

ECE/CS 559 - Fall 2017 - Homework #4

Due: 10/16/2017, the end of class.

This is the midterm of Fall 2016.

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Note: All notes in the beginning of Homework #1 apply. Only a subset of the problems may be graded.

- **Q1 (24 pts):** In the following, we follow the convention that $x_0 = 1$.

Recall that the step-activation function $u : \mathbb{R} \rightarrow \{0, 1\}$ is defined as $u(v) = 1$ if $v \geq 0$, and $u(v) = 0$, otherwise. Then, for n inputs x_1, \dots, x_n , a **perceptron** can be defined via the input-output relationship

$$y' = u(\sum_{i=0}^n w_i x_i) = u(w_0 + w_1 x_1 + \dots + w_n x_n),$$

where y' is the perceptron output, w_1, \dots, w_n are the synaptic weights, and w_0 is the bias term.

We define a new type of neuron, namely, a **sauron**, via the input-output relationship

$$y = u(\prod_{i=0}^n (w_i + x_i)) = u((w_0 + 1)(w_1 + x_1) \dots (w_n + x_n)),$$

where y is called the sauron output.

Let the real number 1 represent a **TRUE**, and the real number 0 represent a **FALSE**.

- (a) **(8 pts):** Let $n = 1$. Does there exist w_0, w_1 such that $y = 1 - x_1$ for $x_1 \in \{0, 1\}$? In other words, can a single sauron implement the **NOT** gate? If your answer is “Yes,” find specific w_0, w_1 such that the sauron implements the **NOT** gate. If your answer is “No,” prove that no choice for w_0, w_1 can result in a sauron that implements the **NOT** gate.
- (b) **(8 pts):** Let $n = 2$. Does there exist w_0, w_1, w_2 such that $y = x_1 x_2$ for $x_1, x_2 \in \{0, 1\}$? In other words, can a single sauron implement the **AND** gate? Justify your answer as in (a).
- (c) **(8 pts):** Let $n = 2$. Does there exist w_0, w_1, w_2 such that $y = (x_1 + x_2) \bmod 2$ for $x_1, x_2 \in \{0, 1\}$? In other words, can a single sauron implement the **XOR** gate? Justify your answer as in (a).

• **Q2 (26 pts):** In the following, consider only neurons with the step-activation function $u(\cdot)$.

(a) **(13 pts):** Let $\mathcal{C}_0 = \{[\begin{smallmatrix} 1 \\ 1 \end{smallmatrix}], [\begin{smallmatrix} -1 \\ 1 \end{smallmatrix}], [\begin{smallmatrix} 0 \\ 4 \end{smallmatrix}]\}$ and $\mathcal{C}_1 = \{[\begin{smallmatrix} 0 \\ 2 \end{smallmatrix}], [\begin{smallmatrix} 0 \\ -1 \end{smallmatrix}], [\begin{smallmatrix} 0 \\ -2 \end{smallmatrix}]\}$ as illustrated in Figure (i). Members of classes \mathcal{C}_0 and \mathcal{C}_1 are represented by black disks and crosses, respectively.

[I] **(7 pts):** We wish to design a perceptron $y = u(w_0 + w_1x_1 + w_2x_2)$ such that $y = 0$ if $[\begin{smallmatrix} x_1 \\ x_2 \end{smallmatrix}] \in \mathcal{C}_0$ and $y = 1$ if $[\begin{smallmatrix} x_1 \\ x_2 \end{smallmatrix}] \in \mathcal{C}_1$. Suppose that we use the perceptron training algorithm for this purpose with initial weights $w_0 = 1$, $w_1 = 0$, $w_2 = 1$ and learning rate $\eta = 1$. Either prove that the algorithm will converge, or prove that it will not converge. You may use the perceptron convergence theorem.

[II] **(6 pts):** Design a neural network (single-layer or multi-layer) such that the network provides an output of 0 if $[\begin{smallmatrix} x_1 \\ x_2 \end{smallmatrix}] \in \mathcal{C}_0$ and an output of 1 if $[\begin{smallmatrix} x_1 \\ x_2 \end{smallmatrix}] \in \mathcal{C}_1$.

(b) **(13 pts)** Repeat (a) for classes $\mathcal{C}_0 = \{[\begin{smallmatrix} 1 \\ 1 \end{smallmatrix}], [\begin{smallmatrix} -1 \\ 1 \end{smallmatrix}], [\begin{smallmatrix} 0 \\ 4 \end{smallmatrix}]\}$ and $\mathcal{C}_1 = \{[\begin{smallmatrix} 0 \\ 0 \end{smallmatrix}], [\begin{smallmatrix} 0 \\ -1 \end{smallmatrix}], [\begin{smallmatrix} 0 \\ -2 \end{smallmatrix}]\}$ illustrated in Figure (ii). Note that the only difference is that now, instead of the point $[\begin{smallmatrix} 0 \\ 2 \end{smallmatrix}]$, we have the point $[\begin{smallmatrix} 0 \\ 0 \end{smallmatrix}]$ in class \mathcal{C}_1 .

