This code implements a **simplified protocol** to allow managing Arduino Uno R3 I/O from whatever *platform* capable to manage UART data flow, including Raspberry PI or your laptop.

Arduino I/O is controlld by means of a set of commands sent to Arduino through its UART interface.

I2C (TWI) and SPI are not (yet) supported.

# SET UP

To prepare Arduino please download the sketch serPiArduino2.ino on Arduino.

Connect Arduino’s UART pins and power it on (or simply connect USB port).

On the *platform* you want to use to manage Arduino, connect UART (by cross-wiring RX and TX and connecting GND) pins or simply connect USB cable.

## THE “PROTOCOL”

The simplified protocol provides a master/slave mechanism where Arduino is slave and your platform is master.

The protocol commands (from Master *platform* to Arduino) have all the following frame structure:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| 0xF7  START BYTE  (1 byte) | COMMAND  (1 byte) | PIN  Number  (1 byte) | VALUE  (2 bytes) | CRC (mod 256)  (1 byte) | 0xF6  END BYTE  (1 byte) |

CRC is evaluated by simply adding bytes from COMMAND up to VALUE fields. (0xF7 start character is not taken into account) and evaluating mod(2^8) (the remainder of the division).

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Arduino will answer the received command with:

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| 0xF7  START BYTE  (1 byte) | COMMAND ANSWER  (1 byte) | PIN  Number  (1 byte) | VALUE  (2 bytes) | Error Code  (1 byte) | CRC (mod 256)  (1 byte) | 0xF8  END BYTE  (1 byte) |

CRC is evaluated by simply adding bytes from COMMAND ANSWER up to “ERROR CODE” fields. (0xF7 start character is not taken into account) and evaluating mod(2^8) (the remainder of the division).

### COMMANDS

These are the implemented COMMANDS:

* 0x01 READ PIN VALUE,
* 0x02 WRITE PIN VALUE,
* 0x03 SET PIN MODE,
* 0x04 GET PIN MODE

### COMMANDS ANSWERS

Arduino will answer (acknowledge) the received commands by issuing these answers:

* 0x31 PIN VALUE READ,
* 0x32 PIN VALUE WRITEN,
* 0x33 PIN MODE SET,
* 0x34 GET PIN MODE ANSWER

PIN number are AS FOLLOWS:

* Digital I/Os from **0** (Rx) up to **13** (the “debug” built-in led) are referenced with their PIN number on Arduino connector (i.e from 0 to 13)
* Analog from **A0** up to **A5** are referenced with 16 (0x10) up to 21 (0x15).

### THE “VALUE” FIELD

VALUE field is a 2 bytes field with these meaning according to considered command/answers:

|  |  |  |
| --- | --- | --- |
| COMMAND | VALUE FIELD (HIGH BYTE) | VALUE FIELD (LOW BYTE) |
| 0x01 READ PIN VALUE | Dummy byte | Dummy byte |
| 0x02 WRITE PIN VALUE | HIGH BYTE VALUE TO WRITE | LOW BYTE VALUE TO WRITE |
| 0x03 SET PIN MODE | HIGH BYTE MODE TO SET (0x00) | LOW BYTE MODE TO SET (see legend) |
| 0x04 GET PIN MODE | Dummy byte | Dummy byte |

Value in answer messages from Arduino are coded as follows:

| ANSWER | VALUE FIELD (HIGH BYTE) | VALUE FIELD (LOW BYTE) |
| --- | --- | --- |
| 0x31 PIN READ VALUE | Read value High Byte | Read value Low Byte |
| 0x32 PIN WRITEN VALUE | Written value High Byte | Written value Low Byte |
| 0x33 PIN MODE SET | HIGH BYTE MODE SET (0x00) | LOW BYTE MODE SET (see Table 1) |
| 0x34 GET PIN MODE ANSWER | HIGH BYTE CURRENT SET MODE (0x00) | LOW BYTE CURRENT SET MODE (see Table 1) |

These are the possible values for **MODE** field:

Table – Admissible MODE field values

|  |  |
| --- | --- |
| MODE FIELD VALUE | MEANING |
| 0x00 | Digital Input |
| 0x01 | Digital Input Pull-Up |
| 0x02 | Digital Output |
| 0x03 | Digital Output PWM |
| 0x04 | Analogue Input |

These are the possible values for **ERROR CODE** field:

Table - Error Code values

|  |  |
| --- | --- |
| ERROR CODE FIELD VALUE | MEANING |
| 0x00 =0 | OK (No Error) |
| 0xE1 =225 | Invalid CRC |
| 0xE2 =226 | Required WRITE operation on Input or Required READ on output |
| 0xE3 = 227 | No valid mode for PIN number |
| 0xE4 = 228 | Not valid PIN number |
| 0xE5 = 229e | Not valid MODE code |
| 0xE6 = 230 | Not valid COMMAND code |

### THE PHYTON PROGRAM

The Arduino code comes with an example program written in Python (currently) providing you with a textual interface.

You can use this code to get familiar with the functionalities offered by the program running on Arduino (the protocol).

Python code is made up of three code files and one configuration file:

* **interfaccia\_Arduino.py**: this is the main program you have to run
* **lib\_Arduino\_Funcs.py**: this implements all the functions to generate and decode the messages to be exchanged with Arduino
* **lib\_menu.py**: this provide a function to generate and manage textual menus, used throughout main application and protocol interface functions
* **config\_IfArduino.txt**: this is a configuration file used to set-up serial communication on your platform. This file considers these fields:
  + ***baudrate*** (set the baud rate to use – if no value is specified it defaults to 57200 bps)
  + ***useDefaultUART***, with these possible values:
    - Yes: this tells the python Application to read the vale in the next config file row (default\_UART) and use this as the serial port to use
    - No: Ignore the value written in the default\_UART config file row
  + ***default\_UART***: this field specifies the path to the serial port:
    - *in windows this is tipically indicated as “COMXY” (e*.g. COM31)
    - *in linux this is tipically indicated as “/dev/ttyXXX” (e*.g. /dev/ACM0)
  + **Autofind** with these possible values:
    - Yes: this tells the python Application to try to identify the serial port where Arduino is connected and use this serial port (this value takes the precedence on the value written in ***useDefaultUART***).

If no auto-found port is available and no default serial port is specified, then a menu is displayed to ask the user to manually enter the serial port, by chosing between the identified serial ports.

**NOTE:** The python program, on Linux platforms, provides you with the option to select ‘/dev/ttyS0’ serial port, which is in fact available only on the Raspberry PI.

**NOTE:** If you want to change data rate, you should set the same value on both Arduino (by changing the relvant line in SerPiArduino2.ino program) and the configuration file. In this case you have to edit this line in SerPiArduino2.ino:

*Serial.begin(****9600****);*

And, in the configuration file:

*baudrate= 9600*