

# What about **the Data**?

## Towards Continual Learning **in the Wild**



Ameya Prabhu

# Motivations for This Talk

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- Quite Experimental! Need feedback.

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- Quite Experimental! Need feedback.

## Backstory

- Gave my first broader talk recently at Computer Vision Talks
  - Title: "Computationally Budgeted Continual Learning"
  - Link: [drimpossible.github.io/talks\\_and\\_blogs/](https://drimpossible.github.io/talks_and_blogs/)
- Asked to elaborate on "How I Look at Problems?"
  - Me: "How Phil, Adel, Ozan/Vladlen, Anoop, Maneesh taught me"
  - This talk!

## My Thought Process

- [Methods] Beware: Complex Methods (5 mins)
- [Evaluation] Ask: Why Evaluate X? (15 mins)
- [Problem Setup] Target the Most Pressing Problems first.. (15 mins)

## My Thought Process

- **[Methods]** Beware: Complex Methods (5mins)
- [Evaluation] Ask Why Evaluate X?
- [Data] Target the Most Pressing Problems first..

## Part 1 [Brief]

# My Way of Thinking about Methods

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# Continual Learning **Research** as **Treatment Effects**

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- Come up with a **novel idea A**

# Continual Learning **Research** as **Treatment Effects**

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- Come up with a novel idea A
- **Add it** to a state-of-the-art pipeline P
- And **evaluate**



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- Write a paper => reviewers recognize how smart we are => publish

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^A **Large Fraction** of Continual Learning Papers

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- And it breaks!
- **Fix it** with **incremental** changes  $i1 + i2 + \dots$
- And Evaluate  $E(P + A + i1 + i2 + \dots) > E(P)$
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## The Problem

A was the **novel** idea! But **all performance increases** came from  $i1 + i2 + \dots$

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## The Problem

A was the novel idea! But all performance increases came from  $i1 + i2 + \dots$

**Solution:** **Ablate** A?

# Ablations Are **Not** Enough!

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The problem:

- We picked and tuned  $i_1 + i_2 + \dots$  to make  $P + A$  work
- Of course, when we remove  $A \Rightarrow$  Something **degrades**
- **Doesn't mean**  $A$  is needed!

Hence, my skepticism



# Preliminary Takeaways

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- Novelty is Overrated!
  - Be radically **more skeptical** of complex approaches: **Justify** extra burden!

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- Best Practices remain Stable!
  - Incremental "tricks" which generalize drive the field forward!

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  - Be radically more skeptical of complex systems: Justify extra burden!
- Best Practices remain Stable!
  - Incremental "tricks" which generalize drive the field forward!

So is simplicity better? Yes, but..  
We need to go one important step ahead

# Hypothesis **Testing**: Methods as **Interventions**

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Form **Hypothesis**, Give an **Intervention** to test it: Benchmark & See Results

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- GDumb (ECCV 2020):
  - Methods don't use online stream
  - Performance degrades! Test on longer time horizons, best: Reset (B2/B3)
- BudgetCL (CVPR 2023):
  - (i) Methods focus on memory rather than compute! Bad!

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- BudgetCL (CVPR 2023):
  - (i) Methods focus on memory rather than compute! Do they generalize?

Simplicity comes **for free**, as a by-product of a **focused** question

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## Excitement about Pre-Registration

- Pre-registration promising to encourage this style of research!
- Excited to see what happens in CLAI Unconference!

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Let's Extend this thinking to **Metrics** and **Data**..



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## Part 2

# My Way of Thinking about Metrics

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# Chronic **Over-Reporting** of Metrics

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## Case Study: Online Continual Learning

Report a whole bunch of metrics **E**:

- Avg. Accuracy **and** Forgetting **and** Anytime Accuracy **and** LP Accuracy  
.. and just say we are better!

Bad!

# Metrics as Measuring Progress on some Objective

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State an Objective, propose/use a metric to measures progress, Benchmark!

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Case Study: Online Continual Learning

**Objective**: I want to **rapidly adapt** to incoming data! (Goal of all online systems!)

# Metrics as Measuring Progress on some Objective

State an Objective, propose/use a metric which measures that, Benchmark!

Case Study: Online Continual Learning

Objective: I want to rapidly adapt to incoming data! (Goal of all online systems!)

Relooking metrics in online continual learning:

Avg. Accuracy **and** Forgetting **and** Anytime Accuracy **and** LP Accuracy

None of them measure rapid adaptation! They measure forgetting!

# Metrics as Measuring Progress on some Objective

State a Objective, propose/use a metric which measures that, Benchmark!

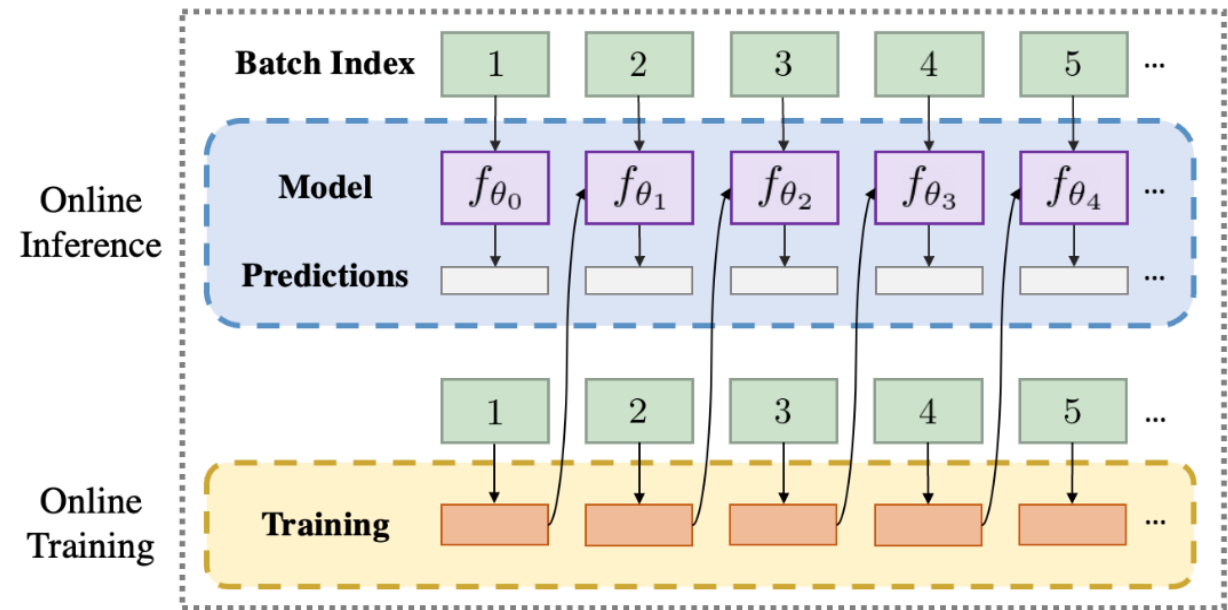
## Case Study: Online Continual Learning

Objective: I want to rapidly adapt to incoming data!

(Goal of all online systems!)

Trad. Online Learning uses Online accuracy

- Measure of the model's performance on the **next unseen** sample/batch.



Free from Memory Limits: Prabhu et. al., "Online Continual Learning Without the Storage Constraint" Arxiv.

With Memory Limits: "Real-Time Evaluation in Online Continual Learning: A New Hope" Ghunaim et al, CVPR23.



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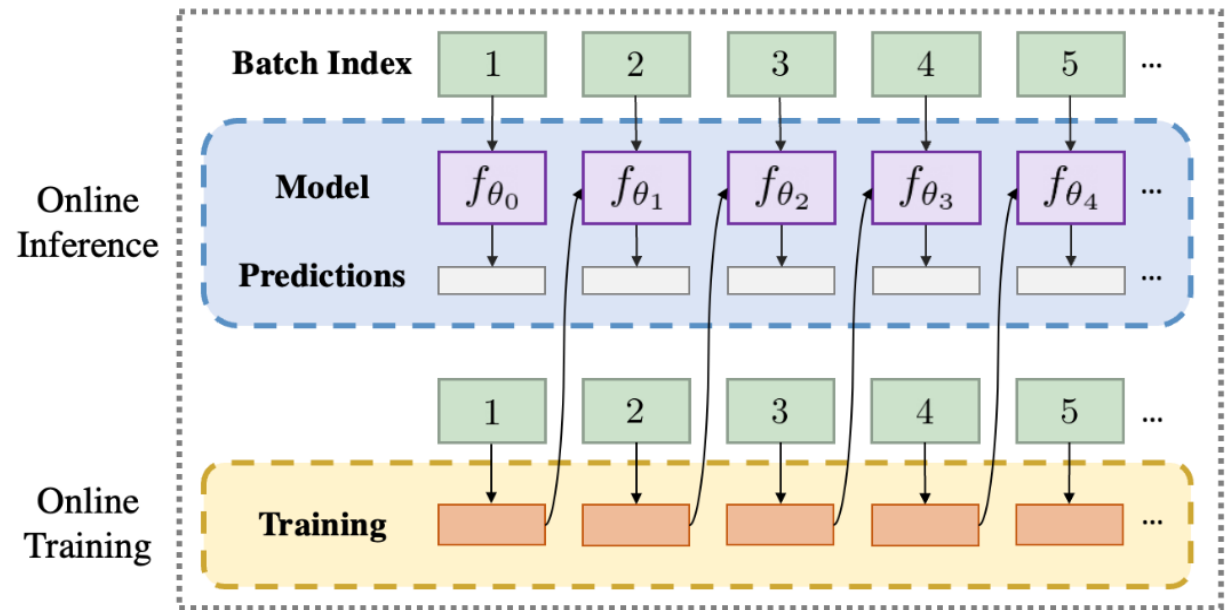
(Goal of all online systems!)

Trad. Online Learning uses Online accuracy

- Measure of the model's performance on the **next unseen** sample/batch.

**Impractical** in class-incremental OCL Setups!

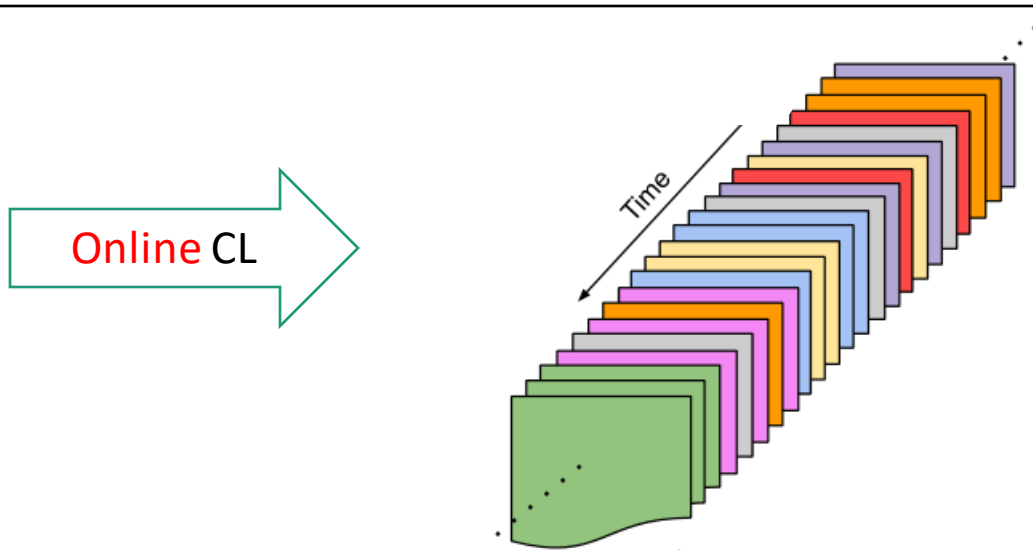
- Next samples are **by design** same class



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# Studying Data Streams: Measuring Adaptation



## Online accuracy

Measure of the model's performance on the next unseen sample/batch.

Hard to do in class-incremental setups

- Next samples are by design same class

## Better Datasets

### Continual geoLOCalization (Cai et. al., 2021)

- *Geolocation at scale*
- 713 classes, **39M images**
- Simulates images arriving on a [Flickr](#) server.

### Continual Google Land Marks V2 (Prabhu et. al., 2023)

- *Long-tailed landmark classification*
- **10,788 classes**, 450K images
- Simulates arrival on a [Wikimedia Commons](#) server.

Free from Memory Limits: Prabhu et. al., “Online Continual Learning Without the Storage Constraint” Arxiv.

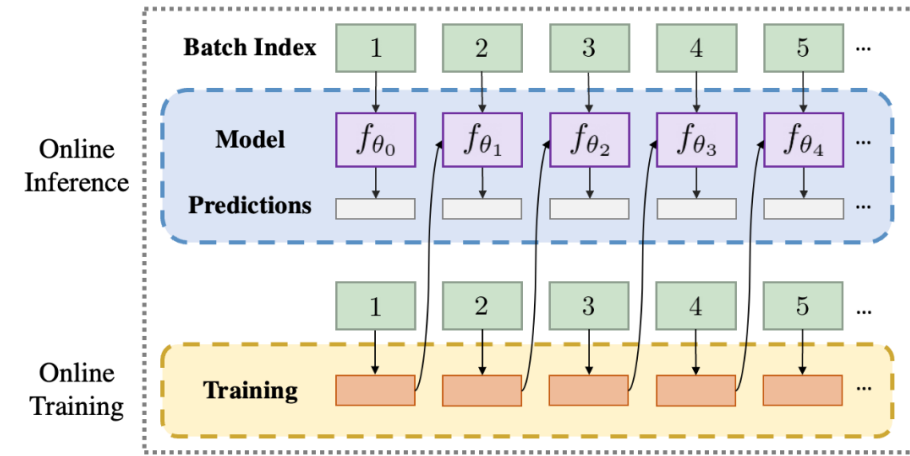
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# Insight: Metric Does not Evaluate Adaptation Well!

## Online accuracy

Measures model's performance on the next unseen sample/batch.

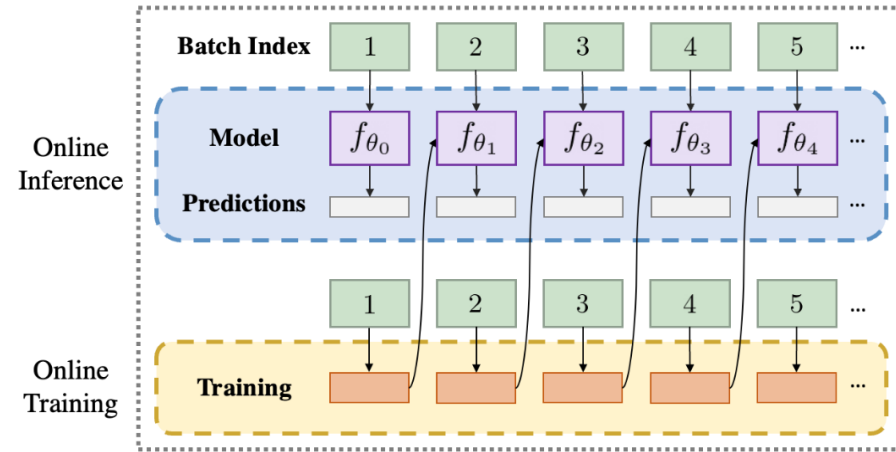
**Finding:** The stream labels are **correlated** in natural streams!



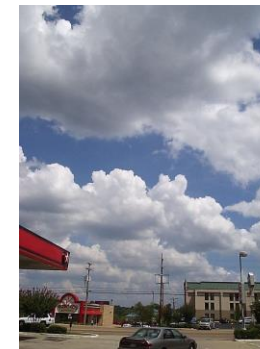
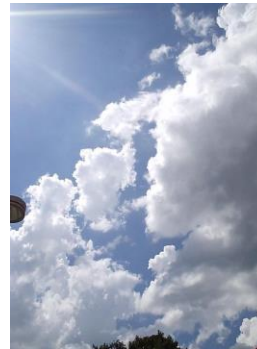
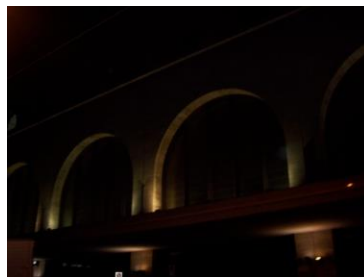
# Insight: Incorrect Evaluation of Adaptation

## Online accuracy

Measures model's performance on the next unseen sample/batch.



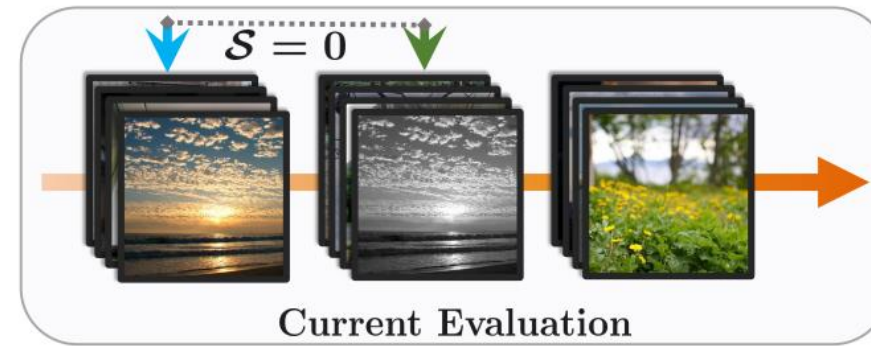
Let us look at Real CLOC Samples!



Same label !

# Insight+: Why are Correlated Samples Important?

**Finding:** The stream labels are **correlated** in natural streams!



Why is it important?

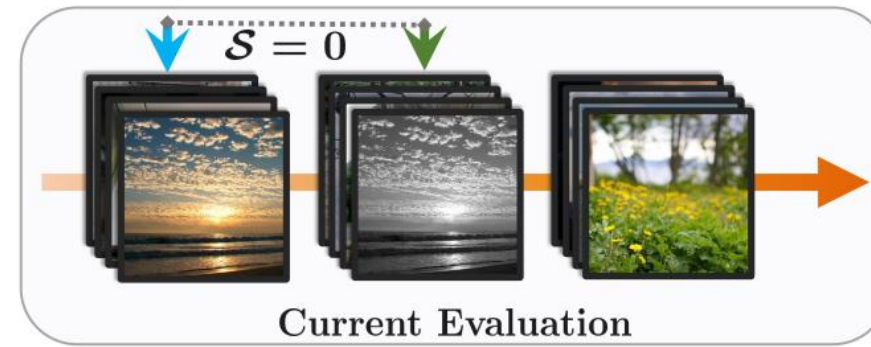
## A Blind Classifier

**Blind Classifier:** A model that predicts the mode of the last  $K$  samples seen without access to the input images.

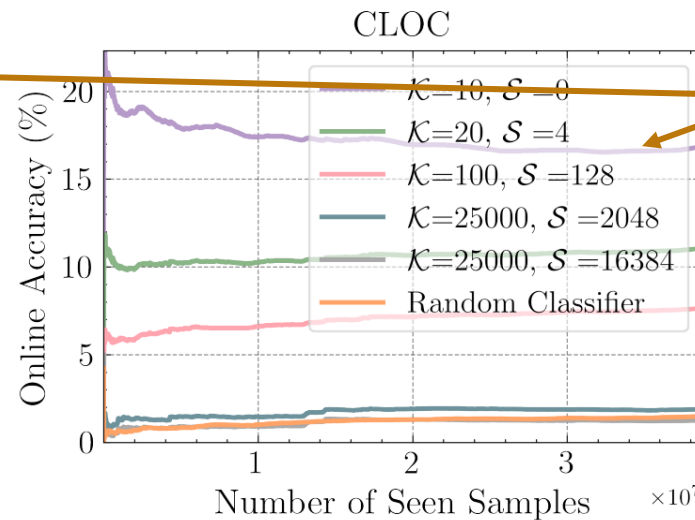
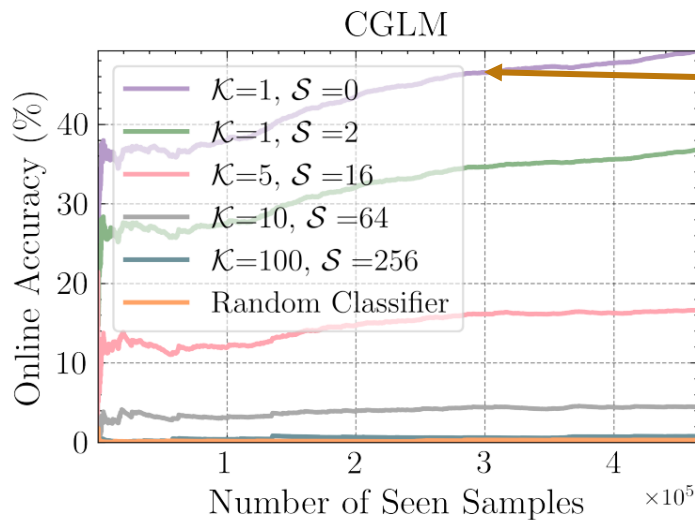
# Insight+: Why are Correlated Samples Important?

**Finding:** The stream labels are **correlated** in natural streams!

Why is it important?



## A Blind Classifier has Great Performance



*Competitive accuracies to OCL methods!*

*It's **unambiguously** a bad model!*

# OverAdapt: **Hacking** the Label Correlations

**Finding:** The stream labels are **correlated** in natural streams!

A Blind Classifier has Great Performance



OverAdapt: A simple and clearly **wrong** baseline!

A model made to overfit to the latest data by:

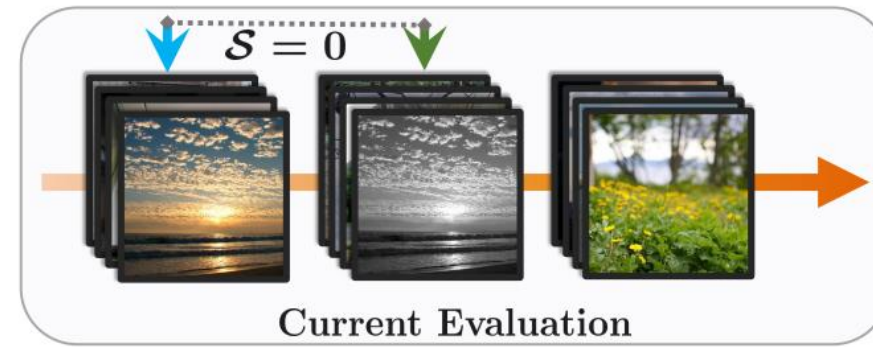
1. Adopting **FIFO sampling** to select training samples: The Bad Design Component in Cai et. al. 2021
2. Fix a pretrained ResNet50 backbone and train linear layer only



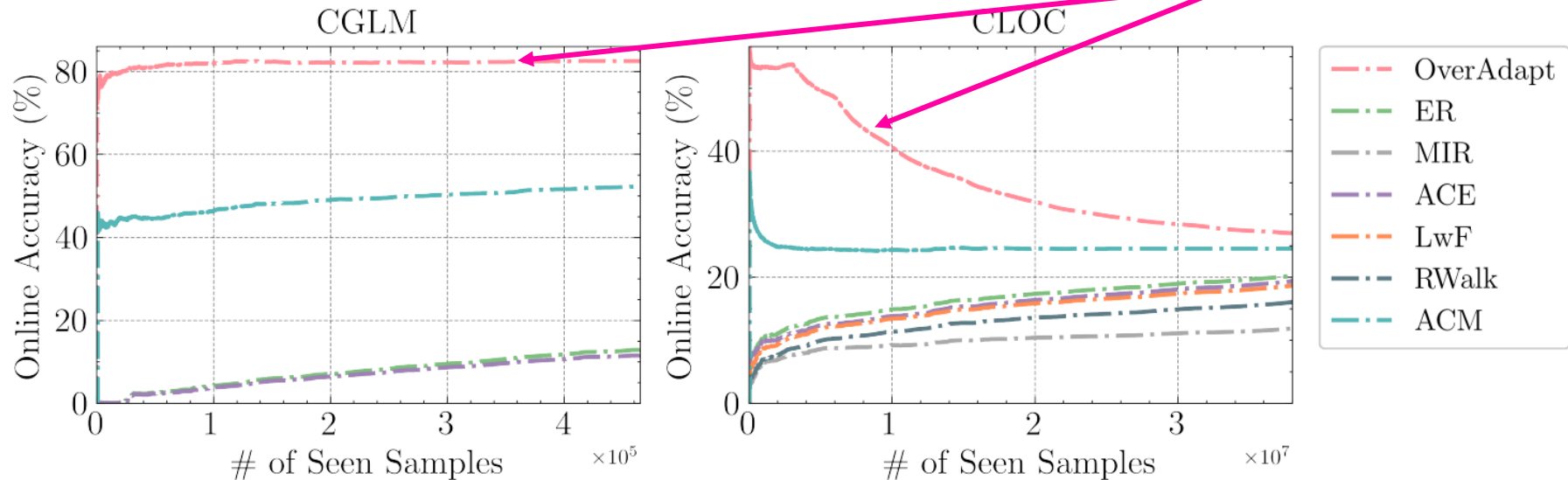
# OverAdapt: **Hacking** the Label Correlations

**Finding:** The stream labels are **correlated** in natural streams!

A Blind Classifier has Great Performance



- OverAdapt: A simple and clearly **wrong** baseline!



- Online Accuracy favours methods which **overfit to incoming data!**
- Incentivizes **bad** algorithms!



# Recent **Methods** which I think **Fall into this Trap**

**Finding:** The stream labels are **correlated** in natural streams!

A Blind Classifier has Great Performance



## Kalman Filter for Online Classification of Non-Stationary Data

**Michalis K. Titsias\***  
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Google DeepMind  
agalashov@google.com

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razp@google.com

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**Jörg Bornschein**  
Google DeepMind  
bornschein@google.com

CoLLAs 

[Conference Papers](#) [Journal Track Papers](#)

### Low-rank extended Kalman filtering for online learning of neural networks from streaming data

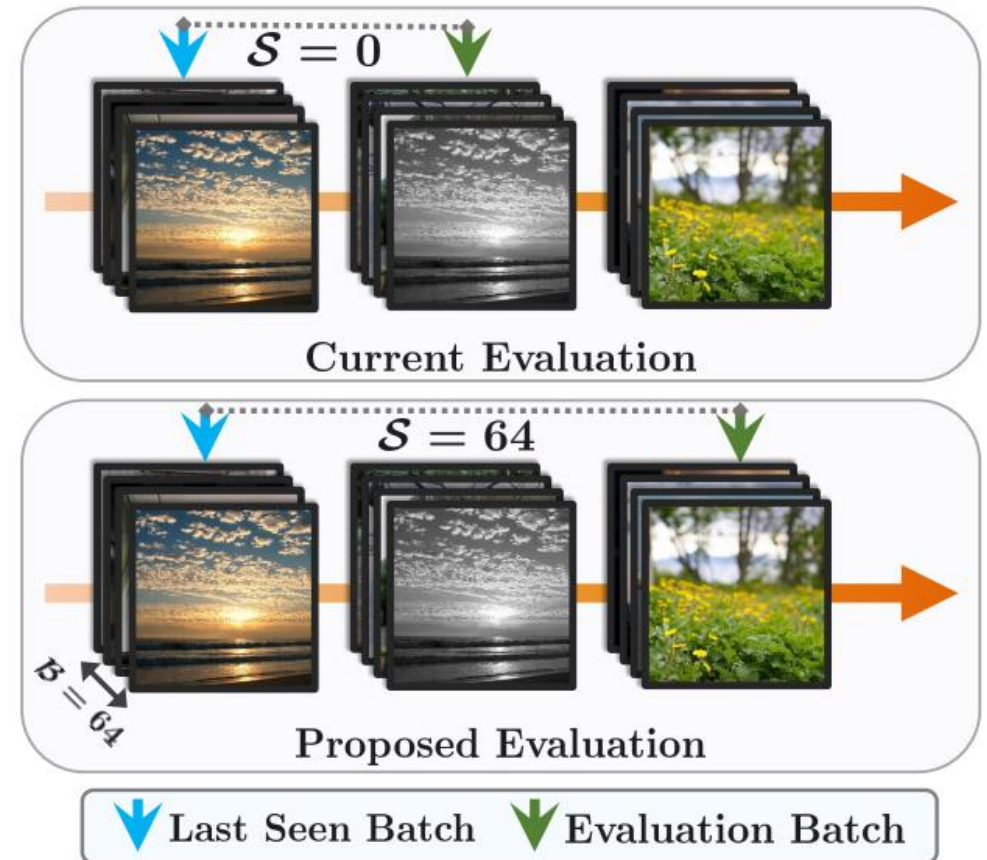
Peter G. Chang, Gerardo Durán-Martín, Alex Shestopaloff, Matt Jones, Kevin Patrick Murphy

Keywords: Bayesian inference, online learning, extended Kalman filter, deep neural networks, non-stationary distributions, continual learning

[Abstract](#) [Paper](#)

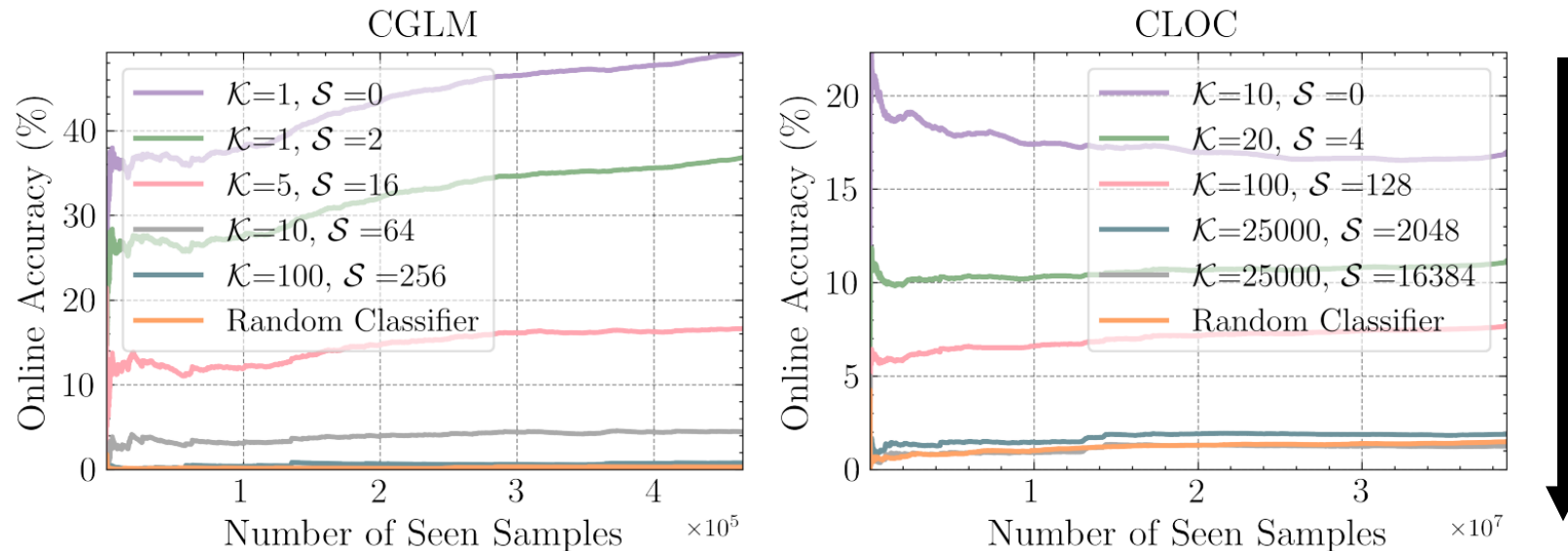
# Our Solution: Near-Future Accuracy

- Instead of measuring the accuracy on the immediate next batch how about we measure the accuracy on the next uncorrelated batch?
- **Question:** How do we estimate the batches to delay our evaluation with?



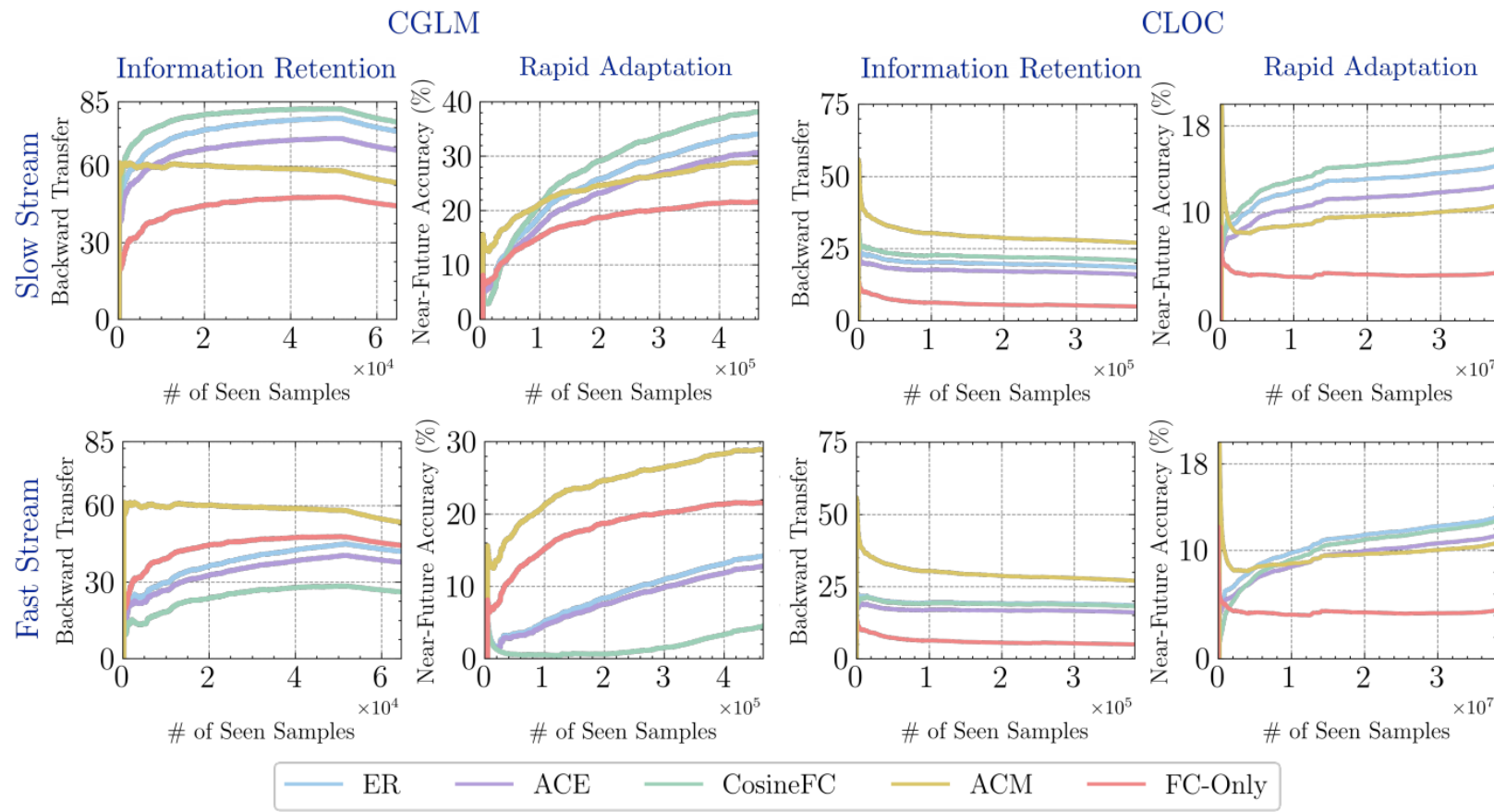
# Near-Future Accuracy: Blind Classifier to Rescue

- Question: How to estimate the batches to delay our evaluation with?



*Delay the Blind Classifier evaluation just until it **converges** to a random classifier!*

# Near-Future Accuracy: Benchmark



## My Thought Process

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- [**Problem Setup**] Target the **Most Pressing** Problems **First**.. (15 mins)

## Part 3

# My Approach about Deciding Problem Setup

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# Thinking About the Problem Setup

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Hypothesis testing frame hopefully clear by now!

# Thinking About the Problem Setup

Problem Setup: How to choose assumptions while formulating a problem?

Assumptions help simplify and contextualize hard problems which..

- Allows **principled** approaches, far faster than hit-and-try **grad student descent**!
  - This is for the empirical/applied folks in the audience



# Thinking About the Problem Setup

Problem Setup: How to choose assumptions while formulating a problem?

Assumptions help simplify and contextualize hard problems which

- Allows principled approaches, far faster than hit-and-try grad student descent!
  - This is for the empirical/applied folks in the audience
- Assumptions should reflect the real world
  - For the theoretical folks in the audience

# Thinking About the Problem Setup

Problem Setup: How to choose assumptions while formulating a problem?

Great to see continual **progression** towards more **realistic assumptions**!

- Task-increment => Class-increment => Blurry-boundaries => Time-incremental
- Small-scale => Large-scale
- No memory => Tiny-memory => Memory-limited => Memory-unconstrained

..while imposing computational constraints!

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A new dimension today: Where does **labeled** data come from?

# Studying Data Streams: Where is Training Data?

Continual Manual Annotation is costly and time-consuming — huge problem!

- CLEAR10 required \$4500 for 30K



# Alternate **Task**: Going from Categories to Classifier

---

Task: Go from Category List to Trained Classifier within minutes *continually*

1. The data stream,  $\mathcal{S}$ , presents a set of categories,  $\mathcal{Y}_t$ , to be learned.

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2. Under a given computational budget,  $\mathcal{C}_t$ , the classifier  $f_{\theta_{t-1}}$  is updated to  $f_{\theta_t}$ .



Can use any public data/model assistance to do this! E.g. GPT3, DALL-E, LAION5B

# Alternate **Task**: Going from Categories to Classifier

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2. Under a given computational budget,  $\mathcal{C}_t$ , the classifier  $f_{\theta_{t-1}}$  is updated to  $f_{\theta_t}$ .
3. To evaluate the learner, the stream  $\mathcal{S}$  presents test samples  $\{(\mathbf{x}_i, y_i)\}_{i=1}^n$  with  $y_i$  belonging to the collective set  $\bigcup_{i=1}^t \mathcal{Y}_i$ .

# How to Get Around **Manual** Data **Annotation**?

Manual Annotation



Stable Diffusion

 OpenAI  
**DALL-E**

Retrieval from Source



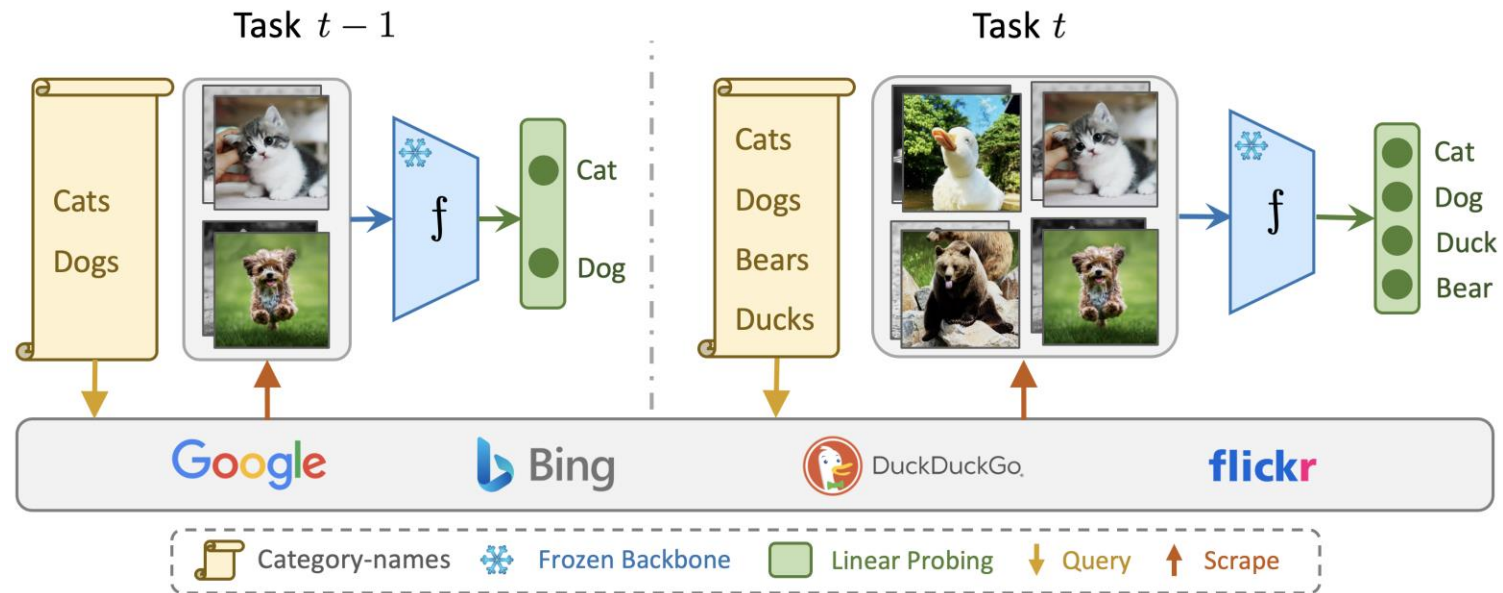
Internet: Billions of images uploaded **each day**

*Static* datasets are miniscule and out-of-date in comparison to the Internet!



# Internet as a Huge, Continually Evolving Train Set

Idea: Download data from searching the Internet! [Fergus, et.al. 2005]



=> Go from Category List to Trained Classifier within minutes *continually*!

# Internet as a Huge, Continually Evolving Train Set

Is it better than using Stable Diffusion or Retrieval From LAION5B?

Table 3: **Comparison with Name-Only Classification Techniques with ResNet50:** When comparing with existing state-of-the-art name-only classification techniques, we show that our method outperforms those methods by margins ranging from 2% to 25%.

Type	Method	Model	Birdsnap	Aircraft	Flowers	Pets	Cars	DTD	Better Prompts
Data-Free	CLIP-ZS (Radford et al., 2021)	CLIP	32.6	19.3	65.9	85.4	55.8	41.7	
	CaFo-ZS (Zhang et al., 2023)	CLIP	-	17.3	66.1	85.8	55.6	50.3	
	CALIP (Guo et al., 2023)	CLIP	-	17.8	66.4	86.2	56.3	42.4	
	CLIP-DN (Zhou et al., 2023)	CLIP	31.2	17.4	63.3	81.9	56.6	41.2	
	CuPL (Pratt et al., 2023)	CLIP	35.8	19.3	65.9	85.1	57.2	47.5	
	VisDesc (Menon & Vondrick, 2022)	CLIP	35.7	16.3	65.4	82.4	54.8	42.0	
	SD-Clf (Li et al., 2023a)	SD-2.0	-	26.4	66.3	87.3	-	-	
Use-Data	GLIDE-Syn (He et al., 2022)	CLIP	38.1	22.0	67.1	86.8	56.9	43.2	SD/ LAION
	CaFo (Zhang et al., 2023)	CLIP	-	21.1	66.5	87.5	58.5	50.2	
	SuS-X-LC (Udandarao et al., 2023)	CLIP	38.5	21.1	67.1	86.6	57.3	50.6	
	SuS-X-SD (Udandarao et al., 2023)	CLIP	37.1	19.5	67.7	85.3	57.2	49.2	
	C2C (Ours-Linear Probe)	CLIP	48.1 (+9.6)	44.0 (+22.0)	82.0 (+14.3)	88.1 (+0.6)	71.3 (+12.8)	57.1 (+6.5)	
	C2C (Ours-MLP Adapter)	CLIP	46.6 (+8.1)	48.9 (+26.9)	84.8 (+17.1)	89.4 (+1.9)	72.6 (+14.1)	57.6 (+7.0)	
	C2C (Ours-Linear Probe)	MocoV3	56.1 (+17.6)	57.5 (+35.5)	85.7 (+18.0)	91.7 (+4.2)	62.1 (+3.6)	54.6 (+4.0)	
	C2C (Ours-MLP Adapter)	MocoV3	53.7 (+15.2)	65.5 (+43.5)	87.1 (+19.4)	92.8 (+5.3)	66.8 (+8.3)	55.8 (+5.2)	

Using Internet is Vastly Better!

A dark, textured, ink-splattered background shape, resembling a large, irregular ink blot or a splash of paint, centered on a white background. The shape has a rough, organic edge with various shades of dark gray and black, and some lighter gray splatters extending outwards.

# Questions?

[Anonymous Feedback](https://admonymous.co/bayesiankitten)  
[admonymous.co/bayesiankitten](https://admonymous.co/bayesiankitten)