

Assignment5

December 7, 2021

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[1]: # Assignment 5
# Author: David Bui
# DSC-540
# Date: 12/06/2021
# Description: In this assignment we are implementing a decision tree with data
↳ that contains uncertainty. A fuzzy decision tree
# is used to provide an improved method while still using logic.

import pandas as pd
import numpy as np

# Creating a dataframe to hold list arrays.
x1 =
↳ ["hot", "hot", "hot", "mild", "cool", "cool", "cool", "mild", "cool", "mild", "mild", "mild", "hot", "mi
x2 =
↳ ["weak", "strong", "weak", "weak", "weak", "strong", "strong", "weak", "weak", "weak", "strong", "stro
x3 =
↳ ["long", "long", "long", "long", "short", "short", "short", "long", "short", "short", "short", "long",
y=
↳ ["no", "no", "yes", "yes", "yes", "no", "yes", "no", "yes", "yes", "yes", "yes", "yes", "no"]

df = pd.DataFrame([y,x1,x2,x3]).T #Transposing the matrix of lists
df.columns = ['Drive Car', 'Temperature', 'Wind', 'Traffic-Jam'] # adding column
↳ labels
df.head()
```

```
[1]: Drive Car Temperature Wind Traffic-Jam
0      no      hot      weak      long
1      no      hot strong      long
2      yes     hot      weak      long
3      yes     mild     weak      long
4      yes     cool     weak     short
```

```
[2]: # Transforming data into nominal form.
from sklearn.preprocessing import LabelEncoder
from sklearn.tree import DecisionTreeClassifier
```

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le= LabelEncoder() # Used to transform categorical data into numeric.

df['Drive Car']=le.fit_transform(df['Drive Car'])
df['Temperature']=le.fit_transform(df['Temperature'])
df['Wind']=le.fit_transform(df['Wind'])
df['Traffic-Jam']=le.fit_transform(df['Traffic-Jam'])
df['Drive Car']=le.fit_transform(df['Drive Car'])

X = df.iloc[:,1:4]
y = df.iloc[:,0]

dt = DecisionTreeClassifier(max_depth = 3, random_state = 0) # max_depth can be
↳used to grow the decision tree.
dt.fit(X, y)

```

[2]: DecisionTreeClassifier(max_depth=3, random_state=0)

```

[3]: # a. Calculate the information gain for x1, x2, and x3.
def entropy(input):
    elements,counts = np.unique(input,return_counts = True)
    entropy = np.sum([(-counts[i]/np.sum(counts))*np.log2(counts[i]/np.
↳sum(counts)) for i in range(len(elements))])
    return entropy

def IG(df,feature,target):
    totalEntropy = entropy(df[target])
    vals,counts= np.unique(df[feature],return_counts=True)
    WeightedEntropy = np.sum([(counts[i]/np.sum(counts))*entropy(df.
↳where(df[feature]==vals[i]).dropna()[target]) for i in range(len(vals))])
    Information_Gain = totalEntropy - WeightedEntropy
    return Information_Gain

print("Temperature Information Gain: ",IG(df,'Temperature','Drive Car'))
print("Wind Information Gain:          ",IG(df,'Wind','Drive Car'))
print("Traffic-Jam Information Gain: ",IG(df,'Traffic-Jam','Drive Car'))

# b. Choose the root node for the decision tree.
print("Traffic-Jam has the highest Information Gain which makes it our ROOT_
↳NODE.")

```

```

Temperature Information Gain:  0.02922256565895487
Wind Information Gain:        0.04812703040826949
Traffic-Jam Information Gain:  0.15183550136234159
Traffic-Jam has the highest Information Gain which makes it our ROOT NODE.

```

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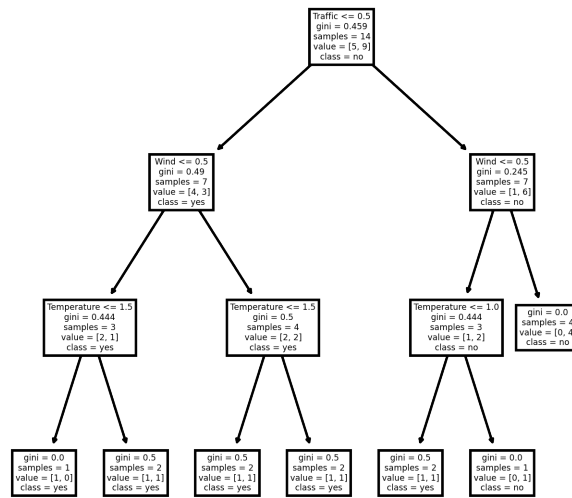
[4]: # c. Plot a partial decision tree from root node along with training examples_
↳sorted to each of its descendent nodes.

