only tool is the ability to jump to a label on another line based on the result of various comparisons. The relevant instructions are listed in the following table:

Table 3. RISC-V branching related instructions (and some pseudoinstructions)

| Name | Opcode | Format | Operation |
|----------------------------------|--------|---------------------|----------------------------|
| Branch On Equal | beq | beq rs1, rs2, label | if (rs1 == rs2) goto label |
| Branch On Not Equal | bne | bne rs1, rs2, label | if (rs1 != rs2) goto label |
| Branch Less Than | blt | blt rs1, rs2, label | if (rs1 < rs2) goto label |
| Branch Greater Than | bgt | bgt rs1, rs2, label | if (rs2 > rs2) goto label |
| Branch Less Than Or Equal | ble | ble rs1, rs2, label | if (rs1 ≤ rs2) goto label |
| Branch Greater Than Or Equal | bge | bge rs1, rs2, label | if (rs1 ≥ rs2) goto label |
| Set Less Than | slt | slt rd, rs1, rs2 | rd = (rs1 < rs2) ? 1 : 0 |
| Set Less Than Immediate | slti | slti rd, rs1, imm | rd = (rs1 < imm) ? 1 : 0 |
| Set Less Than Immediate Unsigned | sltiu | sltiu rd, rs1, imm | rd = (rs1 < imm) ? 1 : 0 |
| Set Less Than Unsigned | sltu | sltu rd, rs1, rs2 | rd = (rs1 < rs2) ? 1 : 0 |

You can see the same information and more on the RISC-V greensheet and the RARS Supported Instructions list.^{[1][2]}

There are additional pseudoinstructions in the form of beq/bne/blt/bgt/ble/bge + 'z' which are syntactic sugar to compare a register against 0, ie the 0 register.

So the following:

```
beq    t0, x0, label
bne    t1, x0, label
blt    t2, x0, label
```

would be equivalent to:

```
beqz   t0, label
bnez   t1, label
bltz   t2, label
```

Note `x0` is the same as `zero` and is the hard coded 0 register. I'll cover registers in [more detail](#) in the chapter on functions and the calling conventions.

One final thing is that labels have the same naming requirements as C variables and functions. They must start with a letter or underscore and the rest can be letters, underscores, or digits.

Practice

The rest of this chapter will be going over many examples, looking at snippets of code in C and translating them to RISC-V.

Basics

Let's start with the most basic if statement. The code in and after the if statement is arbitrary.

```
1  if (a > 0) {
2      a++;
3  }
4  a *= 2;
```

Now in RISC-V, let's assume that `a` is in `t0`. The translation would look like this:

```
1  ble    t0, x0, less_eq_0    # if (a <= 0) goto less_eq_0
2  addi   t0, t0, 1            # a++
3 less_eq_0:
4  slli   t0, t0, 1            # a *= 2 (shifting left by n is multiplying by 2^n)
```

There are a few things to note in this example. The first is that in assembly we test for the opposite of what was in the if statement. This will always be the case when jumping forward because (if we want to keep the same order of code) we can only jump *over* a block of code, whereas in C we fall into the block if the condition is true. In the process of mentally compiling a bit of C to assembly, it can be helpful to change to jump based logic first. For example the previous C would become:

```
1  if (a <= 0)
2      goto less_eq_0;
3  a++;
4 less_eq_0:
5  a *= 2;
```

This is obviously still valid C but matches the branching behavior of assembly exactly. You can see I put comments for the equivalent C code in my assembly; it helps with readability to comment every line or group of lines that way.

The second thing to notice is how we handled the multiplication. This has nothing to do with branching but is something we'll touch on multiple times throughout the book. Your job when acting as a human compiler is to match the *behavior*. You are under no obligation to match the

structure or operations of the higher level code exactly (unless your professor stupidly forces you to).

Given that, it is in your best interest to change and rearrange things in order to simplify the assembly as much as possible to make your life easier. Generally speaking, this also tends to result in more performant code, since using fewer instructions and fewer branches (the most common outcomes) saves execution time.

In this case, using the standard `mul` instruction would actually take 2 instructions:

```
1    li    t1, 2
2    mul   t0, t0, t1    # a *= 2
```

This is why, when multiplying or dividing by a constant power of 2 it's common practice to use `slli` or `srai`. This is true in all assembly languages because multiplication and division are relatively costly operations so using shifts when you can saves performance even if you didn't actually save instructions.

Ok, let's look at an `if-else` example. Again, the actual code is arbitrary and we're assuming a and b are in `t0` and `t1` respectively

```
1    if (a > 0) {
2        b = 100;
3    } else {
4        b -= 50;
5    }
```

You could do it something like these two ways

```
1    bgt    t0, x0, greater_0    # if (a > 0) goto greater_0
2    addi   t1, t1, -50          # b -= 50
3    j      less_eq_0
4 greater_0:
5    li     t1, 100              # b = 100
6 less_eq_0:
7
8    # or
9
10   ble    t0, x0, less_eq0     # if (a <= 0) goto less_eq_0
11   li     t1, 100              # b = 100
12   j      greater_0
13 less_eq_0:
14   addi   t1, t1, -50          # b -= 50
15 greater_0:
```

You can see how the first swaps the order of the actual code which keeps the actual conditions the same as in C, while the second does what we discussed before and inverts the condition in order

keep the the blocks in the same order. In both cases, an extra unconditional branch and label are necessary so we don't fall through the else case. This is inefficient and wasteful, not to mention complicates the code unnecessarily. Remember how our job is to match the behavior, not the exact structure? Imagine how we could rewrite it in C to simplify the logic:

```
1    b -= 50;
2    if (a > 0) {
3        b = 100;
4    }
```

which becomes

```
1    addi    t1, t1, -50      # b -= 50;
2    ble     t0, x0, less_eq_0 # if (a <= 0) goto less_eq_0
3    li      t1, 100         # b = 100
4 less_eq_0:
```

That is a simple example of rearranging code to make your life easier. In this case, we are taking advantage of what the code is doing to make a default path or default case. Obviously, because of the nature of the code subtracting 50 has to be the default since setting b to 100 overwrites the original value which we'd need if we were supposed to subtract 50 instead. In cases where you can't avoid destructive changes (like where the condition and the code are using/modifying the same variable), you can use a temporary variable; i.e. copy the value into a spare register. You still save yourself an unnecessary jump and label.

Compound Conditions

These first 2 examples have been based on simple conditions, but what if you have compound conditions? How does that work with branch operations that only test a single condition? As you might expect, you have to break things down to match the logic using the operations you have.

Let's look at **and** first. Variables a, b, and c are in t0, t1, and t2.

```
1    if (a > 10 && a < b) {
2        c += 20;
3    }
4    b &= 0xFF;
```

So what's our first step? Like previous examples, we need to test for the opposite when we switch to assembly, so we need the equivalent of

```
1    if (!(a > 10 && a < b))
2        goto no_add20;
3    c += 20;
4 no_add20:
```

That didn't help us much because we still don't know how to handle that compound condition. In fact we've made it more complicated. If only there were a way to convert it to **or** instead of **and**. Why would we want that? Because, while both **and** and **or** in C allow for short circuit evaluation (where the result of the whole expression is known early and the rest of expression is not evaluated), with **or**, it short circuits on success while **and** short circuits on failure. What does that mean? It means that with **or**, the whole expression is true the second a single true term is found, while with **and** the whole expression is false the second a single false term is found.

Let's look at the following code to demonstrate:

```

1   if (a || b || c) {
2       something;
3   }
4
5   // What does this actually look like if we rewrote it to show what it's
6   // actually doing with short circuit evaluation?
7
8   if (a) goto do_something;
9   if (b) goto do_something;
10  if (c) goto do_something;
11  goto dont_do_something;
12
13 do_something:
14     something;
15
16 dont_do_something:
17
18     // You can see how the first success is all you need
19     // Compare that with and below:
20
21     if (a && b && c) {
22         something;
23     }
24
25     if (a) {
26         if (b) {
27             if (c) {
28                 something;
29             }
30         }
31     }
32     // which in jump form is
33
34     if (a)
35         goto a_true;
36     goto failure;
37 a_true:

```

```

38     if (b)
39         goto b_true;
40     goto failure;
41
42 b_true:
43     if (c)
44         goto c_true;
45     goto failure;
46
47 c_true:
48     something;
49 failure:
50
51     // Man that's ugly, overcomplicated, and hard to read
52     // But what if we did this instead:
53
54     if (!a) goto dont_do_something;
55     if (!b) goto dont_do_something;
56     if (!c) goto dont_do_something;
57
58     something;
59
60 dont_do_something:
61
62     // Clearly you need all successes for and. In other words
63     // to do and directly, you need state, knowledge of past
64     // successes. But what about that second translation of and?
65     // It looks a lot like or?

```

You're exactly right. That final translation of **and** is exactly like **or**.

It takes advantage of De Morgan's laws.^[3] For those of you who haven't taken a Digital Logic course (or have forgotten), De Morgan's laws are 2 equivalencies, a way to change an **or** to an **and**, and vice versa.

They are (in C notation):

$!(A \ || \ B) == !A \ \&\& \ !B$

$!(A \ \&\& \ B) == !A \ || \ !B$

Essentially you can think of it as splitting the not across the terms and changing the logical operation. The law works for arbitrary numbers of terms, not just 2:

(A && B && C)
 is really
 ((A && B) && C)
 so when you apply De Morgan's Law recursively you get:
 !((A && B) && C) == !(A && B) || !C == !A || !B || !C

Let's apply the law to our current compound **and** example. Of course the negation of greater or less than comparisons means covering the rest of the number line so it becomes:

```
1  if (a <= 10 || a >= b)
2      goto no_add20;
3  c += 20;
4 no_add20:
5  b &= 0xFF;
```

which turns into:

```
1  li      t6, 10
2  ble     t0, t6, no_add20    # if (a <= 10) goto no_add20
3  bge     t0, t1, no_add20    # if (a >= b) goto no_add20
4
5  addi    t2, t2, 20          # c += 20
6 no_add20:
7  andi    t1, t1, 0xFF        # b &= 0xFF
```

See how that works? **Or**'s do not need to remember state. Just the fact that you reached a line in a multi-term **or** expression means the previous checks were false, otherwise you'd have jumped. If you tried to emulate the same thing with an **and**, as you saw in the larger snippet above, you'd need a bunch of extra labels and jumps for each term.

What about mixed compound statements?

```
1  if (a > 10 || c > 100 && b >= c)
2      printf("true\n");
3
4  b |= 0xAA;
```

Well, the first thing to remember is that **&&** has a higher priority than **||**, which is why most compilers these days will give a warning for the above code about putting parenthesis around the **&&** expression to show you meant it (even though it's completely legal as is).

