## Building a Survival Model in Stan

**Materials:** 

https://github.com/bayesianops/stan-survival-model-workshop

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#### Outline

#### 4 Examples

- 1. Constant Hazard Model (Simple)
- 2. Add Covariates
- 3. Add Censoring
- 4. Hierarchical Model

#### Notes

My (honest) goal: at least one person learns something useful

- Techniques apply beyond survival models.
- Ask questions. Please, make this time yours.
- Slack invite: <a href="https://join.slack.com/t/rinpharmaconf/shared">https://join.slack.com/t/rinpharmaconf/shared</a> invite/</a>
   zt-24w18rs6f-I7Y3PM4eCilF6VIDYTInYA
- Slack channel: <a href="https://rinpharmaconf.slack.com/?">https://rinpharmaconf.slack.com/?</a> redir=%2Farchives%2FC02JRJL2C82

• Thank you, R/Pharma! Thanks, Phil Bowsher!

#### Contact

#### Feel free to reach out

• LinkedIn: <a href="https://www.linkedin.com/in/syclik/">https://www.linkedin.com/in/syclik/</a>

• Sports: <u>dlee@zelusanalytics.com</u>

• All other: <u>daniel@bayesianops.com</u>

#### Setup

#### Stan + R

Install CmdStanR

```
install.packages("cmdstanr", repos = c("https://mc-
stan.org/r-packages/", getOption("repos")))
```

- Install survival, ggplot install.packages(c("survival", "ggplot2"))
- Git Clone / download materials from:
   https://github.com/bayesianops/stan-survival-model-workshop
   script.R

## What is Stan?



## Simplified Overview

- 1. Language for writing statistical models.
- 2. Provides Bayesian estimates, (penalized) maximum likelihood, approximate Bayesian inference.

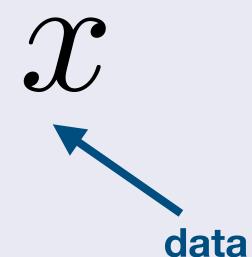
  Best known for Bayesian estimates.
- 3. Built for complicated models. Effort high for simple models.

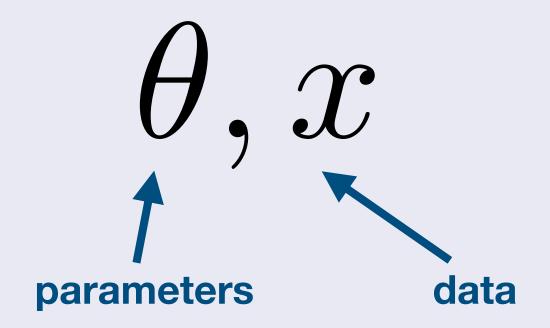
## What is Stan?

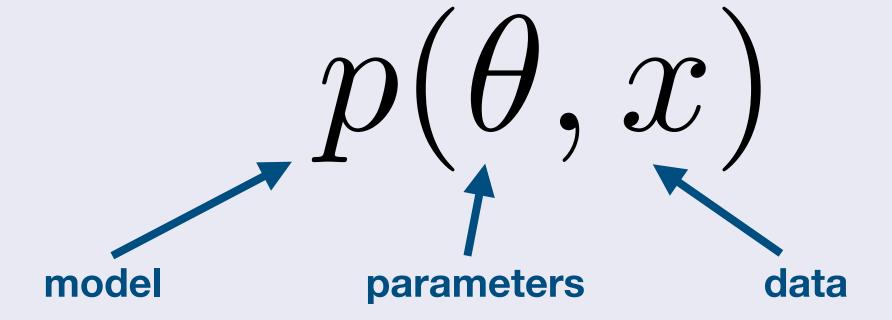
1. Language

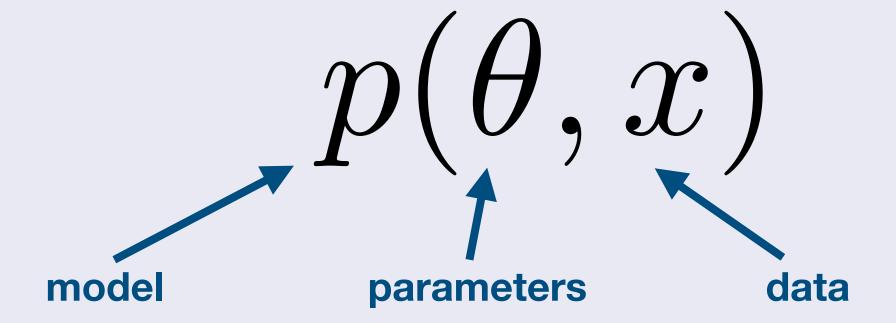
2. Algorithms

3. Interfaces

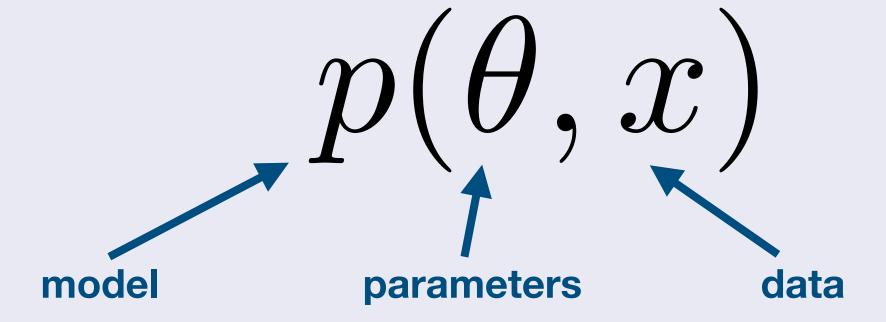








- Stan is a language
  - statically typed, imperative
  - users define programs: data, parameters, log joint pdf
- User can specify any differentiable joint probability distribution function over data and parameters



## Example: Logistic Regression

```
data {
  int<lower = 0> N;
  vector[N] x;
 array[N] int<lower = 0, upper = 1> y;
parameters {
  real alpha;
  real beta;
model {
  y ~ bernoulli_logit(alpha + beta * x);
```

## Users define the statistical model $p(\theta, x)$

# Users define the statistical model $p(\theta, x)$

## The statistical model is neither Bayesian or frequentist!!

## Inference algorithms use $p(\theta, x)$

▶ Bayesian inference; Markov Chain Monte Carlo (MCMC)

Approximate Bayesian inference

Optimization

## Inference algorithms use $p(\theta, x)$

- ▶ Bayesian inference; Markov Chain Monte Carlo (MCMC)
  - $p(\theta \mid x)$  approximated with  $\{\theta^{(1)}, \theta^{(2)}, \dots, \theta^{(N)}\}$

- Approximate Bayesian inference
  - ex:  $\hat{p}(\theta \mid x) \approx q(\hat{\phi})$  where  $\hat{\phi} = \underset{\phi}{\operatorname{argmin}} \ D_{\mathrm{KL}} \left( q(\theta \mid \phi) \mid\mid p(\theta, x) \right)$
- Optimization

$$\hat{\theta} = \underset{\theta}{\operatorname{argmax}} \ p(\theta, x)$$
 (only holds when there's a single optima)

## Survival Analysis: The Problem

#### The Problem

- For an individual, how long before an event happens?
  - What's an event?
  - Examples: death, hospitalization, equipment failure
- Difficult to predict for individuals
  - Analysis done on groups of individuals
  - Assumption: exchangeability

What's the expected time to an event?

