Problem Set 4 for Machine Learning 15 Fall

Jingyuan Liu

AndrewId: jingyual jingyual@andrew.cmu.edu

1 VC dimension

1.1 Show the VC dimension of linear classifier

To prove that the linear classifier h with x in \mathbb{R}^n has the VC dimension of n + 1, we need to prove that $VCdim(h_n) >= n+1$, and then prove that $VCdim(h_n) <= n+1$.

(a). Prove
$$VCdim(h_n) >= n+1$$

First of all, we could use the Mathematical Induction to prove that VCdim(H) >= n + 1:

For n = 1, it is easy to get $VCdim(h_1) >= 2$

For n = 2, we could also get $VCdim(h_2) >= 3$, which could be proved using following figures:

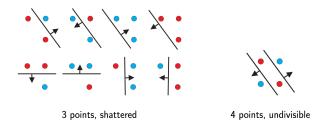


Figure 1: The representation of $VCdim(h_2)$

For n = i, we assume that the $VCdim(h_i) >= i + 1$. We could form a matrix of (i+1)*(i+1), with the rank of i+1, since the VCdim is i+1.

For n = i+1, we could form a matrix of (i+2)*(i+2), since the variable x have one more independent dimension. Therefore, $VCdim(h_{i+1}) >= VCdim(h_i) + 1 >= i + 2$.

Therefore, we have $VCdim(h_n) >= n+1$. We could use a more straight forward detailed example to show that. Say we have n dimensions of the data, then we could construct a dataset:

 $1th: \quad (1,0,0,...,0)$ $2th: \quad (0,1,0,...,0)$ $ith: \quad (0,0,...,i...,0)$ $nth: \quad (0,0,0,...,n)$ $n+1th: \quad (0,0,0,...,0)$

For these dataset, we could see that for the ith data point, the ith dimension is 1, otherwise 0. And for the n+1th data, all dimension are 0. In this case, we could see that the linear classifier could shatter this dataset.

(b). Prove $VCdim(h_n) \le n+1$

Then we should prove that $VCdim(h_n) \le n+1$:

Suppose we could shatter n+2 points, then using the convex combinations of points in C, we could separate points into S1 and S2, that:

$$conv(s1) \cap conv(s2) \neq \emptyset$$
 (1)

However, if $VCdim(h_n) = n + 2$, then we could spilt points to half space contains s1 and the complement of the half space contains s2. This implies that the both half space contains the convex hull of s1 and the complement of the half space the contains the convex hull of s2. Thus, we get:

$$conv(s1) \cap conv(s2) = \emptyset \tag{2}$$

These two observations are contradictory to each other. So we know that for the n+2 points here, we could not use the linear classifier to shatter all of them.

In conclusion, we prove that $VCdim(h_n) >= n+1$ and $VCdim(h_n) <= n+1$ for the linear classifier, then we have $VCdim(h_n) = n+1$

1.2 Show the VC dimension of axis-aligned boxes

Similarly, for this case, to prove that the axis-aligned boxes classifier h with x in \mathbb{R}^n has the VC dimension of 2n, we need to prove that $VCdim(h_n) >= 2n$, and then prove that $VCdim(h_n) <= 2n$.

(a). Prove $VCdim(h_n) >= 2n$

First of all, we need to prove that for any case, $VCdim(h_n) >= 2n$, which means if the x has n dimensions, we can use the axis-aligned boxes classifiers to shatter 2n points.

Suppose we have n dimensions, then we can map all the x to a dimension i. In the dimension i, we can have x^i_{max} and x^i_{min} . Therefore, in this dimension i, we could always shatter at least 2 points via a split between the x^i_{max} and x^i_{min} .

Considering we have n dimensions, and the mapping of each dimension of the data is independent to the mapping of other dimension of the data. Therefore, we could at least shatter 2*n points via the axias-alighed boxes. Therefore, we have $VCdim(h_n) >= 2n$.

(b). Prove $VCdim(h_n) \le 2n$

Then we need to prove that $VCdim(h_n) \le 2n$. Suppose we have 2n + 1 points, we could always find the 2n "boundries", which is the min value and max value for each dimension, and form an "area". Then the 2n+1th points will be guaranteed to appear within the selected "area".

For any 2n+1 points, we could always transfer to the above mentioned scenario. In this scenario, we could not classify the 2n+1th point, because it is contained within the "area", and no rules are guaranteed to rightly classify it.

Therefore, by mapping the data to each dimension and form an "area", we could prove that $VCdim(h_n) <= 2n$.

In conclusion, we prove that $VCdim(h_n) >= 2n$ and $VCdim(h_n) <= 2n$ for the axis-alighed boxes, then we have $VCdim(h_n) = 2n$

2 AdaBoost

2.1 Justify the Update Rule

Based on the defination, if we change the distribution, the previous learned hypothesis h_t would be a "random guess" to the new distribution of data, therefore:

$$\epsilon_t = err_{D_t}(h_t) = Pr_{x \sim D_t}(y \neq h_t(x)) = \frac{1}{2}$$
(3)

The error rate is $\frac{1}{2}$ for a random guess with margin $\gamma_t = 0$. Then we would have, for all i:

$$\alpha_t = \frac{1}{2}log(\frac{1 - \epsilon_t}{\epsilon_t}) = 0 \tag{4}$$

$$D_{t+1}(i) = \frac{D_t(i)}{Z_t} e^{-\alpha_t y_i h_t(x_i)}$$
 (5)

$$=\frac{D_t(i)}{Z_t}\tag{6}$$

Therefore, we could see that the $D_{t+1} = D_t$, so:

$$err_{D_{t+1}}(h_t) = Pr_{x \sim D_t}(y \neq h_t(x)) \tag{7}$$

$$= \sum_{y_i \neq h_t(x_i)} D_{t+1}(i) \tag{8}$$

$$= \sum_{y_i \neq h_t(x_i)} D_t(i) \tag{9}$$

$$=err_{D_t} = \frac{1}{2} \tag{10}$$

2.2 Show the $D_{t+1}(i)$

$$D_{t+1}(i) = \frac{D_t(i)}{Z_t} e^{-\alpha_t y_i h_t(x_i)}$$
(11)

$$=\frac{e^{-y_i}}{Z_t}e^{\alpha_t h_t(x_i)}D_t(i) \tag{12}$$

$$= \frac{e^{-y_i}}{Z_t} e^{\alpha_t h_t(x_i)} \cdot \frac{e^{-y_i}}{Z_{t-1}} e^{\alpha_{t-1} h_{t-1}(x_i)} D_{t-2}(i)$$
 (13)

$$=\frac{e^{-y_i}}{Z_t}e^{\alpha_t h_t(x_i)}\cdots\frac{1}{m}e^{\alpha_1 h_1(x_i)}$$
(14)

$$= (m \prod_{t} Z_t)^{-1} e^{-y_i \sum_{t} \alpha_t h_t(x)}$$

$$\tag{15}$$

2.3 Show the error upperbound

$$err_S(H) = Pr(y \neq H(x)) = \frac{1}{m} \sum_{H(i) \neq y_i} D_S(i)$$
(16)

When $H(i) \neq y_i$, we have $y_i f(x_i) < 0$, and $exp(-y_i f(x_i)) > 0$, therefore:

$$err_S(H) < \frac{1}{m} \sum_{i} exp(-y_i f(x_i))$$
 (17)

For the right term, according to the defination of Z and W, we have:

$$w_{t,i}exp(-\alpha_t y_i h_t(x_i)) = Z_m w_{t+1,i}$$
(18)

$$\frac{1}{m}\sum_{i}exp(-y_{i}f(x_{i})) = \frac{1}{m}\sum_{i}exp(-\sum_{t}\alpha_{t}y_{i}h_{t}(x_{i}))$$
(19)

$$= \sum_{1,i} w_{1,i} \prod_{t} exp(-\alpha_t y_i h_t(x_i))$$
 (20)

$$= Z_1 \sum_{2,i} w_{2,i} \prod_{t=2}^{T} exp(-\alpha_t y_i h_t(x_i))$$
 (21)

$$= Z_1 Z_2 \sum_{3,i} w_{3,i} \prod_{t=3}^{T} exp(-\alpha_t y_i h_t(x_i))$$
 (22)

$$= Z_1 Z_2 \cdots \sum_{i} w_{T,i} exp(\alpha_T y_i H(x_i))$$
 (23)

$$=\prod_{t} Z_{t} \tag{24}$$

Therefore, we have:

$$err_S(H) < \frac{1}{m} \sum_{i} exp(-y_i f(x_i)) = \prod_{t} Z_t$$
 (25)

2.4 Show the $\prod_t Z_t$ upperbound

$$Z_t = \sum_{i} exp(-\alpha_t y_i h_t(x_i))$$
 (26)

$$= \sum_{h_t(x_i)=y_i} w_i e^{-\alpha_t} + \sum_{h_t(x_i)\neq y_i} w_i e^{\alpha_t}$$
 (27)

$$= (1 - \epsilon_t)e^{-\alpha_t} + \epsilon e^{\alpha_t} \tag{28}$$

$$=2\sqrt{\epsilon_t(1-\epsilon_t)} = \sqrt{1-4\gamma_t^2} \tag{29}$$

Therefore, we could use Taylor expansion series to get $\sqrt{1-4\gamma_t^2} <= exp(-2\gamma_t^2)$, so we have:

$$\prod_{t} Z_t \le e^{-2\sum_{t} \gamma_t^2} \tag{30}$$

2.5 Express big-O notation of T

From above questions, we could get:

$$\epsilon \le e^{-2\sum_t \gamma_t^2} \tag{31}$$

With the smallest margin of γ , we could transfer to

$$\epsilon \le e^{-2T\gamma^2} \tag{32}$$

$$T = O(\frac{-log(\epsilon)}{\gamma^2}) \tag{33}$$

3 Gaussian Mixture Model

3.1 Show the expectation

$$E(x) = \int p(x)dx = \sum_{k} p(x_k)x_k \tag{34}$$

$$=\sum_{k}\pi_{k}E_{k}(x)\tag{35}$$

We know that for each k, the implict distribution of x is a Gaussian distribution, and $E_k(x) = \mu_k$, μ_k is the mean of the kth guassian distribution, so we have:

$$E(x) = \sum_{k} \pi_k \mu_k \tag{36}$$

3.2 Show the covariance

$$cov(x) = E(xx^{T}) - E(x)E(x)^{T}$$
(37)

$$= \sum_{k} \pi_{k} E_{k}(xx^{T}) - E(x)E(x)^{T}$$
(38)

$$= \sum_{k} \pi_{k} (\Sigma_{k} + \mu_{k} \mu_{k}^{T}) - E(X) E(x)^{T}$$
(39)

4 K-Means

5 Collaboration

I dicussed with Zheng Chen with problem 1.2 on how to calculate the parameters, and he also informed me about 2.2.1(b).