

**Continuous-time periodic square wave 连续时间方波**

$$x(t) = \begin{cases} 1 & |t| < T_1 \\ 0 & T_1 < |t| < \frac{T}{2} \end{cases} \quad a_k = \frac{1}{T} \int_{-T_1}^{T_1} e^{-jk\omega_0 t} dt = \begin{cases} \frac{2T_1}{T} & k = 0 \\ \frac{e^{-jk\omega_0 T_1} - e^{jk\omega_0 T_1}}{jk\omega_0 T} & k \neq 0 \end{cases} = \begin{cases} \frac{2T_1}{T} & k = 0 \\ \frac{\sin(k\omega_0 T_1)}{k\pi} & k \neq 0 \end{cases}$$

**等比数列**

通项公式:  $a_n = a_1 q^{n-1}$   
 两项关系:  $a_n = a_m q^{n-m}$   
 求和公式:  $S_n = a_1 \frac{1-q^n}{1-q} = \frac{a_1 - a_n q}{1-q}$

**Discrete-time periodic square wave 离散时间方波**

When  $k = 0, \pm N, \pm 2N, \dots$ ,  $a_k = \frac{1}{N} \sum_{n=-N}^{N-1} x[n] e^{-jk\omega_0 n} = \frac{1}{N} \sum_{n=-N}^{N-1} e^{-jk\frac{2\pi}{N}n} = \frac{1}{N} \sum_{n=-N}^{N-1} 1 = \frac{2N+1}{N}$

When  $k \neq 0, \pm N, \pm 2N, \dots$ ,  $a_k = \frac{1}{N} \sum_{n=-N}^{N-1} x[n] e^{-jk\omega_0 n} = \frac{1}{N} \sum_{n=-N}^{N-1} e^{-jk\frac{2\pi}{N}n} = \frac{1}{N} e^{jk\frac{2\pi}{N}N} \frac{1 - e^{-jk\frac{2\pi}{N}(2N+1)}}{1 - e^{-jk\frac{2\pi}{N}}} = \frac{1}{N} \frac{\sin\left(\frac{2k\pi(N+1)}{N}\right)}{\sin\left(\frac{k\pi}{N}\right)}$

化简技巧  $1 - e^{-jk\frac{2\pi}{N}} = e^{-jk\frac{2\pi}{N}} (e^{jk\frac{2\pi}{N}} - e^{-jk\frac{2\pi}{N}})$

**Even and odd decomposition**

$\mathcal{E}\{x[t]\} = \frac{1}{2}\{x(t) + x(-t)\}$   
 $\mathcal{O}\{x[t]\} = \frac{1}{2}\{x(t) - x(-t)\}$   
 奇分解围绕原点旋转除 2, 偶分解围绕 y 轴变换除 2

**系统性质的判据**

系统性质的判据	输入输出关系	单位冲激响应
Memoryless	Output at $t = t_0$ depends only on the value of input at $t = t_0$	$h(t) = 0$ for $t \neq 0$
Invertible	There exist an inverse system	$\exists h_1[n]$ s.t. $h[n] * h_1[n] = \delta[n]$
Causality	Output at this time only depends on values of the input at the present time and in the past	$h[n] = 0$ for $n < 0$
Stability	BIBO	$\int_{-\infty}^{\infty}  h(\tau)  d\tau < \infty$
Time-invariance	Let $x_1(t) = x(t - t_0)$ Check $y_1(t) = ? y(t - t_0)$	Must satisfy
Linearity	Let $x_1(t), x_2(t), x_3(t) = x_1(t) + x_2(t)$ Check $y_3(t) = ? ay_1(t) + by_2(t)$	Must satisfy

**Convolution 卷积**

$$y[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k] = \sum_{k=-\infty}^{\infty} x[n-k]h[k]$$

$$y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau = \int_{-\infty}^{\infty} x(t-\tau)h(\tau)d\tau$$

一个函数的  $t$  换成  $\tau$ , 另一个函数的  $t$  换成  $t-\tau$ ; 如果结果以原点为界, 记得写成  $u[n]u(t)$  的形式;  $x(\tau)$  的图像正常,  $h(t-\tau)$  的图像关于  $y$  轴翻转后, 原点为  $t$

**Singularity functions**

$u_k(t)$  求导;  $u_{-k}(t)$  积分;  $u_1(t)$  是 unit doublet

**Impulse train**

$$x(t) = \sum_{k \in \mathbb{Z}} \delta(t - kT) \xleftrightarrow{FS} a_k = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} \delta(t) e^{-jk\omega_0 t} dt = \frac{1}{T}$$

**Properties of convolution 卷积的性质**

$x(t) * \delta(t) = x(t)$   
 $x(t) * \delta(t - t_0) = x(t - t_0)$   
 $x(t - t_1) * \delta(t - t_2) = x(t - t_1 - t_2)$   
 $x(t) * \delta'(t) = x'(t)$   
 $x(t) * u(t) = x^{-1}(t) = \int_{-\infty}^t x(\tau) d\tau$   
 $x(t) * h(t) = x'(t) * h^{-1}(t)$

**Euler's formula 欧拉公式**

$e^{j\theta} = \cos \theta + j \sin \theta$   
 $\cos \theta = \frac{e^{j\theta} + e^{-j\theta}}{2}$   
 $\sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2j}$

**诱导公式**

$\sin(2k\pi + \alpha) = \sin \alpha$   
 $\cos(2k\pi + \alpha) = \cos \alpha$   
 $\sin(-\alpha) = -\sin \alpha$   
 $\cos(-\alpha) = \cos \alpha$   
 $\sin(\pi - \alpha) = \sin \alpha$   
 $\cos(\pi - \alpha) = -\cos \alpha$   
 $\sin(\pi + \alpha) = -\sin \alpha$   
 $\cos(\pi + \alpha) = -\cos \alpha$   
 $\sin\left(\frac{\pi}{2} - \alpha\right) = \cos \alpha$   
 $\cos\left(\frac{\pi}{2} - \alpha\right) = \sin \alpha$   
 $\sin\left(\frac{\pi}{2} + \alpha\right) = \cos \alpha$   
 $\cos\left(\frac{\pi}{2} + \alpha\right) = -\sin \alpha$   
 $\operatorname{tg}(k\pi + \alpha) = \operatorname{tg} \alpha$   
 $\operatorname{tg}(-\alpha) = -\operatorname{tg} \alpha$   
 $\operatorname{tg}(\pi - \alpha) = -\operatorname{tg} \alpha$   
 $\operatorname{tg}(\pi + \alpha) = \operatorname{tg} \alpha$   
 $\operatorname{tg}\left(\frac{\pi}{2} - \alpha\right) = \operatorname{ctg} \alpha$   
 $\operatorname{tg}\left(\frac{\pi}{2} + \alpha\right) = -\operatorname{ctg} \alpha$

**Fourier Series 傅里叶级数**

$x(t) = e^{st} \xrightarrow{LTI} y(t) = H(s)e^{st}$ $\sum_k a_k e^{s_k t} \xrightarrow{LTI} \sum_k a_k H(s_k) e^{s_k t}$	$x[n]z^n \xrightarrow{LTI} y[n] = H(z)z^n$ $\sum_k a_k z_k^n \xrightarrow{LTI} \sum_k a_k H(z_k) z_k^n$
$H(s) = \int_{-\infty}^{\infty} h(t) e^{-st} dt$ $H(j\omega) = \int_{-\infty}^{\infty} h(t) e^{-j\omega t} dt$	$H(z) = \sum_{k=-\infty}^{\infty} h[k] z^{-k}$ $H(e^{j\omega}) = \sum_{n=-\infty}^{\infty} h[n] e^{-j\omega n}$
$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$ $a_k = \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt$	$x[n] = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 n}$ $a_k = \frac{1}{N} \sum_{n=-\infty}^{\infty} x[n] e^{-jk\omega_0 n}$

**TABLE 17.1** The method of undetermined coefficients for selected equations of the form

$$ay'' + by' + cy = G(x).$$

If $G(x)$ has a term that is a constant multiple of ...	And if	Then include this expression in the trial function for $y_p$ .
$e^{rx}$	$r$ is not a root of the auxiliary equation $r$ is a single root of the auxiliary equation $r$ is a double root of the auxiliary equation	$Ae^{rx}$ $Axe^{rx}$ $Ax^2e^{rx}$
$\sin kx, \cos kx$	$ki$ is not a root of the auxiliary equation	$B \cos kx + C \sin kx$
$px^2 + qx + m$	$0$ is not a root of the auxiliary equation $0$ is a single root of the auxiliary equation $0$ is a double root of the auxiliary equation	$Dx^2 + Ex + F$ $Dx^3 + Ex^2 + Fx$ $Dx^4 + Ex^3 + Fx^2$

和差化积公式与积化和差公式

$$\begin{aligned}\sin \alpha + \sin \beta &= 2 \sin \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2} \\ \sin \alpha - \sin \beta &= 2 \cos \frac{\alpha + \beta}{2} \sin \frac{\alpha - \beta}{2} \\ \cos \alpha + \cos \beta &= 2 \cos \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2} \\ \cos \alpha - \cos \beta &= -2 \sin \frac{\alpha + \beta}{2} \sin \frac{\alpha - \beta}{2} \\ \sin \alpha \cos \beta &= \frac{1}{2} [\sin(\alpha + \beta) + \sin(\alpha - \beta)] \\ \cos \alpha \sin \beta &= \frac{1}{2} [\sin(\alpha + \beta) - \sin(\alpha - \beta)] \\ \cos \alpha \cos \beta &= \frac{1}{2} [\cos(\alpha + \beta) + \cos(\alpha - \beta)] \\ \sin \alpha \sin \beta &= \frac{1}{2} [\cos(\alpha + \beta) - \cos(\alpha - \beta)]\end{aligned}$$

**自变量变换**  
Systematic approach:  $x(t) \rightarrow x(t + \beta) \rightarrow x(\alpha t + \beta)$

**Real, even, odd properties of a signal**  
If  $x(t)$  is real, then from the synthesis equation:  
$$\sum_{k \in \mathbb{R}} a_k e^{jk\omega_0 t} = \sum_{k \in \mathbb{R}} a_k^* e^{-jk\omega_0 t} = \sum_{-k \in \mathbb{R}} a_{-k}^* e^{jk\omega_0 t} \Rightarrow a_k = a_{-k}^*$$
  
If  $x(t)$  is real and even, then  $x(t) = x(-t) \Rightarrow a_k = a_{-k}$ ;  $a_{-k} = a_{-k}^* \Rightarrow a_k = a_k^*$   
Hence  $a_k$  is real and even.  
Similarly, if  $x(t)$  is real and odd, then  $a_k = -a_{-k}$  and  $a_k = -a_k^*$ ,  $a_k$  is purely imaginary and odd.

**N<sup>th</sup> order linear constant-coefficient differential equation**  
Expression:  $\sum_{k=0}^N a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^M b_k \frac{d^k x(t)}{dt^k}$   
Solution:  $y(t) = y_p(t) + y_h(t)$ , where  $y_h(t) = A_1 e^{s_1 t} + \dots + A_N e^{s_N t}$   
Causal and LTI  $\Leftrightarrow$  Initial rest (i.e. if  $x(t) = 0$  for  $t < t_0$  then  $y(t) = 0$  for  $t < t_0$ )  
**N<sup>th</sup> order linear constant-coefficient difference equation**  
Expression:  $\sum_{k=0}^N a_k y[n-k] = \sum_{k=0}^M b_k x[n-k]$   
Solution:  $y[n] = y_p[n] + y_h[n]$ , where  $y_h[n] = A_1 z_1^n + \dots + A_N z_N^n$   
Causal and LTI  $\Leftrightarrow$  Initial rest (i.e. if  $x[n] = 0$  for  $n < n_0$  then  $y[n] = 0$  for  $n < n_0$ )

TABLE 3.1 PROPERTIES OF CONTINUOUS-TIME FOURIER SERIES

Property	Section	Periodic Signal	Fourier Series Coefficients
Linearity	3.5.1	$Ax(t) + Bx(t)$	$Aa_k + Bb_k$
Time Shifting	3.5.2	$x(t - t_0)$	$a_k e^{-jk\omega_0 t_0} = a_k e^{-jk(2\pi/T)t_0}$
Frequency Shifting	3.5.6	$e^{j\omega_0 t} x(t)$	$a_{k-M}$
Conjugation	3.5.6	$x^*(t)$	$a_{-k}^*$
Time Reversal	3.5.3	$x(-t)$	$a_{-k}$
Time Scaling	3.5.4	$x(\alpha t), \alpha > 0$ (periodic with period $T/\alpha$ )	$a_k$
Periodic Convolution		$\int_T x(\tau)y(t-\tau)d\tau$	$T a_k b_k$
Multiplication	3.5.5	$x(t)y(t)$	$\sum_{l=-\infty}^{\infty} a_l b_{k-l}$
Differentiation		$\frac{d}{dt} x(t)$	$jk\omega_0 a_k = jk \frac{2\pi}{T} a_k$
Integration		$\int_{-\infty}^t x(t)dt$ (finite valued and periodic only if $a_0 = 0$ )	$\left(\frac{1}{jk\omega_0}\right)a_k = \left(\frac{1}{jk(2\pi/T)}\right)a_k$
Conjugate Symmetry for Real Signals	3.5.6	$x(t)$ real	$a_k = a_{-k}^*$ $\begin{cases} \operatorname{Re}\{a_k\} = \operatorname{Re}\{a_{-k}\} \\ \operatorname{Im}\{a_k\} = -\operatorname{Im}\{a_{-k}\} \\  a_k  =  a_{-k}  \end{cases}$ $\angle a_k = -\angle a_{-k}$
Real and Even Signals	3.5.6	$x(t)$ real and even	$a_k$ real and even
Real and Odd Signals	3.5.6	$x(t)$ real and odd	$a_k$ purely imaginary and odd
Even-Odd Decomposition of Real Signals		$\begin{cases} x_e(t) = \operatorname{Re}\{x(t)\} \\ x_o(t) = \operatorname{Od}\{x(t)\} \end{cases}$	$\begin{cases} [x(t) \text{ real}] \\ [x(t) \text{ real}] \\ [x(t) \text{ real}] \end{cases}$ $\operatorname{Re}\{a_k\}$ $j\operatorname{Im}\{a_k\}$

Parseval's Relation for Periodic Signals

$$\frac{1}{T} \int_T |x(t)|^2 dt = \sum_{k=-\infty}^{+\infty} |a_k|^2$$

TABLE 3.2 PROPERTIES OF DISCRETE-TIME FOURIER SERIES

Property	Section	Periodic Signal	Fourier Series Coefficients
Linearity		$Ax[n] + Bx[n]$	$Aa_k + Bb_k$
Time Shifting		$x[n - n_0]$	$a_k e^{-jk(2\pi/N)n_0}$
Frequency Shifting		$e^{j\omega_0 n} x[n]$	$a_{k-M}$
Conjugation		$x^*[n]$	$a_{-k}^*$
Time Reversal		$x[-n]$	$a_{-k}$
Time Scaling		$x[mn]$ , if $n$ is a multiple of $m$ if $n$ is not a multiple of $m$ (periodic with period $mN$ )	$\frac{1}{m} a_k$ (viewed as periodic with period $mN$ )
Periodic Convolution		$\sum_{r=0}^{n-1} x[r]y[n-r]$	$N a_k b_k$
Multiplication		$x[n]y[n]$	$\sum_{l=0}^{N-1} a_l b_{k-l}$
First Difference		$x[n] - x[n-1]$	$(1 - e^{-jk(2\pi/N)})a_k$
Running Sum		$\sum_{k=-\infty}^n x[k]$ (finite valued and periodic only if $a_0 = 0$ )	$\left(\frac{1}{1 - e^{-jk(2\pi/N)}}\right)a_k$
Conjugate Symmetry for Real Signals		$x[n]$ real	$a_k = a_{-k}^*$ $\begin{cases} \operatorname{Re}\{a_k\} = \operatorname{Re}\{a_{-k}\} \\ \operatorname{Im}\{a_k\} = -\operatorname{Im}\{a_{-k}\} \\  a_k  =  a_{-k}  \end{cases}$ $\angle a_k = -\angle a_{-k}$
Real and Even Signals		$x[n]$ real and even	$a_k$ real and even
Real and Odd Signals		$x[n]$ real and odd	$a_k$ purely imaginary and odd
Even-Odd Decomposition of Real Signals		$\begin{cases} x_e[n] = \operatorname{Re}\{x[n]\} \\ x_o[n] = \operatorname{Od}\{x[n]\} \end{cases}$	$\begin{cases} [x[n] \text{ real}] \\ [x[n] \text{ real}] \\ [x[n] \text{ real}] \end{cases}$ $\operatorname{Re}\{a_k\}$ $j\operatorname{Im}\{a_k\}$

Parseval's Relation for Periodic Signals

$$\frac{1}{N} \sum_{n=0}^{N-1} |x[n]|^2 = \sum_{k=0}^{N-1} |a_k|^2$$

**System Properties (Laplace Transform)**

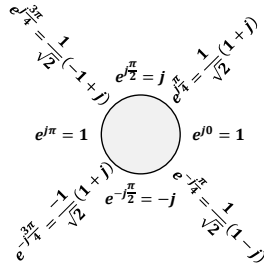
Causality	ROC is a right-half plane
Causality (Rational $H(s)$ )	ROC is the right-half plane to the right of the rightmost pole
Anticausality	ROC is a left-half plane (to the left of the leftmost pole)
Stability	ROC includes the entire $j\omega$ -axis

Causal LTI system with rational  $H(s)$ : all poles lie in the left-half of the  $s$ -plane

**System Properties (Z-Transform)**

Causality	ROC is the exterior of a circle including infinity
Causality (Rational $H(z)$ )	ROC is the exterior of a circle outside the outermost pole + 分子 $z$ 阶数不能比分母大
Stability	ROC includes the unit circle

Causal LTI system with rational  $H(z)$ : all poles lie inside the

**Z-Transform Z 变换**

$$X(z) \triangleq \sum_{n=-\infty}^{\infty} x[n]z^{-n}$$

$$x[n] = \frac{1}{2\pi j} \oint X(z)z^{n-1}dz$$

**Euler's formula 欧拉公式**

$$e^{j\theta} = \cos \theta + j \sin \theta$$

$$\cos \theta = \frac{e^{j\theta} + e^{-j\theta}}{2}$$

$$\sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2j}$$

**Nyquist Sampling Theorem**

Let  $x(t)$  be a band-limited signal within  $\pm\omega_M$ , then  $x(t)$  is uniquely determined by its samples  $x(nT)$  if  $\omega_s > 2\omega_M$ , where  $\omega_s = \frac{2\pi}{T}$ .

Nyquist rate:  $2\omega_M$

**Z 变换特殊峰的判断**

信号为正，零点有峰  
信号为负，无穷有峰

**诱导公式**

$$\begin{aligned} \sin(2k\pi + \alpha) &= \sin \alpha \\ \cos(2k\pi + \alpha) &= \cos \alpha \\ \sin(-\alpha) &= -\sin \alpha \\ \cos(-\alpha) &= \cos \alpha \\ \sin(\pi - \alpha) &= \sin \alpha \\ \cos(\pi - \alpha) &= -\cos \alpha \\ \sin(\pi + \alpha) &= -\sin \alpha \\ \cos(\pi + \alpha) &= -\cos \alpha \\ \sin\left(\frac{\pi}{2} - \alpha\right) &= \cos \alpha \\ \cos\left(\frac{\pi}{2} - \alpha\right) &= \sin \alpha \\ \sin\left(\frac{\pi}{2} + \alpha\right) &= \cos \alpha \\ \cos\left(\frac{\pi}{2} + \alpha\right) &= -\sin \alpha \\ \operatorname{tg}(k\pi + \alpha) &= \operatorname{tg} \alpha \\ \operatorname{tg}(-\alpha) &= -\operatorname{tg} \alpha \\ \operatorname{tg}(\pi - \alpha) &= -\operatorname{tg} \alpha \\ \operatorname{tg}(\pi + \alpha) &= \operatorname{tg} \alpha \\ \operatorname{tg}\left(\frac{\pi}{2} - \alpha\right) &= \operatorname{ctg} \alpha \\ \operatorname{tg}\left(\frac{\pi}{2} + \alpha\right) &= -\operatorname{ctg} \alpha \end{aligned}$$

**Fourier Transform 傅里叶变换**

$$X(j\omega) = \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt$$

$$X(j\omega) = \sum_{k=-\infty}^{\infty} 2\pi a_k \delta(\omega - k\omega_0)$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega)e^{j\omega t} d\omega$$