So with that in mind, let's change it to jump format to better see what we need to do. While we're at it, let's apply De Morgan's law to the **&&**.

```
1  if (a > 10)
2      goto do_true;
3  if (c <= 100)
4      goto done_if;
5  if (b < c)
6      goto done_if;
7 do_true:
8  printf("true\n");
9
```

```

10 done_if:
11     b |= 0xAA;

```

This one is trickier because we don't flip the initial expression like normal. Instead of jumping *over* the body which would require testing for the opposite, we jump to the true case. We do this because we don't want to have multiple print statements and it lets us fall through the following conditions. We would need multiple print statements because failure for the first expression is *not* failure for the entire expression. Here's how it would look otherwise:

```

1     if (a <= 10)
2         goto check_and;
3     printf("true\n");
4     goto done_if;
5 check_and:
6     if (c <= 100)
7         goto done_if;
8     if (b < c)
9         goto done_if;
10
11    printf("true\n");
12
13 done_if:
14    b |= 0xAA;

```

That is harder to read and has both an extra print and an extra jump.

So let's convert the better version to RISC-V (a,b,c = t0, t1, t2):

```

1 .data
2 true_str: .asciz "true\n"
3
4 .text
5     li    t5, 10    # get the necessary literals in some unused regs
6     li    t6, 100
7
8     bgt   t0, t5, do_true    # if (a > 10) goto do_true
9     ble   t2, t6, done_if    # if (c <= 100) goto done_if
10    blt   t1, t2, done_if    # if (b < c) goto done_if
11
12 do_true:
13     li    a7, 4            # print string
14     la    a0, true_str     # address of str in a0
15     ecall
16
17 done_if:
18     ori    t1, t1, 0xAA    # b |= 0xAA

```

If-Else Chain

Ok, let's look at a larger example. Say you're trying to determine a student's letter grade based on their score. We're going to need a chain of `if-else-if`'s to handle all cases.

```
1 #include <stdio.h>
2
3 int main()
4 {
5     int score;
6     char letter_grade;
7     printf("Enter your score: ");
8     scanf("%d", &score);
9     if (score >= 90) {
10         letter_grade = 'A';
11     } else if (score >= 80) {
12         letter_grade = 'B';
13     } else if (score >= 70) {
14         letter_grade = 'C';
15     } else if (score >= 60) {
16         letter_grade = 'D';
17     } else {
18         letter_grade = 'F';
19     }
20     printf("You got a %c\n", letter_grade);
21     return 0;
22 }
```

With chains like these, if you follow everything we've learned, it comes out looking like this (assuming `score` is `t0` and `letter_grade` is `t1`):

```
1 .data
2 prompt: .asciz "Enter your score: "
3 grade_str: .asciz "You got a "
4
5 .text
6 main:
7     li    a7, 4    # print str
8     la    a0, prompt
9     ecall
10
11     li    a7, 5    # read int
12     ecall
13
14     mv    t0, a0    # move score into t0
15     li    t1, 70    # letter_grade default to 'F' ascii value
16
17     li    t2, 90
18     blt   t0, t2, not_a    # if (score < 90) goto not_a
```

```

19     li     t1, 65          # leter_grade = 'A'
20     j      grade_done
21
22 not_a:
23     li     t2, 80
24     blt    t0, t2, not_b    # if (score < 80) goto not_b
25     li     t1, 66          # leter_grade = 'B'
26     j      grade_done
27
28 not_b:
29     li     t2, 70
30     blt    t0, t2, not_c    # if (score < 70) goto not_c
31     li     t1, 67          # leter_grade = 'C'
32     j      grade_done
33
34 not_c:
35     li     t2, 60
36     blt    t0, t2, grade_done # if (score < 60) goto grade_done
37     li     t1, 68          # leter_grade = 'D'
38
39 grade_done:
40     li     a7, 4           # print str
41     la     a0, grade_str
42     ecall
43
44     li     a7, 11          # print character
45     mv     a0, t1          # char to print
46     ecall
47
48     li     a0, 10          # print '\n'
49     ecall
50
51     li     a7, 10          # exit
52     ecall

```

You can see how we set a default value and then test for the opposite of each condition to jump to the next test, until we get one that fails (aka was true in the original C condition) and set the appropriate grade.

You can arrange chains like this in either direction, it doesn't have to match the order of the C code. As long as it works the same, do whatever makes the code simpler and more sensible to you.

Conclusion

Branching and logic and learning to translate from higher level code to assembly is something that takes a lot of practice, but eventually it'll become second nature. We'll get more practice in the chapter on looping which naturally also involves branching.

One final note, there's rarely any reason to use the `slt` family of opcodes *unless* your professor requires it for some strange reason. Even if your professor says you can't use pseudoinstructions,

that would still leave you with `beq`, `bne`, `blt`, `bge`, which covers every possibility even if you sometimes have to switch the order of the operands.

Exercises

You can support the book and purchase the chapter exercise solutions [here](#).

1. Convert the following C code to RISC-V.

```
1 #include <stdio.h>
2
3 int main()
4 {
5     int num;
6     printf("Enter an integer: ");
7     scanf("%d", &num);
8
9     if (num > 50) {
10         puts("The number is greater than 50");
11     } else if (num < 50) {
12         puts("The number is less than 50");
13     } else {
14         puts("You entered 50!");
15     }
16
17     return 0;
18 }
```

2. Prompt for the user's name, then tell them whether their name starts with a letter from the first or second half of the alphabet. Be sure to handle both upper and lower case correctly, but assume they entered a valid letter.

[1] <https://inst.eecs.berkeley.edu/~cs61c/fa17/img/riscvcard.pdf>

[2] <https://github.com/TheThirdOne/rars/wiki/Supported-Instructions>

[3] https://en.wikipedia.org/wiki/De_Morgan%27s_laws

Chapter 4: Loops

"Insanity is doing the same thing over and over again and expecting different results."

— Unknown, Often misattributed to Albert Einstein

Before we get into the RISC-V, I want to cover something that may be obvious to some but may have never occurred to others. Any loop structure can be converted to any other (possibly with the addition of an `if` statement). So a `for` can be written as a `while` and vice versa. Even a `do-while` can be written as a `for` or `while` loop. Let's look at some equivalencies.

```
1  for (int i=0; i<a; i++) {
2      do_something;
3  }
4
5  int i = 0;
6  while (i < a) {
7      do_something;
8      i++;
9  }
10
11 int i = 0;
12 if (i < a) {
13     do {
14         do_something;
15         i++;
16     } while (i < a);
17 }
18 // you could also have an if (i >= a) goto loop_done; to jump over do-while
```

In general, when writing assembly, it can help to think more in terms of `while` or `do-while` rather than `for` because the former more closely resemble what the assembly looks like in terms of what goes where. Like in the last chapter, where we would think of the `if-else` statements in "jump-form" or "branch-form", we can do the same here, converting `for` to `while` in our head as an intermediary step before going to assembly.

Speaking of "jump-form", let's apply it to the loop above:

```
1  int i=0;
2  if (i >= a)
3      goto done_loop;
4 loop:
5  do_something;
6  i++;
7  if (i < a)
8      goto loop;
```

```
9
10 done_loop:
```

You can see how that starts to look more like assembly. Another thing to note is that unlike with `if` statements where we test for the opposite to jump over the block of code, when you're doing the loop test at the bottom like with a `do-while`, it is unchanged from C because you are jumping to *continue* the loop. If you put the test at the top it becomes inverted, and you put an unconditional jump at the bottom:

```
1   int i=0;
2 loop:
3   if (i >= a)
4       goto done_loop;
5   do_something;
6   i++
7   goto loop:
8
9 done_loop:
```

In general it's better to test at the bottom, both because the condition matches the higher level form, and because when you know the loop is going to execute at least once it requires only one jump + label, rather than 2 since you can forgo the the initial `if` check:

```
1   for (int i=0; i<10; i++)
2       do_something;
3
4   // becomes
5
6   int i=0;
7 loop:
8   do_something;
9   i++
10  if (i < 10)
11      goto loop;
```

Ok, now that we've got the theory and structure out of the way, let's try doing a simple one in RISC-V.

```
1   int sum = 0;
2   for (int i=0; i<100; i++) {
3       sum += i;
4   }
```

That's about as basic as it gets, adding up the numbers 0 to 99.

```
1   li    t0, 0    # sum = 0
```

```

2    li    t1, 1    # i = 1 we can start at 1 because obviously adding 0 is
    pointless
3    li    t2, 100
4 loop:
5    addi   t0, t0, t1    # sum += i
6    addi   t1, t1, 1     # i++
7    blt    t1, t2, loop  # while (i < 100)

```

Ok I don't think there's much point in doing any more without getting to what loops are most often used for, looping through data structures, most commonly arrays.

Looping Through Arrays

Looping and arrays go together like peanut butter and jam. An array is a sequence of variables of the same type, almost always related in some way. Naturally, you want to operate on them all together in various ways; sorting, searching, accumulating, etc. Given that the only way to do that is with loops, in this section we'll cover different ways of looping through arrays, including multidimensional arrays.

1D Arrays

Let's pretend there's an array `int numbers[10]`; filled with 10 random numbers.

```

1    int total = 0;
2    for (int i=0; i<10; i++) {
3        total += numbers[i];
4    }

```

There are several ways to do this. The first is the most literal translation.

```

1    li    t0, 0    # total = 0
2    li    t1, 0    # i = 0
3    la    t2, numbers    # t2 = numbers
4    li    t3, 10
5 sum_loop:
6    slli   t4, t1, 2    # t4 = i*sizeof(int) == i*4
7    add    t4, t4, t2    # t4 = &numbers[i]
8    lw     t4, 0(t4)    # t4 = numbers[i]
9    add    t0, t0, t4    # total += numbers[i]
10
11    addi   t1, t1, 1    # i++
12    blt    t1, t3, sum_loop    # while (i < 10)

```

We initialize the relevant variables beforehand (`numbers` and `10` could be loaded every iteration but that's less efficient). Now what's with the `i*4`? We already discussed using shifts to multiply and divide by powers of 2 in a previous chapter, but here we're doing something that higher level languages do automatically for you every time you do an array access. When you access the *i*'th

element, under the hood it is multiplying `i` by the size of the type of the array and adding that number of bytes to the base address and then loading the element located there.

If you're unfamiliar with the C syntax in the comments, `&` means "address of", so `t4` is being set to the address of the `i`'th element. Actually that C syntax is redundant because the `&` counteracts the brackets. In C adding a number to a pointer does pointer math (ie it multiplies by the size of the items as discussed above). This means that the following comparison is true:

```
&numbers[i] == numbers + i
```

which means that this is true too

```
&numbers[0] == numbers
```

The reason I use the form on the left in C/C++ even when I can use the right is it makes it more explicit and obvious that I'm getting the address of an element of an array. If you were scanning the code quickly and saw the expression on the right, you might not realize that's an address at all, it could be some mathematical expression (though the array name would hopefully clue you in if it was picked well).

Anyway, back to the RISC-V code. After we get the address of the element we want, we have to actually read it from memory (ie load it). Since it's an array of words (aka 4 byte ints) we can use load word, `lw`.

Finally, we add that value to `total`, increment `i`, and perform the loop check.