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```
# Visualization of the decision tree
from sklearn.tree import plot_tree
import matplotlib.pyplot as plt

fig, axes = plt.subplots(nrows = 1,ncols = 1,figsize = (4,4), dpi=400)
plot_tree(dt, feature_names = ['Temperature','Wind','Traffic'],
    ↪class_names=['yes','no'])
```

```
[4]: [Text(715.3846153846154, 1057.0, 'Traffic <= 0.5\ngini = 0.459\nsamples =
14\nvalue = [5, 9]\nclass = no'),
Text(381.53846153846155, 755.0, 'Wind <= 0.5\ngini = 0.49\nsamples = 7\nvalue =
[4, 3]\nclass = yes'),
Text(190.76923076923077, 453.0, 'Temperature <= 1.5\ngini = 0.444\nsamples =
3\nvalue = [2, 1]\nclass = yes'),
Text(95.38461538461539, 151.0, 'gini = 0.0\nsamples = 1\nvalue = [1, 0]\nclass
= yes'),
Text(286.1538461538462, 151.0, 'gini = 0.5\nsamples = 2\nvalue = [1, 1]\nclass
= yes'),
Text(572.3076923076924, 453.0, 'Temperature <= 1.5\ngini = 0.5\nsamples =
4\nvalue = [2, 2]\nclass = yes'),
Text(476.9230769230769, 151.0, 'gini = 0.5\nsamples = 2\nvalue = [1, 1]\nclass
= yes'),
Text(667.6923076923077, 151.0, 'gini = 0.5\nsamples = 2\nvalue = [1, 1]\nclass
= yes'),
Text(1049.2307692307693, 755.0, 'Wind <= 0.5\ngini = 0.245\nsamples = 7\nvalue
= [1, 6]\nclass = no'),
Text(953.8461538461538, 453.0, 'Temperature <= 1.0\ngini = 0.444\nsamples =
3\nvalue = [1, 2]\nclass = no'),
Text(858.4615384615385, 151.0, 'gini = 0.5\nsamples = 2\nvalue = [1, 1]\nclass
= yes'),
Text(1049.2307692307693, 151.0, 'gini = 0.0\nsamples = 1\nvalue = [0, 1]\nclass
= no'),
Text(1144.6153846153848, 453.0, 'gini = 0.0\nsamples = 4\nvalue = [0, 4]\nclass
= no')]
```



[5]: # f. Summarize in a technical report
 # Can be found in my GitHub: <https://github.com/DouglasBui/GCU/tree/main/DSC-540/Assignment5>

[6]: # Part 2

```
import skfuzzy as fuzz
from fuzzytree import FuzzyDecisionTreeClassifier

# defuzzification of changed attributes x1, x2, and x3
# First I must apply random elements to the terms of each feature.
import random as rn

# Temperature converted into degrees
x1f = df.Temperature
for i in range(len(x1f)):
    if x1f[i] == 1:
        x1f[i] = rn.randint(80,100)# hot
    elif x1f[i] == 2:
        x1f[i] = rn.randint(60,79)# mild
    elif x1f[i] == 0:
        x1f[i] = rn.randint(40,59)# cool

# Wind being converted into Wind mph
x2f = df.Wind
for i in range(len(x1f)):
    if x2f[i] == 1:
```

```

        x2f[i] = rn.randint(10,29)# Weak
    elif x2f[i] == 0:
        x2f[i] = rn.randint(30,45)# Strong
x1f = x1f.to_numpy()

# Traffic-Jam converted to Number of Traffic-Jams
x3f = df['Traffic-Jam']
for i in range(len(x1f)):
    if x3f[i] == 0:
        x3f[i] = rn.randint(10,20)# Long
    elif x3f[i] == 1:
        x3f[i] = rn.randint(0,9)# Short

data = {'Temperature':x1f,'Wind mph':x2f,'Traffic-Jams':x3f}
Xf = pd.DataFrame(data)
yf = df['Drive Car']
#Xf['Drive Car'] = yf

#x1f = x1f.to_numpy()
tempmf = fuzz.trapmf(x1f,[40,60,79,100])
windmf = fuzz.smf(x2f,10,30)
trafmf = fuzz.smf(x3f,0,10)

mfx = np.column_stack((tempmf,windmf,trafmf))
print(mfx)

```

```

[[0.          0.08          1.          ]
 [0.42857143  1.          1.          ]
 [0.95238095  0.405        1.          ]
 [1.          0.          1.          ]
 [0.7         0.125        0.02        ]
 [0.45         1.          0.68        ]
 [0.55         1.          0.32        ]
 [1.          0.92         1.          ]
 [0.75         0.875       0.08        ]
 [1.          0.82         0.82        ]
 [1.          1.          0.          ]
 [1.          1.          1.          ]
 [0.76190476  0.08         0.82        ]
 [1.          1.          1.          ]]

```

<ipython-input-6-abb1524f0321>:14: SettingWithCopyWarning:
A value is trying to be set on a copy of a slice from a DataFrame

See the caveats in the documentation: https://pandas.pydata.org/pandas-docs/stable/user_guide/indexing.html#returning-a-view-versus-a-copy

```

    x1f[i] = rn.randint(80,100)# hot

```

<ipython-input-6-abb1524f0321>:16: SettingWithCopyWarning:

A value is trying to be set on a copy of a slice from a DataFrame

See the caveats in the documentation: https://pandas.pydata.org/pandas-docs/stable/user_guide/indexing.html#returning-a-view-versus-a-copy

```
x1f[i] = rn.randint(60,79)# mild
<ipython-input-6-abb1524f0321>:18: SettingWithCopyWarning:
A value is trying to be set on a copy of a slice from a DataFrame
```

See the caveats in the documentation: https://pandas.pydata.org/pandas-docs/stable/user_guide/indexing.html#returning-a-view-versus-a-copy

```
x1f[i] = rn.randint(40,59)# cool
<ipython-input-6-abb1524f0321>:24: SettingWithCopyWarning:
A value is trying to be set on a copy of a slice from a DataFrame
```

See the caveats in the documentation: https://pandas.pydata.org/pandas-docs/stable/user_guide/indexing.html#returning-a-view-versus-a-copy

```
x2f[i] = rn.randint(10,29)# Weak
<ipython-input-6-abb1524f0321>:26: SettingWithCopyWarning:
A value is trying to be set on a copy of a slice from a DataFrame
```

See the caveats in the documentation: https://pandas.pydata.org/pandas-docs/stable/user_guide/indexing.html#returning-a-view-versus-a-copy

```
x2f[i] = rn.randint(30,45)# Strong
<ipython-input-6-abb1524f0321>:33: SettingWithCopyWarning:
A value is trying to be set on a copy of a slice from a DataFrame
```

See the caveats in the documentation: https://pandas.pydata.org/pandas-docs/stable/user_guide/indexing.html#returning-a-view-versus-a-copy

```
x3f[i] = rn.randint(10,20)# Long
<ipython-input-6-abb1524f0321>:35: SettingWithCopyWarning:
A value is trying to be set on a copy of a slice from a DataFrame
```

See the caveats in the documentation: https://pandas.pydata.org/pandas-docs/stable/user_guide/indexing.html#returning-a-view-versus-a-copy

```
x3f[i] = rn.randint(0,9)# Short
```

```
[7]: dfmf = pd.DataFrame(mfx,columns=['Temperature','Wind','Traffic-Jams'])
dfmf['Drive Car'] = df['Drive Car']
print("Temperature Information Gain: ",IG(dfmf,'Temperature','Drive Car'))
print("Wind Information Gain:          ",IG(dfmf,'Wind','Drive Car'))
print("Traffic-Jam Information Gain: ",IG(dfmf,'Traffic-Jams','Drive Car'))

# b. Choose the root node for the decision tree.
print("Temperature has the highest Information Gain which makes it our ROOT_
↳NODE.")
```

```
Temperature Information Gain: 0.5467306012187071
Wind Information Gain:      0.36885738724205974
```

Traffic-Jam Information Gain: 0.4476718906535054

Temperature has the highest Information Gain which makes it our ROOT NODE.