**等比数列**

通项公式:  $a_n = a_1 q^{n-1}$

两项关系:  $a_n = a_m q^{n-m}$

求和公式:  $S_n = a_1 \frac{1-q^n}{1-q} = \frac{a_1 - a_n q}{1-q}$

**Even and odd decomposition**

$$\mathcal{E}\nu\{x[t]\} = \frac{1}{2}\{x(t) + x(-t)\}$$

$$\mathcal{O}\nu\{x[t]\} = \frac{1}{2}\{x(t) - x(-t)\}$$

奇分解围绕原点旋转除 2, 偶分解围绕  $y$  轴变换除 2

**和差化积公式与积化和差公式**

$$\sin \alpha + \sin \beta = 2 \sin \frac{\alpha+\beta}{2} \cos \frac{\alpha-\beta}{2}$$

$$\sin \alpha - \sin \beta = 2 \cos \frac{\alpha+\beta}{2} \sin \frac{\alpha-\beta}{2}$$

$$\cos \alpha + \cos \beta = 2 \cos \frac{\alpha+\beta}{2} \cos \frac{\alpha-\beta}{2}$$

$$\cos \alpha - \cos \beta = -2 \sin \frac{\alpha+\beta}{2} \sin \frac{\alpha-\beta}{2}$$

$$\sin \alpha \cos \beta = \frac{1}{2}[\sin(\alpha + \beta) + \sin(\alpha - \beta)]$$

$$\cos \alpha \sin \beta = \frac{1}{2}[\sin(\alpha + \beta) - \sin(\alpha - \beta)]$$

$$\cos \alpha \cos \beta = \frac{1}{2}[\cos(\alpha + \beta) + \cos(\alpha - \beta)]$$

$$\sin \alpha \sin \beta = \frac{1}{2}[\cos(\alpha + \beta) - \cos(\alpha - \beta)]$$

**Hilbert Transform**

$$\frac{1}{\pi t} \xrightarrow{\mathcal{F}} -j \cdot \operatorname{sign} \omega, \cos \omega_0 t \xrightarrow{h(t)} \sin \omega_0 t$$

**Quick Reference Checklist 快速检查单**

Signal	Transform	ROC	Pole
$e^{-at}u(t)$	$\frac{1}{s+a}$	$\operatorname{Re}\{s\} > -a$	$-a$
$e^{-at}u(-t)$	$-\frac{1}{s+a}$	$\operatorname{Re}\{s\} < -a$	$-a$
$e^{at}u(t)$	$\frac{1}{s-a}$	$\operatorname{Re}\{s\} > a$	$a$
$e^{at}u(-t)$	$-\frac{1}{s-a}$	$\operatorname{Re}\{s\} < a$	$a$
$a^n u[n]$	$\frac{1}{1-az^{-1}}$	$ z  >  a $	$a$
$a^n u[-n-1]$	$-\frac{1}{1-az^{-1}}$	$ z  <  a $	$a$
$(-a)^n u[n]$	$\frac{1}{1+az^{-1}}$	$ z  >  a $	$-a$
$(-a)^n u[-n-1]$	$-\frac{1}{1+az^{-1}}$	$ z  <  a $	$-a$
$te^{-at}u(t)$	$\frac{1}{(s+a)^2}$	$\operatorname{Re}\{s\} > -a$	$-a(\times 2)$
$na^n u[n]$	$\frac{1}{(1-az^{-1})^2}$	$ z  >  a $	$a(\times 2)$

**Basic BD Pairs**

$H(s) = \frac{1}{s+3}$ 	$H(z) = \frac{1}{1 - \frac{1}{4}z^{-1}}$ 
$H(s) = \frac{s^2 - s - 6}{s^2 + 2s + 1}$ 	$H(z) = \frac{1 - \frac{7}{4}z^{-1} - \frac{1}{2}z^{-2}}{1 + \frac{1}{4}z^{-1} - \frac{1}{8}z^{-2}}$ 

<b>Parseval's Relation (Aperiodic Sig.)</b> $\int_{-\infty}^{\infty}  x(t) ^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty}  X(j\omega) ^2 d\omega$	<b>Initial/Final Value Theorem</b> $x(0^+) = \lim_{s \rightarrow \infty} sX(s), \lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sX(s)$	<b>Initial Value Theorem</b> If $x[n] = 0$ for $n < 0$ , $x[0] = \lim_{z \rightarrow \infty} X(z)$ .	<b>Group Delay</b> $\tau(\omega) = -\frac{d}{d\omega} \{\angle H(j\omega)\}$
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Properties of Fourier Transform 傅里叶变换的性质		
Property	Aperiodic signal	Fourier transform
	$x(t)$	$X(j\omega)$
	$y(t)$	$Y(j\omega)$
Linearity	$ax(t) + by(t)$	$aX(j\omega) + bY(j\omega)$
Time Shifting	$x(t - t_0)$	$e^{-j\omega t_0} X(j\omega)$
Frequency Shifting	$e^{j\omega_0 t} x(t)$	$X(j(\omega - \omega_0))$
Conjugation	$x^*(t)$	$X^*(-j\omega)$
Time Reversal	$x(-t)$	$X(-j\omega)$
Time and Frequency Scaling	$x(at)$	$\frac{1}{ a } X\left(\frac{j\omega}{a}\right)$
Convolution	$x(t) * y(t)$	$X(j\omega)Y(j\omega)$
Multiplication	$x(t)y(t)$	$\frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\theta)Y(j(\omega - \theta))d\theta$
Differentiation in Time	$\frac{d}{dt}x(t)$	$j\omega X(j\omega)$
Integration	$\int_{-\infty}^t x(t)dt$	$\frac{1}{j\omega} X(j\omega) + \pi X(0)\delta(\omega)$
Differentiation in Frequency	$tx(t)$	$j \frac{d}{d\omega} X(j\omega)$
Conjugate Symmetry for Real Signals	$x(t)$ real	$\begin{cases} X(j\omega) = X^*(-j\omega) \\ \text{Re}\{X(j\omega)\} = \text{Re}\{X(-j\omega)\} \\ \text{Im}\{X(j\omega)\} = -\text{Im}\{X(-j\omega)\} \\  X(j\omega)  =  X(-j\omega)  \\ \angle X(j\omega) = -\angle X(-j\omega) \end{cases}$
Symmetry for Real and Even Signals	$x(t)$ real and even	$X(j\omega)$ real and even
Symmetry for Real and Odd Signals	$x(t)$ real and odd	$X(j\omega)$ purely imaginary and odd
Even-Odd Decomposition for Real Signals	$x_e(t) = \text{Ev}\{x(t)\}$ $x_o(t) = \text{Od}\{x(t)\}$ $x(t)$ real	$\text{Re}\{X(j\omega)\}$ $j\text{Im}\{X(j\omega)\}$

Basic Fourier Transform Pairs		
Signal	Fourier transform	Fourier series coefficients (if periodic)
$\sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$	$2\pi \sum_{k=-\infty}^{\infty} a_k \delta(\omega - k\omega_0)$	$a_k$
$e^{j\omega_0 t}$	$2\pi \delta(\omega - \omega_0)$	$a_1 = 1$ $a_k = 0, \text{ otherwise}$
$\cos \omega_0 t$	$\pi[\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$	$a_1 = a_{-1} = \frac{1}{2}$ $a_k = 0, \text{ otherwise}$
$\sin \omega_0 t$	$\frac{\pi}{j}[\delta(\omega - \omega_0) - \delta(\omega + \omega_0)]$	$a_1 = -a_{-1} = \frac{1}{2j}$ $a_k = 0, \text{ otherwise}$
$x(t) = 1$	$2\pi \delta(\omega)$	$a_0 = 1, a_k = 0, k \neq 0$
Periodic square wave $x(t) = \begin{cases} 1, &  t  < T_1 \\ 0, & T_1 <  t  \leq \frac{T}{2} \end{cases}$ And $x(t+T) = x(t)$	$\sum_{k=-\infty}^{\infty} \frac{2 \sin k\omega_0 T_1}{k} \delta(\omega - k\omega_0)$	$\frac{\omega_0 T_1}{\pi} \text{sinc}\left(\frac{k\omega_0 T_1}{\pi}\right) = \frac{\sin k\omega_0 T_1}{k\pi}$
$\sum_{n=-\infty}^{\infty} \delta(t - nT)$	$\frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta\left(\omega - \frac{2\pi k}{T}\right)$	$a_k = \frac{1}{T}$ for all $k$
$x(t) = \begin{cases} 1, &  t  < T_1 \\ 0, &  t  > T_1 \end{cases}$	$\frac{2 \sin \omega T_1}{\omega}$	
$\sin Wt$	$X(j\omega) = \begin{cases} 1, &  \omega  < W \\ 0, &  \omega  > W \end{cases}$	
$\delta(t)$	1	
$u(t)$	$\frac{1}{j\omega} + \pi \delta(\omega)$	
$\delta(t - t_0)$	$e^{-j\omega t_0}$	
$e^{-at}u(t), \text{Re}\{a\} > 0$	$\frac{1}{a + j\omega}$	
$te^{-at}u(t), \text{Re}\{a\} > 0$	$\frac{1}{(a + j\omega)^2}$	
$\frac{t^{n-1}}{(n-1)!} e^{-at}u(t), \text{Re}\{a\} > 0$	$\frac{1}{(a + j\omega)^n}$	
0		

Properties of Laplace Transform 拉普拉斯变换的性质			
Property	Signal	Laplace Transform	ROC
	$x(t)$	$X(s)$	
	$x_1(t)$	$X_1(s)$	
	$x_2(t)$	$X_2(s)$	
Linearity	$ax_1(t) + bx_2(t)$	$aX_1(s) + bX_2(s)$	At least $R_1 \cap R_2$
Time shifting	$x(t - t_0)$	$e^{-st_0} X(s)$	$R$
Shifting in the $s$ -domain	$e^{s_0 t} x(t)$	$X(s - s_0)$	Shifted version of $R$
Time scaling	$x(at)$	$\frac{1}{ a } X\left(\frac{s}{a}\right)$	Scaled ROC
Conjugation	$x^*(t)$	$X^*(s^*)$	$R$
Convolution	$x_1(t) * x_2(t)$	$X_1(s)X_2(s)$	At least $R_1 \cap R_2$
Differentiation in the Time Domain	$\frac{d}{dt}x(t)$	$sX(s)$	At least $R$
Differentiation in the $s$ -domain	$-tx(t)$	$\frac{d}{ds}X(s)$	$R$
Integration in the Time Domain	$\int_{-\infty}^t x(\tau)d\tau$	$\frac{1}{s}X(s)$	At least $R \cap \text{Re}\{s\} > 0$

Laplace Transform Pairs			
#	Signal	Transform	ROC
1	$\delta(t)$	1	All $s$
2	$u(t)$	$1/s$	$\text{Re}\{s\} > 0$
3	$-u(-t)$	$1/s$	$\text{Re}\{s\} < 0$
6	$e^{-at}u(t)$	$\frac{1}{s+a}$	$\text{Re}\{s\} > -a$
7	$-e^{-at}u(-t)$	$\frac{1}{s+a}$	$\text{Re}\{s\} < -a$
8	$\frac{t^{n-1}}{(n-1)!} e^{-at}u(t)$	$\frac{1}{(s+a)^n}$	$\text{Re}\{s\} > -a$
9	$-\frac{t^{n-1}}{(n-1)!} e^{-at}u(-t)$	$\frac{1}{(s+a)^n}$	$\text{Re}\{s\} < -a$
10	$\delta(t - T)$	$e^{-sT}$	All $s$
11	$[\cos \omega_0 t]u(t)$	$\frac{s}{s^2 + \omega_0^2}$	$\text{Re}\{s\} > 0$
12	$[\sin \omega_0 t]u(t)$	$\frac{\omega_0}{s^2 + \omega_0^2}$	$\text{Re}\{s\} > 0$

Properties of Z-Transform			
Property	Signal	z-Transform	ROC
	$x[n]$	$X(z)$	$R$
	$x_1[n]$	$X_1(z)$	$R_1$
	$x_2[n]$	$X_2(z)$	$R_2$
Linearity	$ax_1[n] + bx_2[n]$	$aX_1(z) + bX_2(z)$	At least $R_1 \cap R_2$
Time shifting	$x[n - n_0]$	$z^{-n_0} X(z)$	$R$ except for possible origin
Scaling in the $z$ -domain	$e^{j\omega_0 n} x[n]$	$X(e^{-j\omega_0} z)$	$R$
	$z_0^n x[n]$	$X\left(\frac{z}{z_0}\right)$	$z_0 R$
	$a^n x[n]$	$X(a^{-1} z)$	Scaled version of $R$
Time reversal	$x[-n]$	$X(z^{-1})$	Inverted $R$
Time expansion	$x_{(k)}[n] = \begin{cases} x[r], & n = rk \\ 0, & n \neq rk \end{cases}$	$X(z^k)$	$\frac{1}{R^k}$
Conjugation	$x^*[n]$	$X^*(z^*)$	$R$
Convolution	$x_1[n] * x_2[n]$	$X_1(z)X_2(z)$	At least $R_1 \cap R_2$
First difference	$x[n] - x[n - 1]$	$(1 - z^{-1})X(z)$	At least $R \cap \{ z  > 0\}$
Accumulation	$\sum_{k=-\infty}^n x[k]$	$\frac{1}{1 - z^{-1}} X(z)$	At least $R \cap \{ z  > 1\}$
Differentiation in the $z$ -domain	$nx[n]$	$-z \frac{dX(z)}{dz}$	$R$

Z-Transform Pairs		
Signal	Transform	ROC
$\delta[n]$	1	All $z$
$u[n]$	$\frac{1}{1 - z^{-1}}$	$ z  > 1$
$-u[-n - 1]$	$\frac{1}{1 - z^{-1}}$	$ z  < 1$
$\delta[n - m]$	$z^{-m}$	All $z$ , except 0 or $\infty$
$a^n u[n]$	$\frac{1}{1 - az^{-1}}$	$ z  >  a $
$-a^n u[-n - 1]$	$\frac{1}{1 - az^{-1}}$	$ z  <  a $
$na^n u[n]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z  >  a $
$-na^n u[-n - 1]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z  <  a $
$[\cos \omega_0 n]u[n]$	$\frac{1 - [\cos \omega_0]z^{-1}}{1 - [2 \cos \omega_0]z^{-1} + z^{-2}}$	$ z  > 1$
$[\sin \omega_0 n]u[n]$	$\frac{[\sin \omega_0]z^{-1}}{1 - [2 \cos \omega_0]z^{-1} + z^{-2}}$	$ z  > 1$
$[r^n \cos \omega_0 n]u[n]$	$\frac{1 - [r \cos \omega_0]z^{-1}}{1 - [2r \cos \omega_0]z^{-1} + r^2 z^{-2}}$	$ z  > r$
$[r^n \sin \omega_0 n]u[n]$	$\frac{[r \sin \omega_0]z^{-1}}{1 - [2r \cos \omega_0]z^{-1} + r^2 z^{-2}}$	$ z  > r$

$\log(4) = 2$   
 $\sum_{n=1}^{\infty} \frac{1}{n} = \infty$   
 $\sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{\pi^2}{6}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^3} = \frac{\pi^2}{6}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^4} = \frac{\pi^4}{90}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^5} = \frac{\pi^5}{315}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^6} = \frac{\pi^6}{945}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^7} = \frac{\pi^7}{4725}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^8} = \frac{\pi^8}{789375}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^9} = \frac{\pi^9}{135265125}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^{10}} = \frac{\pi^{10}}{9355680000}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^{11}} = \frac{\pi^{11}}{101351360000}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^{12}} = \frac{\pi^{12}}{1201753800000}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^{13}} = \frac{\pi^{13}}{15749616000000}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^{14}} = \frac{\pi^{14}}{216498656000000}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^{15}} = \frac{\pi^{15}}{3130527800000000}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^{16}} = \frac{\pi^{16}}{45949665600000000}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^{17}} = \frac{\pi^{17}}{700496656000000000}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^{18}} = \frac{\pi^{18}}{10507416000000000000}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^{19}} = \frac{\pi^{19}}{157496160000000000000}$   
 $\sum_{n=1}^{\infty} \frac{1}{n^{20}} = \frac{\pi^{20}}{2362431040000000000000}$

**System Properties (Z-Transform)**

Causality	ROC is the exterior of a circle including infinity
Causality (Rational $H(s)$ )	ROC is the exterior of a circle outside the outermost pole + 分子 z 阶数不能比分母大
Stability	ROC includes the unit circle

Causal LTI system with rational  $H(s)$ : all poles lies inside the unit circle + 分子 z 阶数不能比分母大

**和差化积公式与积化和差公式**

$$\begin{aligned}\sin \alpha + \sin \beta &= 2 \sin \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2} \\ \sin \alpha - \sin \beta &= 2 \cos \frac{\alpha + \beta}{2} \sin \frac{\alpha - \beta}{2} \\ \cos \alpha + \cos \beta &= 2 \cos \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2} \\ \cos \alpha - \cos \beta &= -2 \sin \frac{\alpha + \beta}{2} \sin \frac{\alpha - \beta}{2} \\ \sin \alpha \cos \beta &= \frac{1}{2} [\sin(\alpha + \beta) + \sin(\alpha - \beta)] \\ \cos \alpha \sin \beta &= \frac{1}{2} [\sin(\alpha + \beta) - \sin(\alpha - \beta)] \\ \cos \alpha \cos \beta &= \frac{1}{2} [\cos(\alpha + \beta) + \cos(\alpha - \beta)] \\ \sin \alpha \sin \beta &= -\frac{1}{2} [\cos(\alpha + \beta) - \cos(\alpha - \beta)]\end{aligned}$$

**Hilbert Transform**

$$\frac{1}{\pi t} \xleftrightarrow{\mathcal{F}} -j \cdot \text{sign } \omega, \cos \omega_0 t \xrightarrow{\mathcal{H}} \sin \omega_0 t$$

**Convolution 卷积**

$$y[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k] = \sum_{k=-\infty}^{\infty} x[n-k]h[k]$$

$$y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau = \int_{-\infty}^{\infty} x(t-\tau)h(\tau)d\tau$$

一个函数的 $t$ 换成 $\tau$ , 另一个函数的 $t$ 换成 $t-\tau$ ; 如果结果以原点为界, 记得写成 $u[n]u(t)$ 的形式;  $x(\tau)$ 的图像正常,  $h(t-\tau)$ 的图像关于 $y$ 轴翻转后, 原点为 $t$

**Sinc Function**

$$\text{sinc } \theta = \frac{\sin \pi \theta}{\pi \theta}$$

**2N-Point DFT using a single N-Point DFT**

$$v[n] \text{ 长 } 2N, g[n] = v[2n], h[n] = v[2n+1]$$

$$\text{则 } V[k] = G[k]_N + W_N^k H[k]_N$$

**Nyquist Sampling Theorem**

Let  $x(t)$  be a band-limited signal within  $\pm \omega_M$ , then  $x(t)$  is uniquely determined by its samples  $x(nT)$  if  $\omega_s > 2\omega_M$ , where  $\omega_s = \frac{2\pi}{T}$ .  
Nyquist rate:  $2\omega_M$

**Euler's formula 欧拉公式**

$$e^{j\theta} = \cos \theta + j \sin \theta$$

$$\cos \theta = \frac{e^{j\theta} + e^{-j\theta}}{2}$$

$$\sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2j}$$

**Z 变换特殊峰的判断**

信号为正, 零点有峰  
信号为负, 无穷有峰

**诱导公式**

$$\begin{aligned}\sin(2k\pi + \alpha) &= \sin \alpha \\ \cos(2k\pi + \alpha) &= \cos \alpha \\ \sin(-\alpha) &= -\sin \alpha \\ \cos(-\alpha) &= \cos \alpha \\ \sin(\pi - \alpha) &= \sin \alpha \\ \cos(\pi - \alpha) &= -\cos \alpha \\ \sin(\pi + \alpha) &= -\sin \alpha \\ \cos(\pi + \alpha) &= -\cos \alpha \\ \sin\left(\frac{\pi}{2} - \alpha\right) &= \cos \alpha \\ \cos\left(\frac{\pi}{2} - \alpha\right) &= \sin \alpha \\ \sin\left(\frac{\pi}{2} + \alpha\right) &= \cos \alpha \\ \cos\left(\frac{\pi}{2} + \alpha\right) &= -\sin \alpha \\ \text{tg}(k\pi + \alpha) &= \text{tg } \alpha \\ \text{tg}(-\alpha) &= -\text{tg } \alpha \\ \text{tg}(\pi - \alpha) &= -\text{tg } \alpha \\ \text{tg}(\pi + \alpha) &= \text{tg } \alpha \\ \text{tg}\left(\frac{\pi}{2} - \alpha\right) &= \text{ctg } \alpha \\ \text{tg}\left(\frac{\pi}{2} + \alpha\right) &= -\text{ctg } \alpha\end{aligned}$$