Now, I said at the beginning that this was the most literal, direct translation (not counting the restructuring to a `do-while` form). However, it is not my preferred form because it's not the simplest, nor the shortest.

Rather than calculate the element address every iteration, why not keep a pointer to the current element and iterate through the array with it? In C what I'm suggesting is this:

```
1  int* p = &numbers[0];
2  int i = 0, total = 0;
3  do {
4      total += *p;
5      i++;
6      p++;
7  } while (i < 10);
```

In other words, we set `p` to point at the first element and then increment it every step to keep it pointing at `numbers[i]`. Again, all mathematical operations on pointers in C deal in increments of the byte size of the type, so `p++` is really adding `1*sizeof(int)`.

```
1  li    t0, 0    # total = 0
2  li    t1, 0    # i = 0
3  la    t2, numbers # p = numbers
4  li    t3, 10
5  sum_loop:
```

```

6    lw    t4, 0(t2)    # t4 = *p
7    add    t0, t0, t4    # total += *p
8
9    addi    t1, t1, 1    # i++
10   addi    t2, t2, 4    # p++ ie p += sizeof(int)
11   blt     t1, t3, sum_loop    # while (i < 10)

```

Now, that may not look much better, we only saved 1 instruction, and if we were looping through a string (aka an array of characters, `sizeof(char) == 1`) we wouldn't have saved any. However, imagine if we weren't using `slli` to do the multiply but `mul`. That would take 2 instructions, even if one could be above the loop. And remember we *would* have to use `mul` instead of `slli` if we were iterating through an array of structures with a size that wasn't a power of 2, so using this method saves even more in that rare case.

However, there is one more variant that you can use that can save a few more instructions. Instead of using `i` and `i < 10` to control the loop, use `p` and the address just past the end of the array. In C it would be this:

```

1    int* p = &numbers[0];
2    int* end = &numbers[10];
3    int total = 0;
4    do {
5        total += *p;
6        p++;
7    } while (p < end);

```

You could also use `!=` instead of `<`. This is similar to using the `.end()` method on many C++ data structures when using iterators. Now the RISC-V version:

```

1    li      t0, 0        # total = 0
2    la      t2, numbers   # p = numbers
3    addi    t3, t2, 40    # end = &numbers[10] = numbers + 10*sizeof(int)
4 sum_loop:
5    lw      t4, 0(t2)     # t4 = *p
6    add     t0, t0, t4    # total += *p
7
8    addi    t2, t2, 4     # p++ ie p += sizeof(int)
9    blt     t2, t3, sum_loop    # while (p < end)

```

So we dropped from 10 to 7 instructions, 6 to 4 in the loop itself which is the most important for performance. And this was for a 1D array. Imagine if you had 2 or 3 indices you had to use to calculate the correct offset. That's what we go over in the next section.

2D Arrays

The first thing to understand is what's really happening when you declare a 2D array in C. The contents of a 2D array are tightly packed, in row-major order, meaning that all the elements from

the first row are followed by all the elements of the second row and so on. What this means is that a 2D array is equivalent to a 1D array with rows*cols elements in the same order:

```
1  #define ROWS 2
2  #define COLS 4
3  // The memory of these two arrays are identical
4  int array[ROWS][COLS] = { { 1, 2, 3, 4 }, { 5, 6, 7, 8 } };
5  int array1d[ROWS*COLS] = { 1, 2, 3, 4, 5, 6, 7, 8 };
```

See the code example [2d_arrays.c](#) for more details.

What this means is that when we declare a 2D array, it's basically a 1D array with the size equal to rows * columns. Also, when we loop through a 2D array, we can often treat it like a 1D array with a single loop. So everything that we learned before applies.

Let's do an example.

```
1  for (int i=0; i<rows; i++) {
2      for (int j=0; j<cols; ++j) {
3          array[i][j] = i + j;
4      }
5  }
6
7  // becomes
8
9  int r, c;
10 for (int i=0; i<rows*cols; i++) {
11     r = i / cols;
12     c = i % cols;
13     array[i] = r + c;
14 }
```

So assuming `rows` and `cols` are in `a0` and `a1` (and nonzero), it would look like this:

```
1  la      t0, array    # p = &array[0]
2  li      t1, 0        # i = 0
3  mul     t2, a0, a1    # t2 = rows * cols
4 loop:
5  div     t3, t1, a1    # r = i / cols
6  rem     t4, t1, a1    # c = i % cols
7  add     t3, t3, t4    # t3 = r + c
8
9  sw      t3, 0(t0)     # array[i] = *p = r + c
10
11 addi    t1, t1, 1      # i++
12 addi    t0, t0, 4      # p++ (keep pointer in sync with i, aka p = &array[i])
13 blt     t1, t2, loop  # while (i < rows*cols)
```

You might ask if it's worth it to convert it to a single loop when you still need the original *i* and *j* as if you were doing nested loops. Generally, it is much nicer to avoid nested loops in assembly if you can. There are many cases when you get the best of both worlds though. If you're doing a clear for example, setting the entire array to a single value, there's no need to calculate the row and column like we did here. I only picked this example to show how you could get them back if you needed them.

For comparison here's the nested translation (while still taking advantage of the 1D arrangement of memory and pointer iterators):

```

1  la    t0, array    # p = &array[0]
2  li    t1, 0        # i = 0
3 looprows:
4  li    t2, 0        # j = 0
5 loopcols:
6  add    t3, t1, t2    # t3 = i + j
7  sw     t3, 0(t0)     # array[i][j] = *p = i + j
8
9  addi   t2, t2, 1     # j++
10 addi   t0, t0, 4     # p++ (keep pointer in sync with i and j, aka p =
    &array[i][j])
11 blt    t2, a1, loopcols # while (j < cols)
12
13 addi   t1, t1, 1     # i++
14 blt    t1, a0, looprows # while (i < rows)

```

It's the same number of instructions, but with an extra label and branch. I think I prefer this version despite the extra branch. On the other hand, either of the last 2 versions are better than the literal translation below:

```

1  la    t0, array    # p = &array[0]
2  li    t1, 0        # i = 0
3 looprows:
4  li    t2, 0        # j = 0
5 loopcols:
6  add    t3, t1, t2    # t3 = i + j
7
8  # need to calculate the byte offset of element array[i][j]
9  mul    t4, t1, a1     # t4 = i * cols
10 add    t4, t4, t2     # t4 = i * cols + j
11 slli   t4, t4, 2      # t4 = (i * cols + j) * sizeof(int)
12
13 add    t4, t4, t0     # t4 = &array[i][j] (calculated as array + (i*cols +
    j)*4)
14
15 sw     t3, 0(t4)     # array[i][j] = i + j
16
17 addi   t2, t2, 1     # j++
18 blt    t2, a1, loopcols # while (j < cols)

```

```

19
20     addi    t1, t1, 1          # i++
21     blt     t1, a0, looprows  # while (i < rows)

```

That chunk in the middle calculating the offset of every element? Not only is it far slower than iterating the pointer through the array, but you can imagine how much worse it would be for a 3D array with 3 nested loops.

Conclusion

Hopefully after those examples you have a more solid understanding of looping in RISC-V and how to transform various loops and array accesses into the form that makes your life the easiest. There is more we could cover here, like looping through a linked list, but I think that's beyond the scope of what we've covered so far. Perhaps in a later chapter.

Exercises

You can support the book and purchase the chapter exercise solutions [here](#).

1. Convert the following C code to RISC-V. If using Venus, you can just hard code a "random" number between 0 and 100.

```

1  #include <stdio.h>
2  #include <stdlib.h>
3
4  int main()
5  {
6      int num = rand() % 101
7      int guess;
8      puts("I'm thinking of a number 0-100. Try to guess it!");
9      while (1) {
10         printf("Guess a number: ");
11         scanf("%d", &guess);
12
13         if (guess > num) {
14             puts("Too high!");
15         } else if (guess < num) {
16             puts("Too low!");
17         } else {
18             break;
19         }
20     }
21
22     printf("Correct, it was %d!\n", num);
23
24     return 0;
25 }

```

2. Write a RISC-V program to find and print the average of the following array. Use integer division.

```
1 .data
2 array: .word 93,8,78,-6,51,49,3,2,128,0
```

3. Write a program to find the min and max of the array in the previous exercise

Chapter 5: Functions and the RISC-V Calling Convention

While I'm sure everyone here probably knows what functions are, you might be wondering what a "Calling Convention" is. In short, it is an agreement between the caller and callee about how to treat/use certain registers. We'll get to the why and how later.

Functions

In assembly, a function is simply a label with a return instruction associated with it; because this is far more ambiguous than a function in a higher level language, it is good practice to only have a single return instruction associated with a function.^[1] A comment above the label is also helpful. Together those help you quickly see the start and end of the function.

```
1 void func1() {}
```

would be

```
1 # void func1()
2 func1:
3     # body goes here
4     ret
```

As you can see my policy is to put a single line comment of the C prototype above label.

But how do you call a function in assembly? You use the instruction Jump and Link: `jal func_label`. Let's change the hello world program from chapter 0 to call a function:

```
1 .data
2 hello: .asciz "Hello World!\n"
3
4 .text
5 main:
6     jal    hello_world
7
8     li     a7, 10    # exit ecall
9     ecall
10
11
12 # void hello_world()
13 hello_world:
14     li     a7, 4      # print string ecall
15     la     a0, hello  # load address of string to print into a0
16     ecall
17
```

What `jal` actually does, is save the address of the next instruction to `ra` and then do an unconditional jump to the function label. So you could achieve the same results with the following:

```
jal    func

# is equivalent to

la     ra, next_instr
j      func
next_instr:
```

That would get tiring and ugly fast though, having to come up with unique labels for the next instruction every time. You also might be confused about why the greensheet says `jal` saves PC+4 in an arbitrary register R[rd] instead of `ra` specifically (which would be R[1]). The instruction does actually take a register argument but since it's most commonly used to call a function if you don't specify a register it will use `ra` as if you did `jal ra, func`. This works in conjunction with the pseudoinstruction `ret` which does PC=R[1] using the instruction `jalr` (specifically `jalr x0, ra, 0`) to easily return from functions. You might also see another way of returning using `jr` which stands for "Jump Register" and jumps to the address in the register, so to return from a function you'd do `jr ra`. It is also a pseudoinstruction that uses `jalr`. Unless your professor insists on something else, prefer `ret`; not only is it the shortest, returning from functions is its sole purpose.

The Convention

We've gone as far as we can without starting to talk about registers and their purposes in functions. You can think of registers as variables^[2] that are part of the CPU. In this case, since we're dealing with a 32-bit RISC-V architecture, they are 32-bit (aka 4 bytes, 1 word) variables.^[3] Since they're part of the CPU, they exist for the life of the program and the whole program shares the same registers.