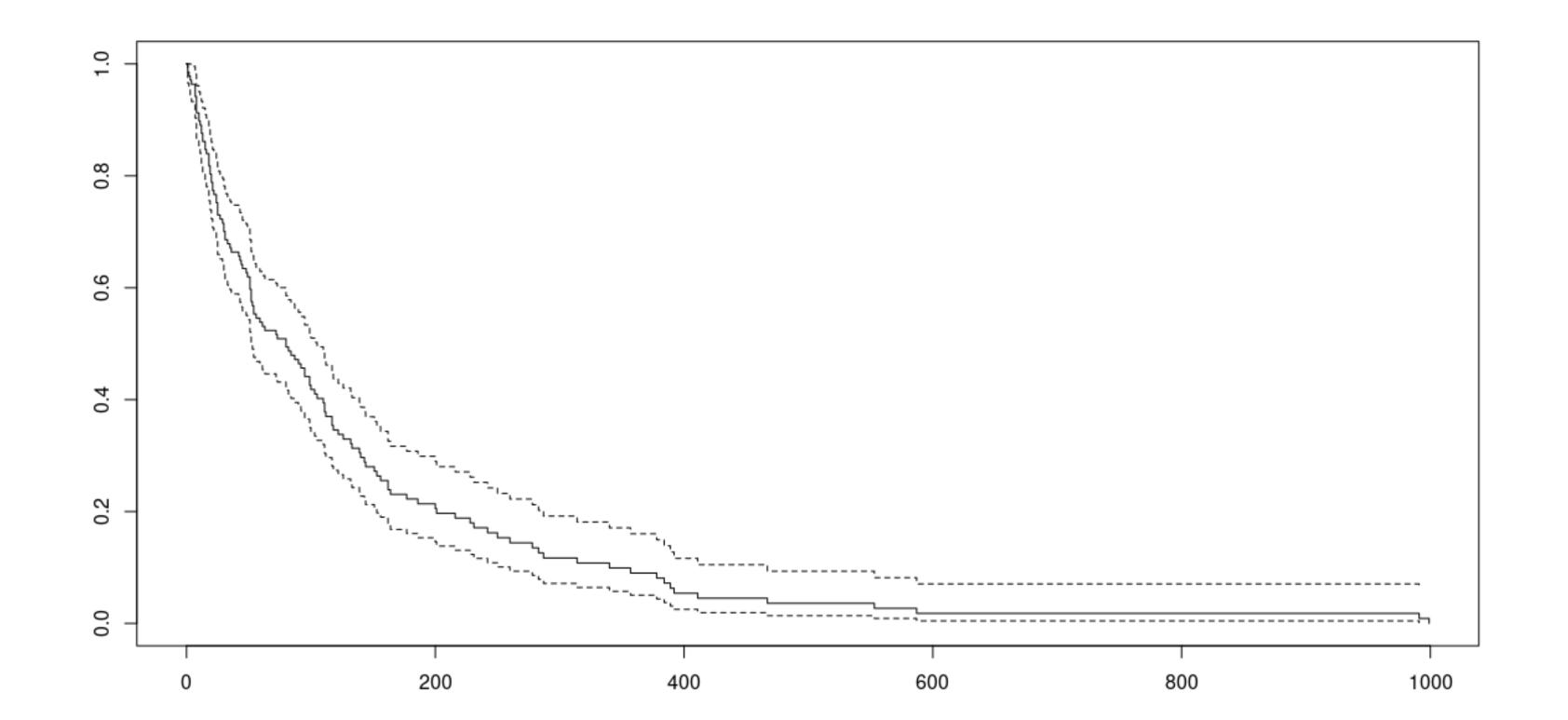
#### The Data

- Event of interest
  - Note: can be multiple events

- For each individual
  - Covariates. Examples: age, sex, bmi, device manufacturer, batch number
  - Event time
  - Censoring time (with the censoring type)
    - Right censoring: event has not happened at time t
    - Left censoring: event happened before time t

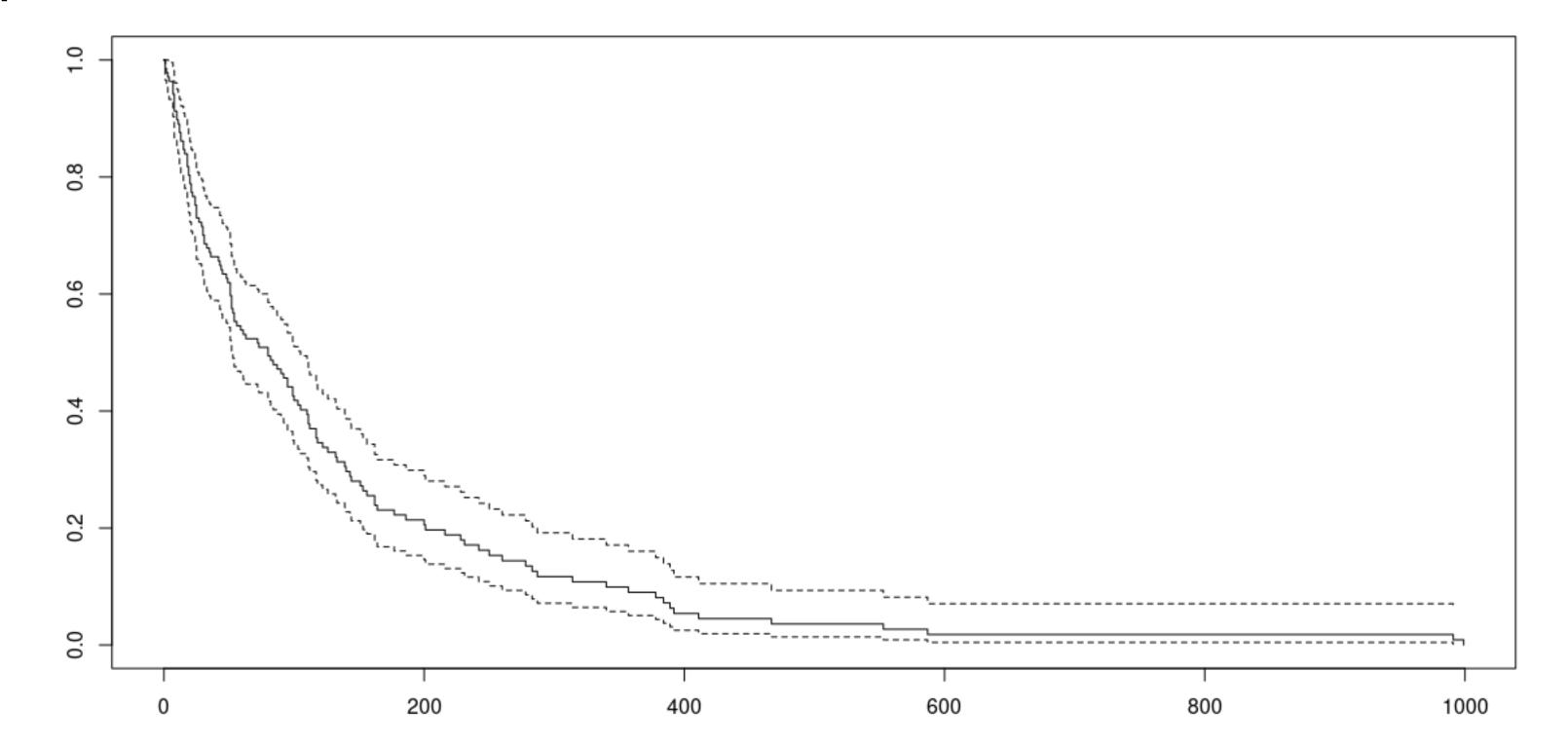
#### Example data: Veterans' Administration Lung Cancer study

```
library(survival)
veteran
head(veteran)
plot(survfit(Surv(veteran$time, veteran$status) ~ 1))
```



#### Example data: Veterans' Administration Lung Cancer study

- This plot is a Kaplan-Meier curve
  - Y-axis: percent survival
  - X-axis: time
  - Non-parametric estimate of survival curve



#### Example data: Veterans' Administration Lung Cancer study

- Take 5 minutes to look at the data.
   Some questions:
  - How many subjects?
  - How many treatments?
  - What's the median survival time?
  - Is there a difference if you only use non-censored observations?

Next up: survival model math

## Survival Model: Math

#### Terminology

• time

• survival time T The "true" event time.

- survival function S(t) The probability that the survival time is past time t, i.e.  $\Pr(T > t)$ .
- hazard function h(t) or  $\lambda(t)$ The event rate at time t conditioned on survival time T  $\geq$  t
- cumulative hazard function  $\Lambda(t)$ Accumulation of hazard over time to t.

#### Terminology

• time

• survival time  $T \label{eq:true} The \mbox{"true" event time.}$ 

- 3 survival function S(t) The probability that the survival time is past time t, i.e.  $\Pr(T > t)$ .
- 1 hazard function h(t) or  $\lambda(t)$ The event rate at time t conditioned on survival time T  $\geq$  t
- cumulative hazard function  $\Lambda(t)$ Accumulation of hazard over time to t.

#### Hazard Function h(t)

- Instantaneous failure rate at time t, conditioned on survival time T ≥ t
- Hazard function. h(t) or  $\lambda(t)$ The event rate at time t conditioned on survival time  $T \ge t$ .

$$h(t) = \lim_{\Delta t \to 0} \frac{\Pr(t \le T < t + \Delta t \mid T \ge t)}{\Delta t}$$

- Conditions
  - For all t,  $h(t) \ge 0$
  - $\bullet \int_{0}^{\infty} h(t)dt = \infty$

This is linked to the cumulative hazard function

#### **Cumulative Hazard Function**

 $\Lambda(t)$ 

Accumulation of hazard (risk) over time.

• Cumulative hazard function  $\Lambda(t)$  Area under the curve of the hazard function up until time t. The more time passes, the more risk accumulates

$$\Lambda(t) = \int_0^t h(u)du$$
$$= \int_0^t \lambda(u)du$$

This is linked to the survival function

#### Survival Function

• The probability that a subject survives past time t.

Survival function.

• 
$$S(t) = \Pr(T > t)$$

• 
$$S(t) = \exp(-\Lambda(t))$$

- S(0) = 1
- $S(\infty) = 0$

- probability that survival time is greater than t
- exp of the negative cumulative survival function

• In Stan, we'll make use of h(t),  $\Lambda(t)$ , and S(t)

## Aside: Why $S(t) = \exp(-\Lambda(t))$ ?

- https://grodri.github.io/glms/notes/c7s1
   Germán Rodríguez
- †
   Section 7.1.2 has a clear, mathematical derivation

#### 7.1.2 The Hazard Function

An alternative characterization of the distribution of T is given by the *hazard* function, or instantaneous rate of occurrence of the event, defined as

$$\lambda(t) = \lim_{dt \to 0} \frac{\Pr\{t \le T < t + dt | T \ge t\}}{dt}.$$
(7.2)

The numerator of this expression is the conditional probability that the event will occur in the interval [t, t + dt) given that it has not occurred before, and the denominator is the width of the interval. Dividing one by the other we obtain a rate of event occurrence per unit of time. Taking the limit as the width of the interval goes down to zero, we obtain an instantaneous rate of occurrence.

The conditional probability in the numerator may be written as the ratio of the joint probability that T is in the interval [t, t+dt) and  $T \ge t$  (which is, of course, the same as the probability that t is in the interval), to the probability of the condition  $T \ge t$ . The former may be written as f(t)dt for small dt, while the latter is S(t) by definition. Dividing by dt and passing to the limit gives the useful result

$$\lambda(t) = \frac{f(t)}{S(t)},\tag{7.3}$$

which some authors give as a definition of the hazard function. In words, the rate of occurrence of the event at duration t equals the density of events at t, divided by the probability of surviving to that duration without experiencing the event.

