

Illumination Correction Techniques

Submitted By

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2013EET2369

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Motivation of Project

- Removal of uneven and non-uniform illumination caused by several factors.
- Illumination correction is based on background subtraction.
- scene is composed of an homogeneous background and relatively small objects brighter or darker than the background.
- visual quality can further be improved by using image enhancement techniques

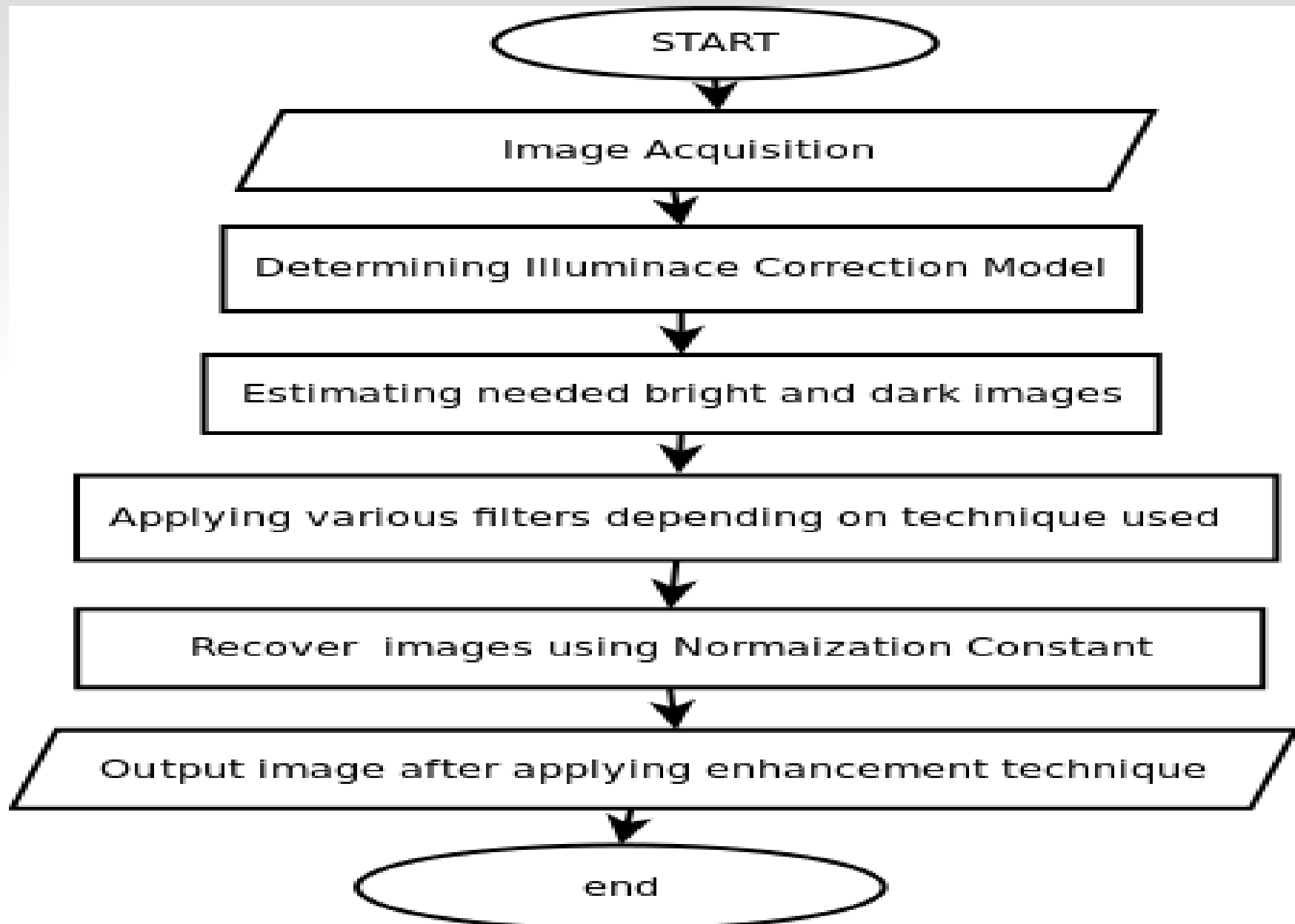
Noises in Image

- Image noise is random variation of brightness or color information.
- Types Of Noises
 - 1- Gaussian Noise
 - 2- Shot Noise
 - 3- Anisotropic Noise
 - 4- Quantization Noise (Uniform Noise)

Illumination Correction Techniques

- Prospective correction - uses additional images obtained at the time of image capture
- retrospective correction - When additional image are not available, model has to estimate the bright image

Project Flow



Prospective Correction

- Correction from a Dark Image and a Bright Image
- Correction from a Bright Image.
- Correction from a Dark Image

• Correction from a Dark and a Bright Image

- The corrected image $g(x,y)$ is obtained using the following transformation:

$$g(x,y) = \frac{f(x,y) - d(x,y)}{b(x,y) - d(x,y)} \cdot C$$

- where $f(x,y)$ is the original image, $d(x,y)$ is the dark image, $b(x,y)$ is the bright image, and C is a

$$C = \frac{\text{mean}(f(x,y))}{\text{mean}\left(\frac{f(x,y) - d(x,y)}{b(x,y) - d(x,y)}\right)} \cdot \frac{1}{\text{mean}(f(x,y))}$$

normalization constant used to recover the original colors.

- where $\text{mean}(i(x,y))$ is the mean value of the image $i(x,y)$.

Correction from a Bright Image

- In case of a linear acquisition device, the corrected image $g(x,y)$ is obtained using the following transformation:

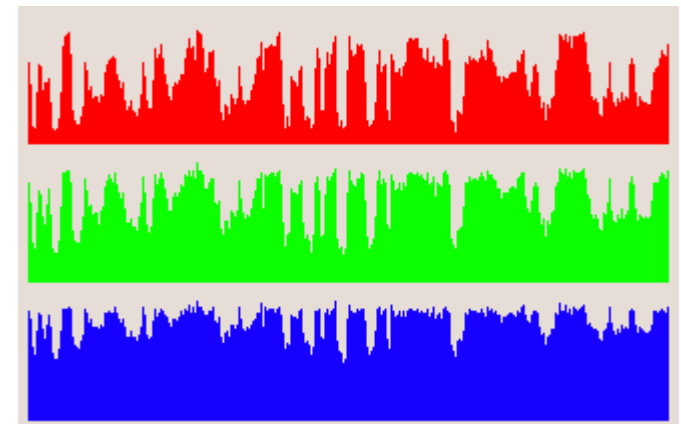
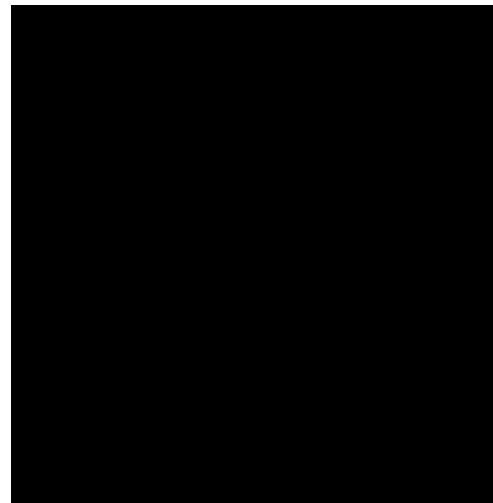
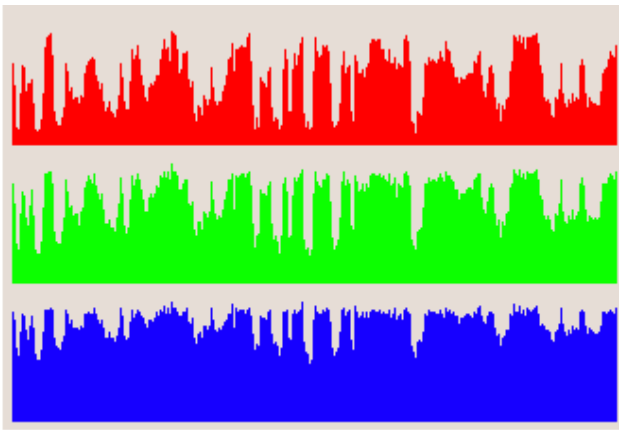
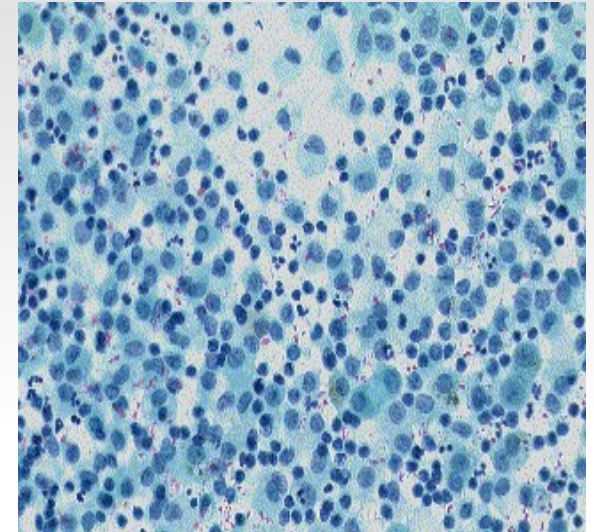
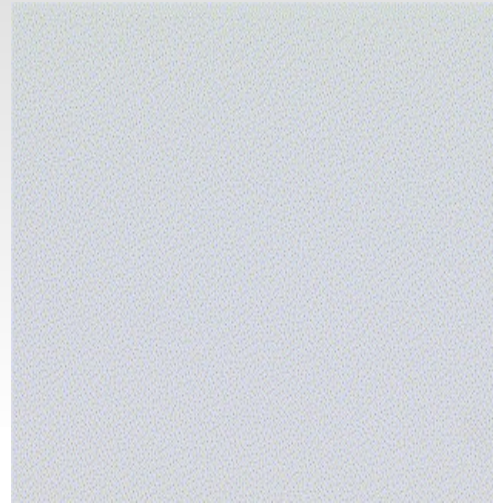
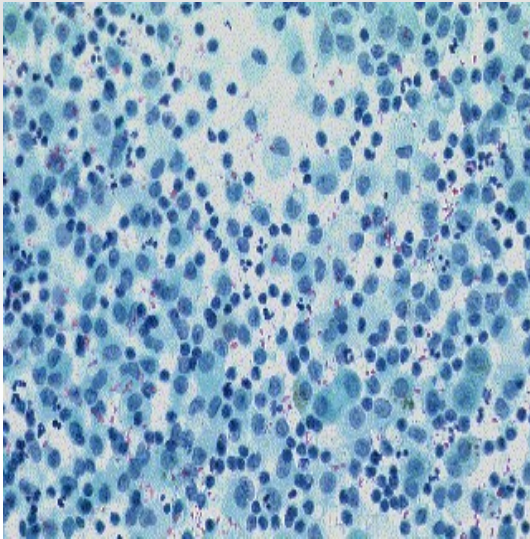
$$g(x,y) = \frac{f(x,y)}{b(x,y)} \cdot C$$

- where $f(x,y)$ is the original image, $b(x,y)$ is the bright image, and C is a normalization constant that is used to recover the initial colors:

$$C = \frac{\text{mean}(f(x,y))}{\text{mean}\left(\frac{f(x,y)}{b(x,y)}\right)}$$

where $\text{mean}(i(x,y))$ is the mean value of the image $i(x,y)$.

- **Correction from a Dark and a Bright Image**



Correction from a Dark Image

- If only the dark image is available, the method consists in subtraction of the dark image with the original image.
- The corrected image $g(x,y)$ is then obtained using the following transformation:
- $g(x,y) = f(x,y) - d(x,y) + \text{mean}(d(x,y))$
- where $f(x,y)$ is the original image, $d(x,y)$ is the dark image and $\text{mean}(d(x,y))$ is the mean value of the dark image.

Retrospective Correction

- using Low-pass Filtering
- using Homomorphic Filtering
- using Morphological Filtering

Retrospective Correction using Low-pass Filtering

- Estimate background image by using a low-pass filtering with a very large kernel and subtract from input image to compensate the illumination.
- The corrected image $g(x,y)$ is obtained from the input image $f(x,y)$ by:
- $$g(x,y) = f(x,y) - \text{LPF}(f(x,y)) + \text{mean}(\text{LPF}(f(x,y)))$$

where $\text{LPF}(f(x,y))$ is the low-pass filtering of image $f(x,y)$, and $\text{mean}(\text{LPF}(f(x,y)))$ is the mean value of the low pass image.

Retrospective Correction using Homomorphic Filtering

- The background is removed by highpass filtering the logarithm of the image and then taking the exponent (inverse logarithm) to restore the image.
- The corrected image $g(x,y)$ is obtained from the input image $f(x,y)$ by:
- $g(x,y) = \exp(\text{LPF}(\log(f(x,y)))) \cdot C$

$$C = \frac{\text{mean}(f(x,y))}{\text{mean}\left(\frac{f(x,y)}{\exp(\text{LPF}(\log(f(x,y))))}\right)}$$

Retrospective Correction using Morphological Filtering

- Estimate background by mathematical morphology opening or closing.
- The total sequence of operations corresponds to a top hat of the image.
- If the background is clear, the corrected image $g(x,y)$ is obtained using:
- $g(x,y) = \text{BTH}[f(x,y)] + \text{mean}(\text{closing}(f(x,y)))$
- $g(x,y) = [f(x,y) - \text{closing}(f(x,y))] + \text{mean}(\text{closing}(f(x,y)))$

Image after correction

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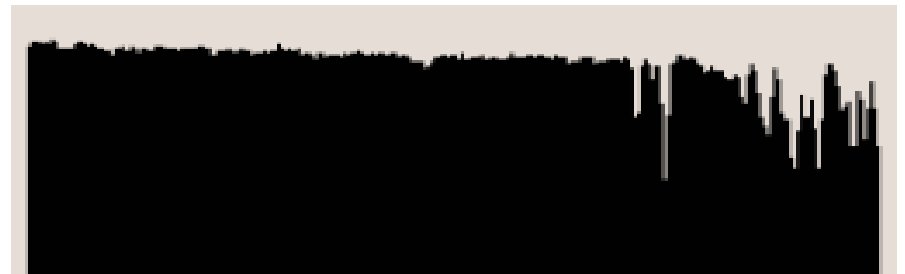
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Comparision Of various Methods

TABLE I. PSNR COMPARISON

No	Value PSNR		
	PSNR	<i>min</i>	<i>max</i>
1	Correction from a Bright Image and Dark Image	48	50
2	<i>Correction from Bright Image</i>	13	20
3	<i>Correction from Dark Image</i>	60	63
4	<i>Retrospective Correction using Low-pass Filtering</i>	20	25
5	Retrospective Correction using Homomorphic Filtering	16	20
6	Retrospective Correction using Morphological Filtering	3	10

Future Work

- Visual quality of images can further be improved by using image enhancement techniques.
- Above method can be used for increasing efficiency of character recognition from textual images.
- Above techniques can also be used in retinal and MRI scan images to remove illumination.

THANK YOU