But how does that work? If all parts of the program use the same 32 registers, how does one function not stomp all over what another was doing when it uses them? In fact, how do functions communicate at all? How do they pass arguments or return results? All these questions are solved by deciding on a "Calling Convention". It's different for different architectures and even different operating systems on the same architecture. This is because different architectures have different numbers of registers, and some registers like `ra` have semi-hardcoded uses. The pseudoinstruction `ret` uses `ra`, and `x0` is a constant 0 and there's no way to change either of those facts. That still leaves a lot of flexibility when designing a calling convention. While they mostly match, you can probably find several variations of RISC-V calling conventions online. They usually differ in how they setup a stack frame. The convention covered in this chapter is consistent with, and sufficient for, almost every college course I've ever heard of.

Regardless, what matters is that the calling convention works by setting rules (and guidelines) for register use, and when/how to use the stack.

If you're unfamiliar with the runtime stack, it's exactly what it sounds like. It's a Last-In-First-Out

(LIFO) data structure that you can use to store smaller values in a program. It grows in a negative direction, so to allocate 12 bytes, you would subtract 12 from the stack pointer (in RISC-V that's `sp`).

RISC-V specifically designates certain registers to be used for passing arguments (at least the first 8), a couple for return values, and others for misc. temporary or saved values. The rest are special use registers like `ra`.

The quickest way to summarize is to look at the table on the greensheet which is reproduced below:

Table 4. RISC-V Registers and Uses

| Register | Name | Use | Preserved Across a Call |
|----------|--------|----------------------------------|-------------------------|
| x0 | zero | Constant 0 | N.A. |
| x1 | ra | Return address | No |
| x2 | sp | Stack pointer | Yes |
| x3 | gp | Global pointer | — |
| x4 | tp | Thread pointer | — |
| x5-x7 | t0-t2 | Temporaries | No |
| x8 | s0/fp | Saved register/Frame pointer | Yes |
| x9 | s1 | Saved register | Yes |
| x10-x11 | a0-a1 | Function arguments/Return values | No |
| x12-x17 | a2-a7 | Function arguments | No |
| x18-x27 | s2-s11 | Saved registers | Yes |
| x28-x31 | t3-t6 | Temporaries | No |

To summarize, you have 15 registers that can be used anytime for temporary values, though some have special uses too (the `a` and `t` registers). You have 12 `s` registers that have to be saved on the stack if you use them, plus `ra` as well. The `zero` register is obviously a special case.

The `sp` register is technically preserved but not in the same way. Basically what you allocate (subtract) you have to deallocate (add) before returning from a function, thus preserving the original value.

You can ignore `gp`, `tp`, and most of the time `fp` too. Also, with 8 registers to pass arguments, you'll almost never need to pass arguments on the stack.

Basic example

Let's start with something simple that doesn't use the stack.

```
int hello_name_number(char* name, int number)
{
    printf("Hello %s!\n", name);
    return number + 10;
}
```

```
}
```

According to the convention that becomes:

```
1 .data
2 hello_space: .asciz "Hello "
3 exclaim_nl:  .asciz "!\n"
4
5 .text
6 # int hello_name_number(char* name, int number)
7 hello_name_number:
8     mv      t0, a0    # save name in t0 since we need a0 for the ecall
9
10    li      a7, 4      # print string
11    la      a0, hello_space
12    ecall
13
14    mv      a0, t0     # print name (a7 is still 4)
15    ecall
16
17    la      a0, exclaim_nl # print "!\n"
18    ecall
19
20
21    addi    a0, a1, 10  # return number + 10
22    ret
```

Some things to note, `ecalls` are not function calls so we can "save" `a0` in a `t` register and know that it'll still be there when the `ecall` is done. In the same way, we know that `a7` is still the same so we don't have to keep setting it to 4 for `print string`. Lastly, to return a value, we make sure that value is in `a0` before returning.

Using the Stack

First, let's establish the rules on when you *have* to use the stack (You can always use it for arbitrary local variables, like a local array for example, but generally don't if you don't have a good reason).

1. You call another function, ie you're a non-leaf function.

This means you have to save `ra` on the stack at the very least, otherwise when you do your `ret` you'd jump back into yourself (right after the last `jal` instruction). This does not apply to `main` because you don't/shouldn't return from `main`, you should call the `exit` (or `exit2`) `ecall` (10 or 93).

2. You need to save values across a function call (automatically includes reason 1).

This is fairly common for non-trivial functions. Obvious examples are calling a function in a loop or loops (you'd have to preserve the iterator(s)), and many recursive functions.

3. You run out of temporary registers and overflow into the `s` registers.

This is very rare. The most common reason this "happens" is people forget they have 8 registers, in addition to the 7 temporary registers, that they can also use for temporaries. 15 is more than enough to handle pretty much any function because you rarely need 16 discrete values at the same time.

Let's look at an example for the first two. Any example for the last rule would be prohibitively large and complicated.

```
1 int non_leaf()
2 {
3     func1();
4     return 42
5 }
```

This calls the empty function discussed at the top of this chapter.

```
1 #int non_leaf()
2 non_leaf:
3     addi    sp, sp, -4    # space to save 1 register, ra
4     sw      ra, 0(sp)    # store ra in the newly allocated stack space
5
6     jal     func1
7
8     li      a0, 42        # return 42
9
10    lw      ra, 0(sp)    # restore original ra
11    addi    sp, sp, 4    # pop the stack
12    ret
```

The bit of code at the top and bottom of the function are called the prologue and epilogue respectively for obvious reasons. We allocate 4 bytes on the stack by subtracting 4 (I add a negative rather than subtract because I can copy-paste the line with a single character change for the epilogue). Then we store the current `ra` in that space at the new top of the stack. Then before we exit we have to load it back and pop the stack.

If we didn't save and restore `ra` we would jump to line 7 when we do our `ret` and then we'd be in an infinite loop.

Next we have the second case, where we need to preserve regular local values across a function call.

```
1 void print_letters(char letter, int count)
2 {
3     for (int i=0; i<count; i++) {
4         putchar(letter);
5     }
6     putchar('\n');
7 }
```

```

8
9 int save_vals()
10 {
11     for (int i=0; i<10; i++) {
12         print_letters('A'+i, i+1);
13     }
14     return 8;
15 }

```

That becomes this in RISC-V:

```

1 #void print_letters(char letter, int count)
2 print_letters:
3     ble     a1, x0, exit_pl    # if (count <= 0) goto exit_pl
4     li      a7, 11             # print character
5 pl_loop:
6     ecall
7     addi    a1, a1, -1         # count--
8     bgt     a1, x0, pl_loop    # while (count > 0)
9
10    li      a0, 10             # '\n'
11    ecall
12
13 exit_pl:
14    ret
15
16
17 #int save_vals()
18 save_vals:
19    addi     sp, sp, -12
20    sw       ra, 0(sp)
21    sw       s0, 4(sp)
22    sw       s1, 8(sp)
23
24    li       s0, 0 # i = 0
25    li       s1, 10
26 sv_loop:
27    addi     a0, s0, 65 # i + 'A'
28    addi     a1, s0, 1  # i + 1
29    jal      print_letters
30
31    addi     s0, s0, 1     # i++
32    blt      s0, s1, sv_loop # while (i < 10)
33
34    lw       ra, 0(sp)
35    lw       s0, 4(sp)
36    lw       s1, 8(sp)
37    addi     sp, sp, 12
38    ret

```

Notice that for `print_letters`, we not only convert the loop to a `do-while`, but we also use the parameter `count` as the iterator to count *down* to 0. It saves us an instruction initializing an `i`.

Second, for `save_vals`, we save not only `ra` because we call another function, but also two s registers to save `i` and our stopping point. The second is not actually necessary; because it's a constant, we could load 10 into a register right before the check every iteration of the loop. Which version is better depends on several factors, like how long or complex the loop is, how many times it executes, and of course personal preference.

Recursive Functions

Let's do a classic recursive function, the fibonacci sequence.

```
1 int fib(int n)
2 {
3     if (n <= 1)
4         return n;
5
6     return fib(n-2) + fib(n-1);
7 }
```

You can see how, at the very least, we'll have to save `ra` and `n`, because we need the original even after the first recursive call. It's not as obvious, but we'll also have to save the return value of the first call so we'll still have it to do the addition after the second. You might think this would require using two s regs, but does it? Let's see...

```
1 #int fib(int n)
2 fib:
3     addi    sp, sp, -8
4     sw      ra, 0(sp)
5     sw      s0, 4(sp)
6
7     # n already in a0 for immediate return
8     li      t0, 1
9     ble     a0, t0, exit_fib # if (n <= 1) goto exit_fib (ie return n)
10
11     mv      s0, a0          # save n
12
13     addi    a0, a0, -2
14     jal     fib             # fib(n-2)
15
16     addi    t0, s0, -1      # calc n-1 first so we can use s0 to save fib(n-2)
17     mv      s0, a0         # save return of fib(n-2) in s0
18     mv      a0, t0         # copy n-1 to a0
19     jal     fib             # fib(n-1)
20
21     add     a0, a0, s0      # a0 = fib(n-1) + fib(n-2)
22
23 exit_fib:
```

```

24    lw    ra, 0(sp)
25    lw    s0, 4(sp)
26    addi  sp, sp, 8
27    ret

```

Notice how we don't have to save `n` any sooner than necessary, ie right before we have to use `a0` to setup the first recursive call. Also, the ordering of lines 16-18 is important. We needed the original `n` to calculate `n-1` but once that's in `a0` ready for the call, because we won't need `n` again afterward, we can now use `s0` to preserve the return value of the first call.

Some of you, if you were paying attention, might point out that you could save a few instructions of performance if you moved the base case testing before the prologue as long as you put the exit label after the epilogue. This is true, but I'd recommend against it unless you were really trying to eke out every last microsecond. It's nicer/cleaner to keep the prologue and epilogue as the first and last things; they're one more thing to catch your eye and help delineate where functions start and end. Regardless, if you're curious, you can see that version, along with every other function in this chapter in the included program [calling.s](#).

Conclusion

While grasping the basics of a calling convention is not too difficult, it takes practice to get used to it. There are many things that we haven't covered in this chapter, like how to pass more than 8 arguments, or use `fp`, or handle floating point arguments or return values. The latter at least, will be covered in the next chapter.

Exercises

You can support the book and purchase the chapter exercise solutions [here](#).

1. Implement the following functions in RISC-V and write a program to demonstrate their use. You can reuse much of your code from the previous chapter's exercises.

```

1 // return the min or max
2 int get_min(int* array, int size);
3 int get_max(int* array, int size);
4
5 // return the index of the min/max
6 int locate_min(int* array, int size);
7 int locate_max(int* array, int size);
8
9 // return the average of the array
10 int calc_average(int* array, int size);

```

2. The Collatz conjecture is defined as follows: start with any positive integer `n`, if `n` is even, divide by 2, otherwise, multiply by 3 and add 1. The conjecture is that all sequences will eventually reach 1. Write 2 versions of the collatz function, one iterative and one recursive. Print out the sequence as they go.

```
1 void collatz_iterative(int n);
2 void collatz_recursive(int n);
3
4 // for an added challenge return the number of steps taken to reach 1
5 // you can remove the printing of the steps
6 int collatz_iterative2(int n);
7 int collatz_recursive2(int n);
```

[1] I do not agree with an ironclad "one return" policy in higher level languages. Sometimes returning early results in cleaner code, sometimes not. Similarly, `goto` is not evil and there are rare cases where using it creates the best code.

[2] Obviously the zero register is not really a variable. I never understood how people could say "const variable" with a straight face, it's literally an oxymoron.

[3] RARS does support 64 bit I think TODO

Chapter 6: Floating Point Types

Up to this point we haven't really mentioned floating point values or instructions at all, except how to declare them in the `.data` section and the `ecalls` for reading and printing them. There are two reasons we've left them alone till now. First, they use a whole separate set of registers and instructions. Second, and partly because of the first reason, most college courses do not ever require you to know or use floating point values. Since this book is targeted at college students, if you know you won't need to know this feel free to skip this chapter.

Floating Point Registers and Instructions

The greensheet contains all the floating point registers and their uses but you can also see them in the table below:

Table 5. RISC-V Floating Point Registers and Uses

| Register | Name | Use | Preserved Across a Call |
|----------|----------|-------------------------|-------------------------|
| f0-f7 | ft0-ft7 | Temporaries | No |
| f8-f9 | fs0-fs1 | Saved registers | Yes |
| f10-f11 | fa0-fa1 | Arguments/Return values | No |
| f12-f17 | fa2-fa7 | Arguments | No |
| f18-f27 | fs2-fs11 | Saved registers | Yes |
| f28-f31 | ft8-ft11 | Temporaries | Yes |

Likewise, you can look to the greensheet to see all the floating point instructions but here are the most important/useful ones:

Table 6. RISC-V floating point instructions (and pseudoinstructions)

| Name | Opcode | Format | Operation |
|--------------------------|-------------|---------------------------------|--------------------------------------|
| Load | flw, fld | <code>flw rd, n(rs1)</code> | $F[rd] = M[R[rs1]+n]$ |
| Store | fsw, fsd | <code>fsw rd, n(rs1)</code> | $M[R[rs1]+n] = F[rd]$ |
| Move from Integer | fmv.[sd].x | <code>fmv.s.x rd, rs1</code> | $F[rd] = R[rs1]$ |
| Move to Integer | fmv.x.[sd] | <code>fmv.x.s rd, rs1</code> | $R[rd] = F[rs1]$ |
| Move | fmv.[sd] | <code>fmv.s rd, rs1</code> | $F[rd] = F[rs1]$ |
| Convert to SP from DP | fcvt.s.d | <code>fcvt.s.d rd, rs1</code> | $F[rd] = (\text{float})F[rs1]$ |
| Convert to DP from SP | fcvt.d.s | <code>fcvt.d.s rd, rs1</code> | $F[rd] = (\text{double})F[rs1]$ |
| Convert from 32b Integer | fcvt.[sd].w | <code>fcvt.s.w rd, rs1</code> | $F[rd] = (\text{float})R[rs1]$ |
| Convert to 32b Integer | fcvt.w.[sd] | <code>fcvt.w.s rd, rs1</code> | $R[rd] = (\text{int})F[rs1]$ |
| Compare Equal | feq.[sd] | <code>feq.s rd, rs1, rs2</code> | $R[rd] = (F[rs1] == F[rs2]) ? 1 : 0$ |

| Name | Opcode | Format | Operation |
|-------------------------|-----------|----------------------------|---|
| Compare Less Than | flt.[sd] | flt.s rd, rs1, rs2 | $R[rd] = (F[rs1] < F[rs2]) ? 1 : 0$ |
| Compare Less Than Equal | fle.[sd] | fle.s rd, rs1, rs2 | $R[rd] = (F[rs1] \leq F[rs2]) ? 1 : 0$ |
| Absolute Value | fabs.[sd] | fabs.s rd, rs1 | $F[rd] = (F[rs1] < 0) ? -F[rs1] : F[rs1]$ |
| Add | fadd.[sd] | fadd.s rd, rs1, rs2 | $F[rd] = F[rs1] + F[rs2]$ |
| Subtract | fsub.[sd] | fsub.s rd, rs1, rs2 | $F[rd] = F[rs1] - F[rs2]$ |
| Multiply | fmul.[sd] | fmul.s rd, rs1, rs2 | $F[rd] = F[rs1] * F[rs2]$ |
| Divide | fdiv.[sd] | fdiv.s rd, rs1, rs2 | $F[rd] = F[rs1] / F[rs2]$ |
| Negation | fneg.[sd] | fneg.s rd, rs1 | $F[rd] = -F[rs1]$ |

Anywhere you see a [sd], use s or d for single or double precision.

You only get equal, less than, and less than equal, but it's easy enough to flip the operands or test for the opposite result to cover the others.

Practice

We're going to briefly go over some of the more different aspects of dealing with floating point numbers, but since most of it is the same but with a new set of registers and calling convention, we won't be rehashing most concepts.

Getting Floating Point Literals

The first thing to know when dealing with floats is how to get float (or double) literals into registers where you can actually operate on them.

There are two ways. The first, and simpler way, is to declare them as globals and then use the **flw** and **fld** instructions:

```

1 .data
2 a:      .float 3.14159
3 b:      .double 1.61
4
5 .text
6 main:
7
8     la    t0, a
9     flw   ft0, 0(t0)    # get a into ft0
10
11     la    t0, b
12     fld   ft1, 0(t0)    # get b into ft1
13
```

```
14      # other code here
```

The second way is to use the regular registers and convert the values. Of course this means unless you want an integer value, you'd have to actually do it twice and divide, and even that would limit you to rational numbers. It looks like this:

```
1      fmv.s.x    ft0, x0      # move 0 to ft0 (0 integer == 0.0 float)
2
3      # get 4 to 4.0 in ft1
4      li         t0, 4
5      fcvt.s.w   ft1, t0      # ft1 = (float)t0
```

As you can see, other than 0 which is a special case, it requires at least 2 instructions.

NOTE

There is a 3rd way in RARS that saves you a step. RARS lets you use **flw** and **fld** like this **flw ft0, label, t0** where t0 is used as a temporary, ie it's doing the load address into t0 for you before doing the actual flw.

Branching

Branching based on floating point values is slightly different than normal. Instead of being able to test and jump in a single convenient instruction, you have to test first and then jump in a second instruction if the test was true or not. This is similar to the way x86 and MIPS (for floats) do it. For them, the test sets a special control/flag register (or a certain bit or bits in the register) and then all jumps are based on its state.

With RISC-V there is no special control register. The float comparisons are like the **slt** instructions where you choose a destination register to set to 1 (true) or 0 (false).

Using them looks like this:

```
1      flt.s      t0, ft0, ft1  # t0 = ft0 < ft1
2      bne       t0, x0, was_less # if (t0 != 0 aka ft0 < ft1) goto was_less
3
4      # do something for ft0 >= ft1
5
6      j         blah
7 was_less:
8
9      # do something for ft0 < ft1
10
11 blah:
```

Functions

Finally, lets do a simple example of writing a function that takes a float and returns a float. I'm not

going to bother doing one for doubles because it'd be effectively the same, or doing one that requires the stack, because the only differences from normal are a new set of registers and knowing which ones to save or not from the table above.

So, how about a function to convert a fahrenheit temperature to celsius:

```
1 .data
2
3 # 5/9 = 0.5 with 5 repeating
4 fahrenheit2celsius: .float 0.555555
5
6 .text
7 # float convert_F2C(float degrees_f)
8 convert_F2C:
9     la        t0, fahrenheit2celsius
10    flw        ft0, 0(t0)    # get conversion factor
11
12    # C = (F - 32) * 5/9
13    li        t0, 32
14    fcvts.w    ft1, t0        # convert to 32.0
15
16    fsub.s     fa0, fa0, ft1   # fa0 = degrees_f - 32
17    fmul.s     fa0, ft0, fa0   # fa0 = 0.555555 * fa0
18
19    ret
```

You can see we follow the convention with the argument coming, and the result being returned, in **fa0**. In this function we use both methods for getting a value into float registers; one we load from memory and the other, being an integer, we convert directly.

Conclusion

As I said before, it is rare for courses to even bother covering floating point instructions or assign any homework or projects that use them. Venus doesn't even support floating point instructions. Hopefully this brief overview, combined with the knowledge of previous chapters is sufficient if you do need or want to work with floating point values.

There are also 2 example programs [conversions.s](#) and [calc_pi.s](#) for you to study.

Exercises

You can support the book and purchase the chapter exercise solutions [here](#).

1. Write a program to convert an input in minutes to hours.
2. Write the following functions and use them in a program.

```
1 float miles2kilometers(float miles);
```

```
2 float pounds2kilograms(float pounds);
```

Chapter 7: Tips and Tricks

This chapter is a grab bag of things you can do to improve your RISC-V programs and make your life easier.

Formatting

You may have noticed I have a general format I like to follow when writing RISC-V (or any) assembly. The guidelines I use are the following

1. **1 indent for all code excluding labels/macros/constants.**

I use hard tabs set to a width of 4 but it really doesn't matter as long as it's just 1 indent according to your preferences.

2. **Use *spaces* to align the first operand of all instructions out far enough.**

Given my 4 space tabs, this means column 13+ (due to longer floating point instructions like `fcvt.s.w`, though I often stop at 10 or 11 when that's sufficient). The reason to use spaces is to prevent the circumstances that gave hard tabs a bad name. When you use hard tabs for alignment, rather than indentation, and then someone else opens your code with their tab set to a different width, suddenly everything looks terrible. Thus, tabs for indentation, spaces for alignment. Or as is increasingly common (thanks Python), spaces for everything but I refuse to do that to the poor planet.^[1]

3. **A comma and a single space between operands.**

The simulators don't actually require the comma but since other assembly languages/assemblers do, you might as well get used to it. Besides I think it's easier to read with the comma, though that might be me comparing it to passing arguments to a function.

4. **Comment every line or group of closely related lines with the purpose.**

This is often simply the equivalent C code. You can relax this a little as you get more experience.

5. **Use a blank line to separate logically grouped lines of code.**

While you can smash everything together vertically, I definitely wouldn't recommend it, even less than I would in a higher level language.

6. **Put the `.data` section at the top, similar to declaring globals in C.**

There are exceptions for this. When dealing with a larger program with lots of strings, it can be convenient to have multiple `.data` sections with the strings you're using declared close to where you use them. The downside is you have to keep swapping back and forth between `.text` and `.data`.

Misc. General Tips

1. Try to use registers starting from 0 and working your way up.

It helps you keep track of where things are (esp. combined with the comments). This can fall apart when you discover you forgot something or need to modify the code later and it's often not worth changing all the registers you're already using so you can maintain that nice sequence. When that happens I'll sometimes just pick the other end of sequence (ie `t6`, `a7`, or `s11`) since if it's out of order I might as well make it obvious.

2. Minimize your jumps, labels, and especially your level of nested loops.

This was already covered in the chapters on branching and loops but it bears repeating.

