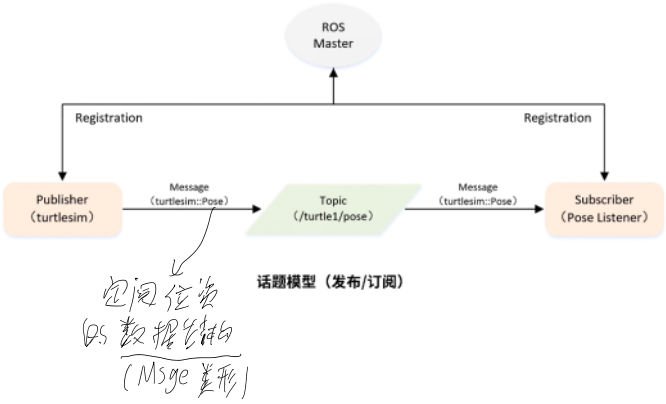
subscriber

2022年11月19日 星期六 16:50

based on

Publisher pkg 包

创个码



订阅信息的数据结构（Msge类型）

workspace/src/package

save 完

于 W_S_ 输入 catkin_make

以编译 subscriber

```
$ cd ~/catkin_ws
$ catkin_make
$ source devel/setup.bash
$ roscore
$ rosrun turtlesim turtlesim_node
$ rosrun learning_topic velocity_publisher
```

NT

运行 sim 完

NT rosrun 功能包 learning_topic 节点 pose_subscriber

```
hcx@hcx-vpc:~/catkin_ws$ rosrun learning_topic pose_subscriber
[ INFO] [1562211557.322259871]: Turtle pose: x:6.389005, y:10.396028
[ INFO] [1562211557.339097278]: Turtle pose: x:6.381475, y:10.398730
[ INFO] [1562211557.354512018]: Turtle pose: x:6.373938, y:10.401410
[ INFO] [1562211557.370549572]: Turtle pose: x:6.366391, y:10.404065
[ INFO] [1562211557.387085434]: Turtle pose: x:6.358836, y:10.406695
[ INFO] [1562211557.402710847]: Turtle pose: x:6.351273, y:10.409303
[ INFO] [1562211557.418887039]: Turtle pose: x:6.343701, y:10.411885
[ INFO] [1562211557.434469988]: Turtle pose: x:6.336121, y:10.414443
[ INFO] [1562211557.450210135]: Turtle pose: x:6.328533, y:10.416977
[ INFO] [1562211557.465994903]: Turtle pose: x:6.320937, y:10.419487
[ INFO] [1562211557.482173454]: Turtle pose: x:6.313333, y:10.421972
```

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rosrun turtlesim turtle_teleop_key