# advent of code day 15

December 28, 2021

# 1 Advent of Code

```
[]: # set up the environment
import numpy as np
from collections import Counter
import networkx as nx
```

## 1.1 Day 15: Chiton

You've almost reached the exit of the cave, but the walls are getting closer together. Your submarine can barely still fit, though; the main problem is that the walls of the cave are covered in chitons, and it would be best not to bump any of them.

The cavern is large, but has a very low ceiling, restricting your motion to two dimensions. The shape of the cavern resembles a square; a quick scan of chiton density produces a map of *risk level* throughout the cave (your puzzle input). For example:

You start in the top left position, your destination is the bottom right position, and you cannot move diagonally. The number at each position is its **risk level**; to determine the total risk of an entire path, add up the risk levels of each position you **enter** (that is, don't count the risk level of your starting position unless you enter it; leaving it adds no risk to your total).

Your goal is to find a path with the **lowest total risk**. In this example, a path with the lowest total risk is highlighted here:

163751742 381373672 136511328 

```
7463417111
1319128137
1359912421
3125421639
1293138521
2311944581
```

The total risk of this path is  $4\theta$  (the starting position is never entered, so its risk is not counted).

What is the lowest total risk of any path from the top left to the bottom right?

#### 1.2 Solution

This is a shortest path problem which is heavily based on graph theory. After a lot of reading(!) it seems that the NetworkX library has the required procedures. A graph can be created using the grid\_2\_graph generator which has the same dimensions as the source grid and connects each node to its nearest neighbour. The DiGraph type can be used to store the weighted edges for entering a node.

The hardest part will be setting the weighting for the edges; we can iterate through the edges and set the weighting of the edge to that of the destination.

Once the array is constructed NetworkX will return the shortest path i.e. the one with the least total weighting.

```
for (xs, ys), (xd, yd), data in g.edges(data=True):
        data["weight"] = source_data[xd][yd]
   return g
# verify the test data
risk_data = get_data(TEST_PATH)
height, width = risk_data.shape
risk_graph = create_graph(risk_data)
path length = nx.shortest path length(risk graph, source=(0, 0),
→target=(height-1, width-1), weight="weight")
assert(path_length == 40)
# OK so get problem solution
risk_data = get_data(PROBLEM_PATH)
height, width = risk_data.shape
risk graph = create graph(risk data)
path_length = nx.shortest_path_length(risk_graph, source=(0, 0),__
 →target=(height-1, width-1), weight="weight")
print(f'Minimum basic problem path length: {path_length}')
```

Minimum basic problem path length: 363

### 1.3 Part Two

Now that you know how to find low-risk paths in the cave, you can try to find your way out.

The entire cave is actually **five times larger in both dimensions** than you thought; the area you originally scanned is just one tile in a 5x5 tile area that forms the full map. Your original map tile repeats to the right and downward; each time the tile repeats to the right or downward, all of its risk levels **are 1 higher** than the tile immediately up or left of it. However, risk levels above 9 wrap back around to 1. So, if your original map had some position with a risk level of 8, then that same position on each of the 25 total tiles would be as follows:

```
8 9 1 2 3 9 1 2 3 4 1 2 3 4 5 2 3 4 5 6 3 4 5 6 7
```

Each single digit above corresponds to the example position with a value of 8 on the top-left tile. Because the full map is actually five times larger in both dimensions, that position appears a total of 25 times, once in each duplicated tile, with the values shown above.

Here is the full five-times-as-large version of the first example above, with the original map in the top left corner highlighted:

```
11637517422274862853338597396444961841755517295286

13813736722492484783351359589446246169155735727126

21365113283247622439435873354154698446526571955763

36949315694715142671582625378269373648937148475914

74634171118574528222968563933317967414442817852555

13191281372421239248353234135946434524615754563572
```

Equipped with the full map, you can now find a path from the top left corner to the bottom right corner with the lowest total risk:

11637517422274862853338597396444961841755517295286

The total risk of this path is **315** (the starting position is still never entered, so its risk is not counted).

Using the full map, what is the lowest total risk of any path from the top left to the bottom right?

## 1.3.1 Thoughts

We have two options here: - create the enlarged risk map from the original and then create the risk graph from that. - create a risk graph that is 5 times larger and set the weighting depending on the iteration of the original graph

The first option looks the easiest at the moment so will work with that and see how it goes!

```
[]: def expand risk data(original risk data):
         ''' Expand the data matrix from 10x10 to 50x50
         new_risk_data: np.array = np.copy(original_risk_data)
         updated_risk_data: np.array = np.copy(original_risk_data)
         for x in range(4):
             updated_risk_data = np.where(updated_risk_data == 9, 1,__
      →updated_risk_data+1)
             new_risk_data = np.concatenate((new_risk_data, updated_risk_data),_
      \rightarrowaxis=1)
         updated_risk_data = np.copy(new_risk_data)
         for x in range(4):
             updated_risk_data = np.where(updated_risk_data == 9, 1,__
      →updated_risk_data+1)
             new_risk_data = np.concatenate((new_risk_data, updated_risk_data),_
      \rightarrowaxis=0)
         return new_risk_data
     # verify the test data
     new_risk_data = expand_risk_data(get_data(TEST_PATH))
     height, width = new_risk_data.shape
     new risk graph = create graph(new risk data)
     path_length = nx.shortest_path_length(new_risk_graph, source=(0, 0),_
     →target=(height-1, width-1), weight="weight")
     assert(path_length == 315)
     # OK so get problem solution
     new_risk_data = expand_risk_data(get_data(PROBLEM_PATH))
     height, width = new_risk_data.shape
     new_risk_graph = create_graph(new_risk_data)
```

Minimum expanded problem path length: 2835

[]: