#### 딥러닝/클라우드

Chapter 15

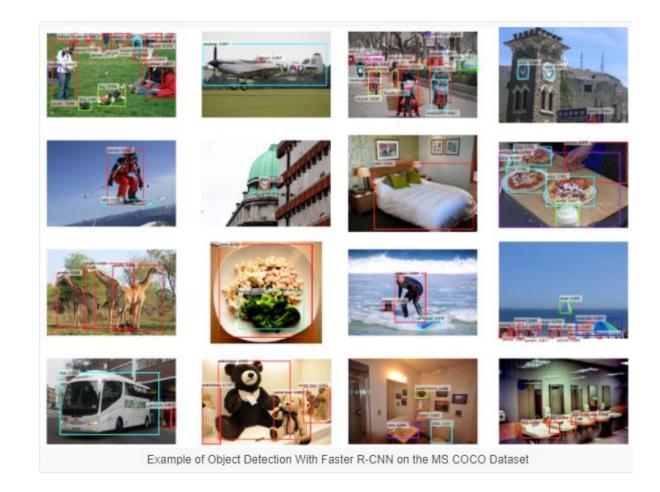
# Object Detection, GAN

오세종

DANKOOK UNIVERSITY

#### **Contents**

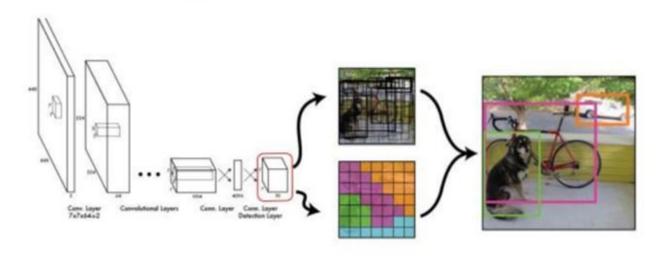
- 1. Object Detection
- 2. GAN
- 3. Applications of GAN



- 학습시 이미지데이터 + object 좌표(xywh) with 레이블 필요
- https://blog.roboflow.com/how-to-train-yolov8-on-a-custom-dataset/
- 3예측결과: object 좌표(xywh) with 레이블

- YOLO model
  - 조셉 레드몬에 의해 2015년 소개
  - o real time object detection 추구
  - 9000 개 이상의 object 탐지

#### YOLO: You Only Look Once



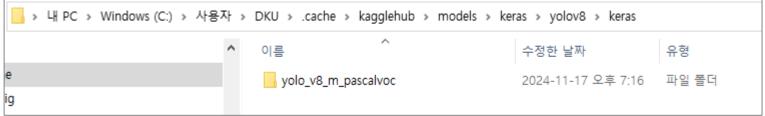
https://www.datascienceprophet.com/object-detection-with-yolo-exploring-the-latest-deep-learning-techniques/

- Example: Keras-cv + YOLO model
  - requirement

```
pip install keras-cv
pip install opencv-python
```

15\_Object dection example.py

```
import os
os.environ["KERAS BACKEND"] = "tensorflow"
import keras
import keras cv
import numpy as np
from keras cv import visualization
import matplotlib.pyplot as plt
# Load a pretrained model
pretrained model = keras cv.models.YOLOV8Detector.from preset(
    "yolo_v8_m_pascalvoc", bounding_box_format="xywh"
```



```
# Load an image from a URL or local path
filepath = "C:/Users/DKU/Downloads/gCNcJJI.jpeg"
image = keras.utils.load_img(filepath)
image = np.array(image)
visualization.plot_image_gallery(
    np.array([image]),
    value_range=(0, 255),
    rows=1,
    cols=1,
    scale=5,
plt.show()
```



```
# resize image
inference resizing = keras cv.layers.Resizing(
    640, 640, pad to aspect ratio=True,
    bounding box format="xywh"
image batch = inference resizing([image])
class ids = [
    "Aeroplane", "Bicycle", "Bird", "Boat", "Bottle",
    "Bus", "Car", "Cat", "Chair", "Cow", "Dining Table",
    "Dog", "Horse", "Motorbike", "Person", "Potted Plant",
    "Sheep", "Sofa", "Train", "Tvmonitor", "Total", ]
class_mapping = dict(zip(range(len(class_ids)), class_ids))
```

```
{0: 'Aeroplane', 1: 'Bicycle', 2: 'Bird', 3: 'Boat', 4: 'Bottle', 5: 'Bus', 6: 'Car', 7: 'Cat', 8: 'Chair', 9: 'Cow',
    10: 'Dining Table', 11: 'Dog', 12: 'Horse', 13: 'Motorbike', 14: 'Person', 15: 'Potted Plant', 16: 'Sheep', 17: 'Sof
    a', 18: 'Train', 19: 'Tvmonitor', 20: 'Total'}
```

>>> class mapping

```
y pred = pretrained model.predict(image batch)
  # y pred is a bounding box Tensor:
  # {"boxes": ..., "confidence": ..., "classes": ...,}
  print(y pred['classes'][0][:4])
  print(y pred['confidence'][0][:4])
  print(y pred['boxes'][0][:4])
>>> v pred
{'boxes': array([[[449.5106 , 142.71707 , 90.91397 , 141.12839 ],
    [374.74982 , 206.06046 , 86.41052 , 94.26883 ],
    [ 59.679283, 229.16298 , 114.07429 , 130.60637 ],
    [238.03307, 223.13684, 95.846085, 102.32648],
    [-1, , -1, , -1, , -1, ],
    Γ -1 -1 -1
    [ -1. , -1. , -1. , -1. ],
[ -1. , -1. , -1. , -1. ]]], dtype=float32), 'confidence': array([[ 0.99133146, 0.975
2819 , 0.9600598 , 0.9280971 , -1. ,
     -1. , -1. , -1. , -1. , -1. ,
```

```
visualization.plot_bounding_box_gallery(
    image_batch,
    value_range=(0, 255),
    rows=1,
    cols=1,
    y_pred=y_pred,
    scale=5,
    font_scale=0.7,
    bounding_box_format="xywh",
    class_mapping=class_mapping,
)
plt.show()
```

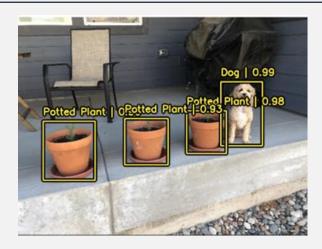


#### [Exercise]

▶ 이미지를 load하면 object detection 결과를 보여주는 앱을 개발한다

#### Object Detection Test

Load image

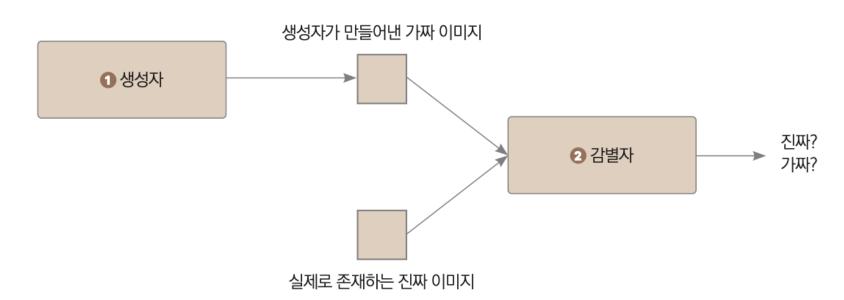


#### Object list

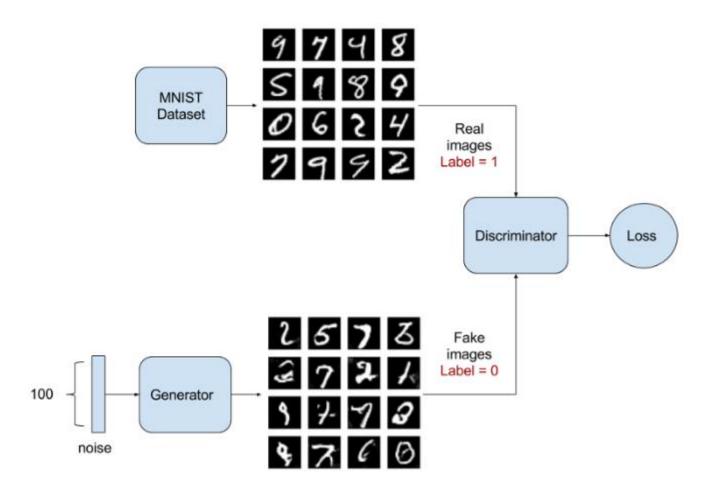
\_\_\_\_\_

- 1. Dog (0.99)
- 2. Potted Plant (0.96)
- 3. Potted Plant (0.95)
- 4. Potted Plant (0.93)

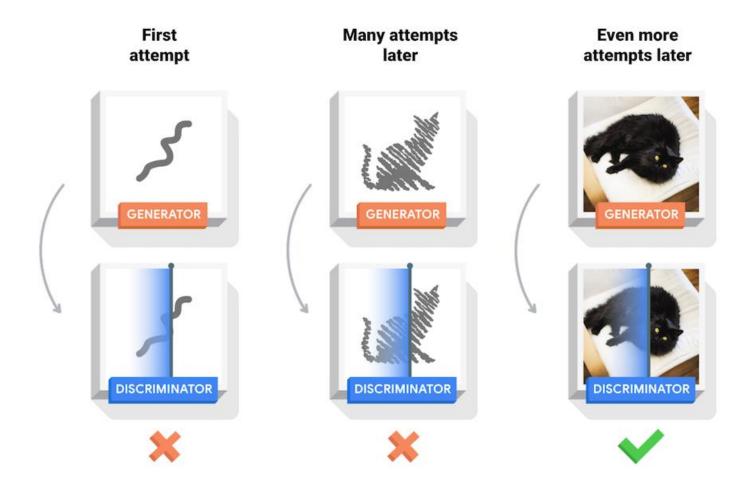
- GAN (Generative Adversarial Networks)
  - 진짜와 너무나도 똑같아서 구별이 가지 않는 가짜 그림이 있다고 하면, 그 그림은 진짜일까, 가짜일까
  - GAN은 이런 생각에서 출발한 모델
  - 1 가짜 이미지를 만들어내도록 학습되는 생성자와 2 가짜와 진짜 이미지를 구별하는 감별자를 경쟁시켜 학습하면, 생성자가 점점 진짜 와 같은 이미지를 만들게 되는 원리



Gan concept



https://towardsdatascience.com/gan-by-example-using-keras-on-tensorflow-backend-1a6d515a60d0



https://www.tensorflow.org/tutorials/generative/dcgan?hl=ko

#### GAN의 장단점

#### ▼ GAN 장단점

#### 장점 단점

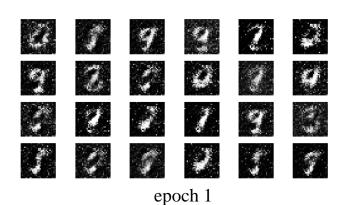
- 일반적인 학습 방법에 비해 자연스러운 이미지를 생성할 수 있습니다.
- 정답과 단순히 비교하는 것이 아니라. 감별자를 이용해 사용하는 특징의 개수에 매우 민감하기 때문에 좋은 성 학습하므로 좋은 성능을 낼 수 있습니다.
- 학습이 올바로 이루어지기 어렵고 필요한 데이터 수가 많아야 합니다.
- 능을 내는 특징의 개수를 정하기 어렵습니다.

#### ▼ GAN 장단점

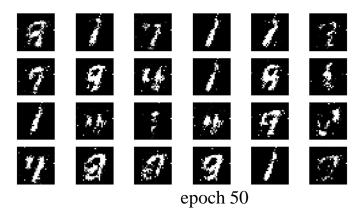
- 이미지 생성, 화질 올리기 등
- 인코더 디코더에서 디코더를 학습할 때 사용하기 좋습니다.

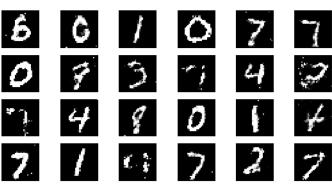
# 

#### Real images

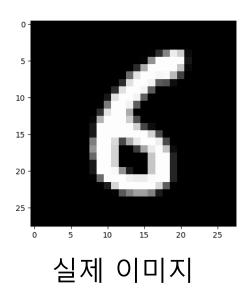


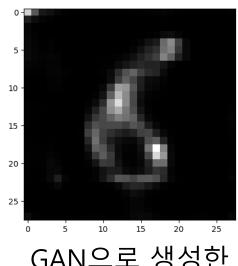
Fake images



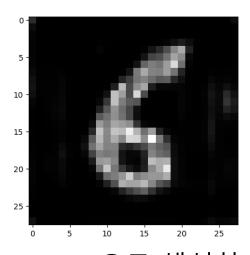


• 존재하지 않는 숫자의 이미지를 생성해 보자





GAN으로 생성한 가짜 이미지 (epoch=300)



GAN으로 생성한 가짜 이미지 (epoch=500)



#### Note

 Keras 3.6 버전에서는 GAN code 실행이 안되니 3.4.1 버전으로 downgrade 할 것

```
pip install keras==3.4.1
pip install tensorflow==2.16.2
```

#### Import modules

15\_keras\_GAN\_example.py

```
import numpy as np
import keras.backend as K
from keras.models import Sequential
from keras.layers import Conv2D, Activation, Dropout, Flatten,
     Dense, BatchNormalization, Reshape, UpSampling2D, LeakyReLU
from keras.optimizers import RMSprop
from keras.preprocessing import image
from keras.preprocessing.image import array_to_img
from skimage import color
import warnings ; warnings.filterwarnings('ignore')
import matplotlib.pyplot as plt
from tqdm import tqdm
                                           # progress bar
```

#### Prepare data

```
K.clear session()
# load data
img = image.load_img('d:/data/6_img.png', target_size=(28,28))
img = color.rgb2gray(img)
img array train = image.img to array(img)
img_array_train = np.expand_dims(img_array_train, axis=0)
Xtrain = img array train
Xtrain = Xtrain / 255
img shape = (img array train.shape[1], img array train.shape[2],
             img_array_train.shape[3]) # row, col, channel
```

```
>>> img_shape (28, 28, 1)
```

● 판별자(discriminator) 만들기

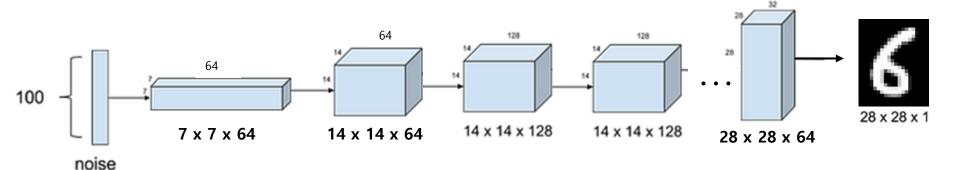
```
discriminator = Sequential()
discriminator.add(Conv2D(64, kernel size=(5, 5),
                        input shape=img shape,
                        strides=2, padding='same',
                        activation=LeakyReLU(alpha=0.2)))
discriminator.add(Dropout(rate=0.4))
discriminator.add(Conv2D(64, kernel_size=(5, 5),
                        strides=2, padding='same',
                        activation=LeakyReLU(alpha=0.2)))
discriminator.add(Dropout(rate=0.4))
discriminator.add(Conv2D(128, kernel size=(5, 5),
                        strides=2, padding='same',
                        activation=LeakyReLU(alpha=0.2)))
discriminator.add(Dropout(rate=0.4))
discriminator.add(Flatten())
discriminator.add(Dense(units=1, activation='sigmoid'))
discriminator.summary()
```

>>> discriminator.summary()
Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 14, 14, 64)	1,664
dropout (Dropout) conv2d_1 (Conv2D)	(None, 14, 14, 64) (None, 7, 7, 64)	0 102,464
dropout_1 (Dropout)	(None, 7, 7, 64)	0
conv2d_2 (Conv2D)	(None, 4, 4, 128)	204,928
dropout_2 (Dropout)	(None, 4, 4, 128)	0
flatten (Flatten)	(None, 2048)	0
dense (Dense)	(None, 1)	2,049

Total params: 311,105 (1.19 MB) Trainable params: 311,105 (1.19 MB) Non-trainable params: 0 (0.00 B)

• 생성자 구조



#### [BatchNormalization]

- 딥러닝 모델에서 학습을 안정화하는 데 사용되는 Keras 레이어
- 그래디언트 소실 문제를 완화, 모델의 가중치 초기화에 덜 민감, 상대적으로 큰 학습률 사용으로 학습 속도가 빨라짐, 정규화를 통해 과적합(overfitting) 문제를 방지

#### ● 생성자 만들기

```
gen dense size=(7, 7, 64)
generator = Sequential()
generator.add(Dense(units=np.prod(gen dense size),
                   input_shape=(100,)))
generator.add(BatchNormalization())
generator.add(Activation('relu'))
generator.add(Reshape(gen dense size))
                             # 이미지 사이즈를 2배로
generator.add(UpSampling2D())
generator.add(Conv2D(filters = 128, kernel size=5,
                    padding='same', strides=1))
generator.add(BatchNormalization(momentum=0.9))
generator.add(Activation('relu'))
```

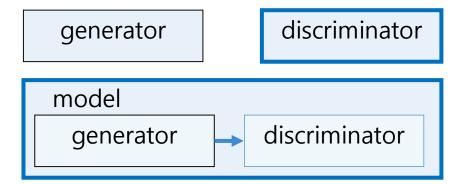
```
generator.add(UpSampling2D())
generator.add(Conv2D(filters = 64, kernel size=5,
                     padding='same', strides=1))
generator.add(BatchNormalization(momentum=0.9))
generator.add(Activation('relu'))
generator.add(Conv2D(filters = 64, kernel size=5,
                     padding='same', strides=1))
generator.add(BatchNormalization(momentum=0.9))
generator.add(Activation('relu'))
generator.add(Conv2D(filters = 1, kernel size=5,
                     padding='same', strides=1))
generator.add(Activation('sigmoid'))
generator.summary()
```

Layer (type)	Output Shape	Param #
dense_1 (Dense)	(None, 3136)	316,736
batch_normalization (BatchNormalization)	(None, 3136)	12,544
activation (Activation)	(None, 3136)	0
reshape (Reshape)	(None, 7, 7, 64)	0
up_sampling2d (UpSampling2D)	(None, 14, 14, 64)	0
conv2d_3 (Conv2D)	(None, 14, 14, 128)	204,928
batch_normalization_1 (BatchNormalization)	(None, 14, 14, 128)	512
activation_1 (Activation) up_sampling2d_1 (UpSampling2D)	(None, 14, 14, 128) (None, 28, 28, 128)	0
conv2d_4 (Conv2D)	(None, 28, 28, 64)	204,864
batch_normalization_2 (BatchNormalization)	(None, 28, 28, 64)	256
activation_2 (Activation)	(None, 28, 28, 64)	0
conv2d_5 (Conv2D)	(None, 28, 28, 64)	102,464
batch_normalization_3 (BatchNormalization)	(None, 28, 28, 64)	256
activation_3 (Activation)	(None, 28, 28, 64)	0
conv2d_6 (Conv2D)	(None, 28, 28, 1)	1,601
activation_4 (Activation)	(None, 28, 28, 1)	0

Total params: 844,161 (3.22 MB) Trainable params: 837,377 (3.19 MB) Non-trainable params: 6,784 (26.50 KB)

#### Model compile

```
discriminator.compile(optimizer=RMSprop(learning_rate=0.0008),
                      loss='binary_crossentropy',
                      metrics=['accuracy'])
model = Sequential()
model.add(generator)
model.add(discriminator)
model.compile(optimizer=RMSprop(learning_rate=0.0004),
              loss='binary_crossentropy',
              metrics=['accuracy'])
```



#### Fitting

```
def train discriminator(x train, batch size):
    valid = np.ones((batch_size, 1))
    fake = np.zeros((batch size, 1))
    idx = np.random.randint(0, len(x_train), batch_size)
    true imgs = x train[idx]
    discriminator.fit(true imgs, valid, verbose=0)
    noise = np.random.normal(0, 1, (batch size, 100))
    gen imgs = generator.predict(noise)
    discriminator.fit(gen_imgs, fake, verbose=0)
def train generator(batch size):
    valid = np.ones((batch size, 1))
    noise = np.random.normal(0, 1, (batch_size, 100))
    model.fit(noise, valid, verbose=1)
```



```
for epoch in tqdm(range(500)): # Try 2000
    train_discriminator(Xtrain, 64)
    train_generator(64)
```