**Group Delay, Phase Delay**

$$\text{Phase delay: } \tau_p(\omega_0) = -\frac{\theta(\omega_0)}{\omega_0}$$

$$\text{Group delay: } \tau_g(\omega) = -\frac{d\theta(\omega)}{d\omega}$$

$$y_a(t) = a \left( t - \tau_g(\Omega_c) \right) \cos \Omega_c \left( t - \tau_p(\Omega_c) \right)$$

**系统性质的判据**

Memoryless

输入输出关系

Output at  $t = t_0$  depends only on the value of input at  $t = t_0$

单位冲激响应

$$h(t) = 0 \text{ for } t \neq 0$$

Invertible

There exist an inverse system

$$\exists h_1[n] \text{ s.t. } h[n] * h_1[n] = \delta[n]$$

Causality

Output at this time only depends on values of the input at the present time and in the past

$$h[n] = 0 \text{ for } n < 0$$

Stability

BIBO

$$\int_{-\infty}^{\infty} |h(\tau)| d\tau < \infty$$

Time-invariance

Let  $x_1(t) = x(t - t_0)$   
Check  $y_1(t) = ? y(t - t_0)$

Must satisfy

Linearity

Let  $x_1(t), x_2(t), x_3(t) = x_1(t) + x_2(t)$   
Check  $y_3(t) = ? ay_1(t) + by_2(t)$

Must satisfy

**Time-Domain Sampling 时域采样**

$$x_a(t) \xleftrightarrow{CTFT} X_a(j\Omega), x(t) = x_a(t)p(t) \xleftrightarrow{CTFT} X(j\Omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_a(j(\Omega - k\Omega_s))$$

$$x[n] = x(t)|_{t=nT} \xleftrightarrow{\mathcal{F}} X(e^{j\omega}) = X(j\Omega)|_{\Omega=\frac{\omega}{T}} = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_a(j(\frac{\omega}{T} - k\frac{\omega_s}{T}))$$

采样后信号的频率响应幅值变为 $1/T$ 倍, 因此恢复信号时要通过一个增益为 $T$ 的BPF, BPF的截止频率最好为 $\frac{\omega_s}{2}$ ;  $\Omega$ 轴上的 $\Omega_s$ 对应 $\omega$ 轴上的 $2\pi$

连续离散公式: 时域 $t = nT$ , 频域 $\omega = \Omega T$ , 任何地方 $f = 1/T$

时域采样导致频域周期化:  $F_{out} = F_{in} \pm kF_s, \Omega_{out} = \Omega_{in} \pm k\Omega_s$

**信号的分解**

奇偶分解	$x_{ev}(t) = \frac{1}{2}(x(t) + x(-t))$ $x_{od}(t) = \frac{1}{2}(x(t) - x(-t))$	$X_{ev}[k] = \frac{1}{2}(X[k] + X[-k]_N)$ $X_{od}[k] = \frac{1}{2}(X[k] - X[-k]_N)$
实虚分解	$x_{re}(t) = \frac{1}{2}(x(t) + x^*(t))$ $x_{im}(t) = \frac{1}{2j}(x(t) - x^*(t))$	$X_{re}[k] = \frac{1}{2}(X[k] + X^*[k])$ $X_{im}[k] = \frac{1}{2}(X[k] - X^*[k])$
共轭对称分解	$x_{cs}(t) = \frac{1}{2}(x(t) + x^*(-t))$ $x_{ca}(t) = \frac{1}{2}(x(t) - x^*(-t))$	$X_{cs}[k] = \frac{1}{2}(X[k] + X^*[-k]_N)$ $X_{ca}[k] = \frac{1}{2}(X[k] - X^*[-k]_N)$

**DFT Matrix Relation**

$$x = D_N^{-1}X, X = D_N x$$

$$D_N = \begin{bmatrix} W_N^0 & W_N^0 & W_N^0 \\ W_N^0 & W_N^1 & W_N^2 \\ W_N^0 & W_N^2 & W_N^4 \end{bmatrix}, D_N^{-1} = \frac{1}{N} \begin{bmatrix} W_N^0 & W_N^0 & W_N^0 \\ W_N^0 & W_N^{-1} & W_N^{-2} \\ W_N^0 & W_N^{-2} & W_N^{-4} \end{bmatrix}, D_4 = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix}$$

**DFT Geometric Symmetry**

Geometric symmetry:  $x[n] = x[N-1-n], \theta(\omega) = -\frac{N-1}{2}\omega + \beta$  (type1 odd, type2 even)

Geometric anti-symmetry:  $x[n] = -x[N-1-n], \theta(\omega) = -\frac{N-1}{2}\omega + \frac{\pi}{2} + \beta$  (type3 odd, type4 even), 中心系数为 0

**圆周卷积线性卷积**

- 补0法: 两序列都补到 $M+N-1$ 长, 算圆周卷积即可
- Overlap-add: 将 $x[n]$ 切段, 每段与 $h[n]$ 用补0法算圆周卷积, 最后相加时要有 $N-1$ 长度的overlap
- Overlap-save: 相加时不重叠, 而是切断时重叠 $N-1$ 长度; 最前面补 $N-1$ 个0, 相加时每段舍去前 $N-1$

**Z-变换对快速检查单**

Signal	Transform	ROC	Pole
$a^n u[n]$	$\frac{1}{1-az^{-1}}$	$ z  >  a $	$a$
$a^n u[-n-1]$	$-\frac{1}{1-az^{-1}}$	$ z  <  a $	$a$
$(-a)^n u[n]$	$\frac{1}{1+az^{-1}}$	$ z  >  a $	$-a$
$(-a)^n u[-n-1]$	$-\frac{1}{1+az^{-1}}$	$ z  <  a $	$-a$
$na^n u[n]$	$\frac{1}{(1-az^{-1})^2}$	$ z  >  a $	$a(\times 2)$

**带通采样**

$$\Omega_H = M(\Delta\Omega) \Rightarrow$$

$$\Omega_T = 2(\Delta\Omega) = \frac{2\Omega_H}{M}$$

恢复使用 gain 为 $T$ 的

$$\Omega_L \leq |\Omega| \leq \Omega_H \text{ 的 BPF}$$

**Geometric Series 等比数列**

$$\text{通项公式: } a_n = a_1 q^{n-1}$$

$$\text{两项关系: } a_n = a_m q^{n-m}$$

$$\text{求和公式: } S_n = a_1 \frac{a-q^n}{1-q} = \frac{a_1-a_n q}{1-q}$$

**Fourier-Domain Sampling 频域采样**

频域采 $N$ 个样 (不关心 $x[n]$ 周期是不是 $N$ ), 时域信号就以 $N$ 为周期

$$y[n] = \sum_{m=-\infty}^{\infty} x[n+mN], 0 \leq n \leq N-1$$

多画几个周期找规律!

**信号的范数、能量、功率**

$$\|x\|_p = (\sum_{n=-\infty}^{\infty} |x[n]|^p)^{\frac{1}{p}}, \|x\|_{\infty} = |x|_{\max}$$

$$\|X\|_p = \left( \frac{1}{2\pi} \int_{-\pi}^{\pi} |X(e^{j\omega})|^p d\omega \right)^{\frac{1}{p}}, \|X\|_{\infty} = \max |X(e^{j\omega})|$$

$$MSE = \frac{1}{N} \sum_{i=0}^{N-1} (|y[n] - x[n]|)^2 = \frac{1}{N} (\|y[n] - x[n]\|_2)^2$$

Total energy:  $\epsilon_x = \sum_{n=-\infty}^{\infty} |x[n]|^2$  (Energy signal: finite energy)

Average power:  $P_x = \lim_{K \rightarrow \infty} \frac{1}{2K+1} \sum_{k=-K}^K |x[k]|^2$  (Power signal: finite power)

Passive system:  $\epsilon_y \leq \epsilon_x < \infty$ , lossless system:  $\epsilon_y = \epsilon_x < \infty$

**离散三角信号的周期性**

$$\omega N = 2k\pi \Rightarrow N = \frac{2k\pi}{\omega}$$

**离散三角信号的周期性小结**

- 周期 $N$ 必须是整数
- 角频率相差 $2k\pi$ 的信号完全相同
- 任何数列的最大频率为 $\pi$  (folding frequency), 且对称频率 ( $0.6\pi$ 和 $1.4\pi$ ) 信号相同

**Circular Time-Shift/Reversal**

原: 0 1 2 3 4

移: 3 4 0 1 2

反: 0 4 3 2 1

变换

CTFT	DTFT	DFT	Z-transform
时域连续非周期 频域连续非周期	时域离散非周期 频域连续周期	时域离散周期 频域离散周期	
$X_a(j\Omega) = \int_{-\infty}^{\infty} x_a(t)e^{-j\Omega t} dt$ $x_a(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X_a(j\Omega)e^{j\Omega t} d\Omega$	$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n}$ $x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega})e^{j\omega n} d\omega$	$X[k] = \sum_{n=0}^{N-1} x[n]W_N^{kn}$ $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k]W_N^{-kn}$	$G(z) = \sum_{n=-\infty}^{\infty} g[n]z^{-n}$ $g[n] = \frac{1}{2\pi j} \oint_C G(z)z^{n-1} dz$
$\int_{-\infty}^{\infty}  x_a(t) ^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty}  X_a(j\Omega) ^2 d\Omega$	$\sum_{n=-\infty}^{\infty}  x[n] ^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi}  X(e^{j\omega}) ^2 d\omega$	$\sum_{n=0}^{N-1}  x[n] ^2 = \frac{1}{N} \sum_{k=0}^{N-1}  X[k] ^2$	
	$x[-n] \leftrightarrow X(e^{-j\omega})$ $x^*[-n] \leftrightarrow X^*(e^{j\omega})$ $x^*[n] \leftrightarrow X^*(e^{-j\omega})$	$x[\langle -n \rangle_N] \leftrightarrow X[\langle -k \rangle_N]$ $x[\langle -n \rangle_N] \leftrightarrow X^*[k]$ $x^*[n] \leftrightarrow X^*[\langle -k \rangle_N]$	$x[-n] \leftrightarrow X(z^{-1}) \text{ with inverted } R$

Property	Signal	DTFT	DFT	Z-Transform	ROC
Linearity	$ax[n] + by[n]$	$aX(e^{j\omega}) + bY(e^{j\omega})$	$aX[k] + bY[k]$	$aX(z) + bY(z)$	At least $R_1 \cap R_2$
Time Shifting	$x[n - n_0]$	$e^{-j\omega n_0} X(e^{j\omega})$	$W_N^{n_0} X[k]$	$z^{-n_0} X(z)$	$R$ except for possible origin
Frequency Shifting (Z-Domain Scaling)	$e^{j\omega_0 n} x[n]$	$X(e^{j(\omega - \omega_0)})$	$X[\langle k - k_0 \rangle_N]$	$X(e^{-j\omega_0} z)$	$R$
Time Expansion	$x_{(k)}[n] = x[\frac{n}{k}]$ if $n = mk$ else 0	$X(e^{jk\omega})$		$X(z^k)$	$\frac{1}{k} R^{\frac{1}{k}}$
Convolution	$x[n] * y[n]$	$X(e^{j\omega})Y(e^{j\omega})$	$X[k]Y[k]$	$X(z)Y(z)$	At least $R_1 \cap R_2$
Multiplication	$x[n]y[n]$	$\frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\theta})Y(e^{j(\omega - \theta)}) d\theta$	$\frac{1}{N} \sum_{m=0}^{N-1} X[m]Y[\langle k - m \rangle_N]$	$\frac{1}{2\pi j} \oint_C X(v)H(\frac{z}{v})v^{-1} dv$	At least $R_1 R_2$
Differencing in Time	$x[n] - x[n - 1]$	$(1 - e^{-j\omega})X(e^{j\omega})$		$(1 - z^{-1})X(z)$	At least $R \cap \{ z  > 0\}$
Accumulation	$\sum_{k=-\infty}^n x[k]$	$\frac{1}{1 - e^{-j\omega}} X(e^{j\omega})$		$\frac{1}{1 - z^{-1}} X(z)$	At least $R \cap \{ z  > 1\}$
Differentiation in Frequency	$nx[n]$	$j \frac{dX(e^{j\omega})}{d\omega}$		$-z \frac{dX(z)}{dz}$	$R$

DTFT Transform Pairs

Signal	Transform
$\delta[n]$	1
$\mu[n]$	$\frac{1}{1 - e^{-j\omega}} + \sum_{k=-\infty}^{\infty} \pi \delta(\omega + 2\pi k)$
1	$\sum_{k=-\infty}^{\infty} 2\pi \delta(\omega + 2\pi k)$
$e^{j\omega_0 n}$	$\sum_{k=-\infty}^{\infty} 2\pi \delta(\omega - \omega_0 + 2\pi k)$
$\alpha^n \mu[n], ( \alpha  < 1)$	$\frac{1}{1 - \alpha e^{-j\omega}}$
$(n + 1)\alpha^n \mu[n], ( \alpha  < 1)$	$\frac{1}{(1 - \alpha e^{-j\omega})^2}$
$h_{LP}[n] = \frac{\sin \omega_c n}{\pi n}$	$H_{LP}(e^{j\omega}) = \begin{cases} 1, & 0 \leq  \omega  \leq \omega_c \\ 0, & \omega_c <  \omega  \leq \pi \end{cases}$
$\cos \omega_0 n$	$\pi \sum_{l=-\infty}^{\infty} \{\delta(\omega - \omega_0 - 2\pi l) + \delta(\omega + \omega_0 - 2\pi l)\}$
$\sin \omega_0 n$	$\frac{\pi}{j} \sum_{l=-\infty}^{\infty} \{\delta(\omega - \omega_0 - 2\pi l) - \delta(\omega + \omega_0 - 2\pi l)\}$

Z-Transform Pairs

Signal	Transform	ROC
$\delta[n]$	1	All $z$
$u[n]$	$\frac{1}{1 - z^{-1}}$	$ z  > 1$
$-u[-n - 1]$	$\frac{1}{1 - z^{-1}}$	$ z  < 1$
$\delta[n - m]$	$z^{-m}$	All $z$ , except 0 or $\infty$
$a^n u[n]$	$\frac{1}{1 - az^{-1}}$	$ z  >  a $
$-a^n u[-n - 1]$	$\frac{1}{1 - az^{-1}}$	$ z  <  a $
$na^n u[n]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z  >  a $
$-na^n u[-n - 1]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z  <  a $
$[\cos \omega_0 n]u[n]$	$\frac{1 - [\cos \omega_0]z^{-1}}{1 - [2 \cos \omega_0]z^{-1} + z^{-2}}$	$ z  > 1$
$[\sin \omega_0 n]u[n]$	$\frac{[\sin \omega_0]z^{-1}}{1 - [2 \cos \omega_0]z^{-1} + z^{-2}}$	$ z  > 1$
$[r^n \cos \omega_0 n]u[n]$	$\frac{1 - [r \cos \omega_0]z^{-1}}{1 - [2r \cos \omega_0]z^{-1} + r^2 z^{-2}}$	$ z  > r$
$[r^n \sin \omega_0 n]u[n]$	$\frac{[r \sin \omega_0]z^{-1}}{1 - [2r \cos \omega_0]z^{-1} + r^2 z^{-2}}$	$ z  > r$

P-Series Test

$\sum_{n=1}^{\infty} \frac{1}{n^p}$  converges for  $p \geq 1$

Initial Value Theorem

If  $x[n] = 0$  for  $n < 0$ ,  $x[0] = \lim_{z \rightarrow \infty} X(z)$ .

DFT 关键公式

$$\frac{1}{N} \sum_{n=0}^N e^{j\frac{2\pi}{N}(k-l)n} = \begin{cases} 1, & k = l + rn \\ 0, & k \neq l \end{cases}$$

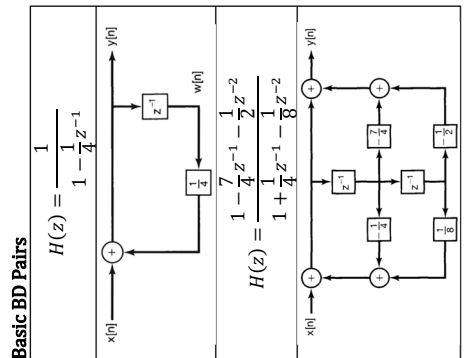
$$W_N = e^{-j\frac{2\pi}{N}}, \quad \cos \left[ \frac{2\pi}{N} rn \right] = \frac{1}{2} (W_N^{rn} + W_N^{-rn})$$

$$\frac{1}{1 - \alpha e^{-j\omega}} = \frac{1}{1 - \alpha \cos \omega - j\alpha \sin \omega} \cdot \frac{1 - \alpha e^{j\omega}}{1 - \alpha e^{j\omega}}$$

$$= \frac{1}{1 - 2\alpha \cos \omega + \alpha^2} \propto \arctan \left( -\frac{\alpha \sin \omega}{1 - \alpha \cos \omega} \right)$$

DFT Transform Pairs

Signal	Transform
$\delta[n]$	1
$\delta[n - m]$	$W_N^{km}$
$\cos \left( \frac{2\pi}{N} rn \right)$	$\begin{cases} N/2, & k = r \text{ or } N - r \\ 0, & \text{otherwise} \end{cases}$



**System Properties (Z-Transform)**

Causality	ROC is the exterior of a circle including infinity
Causality (Rational $H(s)$ )	ROC is the exterior of a circle outside the outermost pole + 分子 z 阶数不能比分母大
Stability	ROC includes the unit circle

Causal LTI system with rational  $H(s)$ : all poles lies inside the unit circle + 分子 z 阶数不能比分母大

**和差化积公式与积化和差公式**

$$\begin{aligned}\sin \alpha + \sin \beta &= 2 \sin \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2} \\ \sin \alpha - \sin \beta &= 2 \cos \frac{\alpha + \beta}{2} \sin \frac{\alpha - \beta}{2} \\ \cos \alpha + \cos \beta &= 2 \cos \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2} \\ \cos \alpha - \cos \beta &= -2 \sin \frac{\alpha + \beta}{2} \sin \frac{\alpha - \beta}{2} \\ \sin \alpha \cos \beta &= \frac{1}{2} [\sin(\alpha + \beta) + \sin(\alpha - \beta)] \\ \cos \alpha \sin \beta &= \frac{1}{2} [\sin(\alpha + \beta) - \sin(\alpha - \beta)] \\ \cos \alpha \cos \beta &= \frac{1}{2} [\cos(\alpha + \beta) + \cos(\alpha - \beta)] \\ \sin \alpha \sin \beta &= -\frac{1}{2} [\cos(\alpha + \beta) - \cos(\alpha - \beta)]\end{aligned}$$

**Hilbert Transform**

$$\frac{1}{\pi t} \xleftrightarrow{F} -j \cdot \text{sign } \omega, \cos \omega_0 t \xrightarrow{H} \sin \omega_0 t$$

**Convolution 卷积**

$$y[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k] = \sum_{k=-\infty}^{\infty} x[n-k]h[k]$$

$$y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau = \int_{-\infty}^{\infty} x(t-\tau)h(\tau)d\tau$$

一个函数的 $t$ 换成 $\tau$ , 另一个函数的 $t$ 换成 $t-\tau$ ; 如果结果以原点为界, 记得写成 $u[n]u(\tau)$ 的形式;  $x(\tau)$ 的图像正常,  $h(t-\tau)$ 的图像关于 $y$ 轴翻转后, 原点为 $t$

**Sinc Function**

$$\text{sinc } \theta = \frac{\sin \pi \theta}{\pi \theta}$$

**2N-Point DFT using a single N-Point DFT**

$$v[n] \text{ 长 } 2N, g[n] = v[2n], h[n] = v[2n+1]$$

$$\text{则 } V[k] = G[k]_N + W_N^k H[k]_N$$

**Nyquist Sampling Theorem**

Let  $x(t)$  be a band-limited signal within  $\pm \omega_M$ , then  $x(t)$  is uniquely determined by its samples  $x(nT)$  if  $\omega_s > 2\omega_M$ , where  $\omega_s = \frac{2\pi}{T}$ .  
Nyquist rate:  $2\omega_M$

**Euler's formula 欧拉公式**

$$e^{j\theta} = \cos \theta + j \sin \theta$$

$$\cos \theta = \frac{e^{j\theta} + e^{-j\theta}}{2}$$

$$\sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2j}$$

**Z 变换特殊峰的判断**

信号为正, 零点有峰  
信号为负, 无穷有峰

**诱导公式**

$$\begin{aligned}\sin(2k\pi + \alpha) &= \sin \alpha \\ \cos(2k\pi + \alpha) &= \cos \alpha \\ \sin(-\alpha) &= -\sin \alpha \\ \cos(-\alpha) &= \cos \alpha \\ \sin(\pi - \alpha) &= \sin \alpha \\ \cos(\pi - \alpha) &= -\cos \alpha \\ \sin(\pi + \alpha) &= -\sin \alpha \\ \cos(\pi + \alpha) &= -\cos \alpha \\ \sin\left(\frac{\pi}{2} - \alpha\right) &= \cos \alpha \\ \cos\left(\frac{\pi}{2} - \alpha\right) &= \sin \alpha \\ \sin\left(\frac{\pi}{2} + \alpha\right) &= \cos \alpha \\ \cos\left(\frac{\pi}{2} + \alpha\right) &= -\sin \alpha \\ \text{tg}(k\pi + \alpha) &= \text{tg } \alpha \\ \text{tg}(-\alpha) &= -\text{tg } \alpha \\ \text{tg}(\pi - \alpha) &= -\text{tg } \alpha \\ \text{tg}(\pi + \alpha) &= \text{tg } \alpha \\ \text{tg}\left(\frac{\pi}{2} - \alpha\right) &= \text{ctg } \alpha \\ \text{tg}\left(\frac{\pi}{2} + \alpha\right) &= -\text{ctg } \alpha\end{aligned}$$

**Group Delay, Phase Delay**

$$\text{Phase delay: } \tau_p(\omega_0) = -\frac{\theta(\omega_0)}{\omega_0}$$

$$\text{Group delay: } \tau_g(\omega) = -\frac{d\theta(\omega)}{d\omega}$$

$$y_a(t) = a \left( t - \tau_g(\Omega_c) \right) \cos \Omega_c \left( t - \tau_p(\Omega_c) \right)$$

**系统性质的判据**

输入输出关系

单位冲激响应

Memoryless

Output at  $t = t_0$  depends only on the value of input at  $t = t_0$

$h(t) = 0$  for  $t \neq 0$

Invertible

There exist an inverse system

$\exists h_1[n] \text{ s.t. } h[n] * h_1[n] = \delta[n]$

Causality

Output at this time only depends on values of the input at the present time and in the past

$h[n] = 0$  for  $n < 0$

Stability

BIBO

$\int_{-\infty}^{\infty} |h(\tau)| d\tau < \infty$

Time-invariance

Let  $x_1(t) = x(t - t_0)$

Check  $y_1(t) = ? y(t - t_0)$

Must satisfy

Linearity

Let  $x_1(t), x_2(t), x_3(t) = x_1(t) + x_2(t)$

Check  $y_3(t) = ? ay_1(t) + by_2(t)$

Must satisfy

**Time-Domain Sampling 时域采样**

$$x_a(t) \xleftrightarrow{CTFT} X_a(j\Omega), x(t) = x_a(t)p(t) \xleftrightarrow{CTFT} X(j\Omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_a(j(\Omega - k\Omega_s))$$

$$x[n] = x(t)|_{t=nT} \xleftrightarrow{F} X(e^{j\omega}) = X(j\Omega)|_{\Omega=\frac{\omega}{T}} = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_a(j(\frac{\omega}{T} - k\frac{\omega_s}{T}))$$

采样后信号的频率响应幅值变为 $1/T$ 倍, 因此恢复信号时要通过一个增益为 $T$ 的BPF, BPF的截止频率最好为 $\frac{\omega_s}{2}$ ;  $\Omega$ 轴上的 $\Omega_s$ 对应 $\omega$ 轴上的 $2\pi$

连续离散公式: 时域 $t = nT$ , 频域 $\omega = \Omega T$ , 任何地方 $f = 1/T$

时域采样导致频域周期化:  $F_{out} = F_{in} \pm kF_s, \Omega_{out} = \Omega_{in} \pm k\Omega_s$

**信号的分解**

奇偶分解	$x_{ev}(t) = \frac{1}{2}(x(t) + x(-t))$ $x_{od}(t) = \frac{1}{2}(x(t) - x(-t))$	$X_{ev}[k] = \frac{1}{2}(X[k] + X[-k]_N)$ $X_{od}[k] = \frac{1}{2}(X[k] - X[-k]_N)$
实虚分解	$x_{re}(t) = \frac{1}{2}(x(t) + x^*(t))$ $x_{im}(t) = \frac{1}{2j}(x(t) - x^*(t))$	$X_{re}[k] = \frac{1}{2}(X[k] + X^*[k])$ $X_{im}[k] = \frac{1}{2}(X[k] - X^*[k])$
共轭对称分解	$x_{cs}(t) = \frac{1}{2}(x(t) + x^*(-t))$ $x_{ca}(t) = \frac{1}{2}(x(t) - x^*(-t))$	$X_{cs}[k] = \frac{1}{2}(X[k] + X^*[-k]_N)$ $X_{ca}[k] = \frac{1}{2}(X[k] - X^*[-k]_N)$

**DFT Matrix Relation**

$$x = D_N^{-1}X, X = D_N x$$

$$D_N = \begin{bmatrix} W_N^0 & W_N^0 & W_N^0 \\ W_N^0 & W_N^1 & W_N^2 \\ W_N^0 & W_N^2 & W_N^4 \end{bmatrix}, D_N^{-1} = \frac{1}{N} \begin{bmatrix} W_N^0 & W_N^0 & W_N^0 \\ W_N^0 & W_N^{-1} & W_N^{-2} \\ W_N^0 & W_N^{-2} & W_N^{-4} \end{bmatrix}, D_4 = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix}$$

**DFT Geometric Symmetry**

Geometric symmetry:  $x[n] = x[N-1-n], \theta(\omega) = -\frac{N-1}{2}\omega + \beta$  (type1 odd, type2 even)

Geometric anti-symmetry:  $x[n] = -x[N-1-n], \theta(\omega) = -\frac{N-1}{2}\omega + \frac{\pi}{2} + \beta$  (type3 odd, type4 even), 中心系数为 0

**Order**

$$\omega_c = \frac{\omega_s + \omega_p}{2}$$

$$\Delta\omega = 2\pi \frac{\Delta f}{FT} \Rightarrow M$$

$$\Rightarrow N = 2M + 1$$

$$hLP[n] = \frac{\sin[\omega(n-M)]}{\pi(n-M)} \cdot w[n-M]$$

$$hHP[n] = \begin{cases} 1 - \frac{\omega_c}{\omega_p} & n = 0 \\ -\frac{\sin(\omega_c n)}{\sin(\omega_p n)} & |n| > 0 \end{cases}$$

$$hBP[n] = \frac{\sin(\omega_c n) - \sin(\omega_p n)}{\pi n}, |n| \geq 0$$

$$hBS[n] = \begin{cases} 1 - \frac{\omega_c 2 - \omega_c 1}{\omega_p} & n = 0 \\ \frac{\sin(\omega_c 2 n) - \sin(\omega_c 1 n)}{\pi n} & |n| \geq 0 \end{cases}$$

$$wR[n] = \begin{cases} 1 & -M \leq n \leq M \\ 0 & |n| > M \end{cases}$$

$$wHann[n] = \frac{1}{2} \left[ 1 + \cos\left(\frac{2\pi n}{2M+1}\right) \right]$$

$$wHamming[n] = \left[ 0.54 + 0.46 \cos\left(\frac{2\pi n}{2M+1}\right) \right]$$

$$wBlackman[n] = \left[ 0.42 + 0.5 \cos\left(\frac{2\pi n}{2M+1}\right) + 0.08 \cos\left(\frac{4\pi n}{2M+1}\right) \right]$$

**信号的范数、能量、功率**

$$\|x\|_p = (\sum_{n=-\infty}^{\infty} |x[n]|^p)^{\frac{1}{p}}, \|x\|_{\infty} = |x|_{\max}$$

$$\|X\|_p = \left( \frac{1}{2\pi} \int_{-\pi}^{\pi} |X(e^{j\omega})|^p d\omega \right)^{\frac{1}{p}}, \|X\|_{\infty} = \max |X(e^{j\omega})|$$

$$MSE = \frac{1}{N} \sum_{i=0}^{N-1} (|y[n] - x[n]|^2) = \frac{1}{N} (\|y[n] - x[n]\|_2^2)$$

Total energy:  $\epsilon_x = \sum_{n=-\infty}^{\infty} |x[n]|^2$  (Energy signal: finite energy)

Average power:  $P_x = \lim_{K \rightarrow \infty} \frac{1}{2K+1} \sum_{k=-K}^K |x[k]|^2$  (Power signal: finite power)

Passive system:  $\epsilon_y \leq \epsilon_x < \infty$ , lossless system:  $\epsilon_y = \epsilon_x < \infty$

**离散三角信号的周期性**

$$\omega N = 2k\pi \Rightarrow N = \frac{2k\pi}{\omega}$$

**离散三角信号的周期性小结**

1. 周期 $N$ 必须是整数
2. 角频率相差 $2k\pi$ 的信号完全相同
3. 任何数列的最大频率为 $\pi$  (folding frequency), 且对称频率 ( $0.6\pi$ 和 $1.4\pi$ ) 信号相同

**圆周卷积线性卷积**

1. 补0法: 两序列都补到 $M+N-1$ 长, 算圆周卷积即可
2. Overlap-add: 将 $x[n]$ 切段, 每段与 $h[n]$ 用补0法算圆周卷积, 最后相加时要有 $N-1$ 长度的overlap
3. Overlap-save: 相加时不重叠, 而是切断时重叠 $N-1$ 长度; 最前面补 $N-1$ 个0, 相加时每段舍去前 $N-1$

**Z-变换对快速检查单**

Signal	Transform	ROC	Pole
$a^n u[n]$	$\frac{1}{1-az^{-1}}$	$ z  >  a $	$a$
$a^n u[-n-1]$	$-\frac{1}{1-az^{-1}}$	$ z  <  a $	$a$
$(-a)^n u[n]$	$\frac{1}{1+az^{-1}}$	$ z  >  a $	$-a$
$(-a)^n u[-n-1]$	$-\frac{1}{1+az^{-1}}$	$ z  <  a $	$-a$
$na^n u[n]$	$\frac{1}{(1-az^{-1})^2}$	$ z  >  a $	$a(\times 2)$

**Fourier-Domain Sampling 频域采样**

频域采 $N$ 个样 (不关心 $x[n]$ 周期是不是 $N$ ), 时域信号就以 $N$ 为周期

$$y[n] = \sum_{m=-\infty}^{\infty} x[n+mN], 0 \leq n \leq N-1$$

多画几个周期找规律!

**Circular Time-Shift/Reversal**

原: 0 1 2 3 4

移: 3 4 0 1 2

反: 0 4 3 2 1

## 变换

CTFT	DTFT	DFT	Z-transform
时域连续非周期 频域连续非周期	时域离散非周期 频域连续周期	时域离散周期 频域离散周期	
$X_a(j\omega) = \int_{-\infty}^{\infty} x_a(t)e^{-j\omega t} dt$ $x_a(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X_a(j\omega)e^{j\omega t} d\omega$	$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n}$ $x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega})e^{j\omega n} d\omega$	$X[k] = \sum_{n=0}^{N-1} x[n]W_N^{kn}$ $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k]W_N^{-kn}$	$G(z) = \sum_{n=-\infty}^{\infty} g[n]z^{-n}$ $g[n] = \frac{1}{2\pi j} \oint_C G(z)z^{n-1} dz$
$\int_{-\infty}^{\infty}  x_a(t) ^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty}  X_a(j\omega) ^2 d\omega$	$\sum_{n=-\infty}^{\infty}  x[n] ^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi}  X(e^{j\omega}) ^2 d\omega$	$\sum_{n=0}^{N-1}  x[n] ^2 = \frac{1}{N} \sum_{k=0}^{N-1}  X[k] ^2$	
	$x[-n] \leftrightarrow X(e^{-j\omega})$ $x^*[-n] \leftrightarrow X^*(e^{j\omega})$ $x^*[n] \leftrightarrow X^*(e^{-j\omega})$	$x[(-n)_N] \leftrightarrow X[(-k)_N]$ $x[(-n)_N] \leftrightarrow X^*[k]$ $x^*[n] \leftrightarrow X^*[(-k)_N]$	$x[-n] \leftrightarrow X(z^{-1}) \text{ with inverted } R$ <div> <b>Butterworth Filter</b>  <math display="block"> H_a(j\Omega) ^2 = \frac{1}{1 + (\Omega/\Omega_c)^{2N}}</math> </div>

Theorems	Signal	DTFT	DFT	Z-Transform	ROC
Property					
Linearity	$ax[n] + by[n]$	$aX(e^{j\omega}) + bY(e^{j\omega})$	$aX[k] + bY[k]$	$aX(z) + bY(z)$	At least $R_1 \cap R_2$
Time Shifting	$x[n - n_0]$	$e^{-j\omega n_0} X(e^{j\omega})$	$W_N^{n_0} X[k]$	$z^{-n_0} X(z)$	$R$ except for possible origin
Frequency Shifting (Z-Domain Scaling)	$e^{j\omega_0 n} x[n]$	$X(e^{j(\omega - \omega_0)})$	$X[(k - k_0)_N]$	$X(e^{-j\omega_0} z)$	$R$
Time Expansion	$x_{(k)}[n] = x[\frac{n}{k}]$ if $n = mk$ else 0	$X(e^{jk\omega})$		$X(z^k)$	$\frac{1}{R^k}$
Convolution	$x[n] * y[n]$	$X(e^{j\omega})Y(e^{j\omega})$	$X[k]Y[k]$	$X(z)Y(z)$	At least $R_1 \cap R_2$
Multiplication	$x[n]y[n]$	$\frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\theta})Y(e^{j(\omega - \theta)}) d\theta$	$\frac{1}{N} \sum_{m=0}^{N-1} X[m]Y[(k - m)_N]$	$\frac{1}{2\pi j} \oint_C X(v)H(\frac{z}{v})v^{-1} dv$	At least $R_1 R_2$
Differencing in Time	$x[n] - x[n - 1]$	$(1 - e^{-j\omega})X(e^{j\omega})$		$(1 - z^{-1})X(z)$	At least $R \cap \{ z  > 0\}$
Accumulation	$\sum_{k=-\infty}^n x[k]$	$\frac{1}{1 - e^{-j\omega}} X(e^{j\omega})$		$\frac{1}{1 - z^{-1}} X(z)$	At least $R \cap \{ z  > 1\}$
Differentiation in Frequency	$nx[n]$	$j \frac{dX(e^{j\omega})}{d\omega}$		$-z \frac{dX(z)}{dz}$	$R$

## DTFT Transform Pairs

Signal	Transform
$\delta[n]$	1
$\mu[n]$	$\frac{1}{1 - e^{-j\omega}} + \sum_{k=-\infty}^{\infty} \pi \delta(\omega + 2\pi k)$
1	$\sum_{k=-\infty}^{\infty} 2\pi \delta(\omega + 2\pi k)$
$e^{j\omega_0 n}$	$\sum_{k=-\infty}^{\infty} 2\pi \delta(\omega - \omega_0 + 2\pi k)$
$\alpha^n \mu[n], ( \alpha  < 1)$	$\frac{1}{1 - \alpha e^{-j\omega}}$
$(n + 1)\alpha^n \mu[n], ( \alpha  < 1)$	$\frac{1}{(1 - \alpha e^{-j\omega})^2}$
$h_{LP}[n] = \frac{\sin \omega_c n}{\pi n}$	$H_{LP}(e^{j\omega}) = \begin{cases} 1, & 0 \leq  \omega  \leq \omega_c \\ 0, & \omega_c <  \omega  \leq \pi \end{cases}$
$\cos \omega_0 n$	$\pi \sum_{l=-\infty}^{\infty} \{\delta(\omega - \omega_0 - 2\pi l) + \delta(\omega + \omega_0 - 2\pi l)\}$
$\sin \omega_0 n$	$\frac{\pi}{j} \sum_{l=-\infty}^{\infty} \{\delta(\omega - \omega_0 - 2\pi l) - \delta(\omega + \omega_0 - 2\pi l)\}$

## Z-Transform Pairs

Signal	Transform	ROC
$\delta[n]$	1	All $z$
$u[n]$	$\frac{1}{1 - z^{-1}}$	$ z  > 1$
$-u[-n - 1]$	$\frac{1}{1 - z^{-1}}$	$ z  < 1$
$\delta[n - m]$	$z^{-m}$	All $z$ , except 0 or $\infty$
$a^n u[n]$	$\frac{1}{1 - az^{-1}}$	$ z  >  a $
$-a^n u[-n - 1]$	$\frac{1}{1 - az^{-1}}$	$ z  <  a $
$na^n u[n]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z  >  a $
$-na^n u[-n - 1]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z  <  a $
$[\cos \omega_0 n]u[n]$	$\frac{1 - [\cos \omega_0]z^{-1}}{1 - [2 \cos \omega_0]z^{-1} + z^{-2}}$	$ z  > 1$
$[\sin \omega_0 n]u[n]$	$\frac{[\sin \omega_0]z^{-1}}{1 - [2 \cos \omega_0]z^{-1} + z^{-2}}$	$ z  > 1$
$[r^n \cos \omega_0 n]u[n]$	$\frac{1 - [r \cos \omega_0]z^{-1}}{1 - [2r \cos \omega_0]z^{-1} + r^2 z^{-2}}$	$ z  > r$
$[r^n \sin \omega_0 n]u[n]$	$\frac{[r \sin \omega_0]z^{-1}}{1 - [2r \cos \omega_0]z^{-1} + r^2 z^{-2}}$	$ z  > r$

$$\frac{1}{1 - ae^{-j\omega}} = \frac{1}{1 - a \cos \omega - ja \sin \omega} \cdot \frac{1 - ae^{j\omega}}{1 - ae^{j\omega}}$$

$$= \frac{1}{1 - 2a \cos \omega + a^2} \propto \arctan\left(-\frac{a \sin \omega}{1 - a \cos \omega}\right)$$

## DFT Transform Pairs

Signal	Transform
$\delta[n]$	1
$\delta[n - m]$	$W_N^{km}$
$\cos\left(\frac{2\pi}{N} rn\right)$	$\begin{cases} \frac{N}{2}, k = r \text{ or } N - r \\ 0, \text{ otherwise} \end{cases}$
$\sin\left(\frac{2\pi}{N} rn\right)$	$\begin{cases} \frac{N}{2j}, k = r \\ -\frac{N}{2j}, k = N - r \\ 0, \text{ otherwise} \end{cases}$

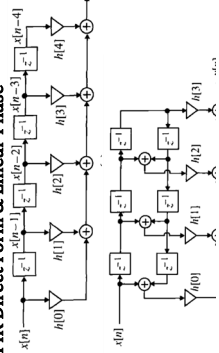
## P-Series Test

$\sum_{n=1}^{\infty} \frac{1}{n^p}$  converges for  $p \geq 1$

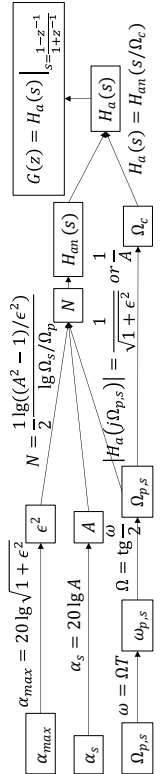
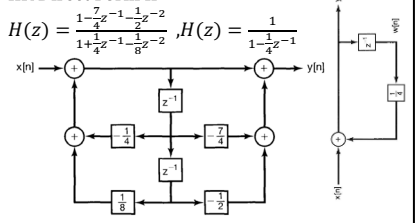
## IIR Filter Design

- ① 对比两个  $\alpha$  选窗
- ②  $\Delta\omega$  算  $M$
- ③  $N = 2M + 1$
- ④  $h[n] = h_{LP}[n - M]w[n - M]$

## FIR Direct Form &amp; Linear Phase



## IIR Direct Form II



DFT 关键公式

$$\frac{1}{N} \sum_{n=0}^{N-1} e^{j\frac{2\pi}{N}(k-l)n} = \begin{cases} 1, & k = l \\ 0, & k \neq l \end{cases}$$

$$W_N = e^{-j\frac{2\pi}{N}}, \quad \cos\left[\frac{2\pi}{N}rn\right] = \frac{1}{2}(W_N^{rn} + W_N^{-rn})$$