```
[18]: # Implementing Defuzzified input into Decision Tree Classifier.
      clf_fuzz = DecisionTreeClassifier().fit(mfx,yf)
      clf_sk = DecisionTreeClassifier().fit(Xf,yf)

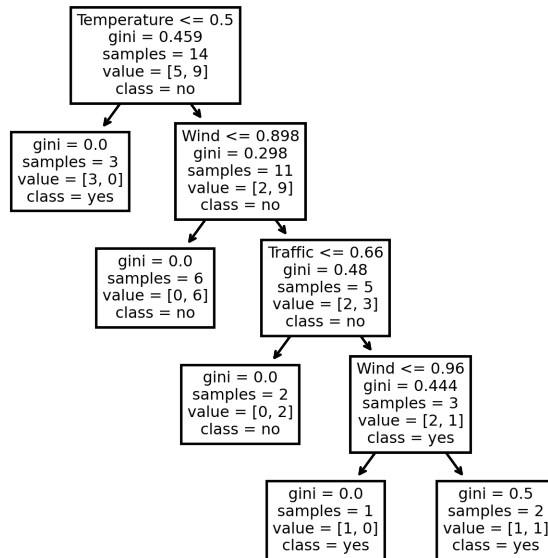
      # Evaluation: The FuzzyTree clearly shows an improvement over the initial
      ↪ decision tree. I ran this model dozens of times
      # and have received the exact same score each time. Showing the sklearn used to
      ↪ form our fuzzytree works perfectly while
      # creating 0 variance.
      print(f"DecisionTree: {dt.score(X,y)}")
      print(f"    FuzzyTree: {clf_fuzz.score(mfx,yf)}")
```

DecisionTree: 0.7142857142857143

FuzzyTree: 0.9285714285714286

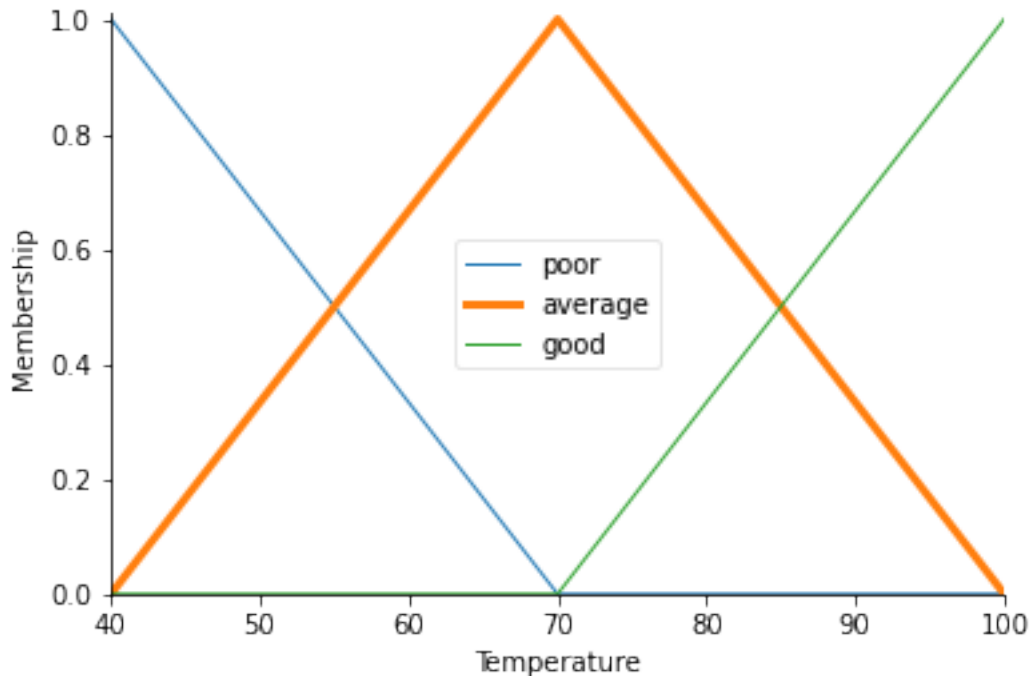
```
[9]: # Visualization of the unity progressing fuzzy tree. With each split the
      ↪ features grow closer to unity until purity
      # or depth is reached.
      fig, axes = plt.subplots(nrows = 1,ncols = 1,figsize = (4,4), dpi=400)
      plot_tree(clf_fuzz, feature_names = ['Temperature','Wind','Traffic'],
      ↪ class_names=['yes','no'])
```