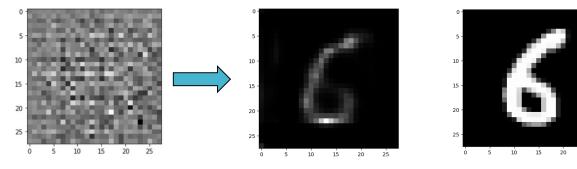
```
2/2 [======= ] - Os 57ms/step
                                                       293/300 [04:09<00:05, 1.19it/s]
2/2 [============ ] - 0s 197ms/step - loss: 1.5356 - accuracy: 0.0625
2/2 [======= ] - Os 56ms/step
                                                       294/300 [04:10<00:04, 1.21it/s]
  [======] - 0s 59ms/step
                                                       295/300 [04:11<00:04, 1.19it/s]
2/2 [========== ] - 1s 293ms/step - loss: 1.9715 - accuracy: 0.0781
                                                       296/300 [04:12<00:03, 1.10it/s]
  [======] - 0s 67ms/step
  [========================] - 0s 190ms/step - loss: 1.7042 - accuracy: 0.3750
                                                       297/300 [04:13<00:02, 1.10it/s]
2/2 [======= ] - 0s 64ms/step
  [=====] - 0s 56ms/step
                                                       298/300 [04:14<00:01, 1.13it/s]
299/300 [04:14<00:00, 1.16it/s]
  100%
                                                       300/300 [04:15<00:00, 1.17it/s]
```

```
for epoch in tqdm(range(300)):
                                         def train_discriminator(x_train, batch_size):
                                             valid = np.ones((batch size, 1))
    train discriminator(Xtrain, 64)
    train generator(64)
                                             fake = np.zeros((batch size, 1))
                                             idx = np.random.randint(0, len(Xtrain), batch size)
                                             true imgs = Xtrain[idx]
  true_image
              vaild (1)
                                             discriminator.fit(true imgs, valid, verbose=0)
                    fit
                                             noise = np.random.normal(0, 1, (batch size, 100))
    discriminator
                                             gen imgs = generator.predict(noise)
                                             discriminator.fit(gen_imgs, fake, verbose=0)
             noise
                          predict
                                         def train generator(batch size):
          generator
                                             valid = np.ones((batch size, 1))
                                             noise = np.random.normal(0, 1, (batch_size, 100))
                                            - model.fit(noise, valid, verbose=1)
          gen image
                        fake (0)
                            fit
              discriminator
                               noise valid (1)
                                                    fit
                                                    model
                                              discriminator
                               generator
                                                              generator 를 훈련
```

#### Test

```
original=array_to_img(Xtrain[0])
plt.imshow(original, cmap='gray')
plt.show()

np.random.seed(123)
random_noise=np.random.normal(0, 1, (1, 100)) # source of fake image
gen_result = generator.predict(random_noise)
gen_img = array_to_img(gen_result[0])
plt.imshow(gen_img, cmap='gray')
plt.show()
```



# [실습]

- 1. 주어진 코드를 이용하여 진짜 이미지와 비슷한 가짜 이미지를 생성해 보자. (진짜 이미지는 각자 선택)
  - 진짜 이미지와 가짜이미지를 보인다
- Note. 주어진 코드는 28x28 이미지 학습에 맞도록 숫자들이 지정되어 있다. 선택한 이미지가 28x28 가 아니어도 코드가 작동하도록 코드를 수정하여 테스트 하시오

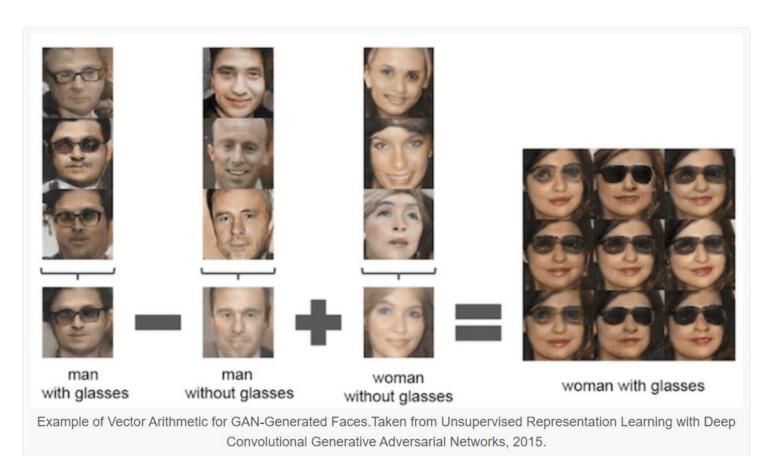
```
# load data
img = image.load_img('d:/data/6_img.png', target_size=(28,28))

여기를 바꾸어도 작동하도록
```

# 3. Applications of GAN

• <a href="https://machinelearningmastery.com/impressive-applications-of-generative-adversarial-networks/">https://machinelearningmastery.com/impressive-applications-of-generative-adversarial-networks/</a>

# 18 Impressive Applications of Generative Adversarial Networks (GANs)



# 3. Applications of GAN

Sketches to Color Photographs



### 3. Applications of GAN

Text to image translation