Note from Equation 7.1 that -f(t) is the derivative of S(t). This suggests rewriting Equation 7.3 as

$$\lambda(t) = -\frac{d}{dt} \log S(t).$$

If we now integrate from 0 to t and introduce the boundary condition S(0) = 1 (since the event is sure not to have occurred by duration 0), we can solve the above expression to obtain a formula for the probability of surviving to duration t as a function of the hazard at all durations up to t:

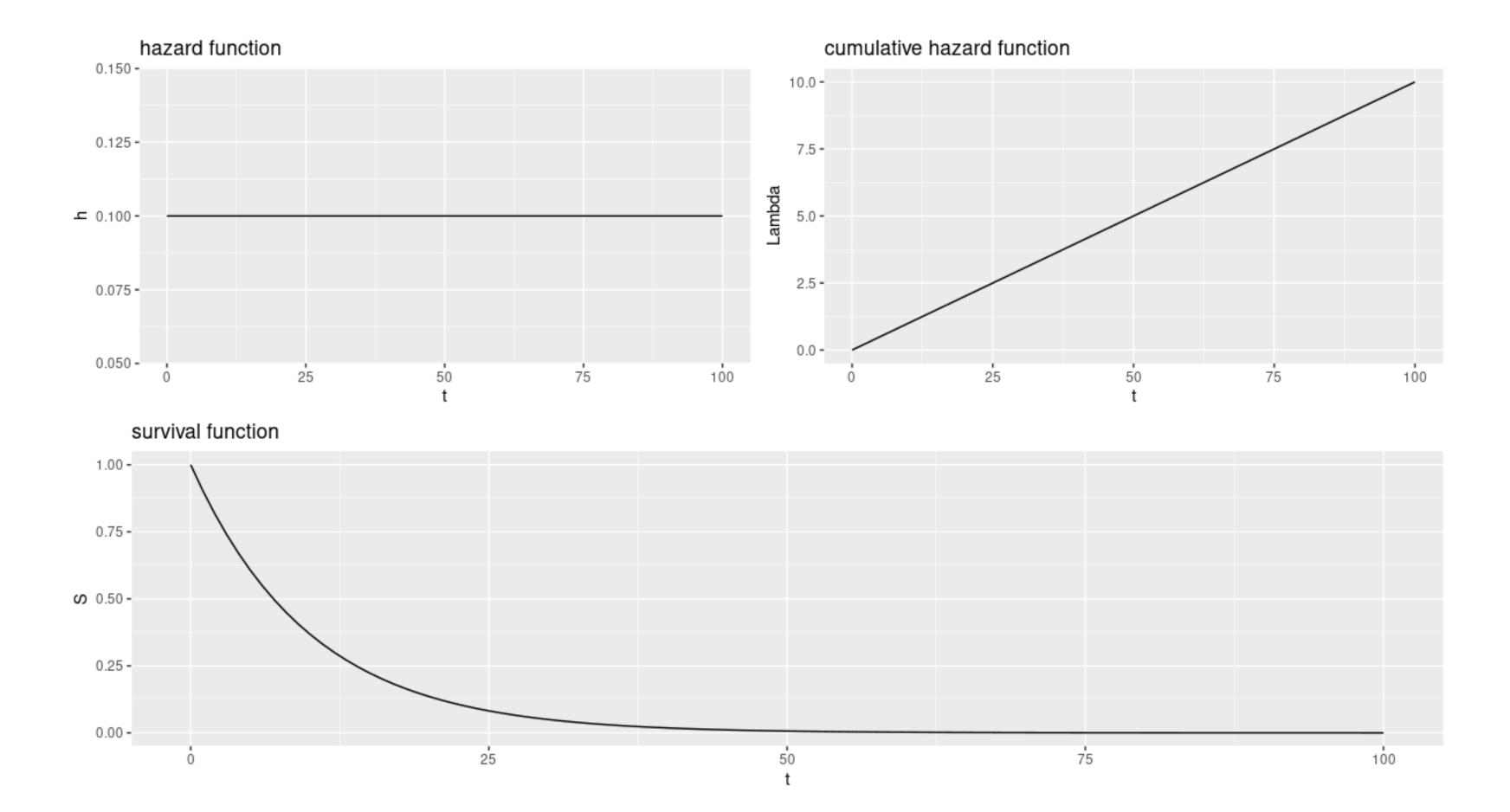
$$S(t) = \exp\{-\int_0^t \lambda(x)dx\}. \tag{7.4}$$

This expression should be familiar to demographers. The integral in curly brackets in this equation is called the *cumulative hazard* (or cumulative risk) and is denoted

$$\Lambda(t) = \int_0^t \lambda(x)dx. \tag{7.5}$$

#### Constant hazard function

- $h(t) = \lambda$ , for all  $t \ge 0$ .
- What does this look like?  $\lambda = 0.1$



#### Constant hazard function

• Hazard function:  $h(t) = \lambda$ 

• Cumulative hazard function: 
$$\Lambda(t) = \lambda * t$$

Survival function:

$$S(t) = \Pr(T > t)$$

$$= \exp(-\Lambda(t))$$

$$= \exp(-\lambda * t)$$

• We're going to simulate data from this model first.

## Simulating Data Inversion Sampling

### Inversion Sampling

#### Technique for pseudo-random number sampling

- Goal: generate random output
  - Need: inverse cumulative distribution function (cdf)

- What is a cdf (of t)?  $F(t) = \Pr(T \le t)$ 
  - Function of t that gives the probability of T ≤ t
- What's the inverse cdf?  $F^{-1}(p)$ Quantile function. If you give the function a probability, it gives you back t.

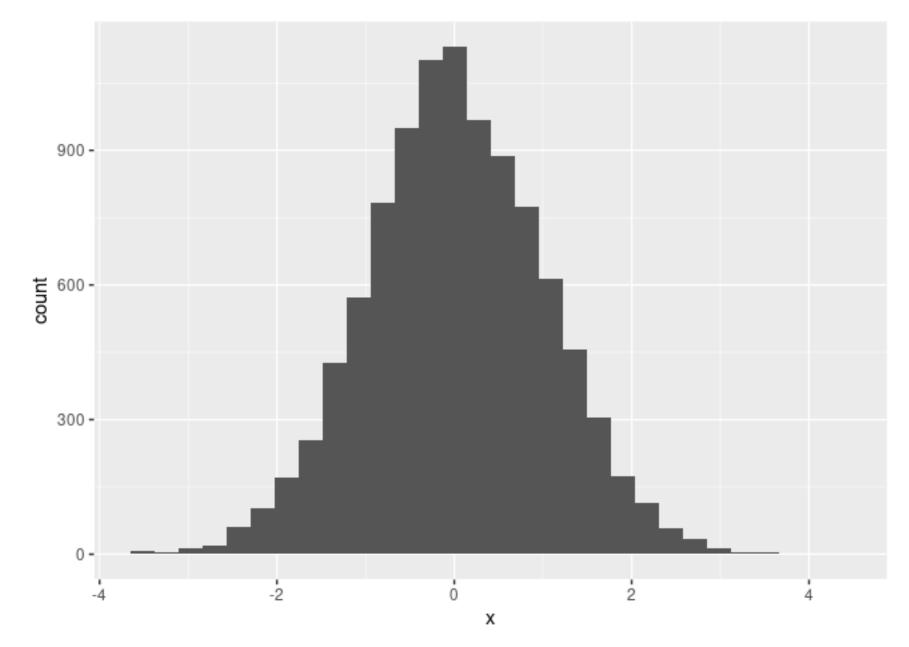
#### Inversion Sampling

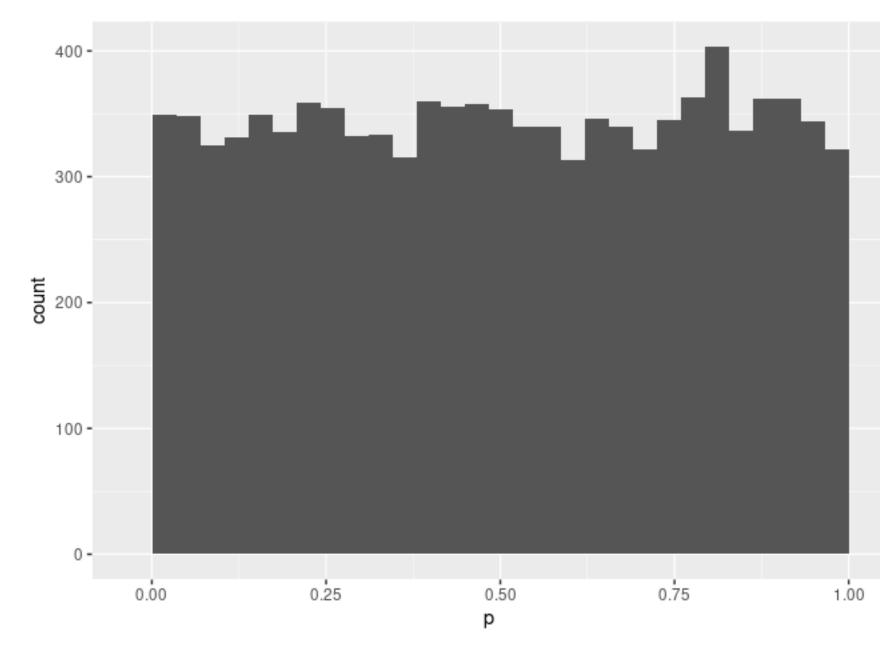
#### Intuition for why it works

# Inversion Sampling

## Intuition for why it works







# Inversion Sampling

### The process

- For each sample
  - Draw p ~ uniform(0, 1)
  - x = inverse\_cdf(p)
  - return x

# Inversion Sampling

### The process; normal example

- For each sample
  - Draw p ~ uniform(0, 1):
  - x = inverse\_cdf(p):
  - return x

#### Vectorized:

```
p <- runif(10000, 0, 1)
x <- qnorm(p)
ggplot(data.frame(x = x), aes(x = x)) + geom_histogram()</pre>
```

p <- runif(1, 0, 1)

x <- qnorm(p)

## What's the CDF of a survival model?

- What is a cdf?  $F(t) = \Pr(T \le t)$  Function of t that gives the probability of T  $\le$  t
- This is linked to the survival function:  $S(t) = \Pr(T > t)$ 
  - cdf: F(t) = 1 S(t)
- For constant hazard function, the cdf:

$$F(t) = 1 - S(t)$$
$$= 1 - \exp(-\lambda * t)$$

• The inverse cdf:

$$F^{-1}(p) = \frac{-\log(1-p)}{\lambda}$$

$$p = 1 - S(t)$$

$$p = 1 - \exp(-\lambda t)$$

$$p - 1 = -\exp(-\lambda t)$$

$$1 - p = \exp(-\lambda t)$$

$$-\log(1 - p) = -\lambda t$$

$$t = \frac{-\log(1 - p)}{\lambda}$$

### Pick lambda = 0.1

- Start with simulating a single subject; no covariates.
  - Draw p = runif(0, 1)
  - Since we know lambda, we want to know what time this corresponds to.
     t = -log(1 p) / lambda
  - What value did you get?
  - Do you think you'll be able to infer lambda just from the single event time?
- Simulate for N = 100
- Advanced: use non-constant hazard function.