```
[9]: [Text(354.2857142857143, 1087.2, 'Temperature <= 0.5\ngini = 0.459\nsamples =
      14\nvalue = [5, 9]\nclass = no'),
      Text(177.14285714285714, 845.6, 'gini = 0.0\nsamples = 3\nvalue = [3, 0]\nclass
      = yes'),
      Text(531.4285714285714, 845.6, 'Wind <= 0.898\ngini = 0.298\nsamples =
      11\nvalue = [2, 9]\nclass = no'),
      Text(354.2857142857143, 604.0, 'gini = 0.0\nsamples = 6\nvalue = [0, 6]\nclass
      = no'),
      Text(708.5714285714286, 604.0, 'Traffic <= 0.66\ngini = 0.48\nsamples =
      5\nvalue = [2, 3]\nclass = no'),
      Text(531.4285714285714, 362.4, 'gini = 0.0\nsamples = 2\nvalue = [0, 2]\nclass
      = no'),
      Text(885.7142857142857, 362.4, 'Wind <= 0.96\ngini = 0.444\nsamples = 3\nvalue
      = [2, 1]\nclass = yes'),
      Text(708.5714285714286, 120.79999999999995, 'gini = 0.0\nsamples = 1\nvalue =
      [1, 0]\nclass = yes'),
      Text(1062.857142857143, 120.79999999999995, 'gini = 0.5\nsamples = 2\nvalue =
      [1, 1]\nclass = yes')]
```



```
[10]: # This shows the visuzlization of a triangular fuzzy logic.
from skfuzzy import control as ctrl
temp = ctrl.Antecedent((40,70,100), 'Temperature')
temp.automf(3)
temp['average'].view()
```

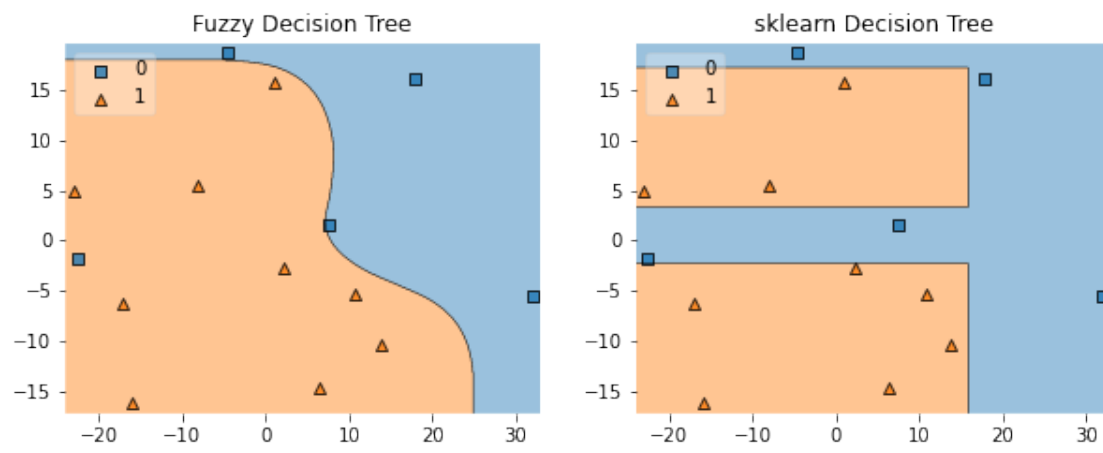
```
C:\Users\David\anaconda3\lib\site-packages\skfuzzy\control\term.py:74:
UserWarning: Matplotlib is currently using
module://ipykernel.pylab.backend_inline, which is a non-GUI backend, so cannot
show the figure.
fig.show()
```

```
[17]: # Here we are making a comparison between a PCA decision tree and a fuzzytree
      ↳with the embellished data.
      # It would make sense that within this framework the decision tree would
      ↳perform better since the embellish data allows for
      # logical distinction. The purpose of this comparison is to show the process of
      ↳fuzzification of a decision tree.

      from mlxtend.plotting import plot_decision_regions
      import matplotlib.pyplot as plt
      import matplotlib.gridspec as gridspec
      from sklearn.decomposition import PCA
      data = {'Temperature':x1f,'Wind mph':x2f,' Traffic-Jams':x3f}
      Xf2 = pd.DataFrame(data)
      Xf2 = Xf2.to_numpy()
      yf = df['Drive Car']
      yf = yf.to_numpy()
      pca = PCA(n_components = 2)
      Xfp = pca.fit_transform(Xf2)
      clf_sk = DecisionTreeClassifier().fit(Xfp,yf)
      clf_fuzz = FuzzyDecisionTreeClassifier().fit(Xfp,yf)
      gs = gridspec.GridSpec(2, 2)
      fig = plt.figure(figsize=(10,8))
      labels = ['Fuzzy Decision Tree', 'sklearn Decision Tree']
      for clf, lab, grd in zip([clf_fuzz, clf_sk], labels, [[0, 0], [0, 1]]):
          ax = plt.subplot(gs[grd[0], grd[1]])
```

```
fig = plot_decision_regions(Xfp,yf, clf=clf, legend=2)
plt.title("%s" % lab)
plt.show()
```



[]: