



$$y(t) = y_0 + v_0 \cdot \sin \alpha \cdot t - \frac{gt^2}{2}$$

$$x(t) = v_0 \cdot \cos \alpha \cdot t$$

$$v_y(t) = v_0 \cdot \sin \alpha - gt$$

$$v_x(t) = v_0 \cdot \cos \alpha$$

$$t_{\text{nog}} = \frac{v_0 \cdot \sin \alpha}{g} \quad (v_y(t_{\text{nog}}) = 0)$$

$$h_{\text{max}} = y_0 + \frac{v_0^2 \cdot \sin^2 \alpha}{2g} \quad (y(t_{\text{nog}}) = h_{\text{max}})$$

$$t_{\text{no1}} = \frac{v_0 \cdot \sin \alpha + \sqrt{v_0^2 \cdot \sin^2 \alpha + 2y_0 \cdot g}}{g} \quad (y(t_{\text{no1}}) = 0)$$

$$L = v_0 \cdot \cos \alpha \cdot t_{\text{no1}}$$

$$v_{kx} = v_0 \cdot \cos \alpha$$

$$v_{ky} = v_0 \cdot \sin \alpha - g \cdot t_{\text{no1}}$$

$$v_k = \sqrt{v_{kx}^2 + v_{ky}^2}$$

$$\beta = \arctg\left(\frac{v_{ky}}{v_{kx}}\right)$$

Уравнение траектории:

$$y(x) = y_0 + x \cdot \tg \alpha - \frac{gx^2}{2v_0^2 \cdot \cos^2 \alpha}$$