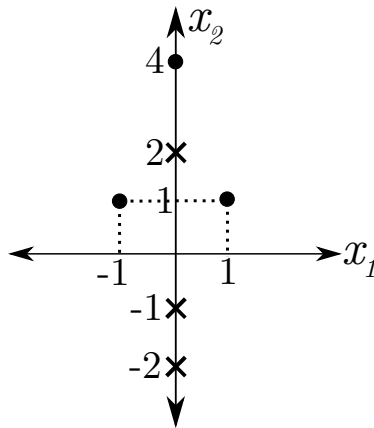


Figure (i)

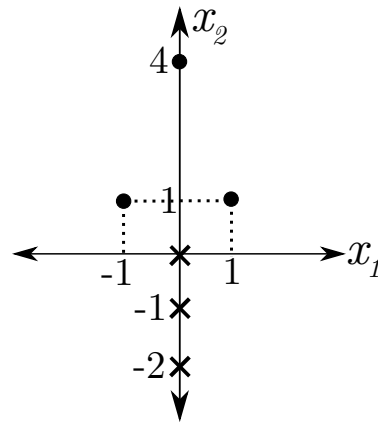


Figure (ii)

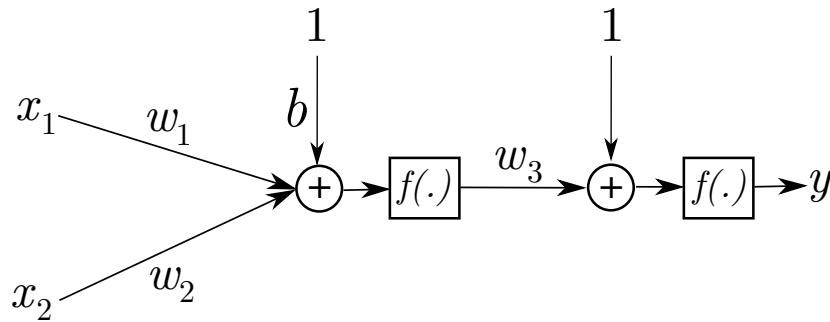
In the following, $\log(\cdot)$ is the natural logarithm, e is the base of the natural logarithm, $|\cdot|$ is the absolute value ($|x| = x$ if $x \geq 0$, and $|x| = -x$ if $x < 0$), and \mathbb{R} is the set of real numbers. Recall $\frac{\partial e^x}{\partial x} = e^x$, and $e^{\log x} = x$, $x > 0$.

- **Q3 (25 pts):** Consider the activation function

$$f(v) = \begin{cases} 1 - e^{-v}, & v \geq 0, \\ -1 + e^{-|v|}, & v < 0. \end{cases}$$

For (a)-(c), consider a single-neuron network with input-output relationship $y = f(b + \mathbf{w}^T \mathbf{x})$, where y is the network output, b is the bias term, $\mathbf{w} = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}$ are the synaptic weights, and $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ is the network input.

- (3 pts):** Calculate the derivative $f'(v)$ in closed form.
- (7 pts):** Let $E = (d - y)^2$, where d is a constant (a generic desired output). Find the delta-learning rule (the gradient-descent update equations) for b, w_1, w_2 given learning parameter $\eta = \frac{1}{2}$. Remember that you can write a single (vectorized) update equation that can handle all variables. The final update expression(s) may however contain only the terms/functions $d, y, f', f, \mathbf{w}, w_1, w_2, b$.
- (6 pts):** Consider the same delta-learning setup as in (b). Consider the training vectors $\mathbf{x}_1 = \begin{bmatrix} \log 2 \\ \log 3 \end{bmatrix}$, $\mathbf{x}_2 = \begin{bmatrix} 0 \\ \log 2 \end{bmatrix}$, with desired outputs $d_1 = \frac{2}{3}$, $d_2 = \frac{5}{2}$, respectively. Find the updated bias and the updated synaptic weights after one epoch of online learning given initial conditions $b = 0$, $\mathbf{w} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$.
- (9 pts)** Consider now a multi-layer network as shown below.



Let $E = e^{(d-y)^4}$. Find the gradient-descent update equations for b, w_1, w_2, w_3 given learning parameter $\eta = \frac{1}{4}$. The final expression may only contain the terms/functions $d, y, f', f, \mathbf{w}, w_1, w_2, b, w_3$.

Hint: You do not have to apply some algorithm. Just write the input-output relationship of the network, and use chain rule. This is more of a calculus problem than a neural network problem!

- **Q4 (25 pts):** Design a (possibly multi-layer) neural network with two inputs $x_1, x_2 \in \mathbb{R}$ and a single output y such that $y = 1$ if $x_1 = 3$ and $x_2 = 2$, and $y = 0$, otherwise. In other words, the network output should assume a value of 1 only at the single point $(x_1, x_2) = (3, 2)$ of the input space \mathbb{R}^2 . Note that the inputs can be any real numbers. The neuron(s) of the network should use the step-activation function $u : \mathbb{R} \rightarrow \{0, 1\}$ given by $u(v) = 1$ if $v \geq 0$, and $u(v) = 0$, otherwise. The network should consist of **5 neurons at most**. Spoilers and their partial credits:

- (a) **(3 pts):** Design a network with input x_1 and output y such that $y = 1$ if $x_1 \geq 3$, and $y = 0$, otherwise.
- (b) **(4 pts):** Design a network with input x_1 and output y such that $y = 1$ if $x_1 \leq 3$, and $y = 0$, otherwise.
- (c) **(6 pts):** Design a network with input x_1 and output y such that $y = 1$ if $x_1 = 3$, and $y = 0$, otherwise.
- (d) **(6 pts):** Solve the original problem without any restrictions on the number of neurons.
- (e) **(6 pts):** Solve the original problem.

You are not required to do (a)-(d) provided you can provide a correct solution to (e).