1 The Expectation of a Random Variable

Certain numbers associated with a random variable's distribution often provide a succinct way of summarizing the distribution. If only two numbers are used to describe a distribution, one is usually a measure of the *center* of the distribution and the second measures how *spread* out it is.

Numbers describing a distribution are commonly defined in terms of *expected values*.

1.1 Expectation of a Discrete RV

The expected value (or mean) of a discrete random variable X with pmf p_X is

$$E(X) = \mu_X = \sum_x x \, p_X(x),$$

where the sum extends over all x such that $p_X(x) > 0$.

Example 24 Expectation Number of Spots on Two Dice.

The number of spots on two dice has the following pmf:

The expected number of spots is

$$E(X) = 2\left(\frac{1}{36}\right) + 3\left(\frac{2}{36}\right) + \dots + 12\left(\frac{1}{36}\right)$$
$$= \frac{2}{36} + \frac{6}{36} + \dots + \frac{12}{36} = \frac{252}{36} = 7$$

Example 12 Again

x	0	1	2	3	4
P(X=x)	0.5	0.25	0.125	0.0625	0.0625

Then

$$E(X) = (0)(0.5) + (1)(0.25) + (2)(0.125) + (3)(0.0625) + (4)(0.0625)$$
$$= 0.9375.$$

Example 25 Expectation of a Poisson Random Variable. The rv X has a Poisson (λ) distribution if its pmf is

$$p_X(x) = \left\{ egin{array}{ll} rac{\lambda^x e^{-\lambda}}{x!}, & x=0,1,\ldots, \\ 0, & ext{otherwise,} \end{array}
ight.$$

where λ is a positive constant. Find E(X) when X has a Poisson (λ) distribution.

$$E(X) = \sum_{x=0}^{\infty} x \cdot \frac{\lambda^x e^{-\lambda}}{x!} = \sum_{x=1}^{\infty} x \cdot \frac{\lambda^x e^{-\lambda}}{x!}$$
$$= \lambda \sum_{x=1}^{\infty} \frac{\lambda^{x-1} e^{-\lambda}}{(x-1)!} = \lambda \sum_{y=0}^{\infty} \frac{\lambda^y e^{-\lambda}}{y!} = \lambda.$$

Remark: This example uses a common "trick" in finding expectations:

Try to factor a constant, C, out of the sum (or integral) so that the "new" summand (or integrand) becomes a pmf or pdf. Then we know that the sum (or integral) is 1, and the expectation is C.

Remark: An important observation is that *expectations need not exist.*

When X is discrete and takes on an infinite number of values, then the sum $\sum_x x \, p_X(x)$ may not exist or may not be finite.

Of course, if X takes on only finitely many values, then E(X) does exist and is finite.

Example 31 Expectation of a Binomial Random Variable A rv X has a binomial (n,θ) distribution if its pmf is

$$p_X(x) = \begin{cases} \binom{n}{x} \theta^x (1-\theta)^{n-x}, & x = 0, 1, \dots, n, \\ 0, & \text{otherwise,} \end{cases}$$

where $0 < \theta < 1$. Find E(X) when X has a binomial (n,θ) distribution.

$$E(X) = \sum_{x=0}^{n} x \cdot \binom{n}{x} \theta^{x} (1-\theta)^{n-x} = \sum_{x=1}^{n} x \cdot \frac{n!}{x!(n-x)!} \theta^{x} (1-\theta)^{n-x}$$
$$= n\theta \sum_{x=1}^{n} \frac{(n-1)!}{(x-1)!(n-x)!} \theta^{x-1} (1-\theta)^{n-x}.$$

Make the change of variable y=x-1 in the last sum to get

$$E(X) = n\theta \sum_{y=0}^{n-1} \frac{(n-1)!}{y!(n-1-y)!} \theta^y (1-\theta)^{n-1-y} = n\theta.$$

The last equality holds since we are summing the pmf of a binomial $(n-1,\theta)$ rv.

1.2 Expectation of a Continuous RV

When X is continuous with pdf f_X , the expected value (or mean) of X is

$$E(X) = \mu_X = \int_{-\infty}^{\infty} x f_X(x) dx.$$

When X is continuous and its density is positive only over an interval of finite length, then E(X) exists and is finite. Otherwise, there are cases where E(X) either doesn't exist or isn't finite.

Important intuition:

In both the discrete and continuous cases, the expected value of X (when it exists and is finite) has the interpretation that it is the *average value of* X in a large number of repetitions of the experiment.

 $\underline{\text{Example 26}}$ Example 26 Expectation of an uniform random variable. Suppose X has the uniform [L,R] distribution with pdf

$$f_X(x) = \frac{1}{R - L} I_{[L,R]}(x).$$

Then

$$E(X) = \int_{L}^{R} x \frac{1}{R - L} dx = \frac{1}{R - L} \frac{x^{2}}{2} \Big|_{L}^{R} = \frac{R^{2} - L^{2}}{2(R - L)} = \frac{L + R}{2}.$$

Example 27 Expectation of an exponential random variable. Suppose X has the exponential density

$$f_X(x) = \frac{1}{\lambda} e^{-x/\lambda} I_{(0,\infty)}.$$

Find the expected value of X.

$$E(X) = \int_0^\infty x \cdot \frac{1}{\lambda} e^{-x/\lambda} dx$$

$$= \int_0^\infty (\lambda y) \cdot \frac{1}{\lambda} e^{-y} d(\lambda y)$$

$$= \lambda \int_0^\infty y e^{-y} dy$$

$$= \lambda,$$

where the last step follows from Example 23 in Chapter 2. Why?

So, we have again used the trick described in Example 25.

1.3 Expectations of Functions of \boldsymbol{X}

Consider a random variable Y=g(X), and let p_Y or f_Y be the pmf or pdf of Y, respectively. According to the previous definition,

$$E(Y) = \begin{cases} \sum_{y} y \, p_Y(y), & \text{if } Y \text{ is discrete,} \\ \\ \int_{-\infty}^{\infty} y \, f_Y(y) \, dy, & \text{if } Y \text{ is continuous.} \end{cases}$$

One can prove (p. 134 and 144 of the text) that E[g(X)] can also be computed as follows:

$$E[g(X)] = \begin{cases} \sum_x g(x) \, p_X(x), & X \text{ discrete,} \\ \\ \int_{-\infty}^\infty g(x) \, f_X(x) \, dx, & X \text{ continuous.} \end{cases}$$

We may also be interested in the expectation of a function of several random variables. Consider the random variables X_1,\ldots,X_n and the function $Y=g(X_1,\ldots,X_n)$. If X_1,\ldots,X_n are continuous random variables with joint pdf f, then

$$E(Y) = \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} g(x_1, \dots, x_n) f(x_1, \dots, x_n) dx_1 \cdots dx_n.$$

If X_1, \ldots, X_n are discrete random variables with joint pmf p, then

$$E(Y) = \sum_{x_1} \cdots \sum_{x_n} g(x_1, \dots, x_n) p(x_1, \dots, x_n).$$

Example 27 Expectation of a Function of a Poisson RV

Let X have the Poisson distribution given in Example 25. Find the expected value of $g(X)=2^X$.

$$E(2^{X}) = \sum_{x=0}^{\infty} 2^{x} \cdot \frac{\lambda^{x} e^{-\lambda}}{x!} = \sum_{x=0}^{\infty} \frac{(2\lambda)^{x} e^{-\lambda}}{x!}$$
$$= \frac{e^{-\lambda}}{e^{-2\lambda}} \sum_{x=0}^{\infty} \frac{(2\lambda)^{x} e^{-2\lambda}}{x!} = e^{\lambda} \cdot 1 = e^{\lambda}.$$

Example 28 Expectation of a Function of a Bivariate RV

Let (X, Y) have the joint pdf

$$f(x,y) = 2, \ 0 < x < 1, \ 0 < y < 1, 0 < x + y < 1.$$

Find the expected value of g(X,Y) = XY.

$$E(XY) = \int_0^1 \int_0^{1-x} xy \, 2 \, dy \, dx = \int_0^1 2x \frac{y^2}{2} \Big|_0^{1-x} dx$$

$$= \int_0^1 x (1-x)^2 dx = \int_0^1 (x - 2x^2 + x^3) dx$$

$$= \left(\frac{x^2}{2} - 2\frac{x^3}{3} + \frac{x^4}{4}\right) \Big|_0^1 = \frac{1}{2} - \frac{2}{3} + \frac{1}{4} = \frac{1}{12}$$

2 Properties of expectations

2.1 Expectation of a linear function of \boldsymbol{X}

Let Y=aX+b, where a and b are constants. If E(X) exists, then

$$E(Y) = aE(X) + b.$$

Proof: Consider the continuous case.

$$E(Y) = \int_{-\infty}^{\infty} (ax+b)f_X(x) dx$$

$$= \int_{-\infty}^{\infty} ax f_X(x) dx + \int_{-\infty}^{\infty} b \cdot f_X(x) dx$$

$$= a \int_{-\infty}^{\infty} x f_X(x) dx + b \int_{-\infty}^{\infty} f_X(x) dx$$

$$= aE(X) + b.$$

Remark: If g(x) is a nonlinear function, $E(g(X)) \neq g(E(X))$ in most situations.

Example: In Example 25, we let X have a Poisson(λ) distribution and considered $g(X)=2^X$. We earlier showed that $E(X)=\lambda$. Thus,

$$E(g(X)) = E[2^X] = e^{\lambda} \neq 2^{\lambda} = g(E(X)).$$

2.2 Expectation of a sum of random variables

Let $Y=a+b_1X_1+b_2X_2+\cdots+b_nX_n$ and assume that $E(X_i)$ exists, $i=1,\ldots,n.$ Then

$$E(Y) = a + b_1 E(X_1) + \dots + b_n E(X_n).$$

This result is easily proven in the continuous case using the fact that the integral of a sum is the sum of integrals.

2.3 Expectation of a product of independent random variables

Suppose that X_1, \ldots, X_n are independent random variables, and let h_1, \ldots, h_n be functions such that $E[h_i(X_i)]$ exists, $i=1,\ldots,n$. Then

$$E\left[\prod_{i=1}^{n} h_i(X_i)\right] = \prod_{i=1}^{n} E[h_i(X_i)].$$

We'll prove this in the case where X_1, X_2 are continuous with joint pdf f.

Let f_i be the marginal pdf of X_i , i=1,2. Then by definition of independence,

$$f(x_1, x_2) = f_1(x_1) \times f_2(x_2).$$

By definition of expectation,

$$E[h_{1}(X_{1})h_{2}(X_{2})] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h_{1}(x_{1})h_{2}(x_{2})f(x_{1}, x_{2}) dx_{1}dx_{2}$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h_{1}(x_{1})h_{2}(x_{2})f_{1}(x_{1})f_{2}(x_{2})dx_{1}dx_{2}$$

$$= \int_{-\infty}^{\infty} h_{1}(x_{1})f_{1}(x_{1})dx_{1} \times \int_{-\infty}^{\infty} h_{2}(x_{2})f_{2}(x_{2})dx_{2}$$

$$= E[h_{1}(X_{1})] E[h_{2}(X_{2})].$$

Example 29 Let X_1 and X_2 be independent and identically distributed (i.i.d.) random variables, with each having a uniform distribution on the interval (L,R), where L>0. Determine $E(X_1/X_2^2)$.

Since X_1 and X_2 are independent,

$$E(X_1/X_2^2) = E(X_1)E(X_2^{-2})$$
$$= \frac{(L+R)}{2} \cdot E(X_2^{-2}).$$

Now,

$$E(X_2^{-2}) = \int_L^R x^{-2} (R - L)^{-1} dx$$
$$= \frac{-x^{-1}}{(R - L)} \Big|_L^R = \frac{1}{LR}.$$

Hence, $E(X_1/X_2^2) = (L+R)/(2LR)$.

2.4 Monotonicity of Expectation

Let X be a random variable where $P[X \ge 0] = 1$. Then

$$E(X) \ge 0.$$

We will show this in the discrete case. Let $R_X = \{x_1, x_2, ...\}$ be the set of values where P[X = x] > 0. Then $x_i \ge 0$ by assumption and

$$E(X) = \sum_{x \in R_X} x P[X = x] \ge 0$$

since each term in the sum is nonnegative.

Let X and Y be random variables where $X \leq Y$. Then

$$E(X) \leq E(Y)$$
.

Note: $X \leq Y$ means $X(s) \leq Y(s)$ for all $s \in \mathcal{S}$.

3 Variance of a Random Variable

Suppose X is a random variable such that $E(X)=\mu_X$ exists. The *variance* of X (if it exists) is defined to be

$$\sigma_X^2 = \text{Var}(X) = E[(X - \mu_X)^2].$$

The variance provides a simple way of summarizing the amount of *variability* or *dispersion* in the distribution of a rv. It is particularly nice for comparing two or more distributions.

The standard deviation of a random variable is defined by

$$\sigma_X = \sqrt{\operatorname{Var}(X)} = \sqrt{E[(X - \mu_X)^2]}.$$

The standard deviation of a random variable X is more often reported than the variance since standard deviation has the same units as X.

Example 24 again Variance of the Number of Spots on Two Dice.

The number of spots on two dice has the following pmf:

The variance and standard deviation of the number of spots are

$$E((X - \mu)^2) = (2 - 7)^2 \left(\frac{1}{36}\right) + (3 - 7)^2 \left(\frac{2}{36}\right) + \dots + (12 - 7)^2 \left(\frac{1}{36}\right)$$

$$= \frac{25}{36} + \frac{32}{36} + \dots + \frac{25}{36} = \frac{210}{36} = \frac{35}{6},$$

$$\sigma_X = \sqrt{\frac{35}{6}}.$$

Another Way of Finding the Variance

Let
$$Y = (X - 7)^2$$
. Then $\sigma^2 = E[(X - 7)^2] = E(Y)$.

We can use the pmf of Y to find E(Y). Using the fact that

$$p_Y(y) = P[Y = y] = P[(X - 7)^2 = y] = \sum_{\{x:(x - 7)^2 = y\}} p_X(x)$$

the pmf of Y is

Then

$$E(Y) = 0\left(\frac{6}{36}\right) + 1\left(\frac{10}{36}\right) + 4\left(\frac{8}{36}\right) + 9\left(\frac{6}{36}\right) + 16\left(\frac{4}{36}\right) + 25\left(\frac{2}{36}\right)$$
$$= \frac{210}{36} = \frac{35}{6}.$$

Example 26 Again Find the variance of a random variable X that is uniformly distributed over (L,R). We know that $\mu=(L+R)/2$.

$$Var(X) = \int_{L}^{R} (x - \mu)^{2} (R - L)^{-1} dx$$

$$= (R - L)^{-1} \int_{L}^{R} (x - \mu)^{2} d(x - \mu)$$

$$= \frac{1}{3(R - L)} (x - \mu)^{3} \Big|_{L}^{R}$$

$$= (R - L)^{2}/12.$$

The standard deviation of a uniform (R,L) rv is

$$\sigma = \frac{R - L}{2\sqrt{3}}.$$

3.1 Properties of Variance

1. The variance of X is equal to

$$E(X^2) - [E(X)]^2 = E(X^2) - \mu_X^2.$$

2. Var(X)=0 if and only if there is a constant c such that P(X=c)=1.

3. If a and b are constants, then $Var(aX + b) = a^2Var(X)$.

Proof: We know that $E(aX+b)=aE(X)+b=a\mu_X+b$, and so

$$Var(aX + b) = E\{[(aX + b) - (a\mu_X + b)]^2\}$$

$$= E\{[a(X - \mu_X)]^2\}$$

$$= E\{a^2(X - \mu_X)^2\}$$

$$= a^2 E\{(X - \mu_X)^2\}$$

$$= a^2 Var(X).$$

4. Suppose that X_1,\ldots,X_n are independent random variables, and let a_1,\ldots,a_n be constants. Then

$$\operatorname{Var}(a_1 X_1 + \dots + a_n X_n) = \sum_{i=1}^n a_i^2 \operatorname{Var}(X_i).$$

Remarks on properties of variance:

- Take a=1 in Property 3. Then we see that $\mathrm{Var}(X+b)=\mathrm{Var}(X)$. This means that *shifting* a distribution to the left or right has no effect on its variance.
- Property 3 implies that the standard deviation of aX + b is $|a|\sigma$, where σ is the standard deviation of X.
- If we take $a_1 = \cdots = a_n = 1$ in Property 4, the result becomes

$$\operatorname{Var}(X_1 + \dots + X_n) = \sum_{i=1}^n \operatorname{Var}(X_i).$$

So, the variance of a sum of *independent* random variables is the sum of variances. This result is **not** necessarily true when X_1, \ldots, X_n are not independent.

Example 31 Variance of a binomial random variable. Suppose X has the binomial distribution. Find $\operatorname{Var}(X)$.

We'll use the fact that ${\rm Var}(X)=E(X^2)-[E(X)]^2$. We know that $E(X)=n\theta$. So we need to find $E(X^2)$.

Suppose we could find $E[X(X-1)]=E(X^2)-E(X)=E(X^2)-n\theta$. Then we have $E(X^2)=E[X(X-1)]+n\theta$.

Assume $n \geq 2$. Now,

$$E[X(X-1)] = \sum_{x=0}^{n} x(x-1) {n \choose x} \theta^{x} (1-\theta)^{n-x}$$

$$= \sum_{x=2}^{n} x(x-1) {n \choose x} \theta^{x} (1-\theta)^{n-x}$$

$$= n(n-1) \sum_{x=2}^{n} {n-2 \choose x-2} \theta^{x} (1-\theta)^{n-x}.$$

Now, make the change of variable y = x - 2 in the last sum. This gives

$$E[X(X-1)] = n(n-1) \sum_{x=2}^{n} {n-2 \choose x-2} \theta^{x} (1-\theta)^{n-x}$$
$$= n(n-1)\theta^{2} \sum_{y=0}^{n-2} {n-2 \choose y} \theta^{y} (1-\theta)^{n-2-y}.$$

The last sum equals 1. Why? So, we have $E[X(X-1)] = n(n-1)\theta^2$, which implies that

$$E(X^{2}) = n(n-1)\theta^{2} + n\theta$$
$$= (n\theta)^{2} + n\theta(1-\theta),$$

and hence

$$Var(X) = n\theta(1 - \theta).$$

4 Covariance and Correlation

In practice it is often of interest to know how two variables are related. When X increases or decreases, how does Y behave?

When the relationship between X and Y is relatively simple, the *covariance* and/or *correlation* are good measures for summarizing the relationship.

The covariance between X and Y is denoted $\mathrm{Cov}(X,Y)$ and defined by

$$Cov(X,Y) = E[(X - \mu_X)(Y - \mu_Y)],$$

where $\mu_X = E(X)$ and $\mu_Y = E(Y)$.

 $\mathrm{Cov}(X,Y)$ measures the tendency of X and Y to be on the same (or opposite) sides of their respective means.

The correlation between X and Y is a scaled version of the covariance. It (correlation) does not depend on the measurement units of X and Y.

The correlation is denoted Corr(X, Y) and defined by

$$\operatorname{Corr}(X, Y) = \frac{\operatorname{Cov}(X, Y)}{\sigma_X \sigma_Y},$$

where σ_X and σ_Y are the standard deviations of X and Y, respectively. We can also use ρ , $\rho(X,Y)$, or $\rho_{X,Y}$ as notation for $\mathrm{Corr}(X,Y)$.

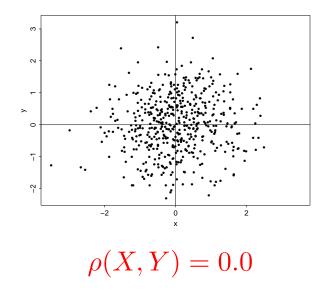
An important property of correlation is that

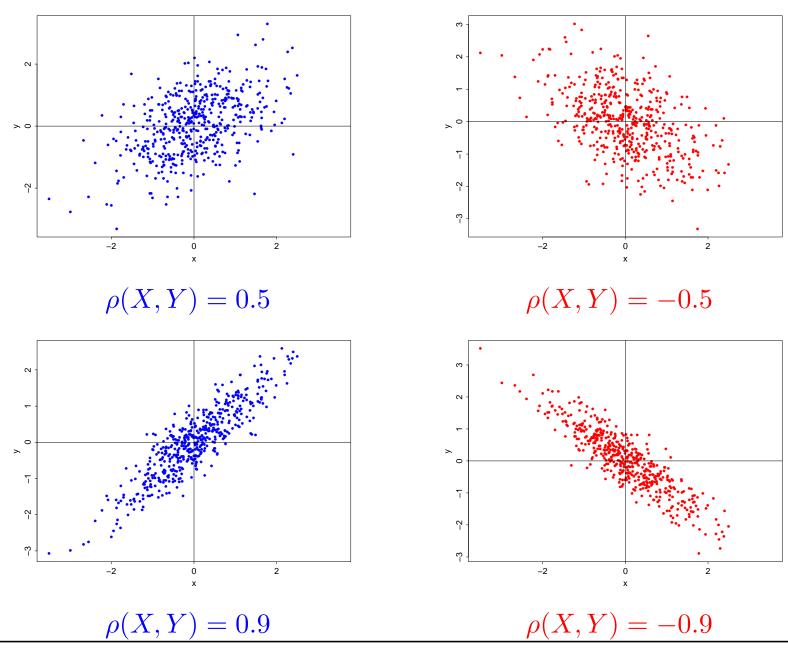
$$-1 \le \operatorname{Corr}(X, Y) \le 1.$$

See the proof on p. 186 of your text.

When X and Y are on the *same* side of their respective means with very high probability, then $\mathrm{Corr}(X,Y)$ will be close to 1. When X and Y are on *opposite* sides of their respective means with very high probability, $\mathrm{Corr}(X,Y)$ is close to -1.

The last comments are best illustrated graphically. Suppose we repeat the experiment that generates X and Y hundreds of times. Each time the experiment is repeated the result is an (x,y) pair. We could plot the hundreds of (x,y) pairs on a *scatter plot*.





4.1 Properties of Covariance and Correlation

• Cov(X,Y) = E(XY) - E(X)E(Y).

Proof: We expand the product in the definition of covariance:

$$Cov(X,Y) = E[(X - \mu_X)(Y - \mu_Y)]$$

$$= E[XY - \mu_X Y - \mu_Y X + \mu_X \mu_Y]$$

$$= E[XY] - \mu_X E(Y) - \mu_Y E(X) + \mu_X \mu_Y$$

$$= E[XY] - E(X)E(Y)$$

• If X and Y are independent, $0<\sigma_X<\infty$ and $0<\sigma_Y<\infty$, then

$$Cov(X, Y) = 0 = Corr(X, Y).$$

• $Cov(X, X) = E[(X - \mu_X)(X - \mu_X)] = Var(X).$

• Suppose a and b are constants with $a \neq 0$ and that $0 < \sigma_X < \infty$. Then if Y = aX + b,

$$Corr(X, Y) = \begin{cases} 1, & a > 0, \\ -1, & a < 0. \end{cases}$$

Proof: We know that $\mu_Y = a\mu_X + b$, and hence

$$Cov(X,Y) = E[(X - \mu_X)(aX - a\mu_X)]$$
$$= aVar(X).$$

We also know that $\sigma_Y = |a|\sigma_X$, and hence

$$Corr(X, Y) = \frac{a}{|a|} = \pm 1,$$

depending on the sign of a.

Note: Cov(X, Y) = 0 is a weaker condition than independence of X and Y.

- "X and Y independent" $\Rightarrow \operatorname{Cov}(X,Y) = 0$.
- Converse of previous implication is not true, i.e., there are cases where $\mathrm{Cov}(X,Y)=0$, but X and Y are **not** independent.

Example: Suppose (X,Y) are discrete rvs with joint pmf

$$p_{X,Y}(x,y) = \begin{cases} \frac{1}{4}, & (x,y) \in \{(0,1),(1,0),(0,-1),(-1,0),(-1,0),$$

First, E(X) = E(Y) = 0. Then

$$Cov(X,Y) = E[XY] = \frac{1}{4}[(0)(1) + (1)(0) + (0)(-1) + (-1)(0)] = 0.$$

		0	1	2	3	4	$p_X(x)$
x	0	1/16	3/16	3/16	1/16	0	8/16
	1	0	1/16	2/16	1/16	0	4/16
	2	0	0	1/16	1/16	0	2/16
	3	0	0	0	1/16	0	1/16
	4	0	0	0	0	1/16	1/16
·	$p_Y(y)$	1/16	4/16	6/16	4/16	1/16	

Previously we found that E(X)=15/16 and E(Y)=4(0.5)=2. Next

$$E(XY) = (1)(1)\left(\frac{1}{16}\right) + (1)(2)\left(\frac{2}{16}\right) + \dots + (4)(4)\left(\frac{1}{16}\right) = \frac{43}{16}$$
$$Cov(X,Y) = \frac{43}{16} - \left(\frac{15}{16}\right)(2) = \frac{13}{16}.$$

We need to calculate the variances of X and Y:

$$E(X^{2}) = (1^{2}) \left(\frac{4}{16}\right) + (2^{2}) \left(\frac{2}{16}\right) + (3^{2} + 4^{2}) \left(\frac{1}{16}\right) = \frac{37}{16}$$
$$Var(X) = E(X^{2}) - (E(X))^{2} = \frac{37}{16} - \left(\frac{15}{16}\right)^{2} = \frac{367}{256}.$$

$$Var(Y) = 4(0.5)(1 - 0.5) = 1$$

Then the correlation of X and Y is

$$Corr(X, Y) = \frac{\frac{13}{16}}{\sqrt{(\frac{367}{256})(1)}} = 0.4798$$

Example 19 again Let X and Y have joint pdf

$$f(x,y) = \begin{cases} 3(x+y), & 0 < x < 1, 0 < y < 1, \\ & 0 < x + y < 1 \\ 0, & \text{otherwise.} \end{cases}$$

Earlier we found that the marginal pdf of X was

$$f_1(x) = \frac{3}{2}(1-x^2), \ 0 < x < 1.$$

The first two moments are

$$E(X) = \frac{3}{8} \text{ and } Var(X) = \frac{19}{320}.$$

The covariance of X and Y is

$$Cov(X,Y) = E(XY) - \mu_X \mu_Y = \int_0^1 \int_0^{1-x} xy \, 3(x+y) dy dx - \left(\frac{3}{8}\right)^2$$
$$= \frac{1}{10} - \left(\frac{3}{8}\right)^2 = -\frac{13}{320}$$

The correlation of X and Y is

$$Corr(X,Y) = \frac{-\frac{13}{320}}{\sqrt{\frac{19}{320}}\sqrt{\frac{19}{320}}} = -\frac{13}{19} = -0.6842$$

Example 28 again Let X and Y have joint pdf

$$f(x,y) = \begin{cases} 2, & 0 < x < 1, 0 < y < 1, \\ & 0 < x + y < 1 \\ 0, & \text{otherwise.} \end{cases}$$

The marginal pdf of X is

$$f_1(x) = \int_0^{1-x} 2dy = 2(1-x), \ 0 < x < 1.$$

The first two moments are

$$E(X) = \frac{1}{3} \text{ and } Var(X) = \frac{1}{18}.$$

The covariance of X and Y is

$$Cov(X,Y) = E(XY) - \mu_X \mu_Y = \int_0^1 \int_0^{1-x} xy \, 2 \, dy dx - \left(\frac{1}{3}\right)^2$$
$$= \frac{1}{12} - \left(\frac{1}{3}\right)^2 = -\frac{1}{36}$$

The correlation of X and Y is

$$Corr(X,Y) = \frac{-\frac{1}{36}}{\sqrt{\frac{1}{18}}\sqrt{\frac{1}{18}}} = -\frac{1}{2}$$

4.2 Variance of a linear combination

Suppose X and Y are jointly distributed random variables and define

Z = aX + bY, where a and b are constants. What is Var(Z)?

We know that $E(Z) = a\mu_X + b\mu_Y$, and so

$$\begin{aligned}
\mathbf{Var}(Z) &= E \left[(aX + bY - a\mu_X - b\mu_Y)^2 \right] \\
&= E \left[(aX - a\mu_X + bY - b\mu_Y)^2 \right] \\
&= E \left[a^2 (X - \mu_X)^2 + b^2 (Y - \mu_Y)^2 + 2ab(X - \mu_X)(Y - \mu_Y) \right] \\
&= a^2 \mathbf{Var}(X) + b^2 \mathbf{Var}(Y) + 2ab \mathbf{Cov}(X, Y).
\end{aligned}$$

What if a=b=1 and $\mathrm{Cov}(X,Y)=0$? Then

$$Var(X + Y) = Var(X) + Var(Y).$$

So, the variance of a sum is the sum of variances if and only if Cov(X,Y)=0.

• We extend the result to a linear combination of several random variables: Suppose $U = a + \sum_{i=1}^{n} b_i X_i$. Then

$$Var(U) = \sum_{i=1}^{n} \sum_{j=1}^{n} b_i b_j Cov(X_i, X_j)$$
$$= \sum_{i=1}^{n} b_i^2 Var(X_i) + 2 \sum_{i < j} b_i b_j Cov(X_i, X_j).$$

 This result can also be extended to the covariance of two linear combinations of random variables:

Suppose
$$U = a + \sum_{i=1}^{n} b_i X_i$$
 and $V = c + \sum_{j=1}^{m} d_j Y_j$. Then

$$Cov(U, V) = \sum_{i=1}^{n} \sum_{j=1}^{m} b_i d_j Cov(X_i, Y_j).$$

5 Moments and the Moment-Generating Function

The *moments* of a random variable X are (when they exist) the expectations of powers of X:

$$E(X^k), \quad k = 1, 2, \dots$$

Moments can be useful in describing the distribution of a rv. In certain situations, the set of all moments uniquely determines the distribution. (More on this shortly.)

Theorem: If $E(X^k)$ exists for some k, then $E(X^j)$ exists for $j=1,2,\ldots,k-1$.

5.1 Central Moments

Assuming existence of the moments (as defined before), the *central moments* of X are

$$E[(X - \mu)^k], \quad k = 1, 2, \dots$$

Remark: When the moments exist, the central moments and the moments are functions of each other. For example, the second central moment can be expressed as

$$E[(X - \mu)^2] = E(X^2) - \mu^2$$

$$E[(X - \mu)^{3}] = E(X^{3}) - 3\mu E(X^{2}) + 3\mu^{2} E(X) - \mu^{3}$$
$$= E(X^{3}) - 3\mu E(X^{2}) + 2\mu^{3}$$

5.2 Moment generating function

Consider the following function of *s*:

$$M_X(s) = E[e^{sX}].$$

If there is a positive number s_0 such that the last expectation exists for all $|s| < s_0$, then $M_X(s)$, $|s| < s_0$, is called the *moment generating function*, or mgf, of X.

When the mgf of X exists, then all the moments of X exist and are finite.

Furthermore, we may find the moments of X from M_X in the following way:

$$E(X^k) = \frac{d^k M_X(s)}{ds^k} \bigg|_{s=0}.$$

For example, $M_X'(0) = E(X)$ and $M_X''(0) = E(X^2)$.

Example 12 Again Suppose that X has the pmf

Then the moment generating function of X is

$$M_X(s) = E(e^{sX}) = \frac{1}{2}e^0 + \frac{1}{4}e^s + \frac{1}{8}e^{2s} + \frac{1}{16}(e^{3s} + e^{4s})$$

We next take the derivative with respect to s:

$$M_X'(s) = \frac{dM_X(s)}{ds} = \frac{1}{4}e^s + \frac{1}{8}2e^{2s} + \frac{1}{16}(3e^{3s} + 4e^{4s}).$$

Evaluate this at s=0 to obtain the mean of X:

$$M_X'(0) = \frac{1}{4} + \frac{1}{8}(2) + \frac{1}{16}(3+4) = \frac{15}{16}.$$

Example 32 Mgf of binomial distribution. Suppose that X has the binomial distribution with pmf

$$p_X(x) = \binom{n}{x} \theta^x (1-\theta)^{n-x}, \ x = 0, 1, \dots, n.$$

The mgf of X is given by

$$M_X(s) = E(e^{sX}) = \sum_{x=0}^n e^{sx} \binom{n}{x} \theta^x (1-\theta)^{n-x}$$
$$= \sum_{x=0}^n \binom{n}{x} (e^s \theta)^x (1-\theta)^{n-x}$$
$$= (\theta e^s + 1 - \theta)^n$$

We can find the moments of the binomial $\operatorname{rv} X$ by differentiation:

$$E(X) = M'(0) = \frac{d}{ds} (\theta e^s + 1 - \theta)^n \Big|_{s=0} = n(\theta e^s + 1 - \theta)^{n-1} \theta e^s \Big|_{s=0} = n\theta.$$

$$E(X^{2}) = M''(0) = \frac{d^{2}}{ds^{2}} (\theta e^{s} + 1 - \theta)^{n} \Big|_{s=0}$$

$$= \frac{d}{ds} \left[n(\theta e^{s} + 1 - \theta)^{n-1} \theta e^{s} \right] \Big|_{s=0}$$

$$= \left[n(n-1)(\theta e^{s} + 1 - \theta)^{n-2} \theta^{2} e^{2s} + n(\theta e^{s} + 1 - \theta)^{n-1} \theta e^{s} \right] \Big|_{s=0}$$

$$= n(n-1)\theta^{2} + n\theta$$

The variance of X is

$$Var(X) = n(n-1)\theta^2 + n\theta - (n\theta)^2 = n\theta - n\theta^2 = n\theta(1-\theta)$$

Example 33 Mgf of normal distribution. Let X have the normal distribution with mean μ_X and variance σ_X^2 , i.e., its pdf is

$$f_X(x) = \frac{1}{\sqrt{2\pi}\sigma_X} \exp\left[-\frac{1}{2\sigma_X^2}(x-\mu_X)^2\right].$$

Find the mgf of X. We have

$$M_X(s) = \int_{-\infty}^{\infty} e^{sx} f_X(x) dx.$$

First we'll make the change of variable $y = (x - \mu_X)/\sigma_X$.

The integral is then

$$\int_{-\infty}^{\infty} e^{s(\sigma_X y + \mu_X)} \cdot \frac{1}{\sqrt{2\pi}} e^{-y^2/2} \, dy = e^{s\mu_X} \int_{-\infty}^{\infty} e^{s\sigma_X y} \cdot \frac{1}{\sqrt{2\pi}} e^{-y^2/2} \, dy.$$

From this point, the trick is to *complete the square* and produce an integrand that is proportional to a normal density. Consider

$$e^{s\sigma_X y - \frac{1}{2}y^2} = \exp\left[-\frac{1}{2}(y^2 - 2s\sigma_X y)\right]$$

$$= \exp\left[-\frac{1}{2}(y^2 - 2s\sigma_X y + s^2\sigma_X^2 - s^2\sigma_X^2)\right]$$

$$= \exp\left[\frac{(s\sigma_X)^2}{2}\right] \exp\left[-\frac{1}{2}(y - s\sigma_X)^2\right].$$

So now we have

$$M_X(s) = e^{s\mu_X + s^2 \sigma_X^2/2} \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-(y - s\sigma_X)^2/2} dy$$
$$= \exp\left(s\mu_X + \frac{s^2 \sigma_X^2}{2}\right).$$

How did we get the very last step?

Now, let's use this mgf to find the first two moments of a normal distribution. Our notation suggests that $\mu_X = E(X)$ and $\sigma_X^2 = \text{Var}(X)$. Is this true?

$$M_X'(s) = \frac{d \exp \left(s\mu_X + s^2 \sigma_X^2 / 2\right)}{ds}$$

$$= \exp \left(s\mu_X + s^2 \sigma_X^2 / 2\right) \frac{d \left(s\mu_X + s^2 \sigma_X^2 / 2\right)}{ds}$$

$$= M_X(s) \left(\mu_X + s\sigma_X^2\right).$$

So,
$$E(X) = M'_X(0) = \mu_X$$
.

To find the second moment, we compute

$$M_X''(s) = \sigma_X^2 M_X(s) + (\mu_X + s\sigma_X^2) M_X'(s),$$

and find $E(X^2) = M_X''(0) = \sigma_X^2 + \mu_X^2$. Therefore,

$$Var(X) = E(X^2) - [E(X)]^2 = (\sigma_X^2 + \mu_X^2) - \mu_X^2 = \sigma_X^2.$$

5.3 Properties of mgfs

- 1. $M_X(0) = 1$
- 2. Let a and b be constants, and M_X be the mgf of X. Then the mgf of Y=aX+b is

$$M_Y(s) = E(e^{sY}) = e^{bs} M_X(as).$$

3. Let X_1, \ldots, X_n be independent random variables with respective mgfs M_1, \ldots, M_n . Then the mgf, M, of $X_1 + \cdots + X_n$ is

$$M(s) = \prod_{i=1}^{n} M_i(s).$$

4. Suppose the mgfs of the random variables X and Y exist, and call them M_X and M_Y , respectively. Then the distribution of X is the same as that of Y if and only if M_X is the same as M_Y .

A corollary to property 4 is that when the mgfs of X and Y exist, then X and Y have the same distribution if and only if the moments of X equal the corresponding moments of Y.

Here's a very interesting fact, however. There exist cases where

$$E(X^k) = E(Y^k), \quad k = 1, 2, \dots,$$

and yet X and Y have remarkably different distributions.

Example 34 Two different distributions that have all the same moments. Consider the two pdfs

$$f_1(x) = \frac{1}{\sqrt{2\pi}x} e^{-(\log x)^2/2} I_{(0,\infty)}(x)$$

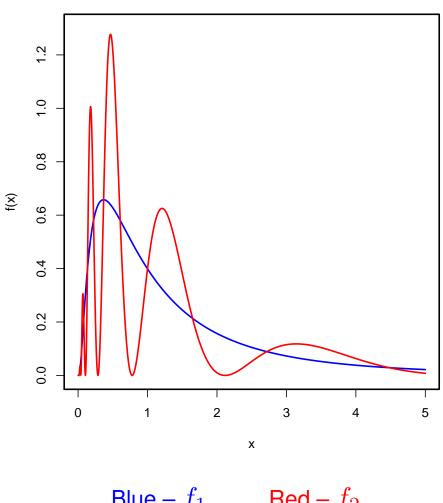
and

$$f_2(x) = f_1(x)[1 + \sin(2\pi \log x)].$$

One can show that the moments exist for these two pdfs and, for $k=1,2,\ldots$,

$$\int_0^\infty x^k f_1(x) \, dx = \int_0^\infty x^k f_2(x) \, dx.$$

Two Densities with Equal Moments



Blue – f_1 Red – f_2

The reason this example does not contradict property 4 (p. 132) is that the mgfs of f_1 and f_2 do not exist.

Combining properties 3 and 4 yields a powerful method for finding the distribution of a sum of independent random variables.

Given independent random variables X_1, \ldots, X_n with mgfs M_1, \ldots, M_n , try to find the distribution of $X_1 + \cdots + X_n$ as follows:

- ullet Find the mgf M of the sum using property 3.
- Since the mgf uniquely determines the distribution (by property 4), if we recognize M as being the mgf of a known distribution, then we've found the distribution of $X_1 + \cdots + X_n$.

Example 35 Distribution of a sum of Bernoulli rvs

Let X_1, \ldots, X_n be independent random variables such that

$$P(X_i = x) = \begin{cases} \theta, & x = 1 \\ 1 - \theta, & x = 0 \\ 0, & \text{otherwise} \end{cases}$$

Each X_i has $\operatorname{mgf} M_i(s) = E(e^{sX_i}) = (1-\theta)e^0 + \theta e^s = 1-\theta + \theta e^s$. Then the mgf of $Y = X_1 + \cdots + X_n$ is

$$M_Y(s) = E(e^{Ys}) = \prod_{i=1}^n E(e^{X_i s})$$
$$= (1 - \theta + \theta e^s)^n$$

We recognize this as the mgf of a binomial rv with n trials and probability of success θ .

Example 36 Distribution of a sum of independent normal rvs

Let X_1, \ldots, X_n be independent random variables such that

$$X_i \sim N(\mu_i, \sigma_i^2), \quad i = 1, \dots, n.$$

Using property 3 and the normal mgf, the mgf of $Y=X_1+\cdots+X_n$ is

$$M_Y(s) = \prod_{i=1}^n \exp\left(s\mu_i + s^2\sigma_i^2/2\right)$$
$$= \exp\left(s\sum_{i=1}^n \mu_i + s^2\sum_{i=1}^n \sigma_i^2/2\right).$$

From property 4 and Example 33, it immediately follows that

$$Y \sim N\left(\sum_{i=1}^{n} \mu_i, \sum_{i=1}^{n} \sigma_i^2\right).$$

6 Conditional Expectation and Prediction

Very simply, a *conditional expectation* is an ordinary expectation but defined with respect to a conditional distribution.

Suppose the conditional pmf or pdf of Y given X=x is $p_{Y\mid X}(y\mid x)$ or $f_{Y\mid X}(y\mid x)$, respectively. Then

$$E[h(Y)|X=x] = \begin{cases} \sum_y h(y) p_{Y|X}(y|x), & \text{for } Y \text{ discrete,} \\ \\ \int_{-\infty}^{\infty} h(y) f_{Y|X}(y|x) \, dy, & \text{for } Y \text{ continuous.} \end{cases}$$

Let $\mu(x)$ denote E(Y|X=x). This is known as the regression function of Y on x. The regression function is often used to predict Y given a value X=x.

Definition: The conditional expectation of Y given X is the random variable E(Y|X) which is equal to E(Y|X=x) when X=x. Thus, E(Y|X) is a rv that is a function of the rv X.

Example 12 again Obtain the conditional expectation of X given Y=y.

We earlier found the conditional pmf of X given Y=0 is

$$p_{X|Y}(0|0) = \frac{1/16}{1/16} = 1, \quad x = 0.$$

Thus, E[X|Y = 0] = 1.

The conditional pmf of X given Y=1 is

$$p_{X|Y}(x|1) = \begin{cases} \frac{3/16}{4/16} = \frac{3}{4}, & x = 0\\ \frac{1/16}{4/16} = \frac{1}{4}, & x = 1 \end{cases}$$

Thus, E[X|Y=1] = (3/4)(0) + (1/4)(1) = 1/4.

The conditional pmf of X given Y=2 is

$$p_{X|Y}(x|2) = \begin{cases} \frac{3/16}{6/16} = \frac{1}{2}, & x = 0\\ \frac{2/16}{6/16} = \frac{1}{3}, & x = 1\\ \frac{1/16}{6/16} = \frac{1}{6}, & x = 2. \end{cases}$$

Thus,
$$E[X|Y=2]=(0)(1/2)+(1)(1/3)+(2)(1/6)=2/3$$
.

We can likewise compute the remaining conditional expectations:

$$E[X|Y = 3] = (0)(1/4) + (1)(1/4) + (2)(1/4) + (3)(1/4) = 3/2$$
$$E[X|Y = 4] = 4$$

We now consider the distribution of W=E[X|Y]. Recall from Chapter 2 that the marginal pmf of Y is

Thus, W is a discrete rv with pmf

Example 19 again Let X and Y have joint pdf

$$f(x,y) = \begin{cases} 3(x+y), & 0 < x < 1, 0 < y < 1, \\ & 0 < x + y < 1 \\ 0, & \text{otherwise.} \end{cases}$$

Earlier we found that the marginal pdf of X was

$$f_X(x) = \frac{3}{2}(1-x^2), \ 0 < x < 1.$$

The conditional pdf of Y given X=x is

$$f_{Y|X}(y|x) = \frac{2(x+y)}{1-x^2}, \ 0 < y < 1-x.$$

The regression function of Y on x is

$$E(Y|x) = \int_0^{1-x} y \frac{2(x+y)}{1-x^2} dy = \frac{2-x-x^2}{3(1+x)}$$

Example 28 again $\ \ \,$ Let X and Y have joint pdf

$$f(x,y) = \begin{cases} 2, & 0 < x < 1, 0 < y < 1, \\ & 0 < x + y < 1 \\ 0, & \text{otherwise.} \end{cases}$$

The marginal pdf of X is

$$f_X(x) = \int_0^{1-x} 2dy = 2(1-x), \ 0 < x < 1.$$

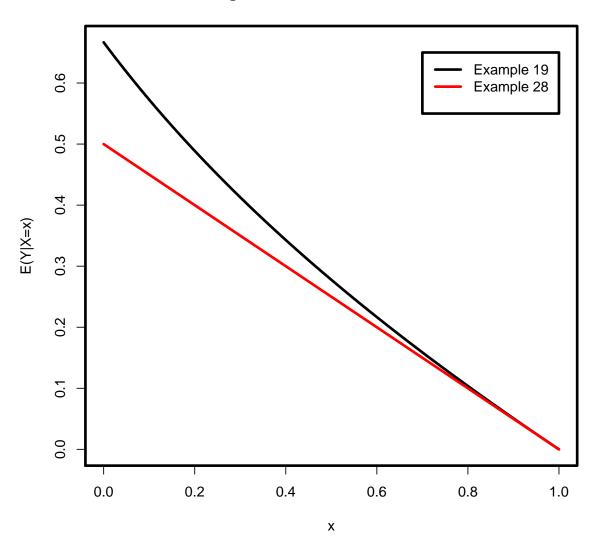
The conditional pdf of Y given X=x is

$$f_{Y|X}(y|x) = \frac{2}{2(1-x)} = \frac{1}{1-x}, \ 0 < y < 1-x.$$

The regression function of Y on x is

$$E(Y|x) = \int_0^{1-x} y \, \frac{1}{1-x} dy = \frac{1-x}{2}$$

Regression Functions of Y on x



6.1 Properties of Conditional Expectation and Conditional Variance

The conditional variance of Y given X=x, $\mathrm{Var}(Y|X=x)$, is defined to be

$$Var(Y|X = x) = E[(Y - \mu(x))^{2}|X = x].$$

Theorem A: E[E(Y|X)] = E(Y).

Theorem B: Var(Y) = Var[E(Y|X)] + E[Var(Y|X)]

Example: Suppose that a particle counter is imperfect and independently detects each incoming particle with probability θ . Suppose that the distribution of number N of incoming particles is Poisson (λ) . Then the conditional distribution of the number (X) of counted particles given N=n is binomial (n,θ) . It is an interesting exercise to show that the unconditional distribution of the counted number of particles X is Poisson $(\lambda\theta)$.

Example: We continue the particle example. We assumed that the conditional distribution of X|N=n is binomial (n,θ) and that N is Poisson (λ) . Find E(X) and Var(X).

The conditional mean and variance of X given N are

$$E(X|N) = N\theta$$
 and $Var(X|N) = N\theta(1-\theta)$.

Then

$$E(X) = E[E(X|N)] = E[N\theta] = \lambda\theta$$

and

$$Var(X) = Var[E(X|N)] + E[Var(X|N)]$$

$$= Var[N\theta] + E[N\theta(1-\theta)]$$

$$= \lambda \theta^2 + \lambda \theta(1-\theta) = \lambda \theta$$

6.2 Inequalities

There are several useful probability inequalities that give bounds on probabilities using certain expectations. A basic inequality is Markov's inequality.

Markov's inequality: Let X be a random variable such that $P(X \ge 0) = 1$. Then for every positive number a,

$$P(X \ge a) \le \frac{E(X)}{a}$$
.

Proof: We'll assume X is a continuous rv with pdf f.

$$E(X) = \int_0^\infty x f(x) dx$$

$$= \int_0^a x f(x) dx + \int_a^\infty x f(x) dx$$

$$\geq \int_0^a x f(x) dx + \int_a^\infty a f(x) dx$$

$$= \int_0^a x f(x) dx + a \int_a^\infty f(x) dx$$

$$= \int_0^a x f(x) dx + a P(X \ge a) \ge a P(X \ge a).$$

Remark: The usefulness of Markov's inequality is that it allows us to say something about the whole distribution of X when all we know is the first moment.

6.3 Chebyshev's Inequality

Chebyshev's inequality: Suppose X is a random variable with finite variance σ_X^2 , and let $\mu_X = E(X)$. Then for each a>0

$$P(|X - \mu_X| \ge a) \le \frac{\sigma_X^2}{a^2}.$$

Proof: We may write

$$P(|X - \mu_X| \ge a) = P[(X - \mu_X)^2 \ge a^2].$$

The result follows upon applying Markov's inequality to the rv $Y=(X-\mu_X)^2$ and using the fact that

$$E(Y) = E\left[(X - \mu_X)^2 \right] = \sigma_X^2.$$

With Chebyshev's inequality, we may make at least crude determinations about a distribution when all we know are the first two moments of the distribution.

For example, take a=1.5. Chebyshev's inequality tells us that

$$P(|X - \mu| \ge 1.5\sigma) \le \frac{1}{1.5^2} = \frac{4}{9} < 0.45,$$

or

$$P(|X - \mu| < 1.5\sigma) > 0.55.$$

So, for **any** distribution with a finite variance, at least 55% of the distribution must lie within 1.5 standard deviations of the mean.