Image Segmentation

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Introduction

In this presentation, I will describe:

• How to use OpenCV to segment an image.

Requirements

To follow along with this tutorial, you will need the following tools:

- Python 3.8.6.
- Visual Studio Code 1.53.1.

You will also need to install the following Python packages:

- OpenCV.
- NumPy.

It is assumed that you are using Windows; however, these instructions should be easily adapted to Linux.

Getting Started

Open Visual Studio Code. To open the app: Open the Start menu, type Visual Studio Code, and then select the app.

Open the Explorer tab. To display the tab: Left click View > Explorer or press ctrl + Shift + E. This will display the Explorer tab.

Left click on the Open Folder button. This will display the Open Folder prompt. Browse to the following directory:

C:/Users/%USER%/Documents

Note: Replace %USER% with your own username. My username is fknoble; hence, the path is C:/Users/fknoble/Documents.

In C:/Users/%USER%/Documents create a new folder named opencv_07. To create a new folder: Right click in the Explorer tab, left click New Folder, and rename it.

In C:/Users/%USER%/Documents/opencv_07 create a new folder named data. Download apples.PNG from here; save it in C:/Users/%USER%/Documents/opencv_07/data.

In C:/Users/%USER%/Documents/opencv_07 create new files named threshold.py and kmeans.py. To create a new file: Right click on /opencv_07 in the Explorer tab, left click New File, and rename it. The file will open automatically.

/opencv_07 should contain the following files and folders:

```
/opencv_07
   /data
      apples.PNG
    threshold.py
    kmeans.py
```

threshold.py

Type the following code into threshold.py:

```
import cv2 as cv
import numpy as np
import matplotlib.pyplot as plt
```

OpenCV's Python module cv2 is imported as cv; NumPy's Python module numpy is imported as np; and Matplotlib's PyPlot Python module is imported as plt.

```
def main():
    img = cv.imread('data/apples.PNG')
    if img is None:
        print('ERROR::CV::Could not read image.')
        return 1
```

This begins main() 's definition. imread() reads an image from a directory and assigns the results to array img. If the array is empty, a message is displayed and main() returns 1.

```
rows, cols, channels = img.shape

rows = rows // 2
cols = cols // 2

img = cv.resize(img, (cols, rows))

cv.imshow('img', img)
cv.waitKey(1)
```

img 's shape is assigned to integers rows, cols, and channels. rows and cols are divided by 2 (rounded down) and the results assigned to themselves. resize() resizes img to shape cols x rows and the result is assigned to itself. The array is then displayed in the img window.



Figure: The img array.

```
img = cv.cvtColor(img, cv.COLOR_BGR2GRAY)

plt.hist(img.ravel(), 256, [0, 256])
plt.savefig("data/threshold_histogram.PNG")
plt.show()

thresholds = [0, 100, 150, 255]

result_img = np.zeros((rows, cols), dtype=np.uint8)
```

cvtColor() converts img to a grayscale image and assigns the results to img.

hist() plots the flattened array and saves it as threshold_histogram.PNG in /data. A list of pre-determined thresholds are assigned to array thresholds. zeros() creates an array of 0's and the results are assigned to array result_img.

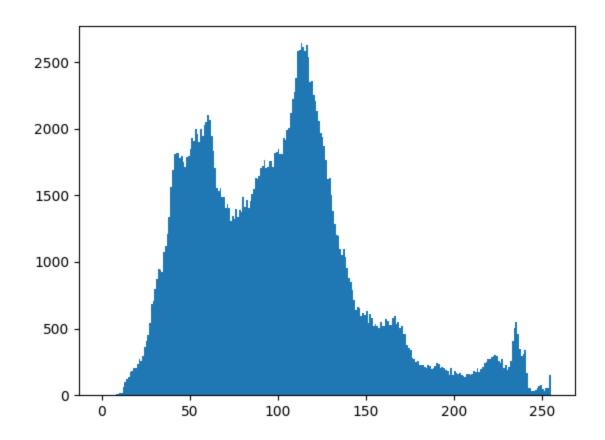


Figure: threshold_histogram.PNG. Here, troughs can be seen at ~100 and ~150.

```
for i in range(len(thresholds) - 1):
    thresholded_img = cv.inRange(img, thresholds[i], thresholds[i+1])
    thresholded_img = np.uint8(thresholded_img / 255) * thresholds[i + 1]
    cv.imshow("thresholded_img", thresholded_img)
    cv.waitKey(1)
    result_img = result_img + thresholded_img
```

inRange() segments img, identifying pixels between thresholds values and assigns
them to array thresholded_img. The array is displayed in the thresholded_img.
thresholded_img is added to result_img and assigned to result_img.

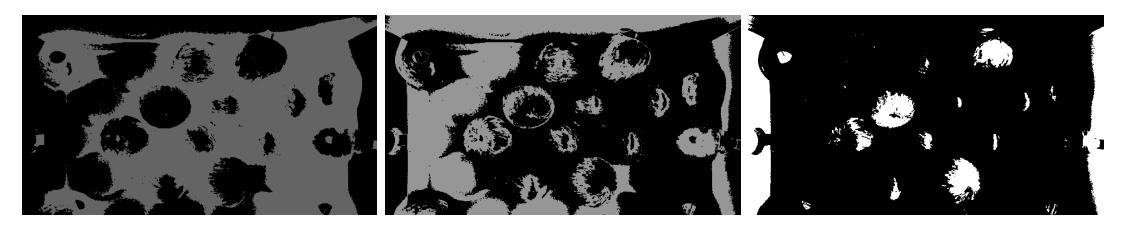


Figure: (Left) The thresholded_img array with range (0, 99); (Middle) The thresholded_img array with range (100, 149); and (Right) The thresholded_img array with range (150, 255).

```
cv.imshow("result_img", result_img)
cv.waitKey(0)
cv.imwrite("data/result_img.PNG", result_img)

cv.destroyAllWindows()
return
```

result_img is displayed in the result_img window and saved as result_img.PNG in /data.

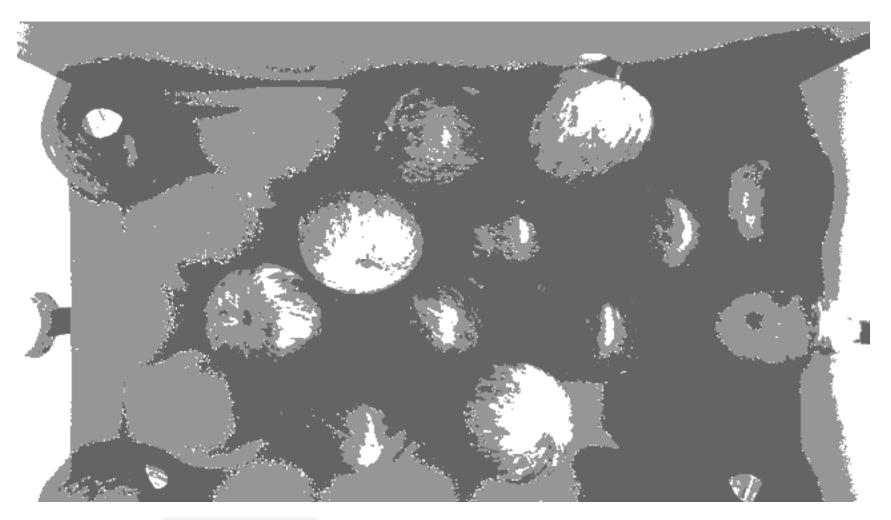


Figure: The result_img array.

```
if __name__ == '__main__':
    main()
```

main() will be called when the threshold.py is run.

Run threshold.py

Open a new terminal in Visual Studio Code. To open a new terminal: Left click View > Terminal or press ctrl + \cdot.

Type the following commands into the terminal and then press ever after each one:

```
cd ./opencv_07
python threshold.py
```

This will change the current directory to the <code>/opencv_07</code> sub-directory and then run threshold.py .

Press any key to close the windows and stop threshold.py.

kmeans.py

Type the following code into kmeans.py:

```
import cv2 as cv
import numpy as np
```

OpenCV's Python module cv2 is imported as cv and NumPy's Python module numpy is imported as np .

```
def main():
    img = cv.imread('data/apples.PNG')
    if img is None:
        print('ERROR::CV::Could not read image.')
        return 1
```

This begins main() 's definition. imread() reads an image from a directory and assigns the results to array img. If the array is empty, a message is displayed and main() returns 1.

```
rows, cols, channels = img.shape

rows = rows // 2
cols = cols // 2

img = cv.resize(img, (cols, rows))

cv.imshow('img', img)
cv.waitKey(1)
```

img 's shape is assigned to integers rows, cols, and channels. rows and cols are divided by 2 (rounded down) and the results assigned to themselves. resize() resizes img to shape cols x rows and the result is assigned to itself. The array is then displayed in the img window.



Figure: The img array.

```
data = np.reshape(img, (-1, channels))
data = np.float32(data)

criteria = (cv.TERM_CRITERIA_EPS + cv.TERM_CRITERIA_MAX_ITER, 10, 1.0)
flags = cv.KMEANS_RANDOM_centreS
```

reshape() reshapes img and assigns the results to array data. float32() converts the array's data to float32. criteria is assigned the algorithm's termination criteria. flags is assigned how the algorithm's initial centres are taken.

```
for K in range(2, 14, 2):
    ret, label, centre = cv.kmeans(data, K, None, criteria, 10, flags)
    centre = np.uint8(centre)
```

```
quantised = centre[label.flatten()]
quantised = quantised.reshape((rows, cols, channels))

cv.imshow("quantised_{}".format(K), quantised)
    cv.waitKey(0)
    cv.imwrite("data/quantised_{}.PNG".format(K), quantised)

cv.destroyAllWindows()

return 0
```

kmeans() computes the compactness, labels, and centres of the data and assigns them to ret, label, and centre. uint8() converts centre 's data to uint8. reshape() reshapes centre and label into array quantised. The array is displayed in a window and saved in /data.

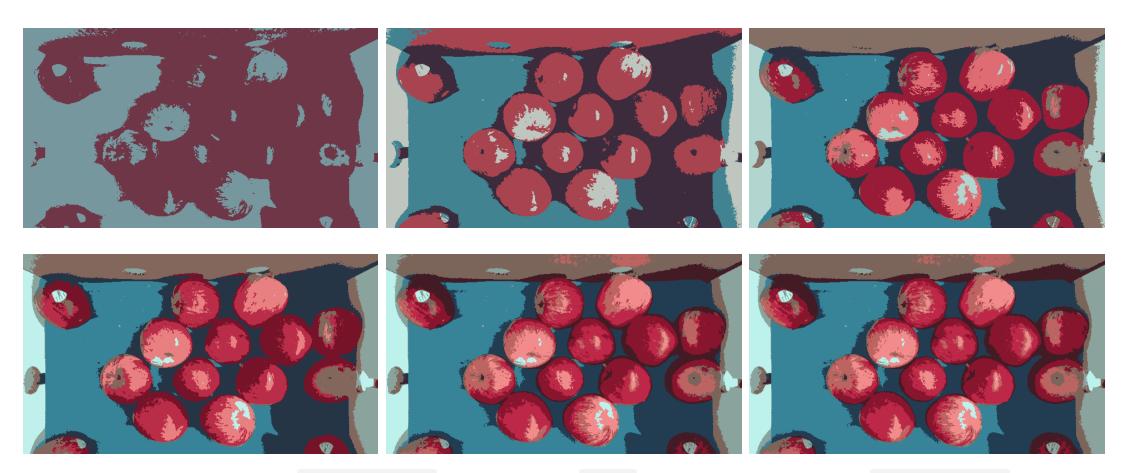


Figure: (Top Left) The quantised array with K=2; (Top Middle) the quantised array with K=4; (Top Left) the quantised array with K=6; (Bottom Left) the quantised array with K=8; (Bottom Middle); and (Bottom Right) the quantised array with K=10.

```
if __name__ == '__main__':
    main()
```

main() will be called when the kmeans.py is run.

Run kmeans.py

Open a new terminal in Visual Studio Code. To open a new terminal: Left click View > Terminal or press ctrl + \cdot.

Type the following commands into the terminal and then press ever after each one:

```
cd ./opencv_07
python kmeans.py
```

This will change the current directory to the <code>/opencv_07</code> sub-directory and then run <code>kmeans.py</code> .

Press any key to close the windows and stop kmeans.py.

Conclusion

In this presentation, I have described:

• How to use OpenCV to segment an image.

References

1. https://docs.opencv.org/.