3. In your prologue save `ra` first, if necessary, then all `s` regs used starting at `s0`.

Then copy paste the whole thing to the bottom, move the first line to the bottom and change the number to positive and change all the `sw` to `lw`.

```
func:
    addi    sp, sp, -20
    sw      ra, 0(sp)
    sw      s0, 4(sp)
    sw      s1, 8(sp)
    sw      s2, 12(sp)
    sw      s3, 16(sp)

    # body of func here that calls another function or functions
    # and needs to preserve 4 values across at least one of those calls

    lw      ra, 0(sp)
    lw      s0, 4(sp)
    lw      s1, 8(sp)
    lw      s2, 12(sp)
    lw      s3, 16(sp)
    addi    sp, sp, 20
```

Constants

One of the easiest things you can do to make your programs more readable is to use defined constants in your programs. RARS has a way of defining constants similar to how C defines macro constants; ie they aren't "constant variables" that take up space in memory, it's as if a search+replace was done on them right before assembling the program.

Let's look at our Hello World program using constants:

```
1 .eqv sys_print_str 4
2 .eqv sys_exit 10
```

```

3
4 .data
5 hello: .asciz "Hello World!\n"
6
7 .text
8 main:
9     li    a7, sys_print_str
10    la    a0, hello # load address of string to print into a0
11    ecall
12
13    li    a7, sys_exit
14    ecall

```

Macros

RARS supports function style macros that can shorten your code and improve readability in some cases (though I feel it can also make it worse or be a wash).

The syntax looks like this:

```

1 .macro macroname
2     instr1  a, b, c
3     instr2, b, d
4 # etc.
5 .end_macro
6
7 # or with parameters
8 .macro macroname(%arg1)
9     instr1    a, %arg1
10    instr2    c, d, e
11 # etc.
12 .end_macro

```

Some common examples are using them to print strings:

```

1 .macro print_str_label(%x)
2     li    a7, 4
3     la    a0, %x
4     ecall
5 .end_macro
6
7 .macro print_str(%str)
8 .data
9 str: .asciz %str
10 .text
11     li    a7, 4
12     la    a0, str
13     ecall

```

```

14 .end_macro
15
16 .data
17
18 str1:  .asciz "Hello 1\n"
19
20 .text
21 # in use:
22     print_str_label(str1)
23
24     print_str("Hello World\n")
25
26     ...

```

You can see an example program in [macros.s](#).

Switch-Case Statements

It is relatively common in programming to compare an integral type variable (ie basically any built-in type but float and double) against a bunch of different constants and do something different based on what it matches or if it matches none.

This could be done with a long `if-else-if` chain, but the longer the chain the more likely the programmer is to choose a `switch-case` statement instead.

Here's a pretty short/simple example in C:

```

1  printf("Enter your grade (capital): ");
2  int grade = getchar();
3  switch (grade) {
4  case 'A': puts("Excellent job!"); break;
5  case 'B': puts("Good job!"); break;
6  case 'C': puts("At least you passed?"); break;
7  case 'D': puts("Probably should have dropped it..."); break;
8  case 'F': puts("Did you even know you were signed up for the class?"); break;
9  default: puts("You entered an invalid grade!");
10 }

```

You could translate this to its equivalent `if-else` chain and handle it like we cover in the chapter on branching. However, imagine if this switch statement had a dozen cases, two dozen etc. The RISC-V code for that quickly becomes long and ugly.

So what if we implemented it in RISC-V the same way it is semantically in C? The same way compilers often (but not necessarily) use? Well, before we do that, what is a switch actually doing? It is *jumping* to a specific case label based on the value in the specified variable. It then starts executing, falling through any other labels, till it hits a `break` which will jump to the end of the switch block. If the value does not have its own case label, it will jump to the default label.

Compilers handle it by creating what's called a jump table, basically an array of label addresses, and using the variable to calculate an index in the table to use to jump to.

The C equivalent of that would look like this:

```
1 #include <stdio.h>
2
3
4 // This compiles with gcc, uses non-standard extension
5 // https://gcc.gnu.org/onlinedocs/gcc/Labels-as-Values.html
6
7 int main()
8 {
9
10     // jump table
11     void* switch_table[] =
12     { &a_label, &b_label, &c_label, &d_label, &default_label, &f_label };
13
14     printf("Enter your grade (capital): ");
15     int grade = getchar();
16     grade -= 'A'; // shift to 0
17
18     if (grade < 0 || grade > 'F' - 'A')
19         goto default_label;
20
21     goto *switch_table[grade];
22
23 a_label:
24     puts("Excellent job!");
25     goto end_switch;
26
27 b_label:
28     puts("Good job!");
29     goto end_switch;
30
31 c_label:
32     puts("At least you passed?");
33     goto end_switch;
34
35 d_label:
36     puts("Probably should have dropped it...");
37     goto end_switch;
38
39 f_label:
40     puts("Did you even know you were signed up for the class?");
41     goto end_switch;
42
43 default_label:
44     puts("You entered an invalid grade!");
45 }
```

```

46
47 end_switch:
48
49
50     return 0;
51 }

```

The `&&` and `goto *var` syntax are actually not standard C/C++ but are GNU extensions that are supported in gcc (naturally) and clang, possibly others.^[2]

First, notice how the size of the jump table is the value of the highest valued label minus the lowest + 1. That's why we subtract the lowest value to shift the range to start at 0 for the indexing. Second, any values without labels within that range are filled with the `default_label` address. Third, there has to be an initial check for values outside the range to jump to default otherwise you could get an error from an invalid access outside of the array's bounds.

The same program/code in RISC-V would look like this:

```

1 .data
2
3 a_str: .asciz "Excellent job!\n"
4 b_str: .asciz "Good job!\n"
5 c_str: .asciz "At least you passed?\n"
6 d_str: .asciz "Probably should have dropped it...\n"
7 f_str: .asciz "Did you even know you were signed up for the class?\n"
8
9 invalid_str: .asciz "You entered an invalid grade!\n"
10
11 enter_grade: .asciz "Enter your grade (capital): "
12
13 switch_labels: .word a_label, b_label, c_label, d_label, default_label, f_label
14
15 .text
16
17 main:
18
19     li    a7, 4
20     la    a0, enter_grade
21     ecall
22
23     li    a7, 12    # read char
24     ecall
25
26     li    t2, 5     # f is at index 5
27
28     la    t0, switch_labels
29     addi   t1, a0, -65    # t1 = grade - 'A'
30     blt    t1, x0, default_label    # if (grade-'A' < 0) goto default
31     bgt    t1, t2, default_label    # if (grade-'A' > 5) goto default
32

```

```

33     slli    t1, t1, 2      # offset *= 4 (sizeof(word))
34     add     t0, t0, t1     # t0 = switch_labels + byte_offset =
    &switch_labels[grade-'A']
35     lw      t0, 0(t0)     # load address from jump table
36     jr      t0           # jump to address
37
38 a_label:
39     la      a0, a_str
40     j       end_switch
41
42 b_label:
43     la      a0, b_str
44     j       end_switch
45
46 c_label:
47     la      a0, c_str
48     j       end_switch
49
50 d_label:
51     la      a0, d_str
52     j       end_switch
53
54 f_label:
55     la      a0, f_str
56     j       end_switch
57
58 default_label:
59     la      a0, invalid_str
60
61
62 end_switch:
63     li      a7, 4
64     ecall
65
66     li      a7, 10      # exit
67     ecall

```

You can see we can use the pseudoinstruction `jr` (jump register) to do the equivalent of the computed `goto` statement in C.

This example probably wasn't worth making switch style, because the overhead and extra code of making the table and preparing to jump balanced out or even outweighed the savings of a branch instruction for every case. However, as the number of options increases, the favor tilts toward using a jump table like this as long as the range of values isn't too sparse. If the range of values is in the 100's or 1000's but you only have cases for a dozen or so, then obviously it isn't worth creating a table that large only to fill it almost entirely with the default label address.

To reiterate, remember it is not about the magnitude of the actual values you're looking for, only the difference between the highest and lowest because $\text{high} - \text{low} + 1$ is the size of your table.

Command Line Arguments

Command line arguments, also known as program arguments, or command line parameters, are strings that are passed to the program on startup. In high level languages like C, they are accessed through the parameters to the main function (naturally):

```
1 #include <stdio.h>
2
3 int main(int argc, char** argv)
4 {
5     printf("There are %d command line arguments:\n", argc);
6
7     for (int i=0; i<argc; i++) {
8         printf("%s\n", argv[i]);
9     }
10
11     return 0;
12 }
```

As you can see, `argc` contains the number of parameters and `argv` is an array of those arguments as C strings. If you run this program you'll get something like this:

```
$ ./args 3 random arguments
There are 4 command line arguments:
./args
3
random
arguments
```

Notice that the first argument is what you actually typed to invoke the program, so you always have at least one argument.

RISC-V works the same way. The number of arguments is in `a0` and an array of strings is in `a1` when main starts. So the same program in RISC-V looks like this:

```
1 .data
2
3 there_are: .asciz "There are "
4 arguments: .asciz " command line arguments:\n"
5
6 .text
7 main:
8     mv      t0, a0 # save argc
9
10    li      a7, 4
11    la      a0, there_are
12    ecall
```

```

13
14     mv      a0, t0
15     li      a7, 1    # print int
16     ecall
17
18     li      a7, 4
19     la      a0, arguments
20     ecall
21
22     li      t1, 0    # i = 0
23     j       arg_loop_test
24
25 arg_loop:
26     li      a7, 4
27     lw      a0, 0(a1)
28     ecall
29
30     li      a7, 11
31     li      a0, 10    # '\n'
32     ecall
33
34     addi     t1, t1, 1    # i++
35     addi     a1, a1, 4    # argv++ ie a1 = &argv[i]
36 arg_loop_test:
37     blt      t1, t0, arg_loop    # while (i < argc)
38
39     li      a7, 10
40     ecall

```

Unfortunately, RARS works slightly differently, probably because it's more GUI focused. It does not pass the program/file name as the first argument, so you can actually get 0 arguments:

```

$ java -jar ~/rars_latest.jar args.s pa 3 random arguments
RARS 1.5 Copyright 2003-2019 Pete Sanderson and Kenneth Vollmar

```

There are 3 command line arguments:

```

3
random
arguments

```

Program terminated by calling exit

You can see that you have to pass "pa" (for "program arguments") to indicate that the following strings are arguments. In the GUI, there is an option in "Settings" called "Program arguments provided to program" which if selected will add a text box above the Text Segment for you to enter in the arguments to be passed.

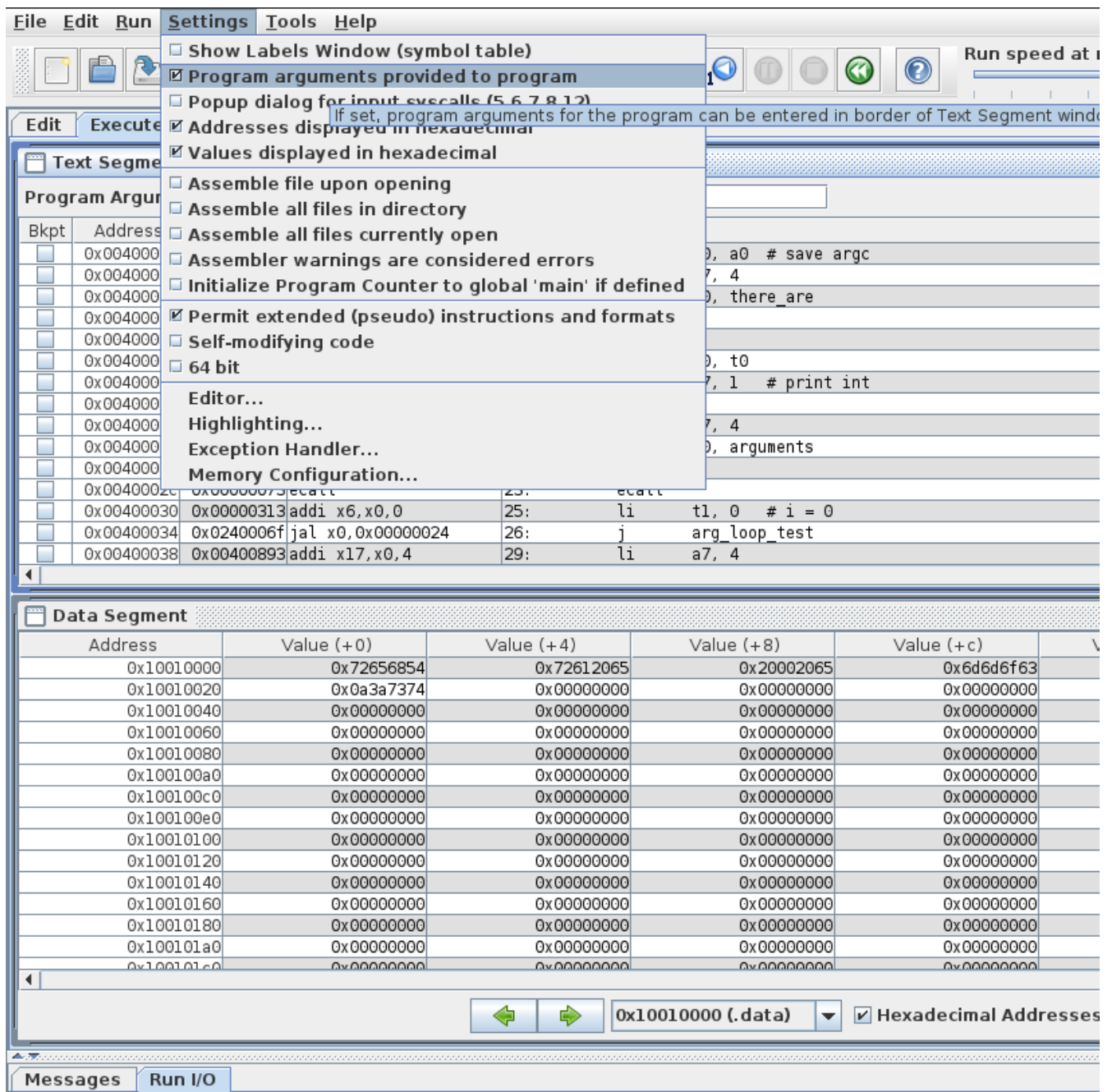


Figure 1. Enable program arguments in RARS GUI

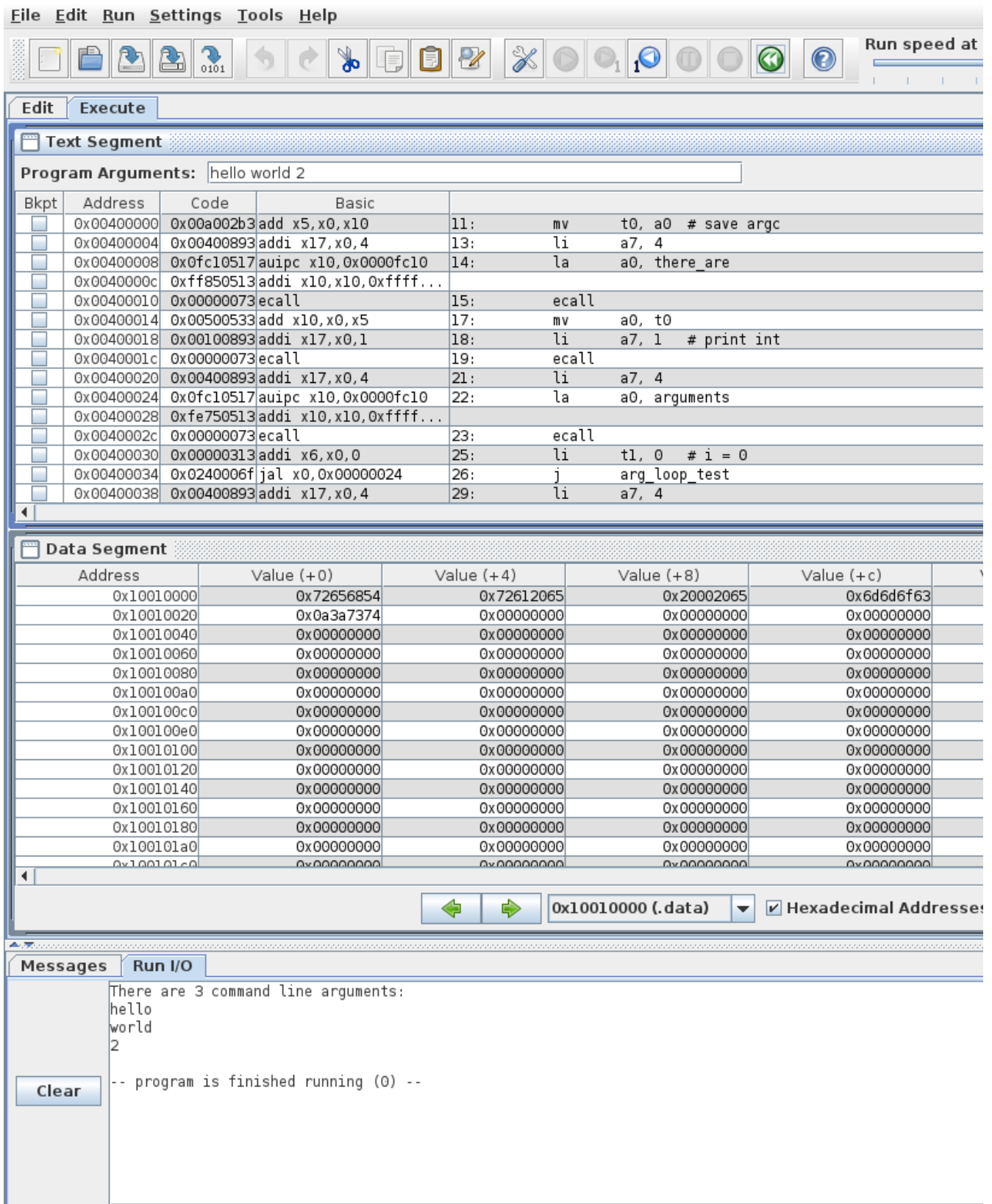


Figure 2. Example using program arguments in RARS GUI

No Pseudoinstructions Allowed

One relatively common assignment requirement is forbidding pseudoinstructions, either all of them, or some subset of them. This forces us to explicitly write what those pseudoinstructions are translated into (or could be translated into since there are often several alternatives).

Table 7. Pseudoinstruction Equivalents

| Pseudoinstruction | Example Use | Equivalence |
|---------------------------|--------------------------------|--|
| Load Immediate | <code>li t0, 42</code> | <pre>ori t0, x0, 42 # or addi t0, x0, 42</pre> |
| Move | <code>mv t0, t1</code> | <pre>or t0, x0, t1 # or add t0, x0, t1 # or addi t0, t1, 0</pre> |
| Load Address | <code>la t0, label</code> | <pre>lui t0, 0x10010 ori t0, t0, byte_offset</pre> |
| Branch Less Than or Equal | <code>ble t0, t1, label</code> | <pre># test for < and = separately blt t0, t1, label beq t0, t1, label</pre> <pre># or add 1 to change <= to < # use a spare reg if you need # to preserve the original value addi t3, t1, 1 blt t0, t3, label</pre> |
| Branch Greater Than | <code>bgt t0, t1, label</code> | <pre># flip the operands and use blt blt t1, t0, label</pre> |
| Return | <code>ret</code> | <pre># as mentioned in chapter 5 jalr x0, ra, 0</pre> |
| Jump Register | <code>jr t0</code> | <pre># as mentioned in chapter 5 jalr x0, t0, 0</pre> |

You can see how you use the non-pseudoinstructions to match the same behavior, and there's often (usually) more than one way.

Another thing I should comment on is the `la` equivalence. The reason it is a pseudoinstruction in the first place is that an address is 32 bits. That's also the size of a whole instruction. Clearly there's no way to represent a whole address and anything else at the same time. The lower right corner of the greensheet has the actual formats of the 6 different types of instructions and even the U and J

formats still needs 12 bits for the opcode and destination. This is why `lui` (and `auipc`) exists, in order to facilitate getting a full address into a register by doing it in two halves, 20 + 12. The lower 12 can be placed with `addi` or `ori` after the `lui`.

NOTE

RARS actually uses `auipc` not `lui` probably because that's what the RISC-V spec says (also see top left on page 2 of the greensheet). They both can accomplish the same thing but the former is needed for PC-relative addressing which whereas `lui` is 0/absolute addressing. Since RARS works with absolute addressing the easier-to-use `lui` is fine.

That begs the question, what actually goes in the upper half? Well, since we're dealing with addresses in the `.data` section, the upper portion should match the upper part of address of the `.data` section. In RARS the `.data` section starts at `0x10010000`.

But what about the lower part of the address? This involves counting the bytes from the top of `.data` to the label you want. If all you have is words, halves, floats, doubles, or space (with a round number), that's fairly easy, but the second you have strings between the start and the label you want, it's a bit more painful. This is why I recommend putting any string declarations at the bottom so at least any other globals will have nice even offsets. Also, if you have a bunch of globals, it doesn't hurt to count once and put the offsets in comments above each label so you don't forget. Of course, none of this matters if you're allowed to just use `la` which is true the vast majority of the time.

Let's look at a small example. We'll convert the `args.s` from above (reproduced here for convenience) to bare mode:

```
1 .data
2
3 there_are: .asciz "There are "
4 arguments: .asciz " command line arguments:\n"
5
6 .text
7 main:
8     mv      t0, a0  # save argc
9
10    li      a7, 4
11    la      a0, there_are
12    ecall
13
14    mv      a0, t0
15    li      a7, 1    # print int
16    ecall
17
18    li      a7, 4
19    la      a0, arguments
20    ecall
21
22    li      t1, 0    # i = 0
23    j       arg_loop_test
```

```

24
25 arg_loop:
26     li        a7, 4
27     lw        a0, 0(a1)
28     ecall
29
30     li        a7, 11
31     li        a0, 10    # '\n'
32     ecall
33
34     addi       t1, t1, 1    # i++
35     addi       a1, a1, 4    # argv++ ie a1 = &argv[i]
36 arg_loop_test:
37     blt        t1, t0, arg_loop # while (i < argc)
38
39     li        a7, 10
40     ecall

```

So we need to change the **mv**, the **li**'s, the **j**, and the **la**.

```

1 # RARS .data (like MARS) always starts at 0x10010000, whether pseudoinstructions
2 # are on or not.
3
4 .data
5
6 there_are: .asciz "There are "
7 arguments: .asciz " command line arguments:\n"
8
9 .text
10
11 .globl main
12 main:
13     or        t0, x0, a0    # save argc
14
15     ori       a7, x0, 4
16
17     #la       a0, there_are
18     lui       a0, 0x10010    # there_are is at beginning of data so just lui, lower
19     is 0
20     ecall
21
22     or        a0, x0, t0
23     ori       a7, x0, 1    # print int
24     ecall
25
26     ori       a7, x0, 4
27     lui       a0, 0x10010
28     ori       a0, a0, 11    # 11 is length in bytes of "There are " 10 chars + '\0'
29     #la       a0, arguments
30     ecall

```

```

30
31     ori      t1, x0, 0    # i = 0
32     #j       arg_loop_test
33     jal      x0, arg_loop_test
34
35 arg_loop:
36     ori      a7, x0, 4    # print string for argv[i]
37     lw       a0, 0(a1)
38     ecall
39
40     ori      a7, x0, 11
41     ori      a0, x0, 10   # '\n'
42     ecall
43
44     addi     t1, t1, 1    # i++
45     addi     a1, a1, 4    # argv++ ie a1 = &argv[i]
46 arg_loop_test:
47     blt      t1, t0, arg_loop # while (i < argc)
48
49     ori      a7, x0, 10
50     ecall

```

Following the table, you can see the `mv` became `or`, the `li` became `ori`, the `j` became `jal` with `x0` as the destination register, and lastly the `la` became `lui` plus an `ori` if necessary for the byte offset.

Exercises

You can support the book and purchase the chapter exercise solutions [here](#).

1. Convert the exercises from chapter 5 to run with no pseudoinstructions (`java -jar ~/rars_latest.jar np file.s` on the command line).
2. Convert the following C code to RISC-V using a jump table (Note in C/C++ enum values start at 0 and go up by one unless the user manually assigns a value, in which case it continues counting up from there).

```

1 enum { STATE0, STATE1, STATE2, STATE3, STATE14 = 14, STATE42 = 42, STATE43,
  STATE44 };
2
3
4 int main()
5 {
6     int num;
7     do {
8         printf("Enter a number between 0 and 50: ");
9         scanf("%d", &num);
10    } while (num < 0 || num > 50);
11
12    switch (num) {
13    case STATE0:

```

```

14     puts("Zilch");
15     break;
16 case STATE1:
17     puts("Uno");
18     break;
19 case STATE2:
20     puts("Dos");
21     break;
22 case STATE3:
23     puts("Tres");
24     break;
25 case STATE14:
26     puts("Catorce");
27 case STATE42:
28     puts("The answer to life, the universe, and everything.");
29 case STATE43:
30     puts("Off by one");
31 case STATE44:
32     puts("4 * 11?");
33     break;
34 }
35
36 puts("Thanks for playing!");
37
38
39 return 0;
40 }

```

[1] When I find the post I read years ago about how using tabs saves CO2 I'll put it here, but I'm joking. I use tabs because it makes sense and there are accessibility reasons too: https://www.reddit.com/r/javascript/comments/c8drjo/nobody_talks_about_the_real_reason_to_use_tabs/

[2] <https://gcc.gnu.org/onlinedocs/gcc/Labels-as-Values.html>

Appendix A: Venus

Venus is the simulator that is used by UC Berkeley's CS 61C course. It's nowhere near as nice nor as full featured as RARS and currently seems poorly documented and maintained.

UC Berkeley is the designer of RISC-V and so was one of the first colleges to start teaching RISC-V, years before RARS existed. Given that they've built up a curriculum around Venus and invested at least a little in their own fork it makes sense that they'd be hesitant to switch.

In any case, this appendix will go over the most important differences between Venus and RARS.

Versions and History

Unlike RARS which seems to have one primary and fairly well maintained stable version, and a few even more updated forks, Venus is less clear. As far as I can tell it was started by [kvakil](#) 5 years ago, was forked by [ThaumicMekanism](#), and finally was forked by Berkeley for their [cs61c course](#). While the latter has the most recent commit none of them are what I would call well maintained, with the former 2 seeming to stall in 2018 and 2020 respectively. Venus (all versions) has a web based interface but I don't know why anyone would prefer that to the standalone JAR version.

As of the end of 2022 you can get Venus jar files from ThaumicMekanism's github [here](#) or from Berkeley's course website [here](#).

I don't know what the minor differences are between them but you should use whatever is provided by the course if you're taking it.

Data section

The documentation is sorely lacking and out of date but the most relevant differences from RARS are that it uses `.asciiz` instead of `.asciz` and while `.float` and `.double` are reserved, Venus doesn't actually support floating point instructions so you can't actually do anything with them.

The only documentation I can find is from ThaumicMekanism's wiki and it doesn't mention `.space` even though Venus seems to allow it.^[1] CS61C's documentation doesn't mention data directives at all.^[2]

Environment Calls

Venus only supports a handful of ecalls and they work differently than they do in RARS. Again, the only documentation I can find is ThaumicMekanism's.^[3]

There is one that I know of that is not listed in that table. Ecall 5 is basically the C function `atoi` which converts a string to an integer. It takes the address of the string in `a1` and returns the number in `a0`. If there is any leading or trailing whitespace or the string isn't a valid number it returns 0.

One thing you might have noticed is that Venus doesn't support any of the input ecalls. This is extremely limiting since you can't write any interactive programs and to test a function you have to actually change the program (usually a variable in the data section) and re-run it. The only way to

even get variable program behavior is to use the file input capability to read data and do something different based on that input.

But aside from the lack of some basic ecalls, there's also a behavioral difference in how they work. In RARS, you use `a7` to select the ecall leaving the lower 4 registers for arguments which matches how you would pass arguments to a function. Venus uses `a0` to select the ecall which means your argument(s) start in `a1`. This is probably why they provide wrapper functions for the ecalls to students for their projects, though it took until recently to get them right.

So, what does this look like in practice? Let's take the simple command line argument program from chapter 7 and convert it for Venus. So the following program:

```
1 .data
2
3 there_are: .asciz "There are "
4 arguments: .asciz " command line arguments:\n"
5
6 .text
7 main:
8     mv      t0, a0  # save argc
9
10    li      a7, 4
11    la      a0, there_are
12    ecall
13
14    mv      a0, t0
15    li      a7, 1    # print int
16    ecall
17
18    li      a7, 4
19    la      a0, arguments
20    ecall
21
22    li      t1, 0    # i = 0
23    j       arg_loop_test
24
25 arg_loop:
26    li      a7, 4
27    lw      a0, 0(a1)
28    ecall
29
30    li      a7, 11
31    li      a0, 10    # '\n'
32    ecall
33
34    addi     t1, t1, 1    # i++
35    addi     a1, a1, 4    # argv++ ie a1 = &argv[i]
36 arg_loop_test:
37    blt      t1, t0, arg_loop  # while (i < argc)
38
```

```

39     li      a7, 10
40     ecall

```

becomes

```

1  .data
2
3  there_are: .asciiz "There are "
4  arguments: .asciiz " command line arguments:\n"
5
6
7  .text
8
9  main:
10     mv      t0, a0  # save argc
11     mv      t2, a1  # save argv
12
13     li      a0, 4      # print str
14     la      a1, there_are
15     ecall
16
17     mv      a1, t0
18     li      a0, 1      # print int
19     ecall
20
21     li      a0, 4
22     la      a1, arguments
23     ecall
24
25     li      t1, 0      # i = 0
26     j       arg_loop_test
27
28 arg_loop:
29     li      a0, 4
30     lw      a1, 0(t2)
31     ecall
32
33     li      a0, 11
34     li      a1, 10      # '\n'
35     ecall
36
37     addi     t1, t1, 1    # i++
38     addi     t2, t2, 4    # argv++ ie t2 = &argv[i]
39 arg_loop_test:
40     blt      t1, t0, arg_loop  # while (i < argc)
41
42
43     li      a0, 10
44     ecall

```

Note that we had to save argv because `a1` is now used in our ecalls. In addition the behavior is different than RARS:

```
$ java -jar ~/venus-jvm-latest.jar args_venus.s
There are 0 command line arguments:
$ java -jar ~/venus-jvm-latest.jar args_venus.s hello
There are 2 command line arguments:
args_venus.s
hello
```

RARS may have decided not to include the program name/"executable" in its arguments but at least it is consistent in its behavior. In addition, the section on passing arguments in CS 61C's documentation is inaccurate as of December 2022. Just like with C and RARS, argc comes first in `a0` then argv in `a1`, not the other way around as described.^[4]

Constants

Another minor difference from RARS is how you declare constants. In Venus you use the same syntax as C, so the constants example from chapter 7:

```
1 .eqv sys_print_str 4
2 .eqv sys_exit 10
3
4 .data
5 hello: .asciz "Hello World!\n"
6
7 .text
8 main:
9     li    a7, sys_print_str
10    la    a0, hello # load address of string to print into a0
11    ecall
12
13    li    a7, sys_exit
14    ecall
```

becomes

```
1 #define sys_print_str 4
2 #define sys_exit 10
3
4 .data
5 hello: .asciiz "Hello World!\n"
6
7 .text
8 main:
9     li    a0, sys_print_str
10    la    a1, hello # load address of string to print into a1
```



```
11    ecall
12
13    li    a0, sys_exit
14    ecall
```

Conclusion

While most of this book applies equally well to both programs (other than chapter 6 of course) and to RISC-V in general, this appendix should clear up any difficulties you might have run into trying to convert the examples to run in Venus. Hopefully Berkeley will decide to switch to RARS eventually.

[1] <https://github.com/ThaumicMekanism/venus/wiki/Assembler-Directives>

[2] <https://inst.eecs.berkeley.edu/~cs61c/su21/resources/venus-reference/>

[3] Funny enough the Wiki link on cs61c's Venus is empty and their own [documentation](#), entirely focused on the web version, links to ThaumicMekanism's [wiki](#)

[4] <https://inst.eecs.berkeley.edu/~cs61c/su21/resources/venus-reference/>

References and Useful Links

- [Greensheet](#)
- [Alternative info sheet](#)
- [RARS ecall list](#)
- [RISC-V calling convention](#)

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