Simulate 100 individuals

```
N = 100
p = runif(N)
event_time = -log(1 - p) / lambda
```

Pick lambda = 0.1

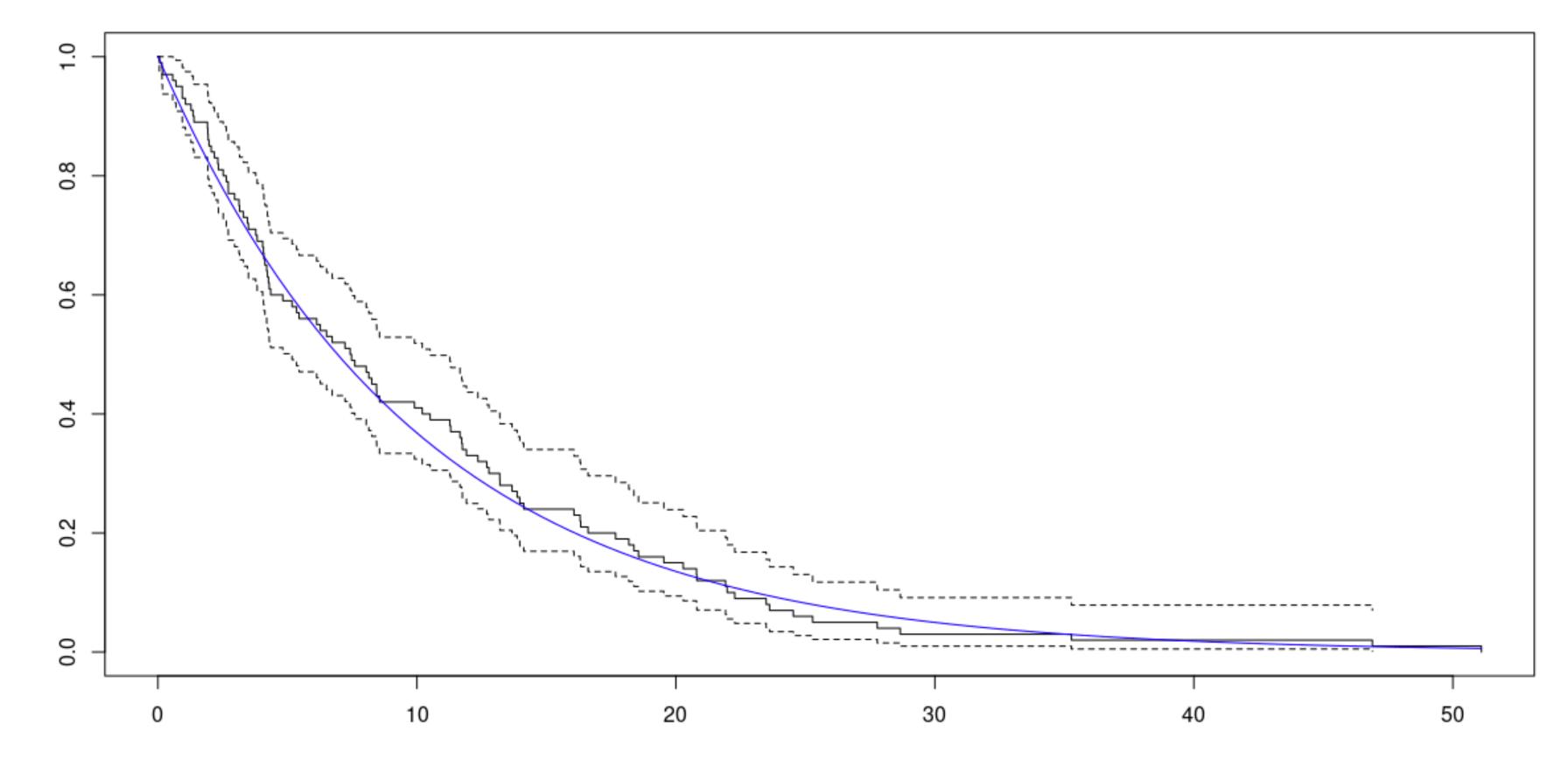
- Simulate N subjects (as variable event\_time)
- Show KM curve.

```
library(survival)
Y = Surv(event_time)
plot(survfit(Y ~ 1))
curve(exp(-x * lambda), add = T, col = 'blue')
```

Bonus: what's the likelihood of an event at time t?

### Pick lambda = 0.1

KM curve



Bonus: what's the likelihood of an event at time t?

## Hands on: 15 minutes

- Change the value of lambda.
- Plot
  - hazard function
  - cumulative hazard function
  - survival function

- What's the median survival? (Find t such that S(t) = 0.5.) What happens with higher lambda?
- Advanced: use a non-constant hazard function

# 1. Constant Hazard Model

# Hands-on. Stan program

### Data and parameters

- Open: survival\_1.stan
- Data
  - int<lower = 0 > N;
  - vector<lower = 0>[N] event\_time;
- Parameters
  - real<lower = 0 > 1ambda;

```
// Constant hazard model
data {
   int<lower = 0> N;
   vector<lower = 0>[N] event_time;
}
parameters {
   real<lower = 0> lambda;
}
model {
   // prior for lambda
   // likelihood for each event time
}
```

# Hands-on. Stan program.

### Model

- 2. Prior on lambda. No likelihood. Let's just put it in the right ballpark. lambda ~ normal(0, 1); (don't like it? Put something wider / different.)
- 3. Next: let's get to the full model

### What's the likelihood of an event at time t?

We need the likelihood for each observation.

- What's the probability that the event occurred right at the event\_time?
  - Pr(T = event\_time | lambda)?
    - Hint: we need to combine two things we have

- The survival time, T, is greater than or equal to event\_time.... AND
- The survival event happened right at time event\_time

## What's the likelihood of an event at time t?

- The survival time, T, is greater than or equal to  $t \rightarrow Pr(T \ge t) = S(t)$ (t = event\_time)

The survival event happened right at time t

 $\rightarrow$  h(t)

Likelihood:

S(t) \* h(t)

Constant hazard model likelihood:

 $\exp(-\lambda * t) \times \lambda$ 

Log likelihood:

 $-\lambda * t + \log(\lambda)$ 

## Hands-on. Stan program. 5 minutes

#### The model

- For each individual, include the log likelihood:  $-\lambda * t + \log(\lambda)$ 
  - 'target +=' is incrementing the log likelihood
  - Likelihood: S(t) \* h(t) = exp(-lambda \* t) \* lambda

```
model {
   lambda ~ normal(0, 1);
   for (n in 1:N) {
     target += ;
   }
}
```

## Hands-on. Stan program

### The model

- For each individual, include the log likelihood
  - 'target +=' is incrementing the log likelihood
  - Likelihood: S(t) \* h(t) = exp(-lambda \* t) \* lambda

```
model {
  lambda ~ normal(0, 1);
  for (n in 1:N) {
    target += -lambda * event_time[n] + log(lambda);
  }
}
```

## Fit the model, look at inferences for lambda

- Are you able to recover lambda?
- Simulate different data
  - More data, less data
- Are you getting good inferences?
- What about the prior?
  - Can you remove the prior?
  - Can you add a stronger prior?

```
mod =
cmdstan_model("survival_1.stan")
mod$print()
data_list = list(N =
length(event_time), event_time =
event_time)
fit = mod$sample(data =
data_list, seed = 123, chains =
4, parallel_chains = 4, refresh
= 500)
```

# 2. Add Covariates

# Proportional hazards model

- A survival model that accounts for covariates
- Widely used.

- Modeling assumptions:
  - Covariates matter
  - Covariates effect hazard rate multiplicatively

# Proportional hazards model

Hazard function:

$$h(t) = h_0(t) \exp(X \cdot \beta)$$

- Two components
  - Baseline hazard function:  $h_0(t)$  (or  $\lambda_0(t)$ ) hazard function for baseline level of covariates

• Effect of covariates:  $\exp(X \cdot \beta)$  X are the covariates (for an individual),  $\beta$  are parameters If X is 0, the effect is 1

Note: no time-varying effect of covariates

## Hands on. Simulate data. 5 minutes

- Simulate data.
  - Pick lambda = 0.1, beta = log(0.5)
  - Simulate N individuals. Output: N, treatment, event\_time
    - Randomly assign a treatment: 0 or 1
    - Compute event time conditional on treatment, lambda, and beta
- Plot KM curves separating on treatment
  - Should see a difference; even taking the median of the times will show it
  - The survival curves should not cross.

### Hands on. Simulate data.

Simulate data with treatment

```
lambda = 0.1
beta = log(0.5)

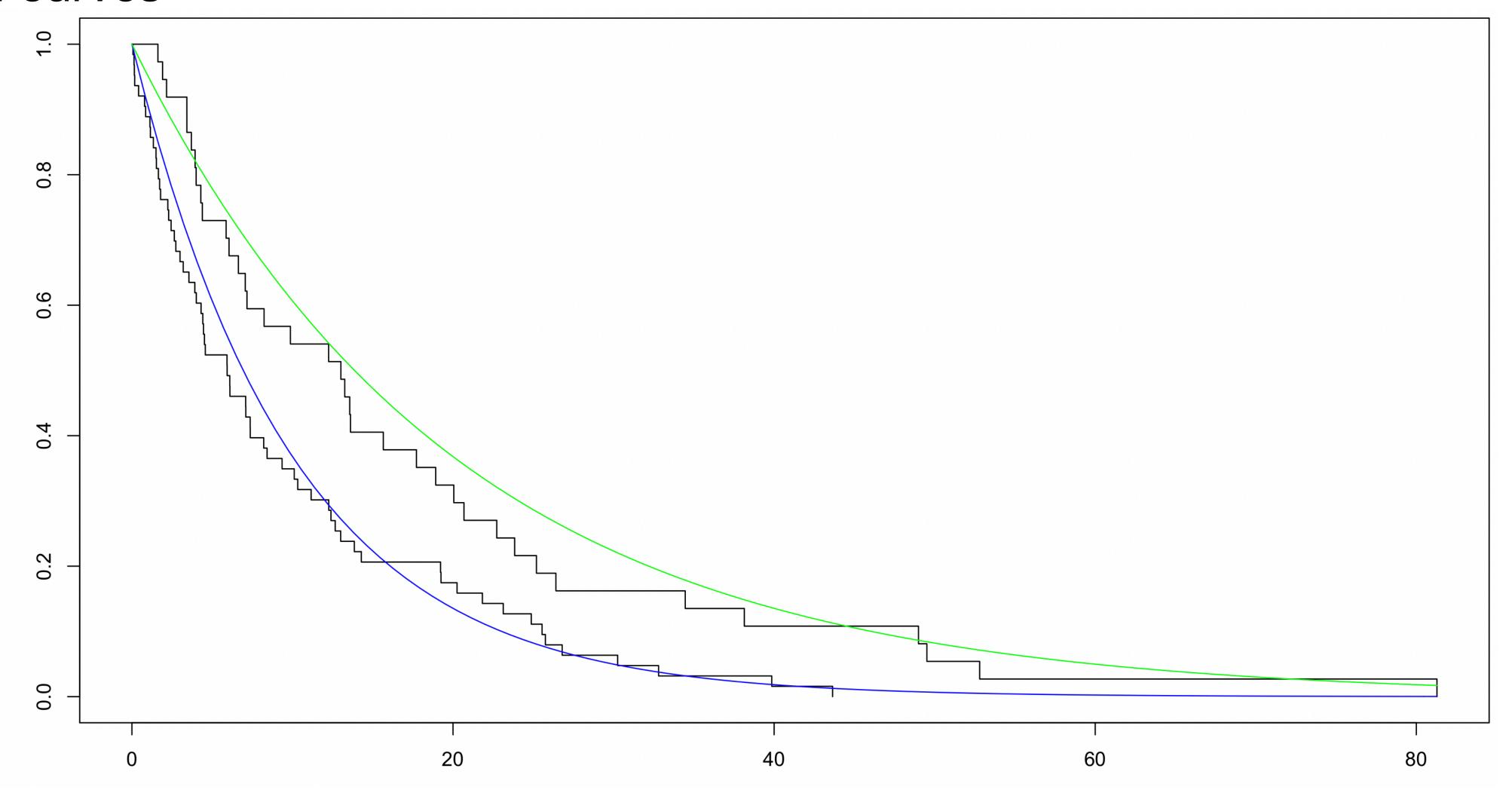
N = 100
treatment = sample(c(0, 1), N, replace = TRUE)
p = runif(N)
event_time = -log(1 - p) / (lambda * exp(treatment * beta))
```

KM curve

```
Y = Surv(event_time)
plot(survfit(Y ~ treatment))
curve(exp(-x * lambda), add = T, col = 'blue')
curve(exp(-x * lambda * exp(beta)), add = T, col = 'green')
```

## Hands on. Simulate data.

### KM curves



# Hands-on. Stan program. 15 minutes

### **Extend the model**

- Add data
  - array[N] int<lower = 0, upper = 1> treatment;
- Add parameter
  - real beta;
- Model
  - 1. Add prior. beta ~ normal(0, 1); Run it.
  - 2. Add proportional hazard
     Original: target += -lambda \* event\_time[n] + log(lambda)
     Updated:

# Hands-on. Stan program. 15 minutes

### **Extend the model**

- Add data
  - array[N] int<lower = 0, upper = 1> treatment;
- Add parameter
  - real beta;
- Model
  - 1. Add prior. beta ~ normal(0, 1); Run it.
  - 2. Add proprotional hazard

# Stan Program

```
data {
  int<lower = 0> N;
  array[N] real event_time;
  array[N] int<lower = 0, upper = 1> treatment;
parameters {
  real<lower = 0> lambda;
  real beta;
model {
  lambda \sim normal(0, 1);
  beta \sim normal(0, 1);
  for (n in 1:N) {
    real lambda_n = lambda * exp(treatment[n] * beta);
    target += -lambda_n * event_time[n] + log(lambda_n);
```

### Problems with this model?

Identifiability problem

```
• lambda = 0.1, beta = log(0.5) = -0.7
```

- lambda = 0.05, beta = log(2) = 0.7
- Other issues?

# 3. Add Censoring

# Censoring

Partial information about the event time

Types

Right: event occurs after some known time

Left: event occurred before some known time

• Interval: event occurs between two time points

•

### Hands on. Simulate data. 15 minutes

- Simulate right censored data. Event occurs after some known time.
  - Pick lambda = 0.1, beta = 0.5, censor\_time = 40
  - Simulate N individuals. Output: N, treatment, event\_time, censored
    - Randomly assign a treatment: 0 or 1
    - Compute event time conditional on: treatment, lambda, beta, and censor\_time
    - Assign censored: 0 or 1

Bonus: random censoring instead of using censor\_time.
 (Draw independent censor\_time per individual)

## Hands on. Simulate data.

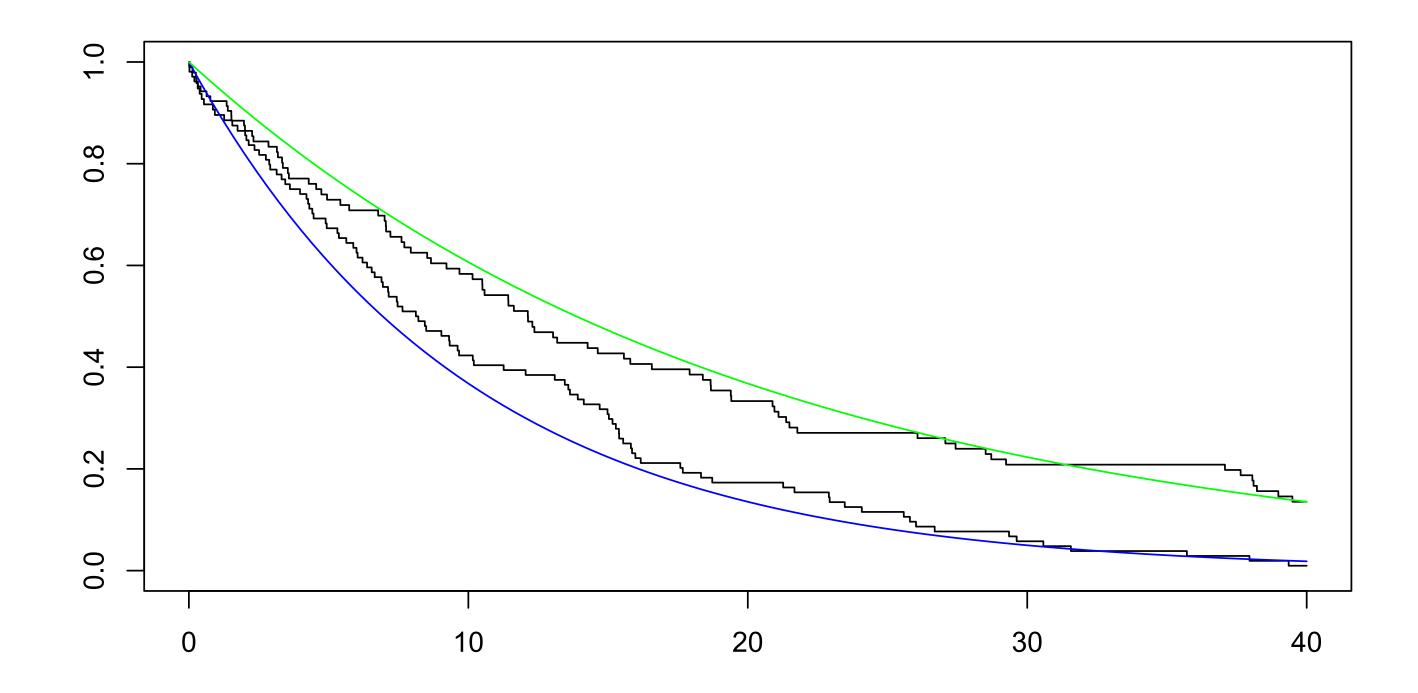
• Simulate right censored data. Event occurs after some known time.

```
lambda = 0.1
beta = log(0.5)
censor_time = 40
N = 200
 treatment = sample(c(0, 1), N, replace = TRUE)
 p = runif(N)
 true_event_time = -\log(1 - p) / (lambda * exp(treatment * lambda + exp(
 beta))
 censored = ifelse(true_event_time > censor_time, 1, 0)
event_time = pmin(true_event_time, censor_time)
```

## Hands on. Simulate data.

#### KM curves

```
Y = Surv(event_time, censored == 0)
plot(survfit(Y ~ treatment))
curve(exp(-x * lambda), add = T, col = 'blue')
curve(exp(-x * lambda * exp(beta)), add = T, col = 'green')
```



### Review: What's the likelihood of an event at time t?

- What's the probability that the event occured right at the event\_time?
  - Pr(T = event\_time | lambda)?

- The survival time, T, is greater than or equal to event\_time.... AND
- The survival event happened right at time event\_time

### Review: What's the likelihood of an event at time t?

- The survival time, T, is greater than or equal to  $t \rightarrow Pr(T \ge t) = S(t)$  $(t = event_time)$

The survival event happened right at time t

 $\rightarrow$  h(t)

Likelihood:

S(t) \* h(t)

Constant hazard model likelihood:

 $\exp(-\lambda * t) \times \lambda$ 

Log likelihood:

 $-\lambda * t + \log(\lambda)$ 

## What's the censored likelihood at time t?

- What's the probability that the event occured after the censor\_time?
  - Pr(T > censor\_time | lambda)?

• The survival time, T, is greater than or equal to censor\_time

• (Does this look familiar?)

## What's the censored likelihood at time t?

The survival time, T, is greater than t
 (t = censor\_time)

- $\rightarrow$  Pr(T > t) = S(t)
- The survival event happened right at time t → h(t)

Likelihood:

S(t)

Constant hazard model censoredlikelihood:

$$\exp(-\lambda * t)$$

Log censored likelihood:

$$-\lambda * t$$

# Hands-on. Stan program. 15 minutes

#### Extend model: censoring

- Add data
  - array[N] int<lower = 0, upper = 1> censored;
- Model
  - Add conditional

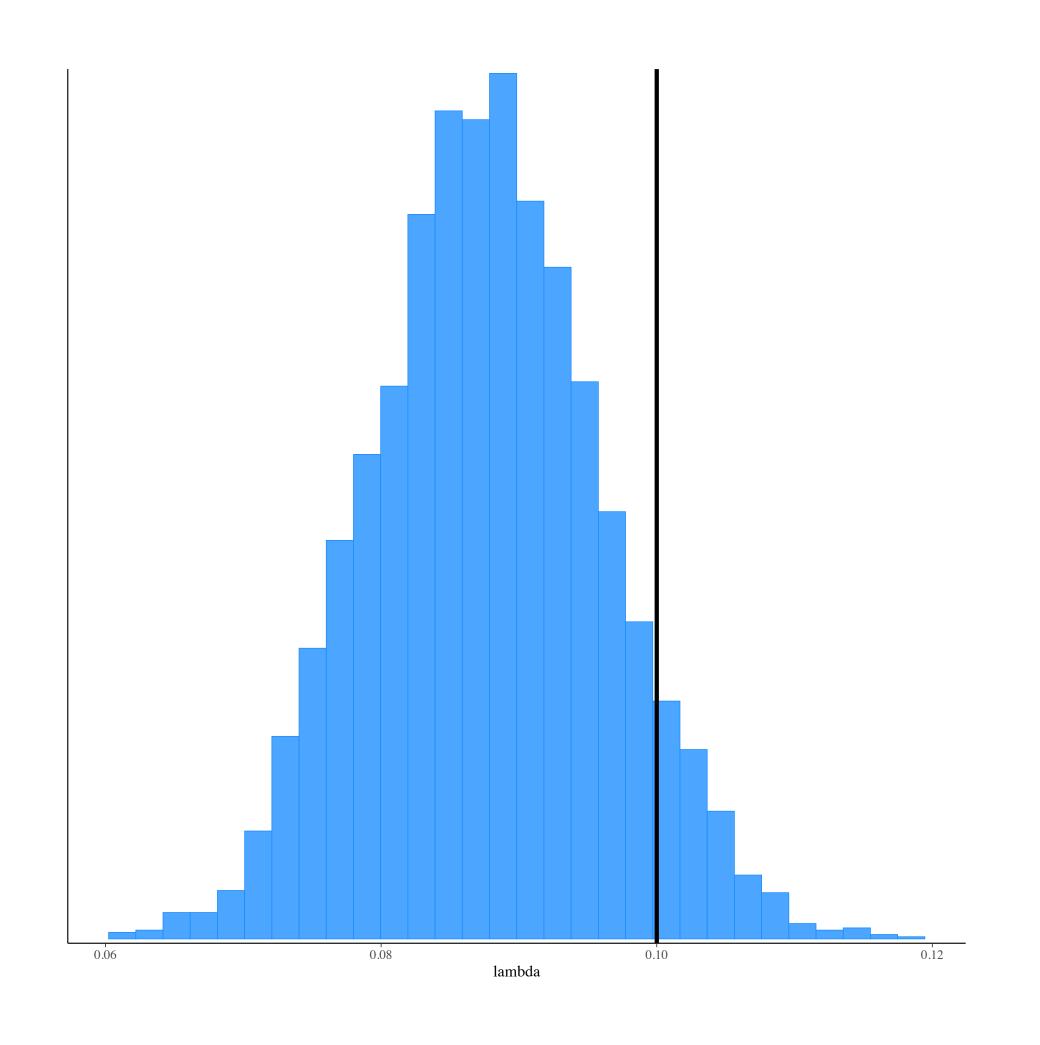
```
if (censored[n] == 0) {
  target += ;
} else {
  target += ;
}
```

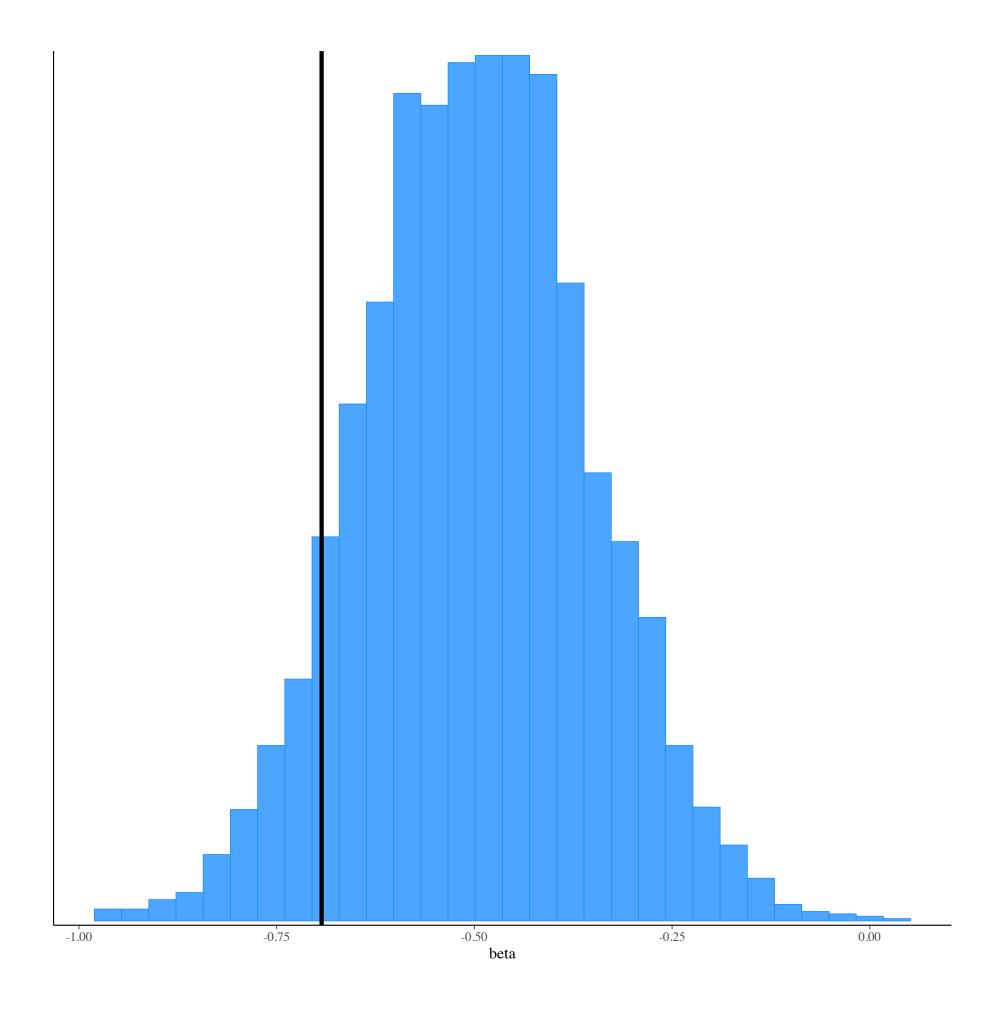
Bonus: optimize code

# Stan Program

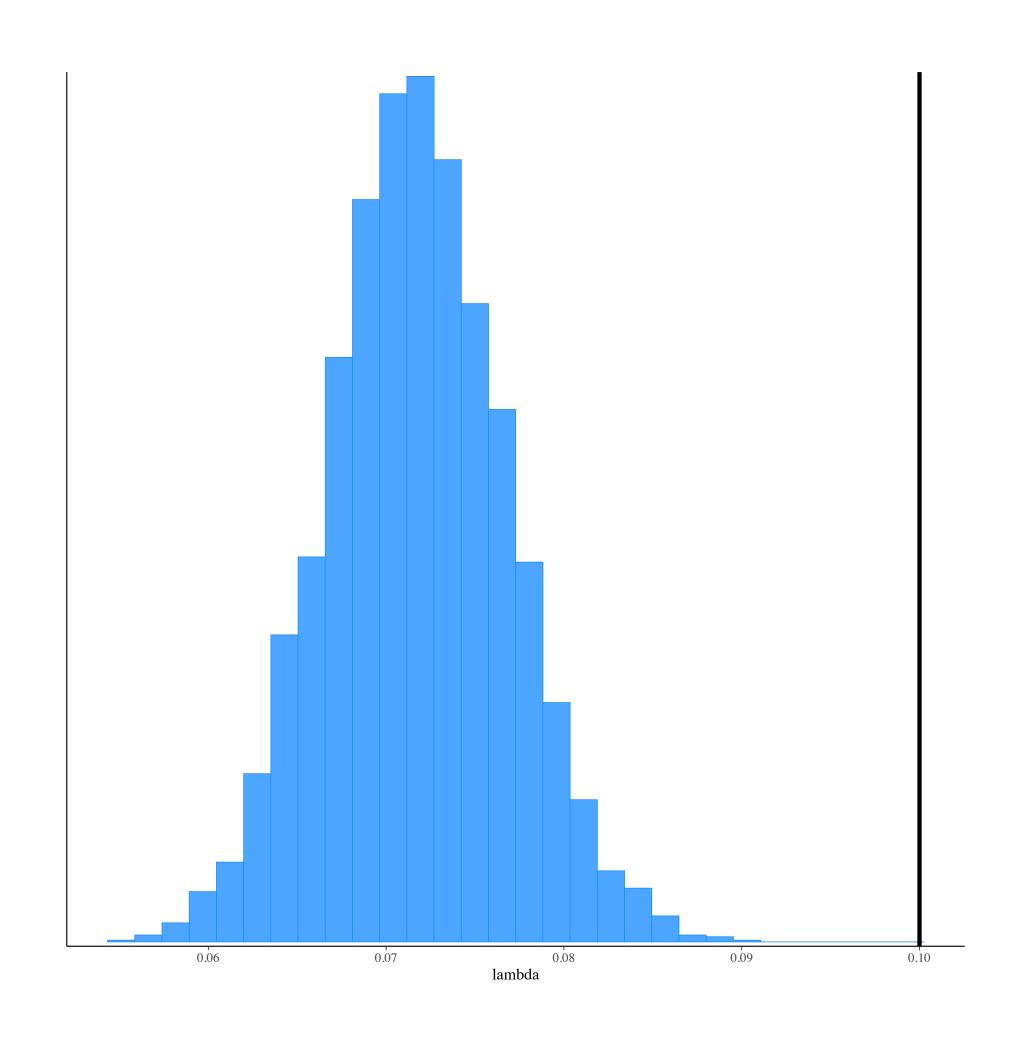
```
data {
  int<lower = 0> N;
  vector<lower = 0>[N] real event_time;
  array[N] int<lower = 0, upper = 1> treatment;
  array[N] int<lower = 0, upper = 1> censored;
parameters {
  real<lower = 0> lambda;
  real beta;
model {
  lambda \sim normal(0, 1);
  beta \sim normal(0, 1);
  for (n in 1:N) {
    real lambda_n = lambda * exp(treatment[n] * beta);
    if (censored[n] == 0) {
      target += -lambda_n * event_time[n] + log(lambda_n);
    } else {
      target += -lambda_n * event_time[n];
```

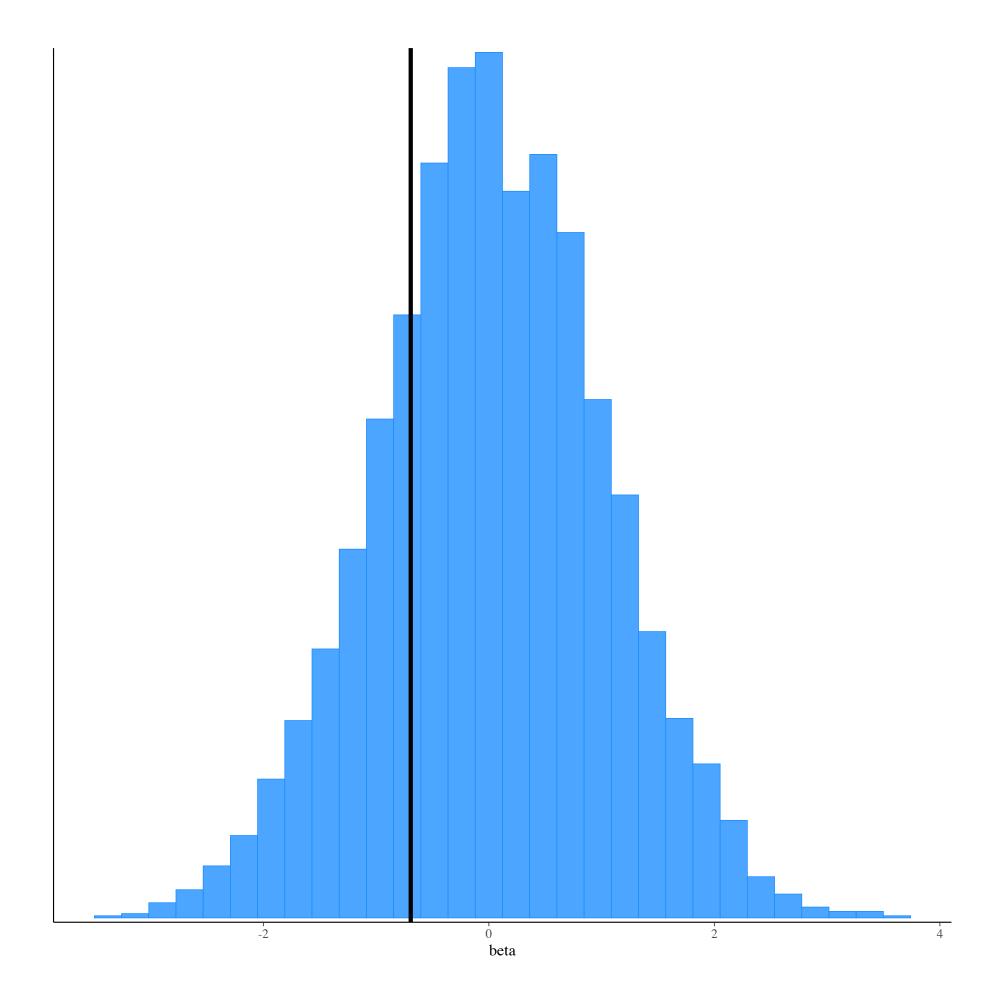
### Censored Model Estimates





### Non-Censored Model Estimates





# 4. Hierarchical Model

### Hierarchical models

- Multiple parameters related
- Natural to model hierarchy of parameters: individuals within groups
- Model is often parametric
- Parameters of the hierarchical model are called hyperparameters

# Example hierarchy

- Instead of a global lambda, each individual has a lambda
  - Model is now overparameterized without a hierarchy.
- Simple model for relating the individual lambdas:

$$\lambda_i \sim \text{Normal}(\mu_{\lambda}, \sigma_{\lambda})$$

 Now we want to estimate each individual lambda and hyperparmeters: mu and sigma

### Hands on. Simulate data. 5 minutes

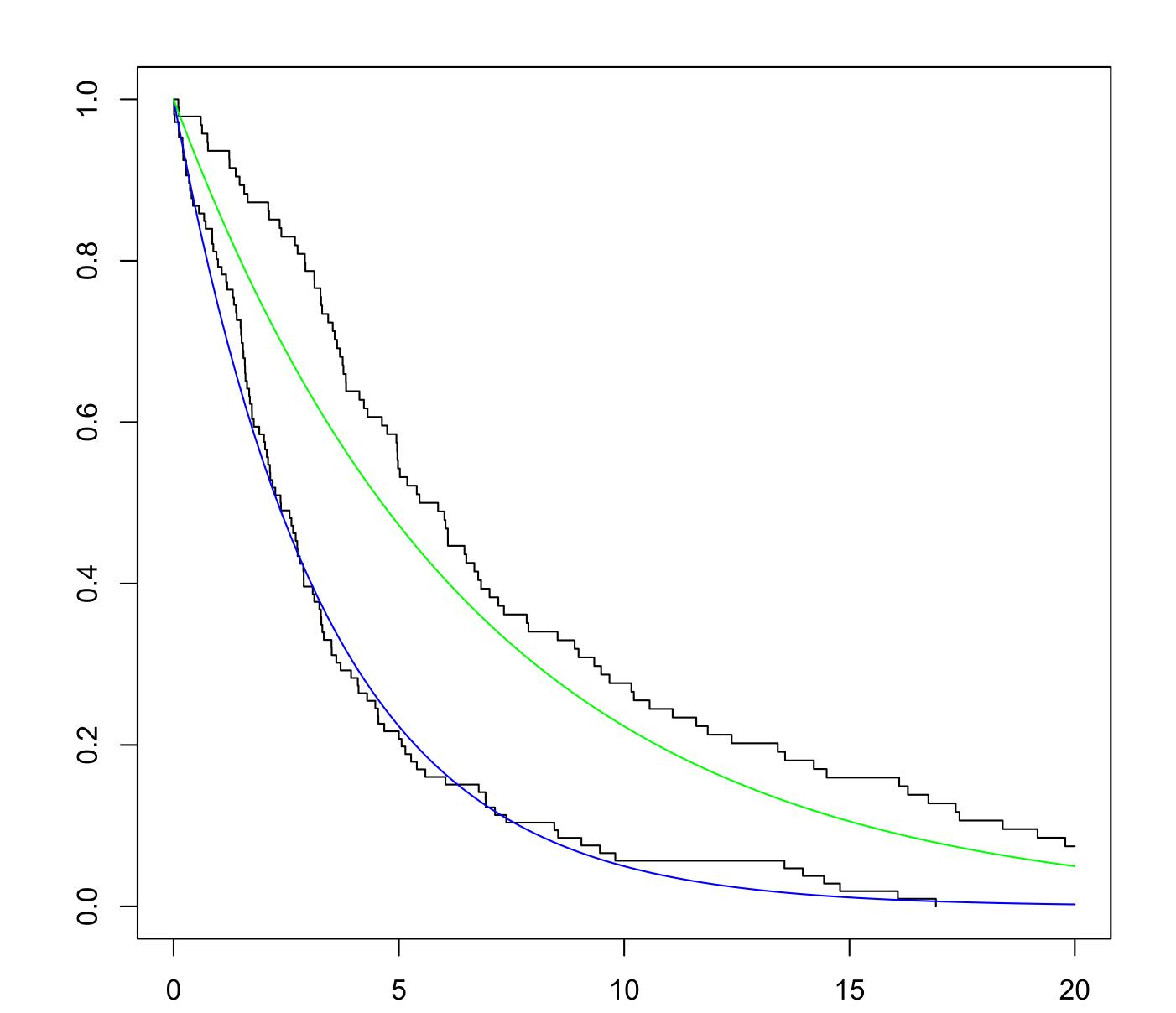
- Simulate data.
  - Pick mu\_lambda = 0.3, sigma\_lambda = 0.05, beta = log(0.5), censor\_time = 15
  - Simulate N individuals. Output: N, lambda, treatment, event\_time, censored
    - Randomly assign a treatment: 0 or 1
    - Compute event time conditional on: lambda (individual), beta, treatment, and censor\_time
    - Assign censored: 0 or 1 (if true\_event\_time > censor\_time)
- Plot KM curves separating on treatment
  - Should see a difference; even taking the median of the times will show it
  - The survival curves may cross (if beta is close to 0)

### Hands on. Simulate data.

 Simulate data with individual lambda  $mu_1ambda = 0.3$  $sigma_1ambda = 0.05$ beta = log(0.5)censor\_time = 15 N = 200lambda = rnorm(N, mu\_lambda, sigma\_lambda) treatment = sample(c(0, 1), N, replace = TRUE) p = runif(N)true\_event\_time =  $-\log(1 - p) / (lambda * exp(treatment * beta))$ censored = ifelse(true\_event\_time > censor\_time, 1, 0) event\_time = pmin(true\_event\_time, censor\_time) KM curve Y = Surv(event\_time) plot(survfit(Y ~ treatment)) curve(exp(-x \* lambda), add = T, col = 'blue')curve(exp(-x \* lambda \* exp(beta)), add = T, col = 'green')

## Hands on. Simulate data.

KM curves



# Hands-on. Stan program. 15 minutes

#### **Extend the model**

- Add data
  - Nothing
- Add parameters / change lambda
  - real<lower = 0> mu\_lambda;
  - real<lower = 0> sigma\_lambda;
  - vector<lower = 0>[N] lambda;
- Model
  - Add priors for hyper parameters: (Note: these are somewhat informative) mu\_lambda ~ normal(0, 0.1); sigma ~ normal(0, 0.1);
  - 2. Add hierarchical model: lambda ~ ...
  - 3. Update likelihood term:

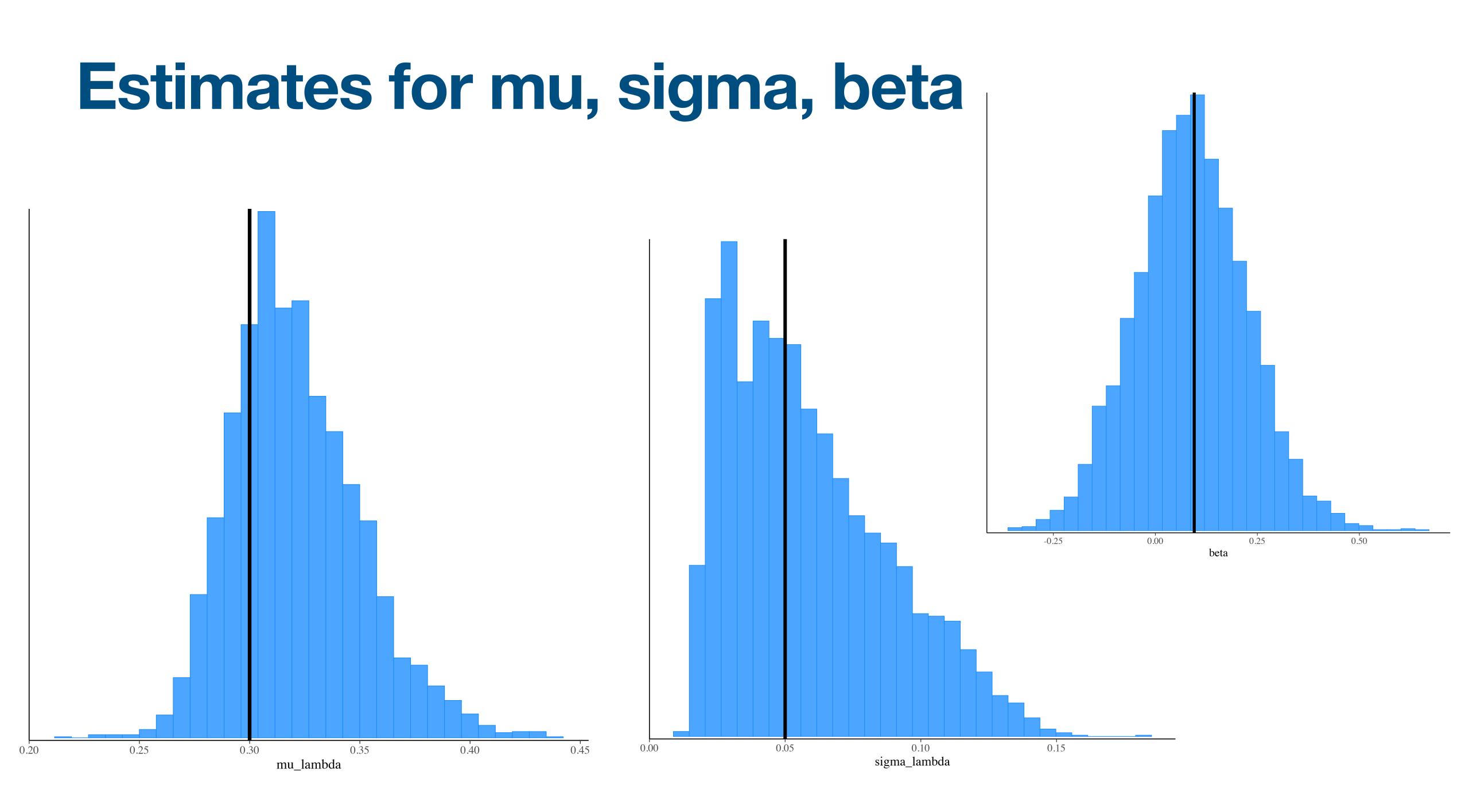
```
Original: real lambda_n = lambda * exp(treatment[n] * beta);
Updated:
```

# Hands-on. Stan program. 15 minutes

#### **Extend the model**

- Model
  - Add priors for hyper parameters: (Note: these are somewhat informative)
    mu\_lambda ~ normal(0, 0.1);
    sigma ~ normal(0, 0.1);
  - 2. Add hierarchical model: lambda ~ normal(mu\_lambda, sigma\_lambda);
  - 3. Update likelihood term:

```
Original: real lambda_n = lambda * exp(treatment[n] * beta);
Updated: real lambda_n = lambda[n] * exp(treatment[n] * beta);
```



### Problems

- Divergences: indicates problem estimating posterior
- In 44 iterations, the algorithm couldn't follow the trajectory.

```
|> fit$diagnostic_summary()
Warning: 44 of 4000 (1.0%) transitions ended with a divergence.
See https://mc-stan.org/misc/warnings for details.

Warning: 4 of 4 chains had an E-BFMI less than 0.2.
See https://mc-stan.org/misc/warnings for details.

$num_divergent
[1] 6 0 2 36

$num_max_treedepth
[1] 0 0 0 0

$ebfmi
[1] 0.03030813 0.02155769 0.01757824 0.02536754
```

- Why?
  - Posterior geometry: stepsize is estimated globally, high curvature vs low curvature
  - Easy to check if Hamiltonian is conserved (potential energy + kinetic energy)

### Potential Fixes

- Add argument to \$sample() adapt\_delta = 0.9 (or 0.99)
  - Asks algorithm to have a higher acceptance rate. Effectively smaller step size.
  - If this ends with max\_treedepth issues, increase max\_treedepth: max\_treedepth = 14 (default = 10)

 Reparameterize model (this is for another day)

# Recap

# Recap

#### Four Examples:

- 1. Constant Hazard Model
- 2. Add Covariates
- 3. Add Censoring
- 4. Hierarchical Model

#### Skills:

- Simulating data
- Running CmdStanR
- Iterating over models
- Visualizing posterior distributions

# Why Use Stan?

- Flexibility to write complex models
  - Time-varying hazard
  - Model covariance structures
  - Incorporate measurement models
  - Censoring / missingness models

# Thank you!

# Open Discussion

### Contact

#### Feel free to reach out

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