1 Random Variables and Distributions

Random variables are the main link between probability and statistics. In statistics we observe numbers (or data) as the result of an experiment, and a random variable links the numbers to the probability structure of the experiment.

Definition of random variable

Let the sample space of an experiment be S. A *random variable* is a mapping, or function, from S to the real number line.

We will use capital letters late in the alphabet, such as X,Y and Z, to denote random variables. If X is a random variable, then X associates with each $s\in\mathcal{S}$ a real number X(s).

The notation X and X(s) parallels the notation we often see in math classes, where

- f is used to denote a function, and
- f(x) is the value of f at argument x.

So,

$$X \Longleftrightarrow f$$
 and $X(s) \Longleftrightarrow f(x)$.

A value of X will often be denoted x, i.e., X(s) = x.

Example 12 Suppose that a coin is tossed four times. Then there are $2^4=16$ possible sequences of tosses (such as HTHT). Let X be the number of heads until the first tail. For our example sequence, the mapping is X(HTHT)=1. We can form a table of the mapping for all possible sequences:

$$X(TTTT) = 0$$
 $X(TTTH) = 0$ $X(TTHT) = 0$ $X(TTHH) = 0$ $X(THHH) = 0$ $X(THTT) = 0$ $X(THTH) = 0$ $X(THHH) = 0$ $X(HTTT) = 1$ $X(HTTH) = 1$ $X(HTHH) = 1$ $X(HTHH) = 1$ $X(HTHH) = 1$ $X(HHHH) = 2$ $X(HHHHH) = 3$ $X(HHHHH) = 4$

Let X be a random variable defined on a sample space $\mathcal S$, and let A be some subset of the real numbers. We then define $P(X\in A)$ by

$$P(X \in A) = P\left(\left\{s \in \mathcal{S} : X(s) \in A\right\}\right).$$

The probabilities so defined by all relevant subsets A is called the *probability* distribution of X.

We use P(X = x) as a shorthand for $P(X \in \{x\})$.

Example 13 In the experiment of Example 12, we assume that the coin is a fair coin. Then each outcome has probability $\frac{1}{16}$.

For example, we have

$$P(X = 1) = P(\{HTTT, HTTH, HTHT, HTHH\}) = \frac{4}{16} = 0.25.$$

Similar reasoning yields:

x	0	1	2	3	4
P(X=x)	0.5	0.25	0.125	0.0625	0.0625

Any other probability of interest concerning the random variable X may be determined from these probabilities.

There are two main types of random variables: discrete and continuous.

Remember, X is a mapping from $\mathcal S$ to some subset of the real numbers.

The domain of the mapping is S, and we'll call the range R_X .

If R_X is countable, then X is a *discrete* random variable. If R_X is not countable, then X is a *continuous* random variable. When X is continuous, R_X is usually an interval or a union of disjoint intervals.

When $\mathcal S$ is countable, then X must be discrete, while if $\mathcal S$ is uncountable, then X can be either discrete or continuous.

2 Discrete Random Variables

The probability function (or probability mass function) of a discrete random variable is a function p_X defined by

$$p_X(x) = P(X = x)$$
 for every real number x .

Write the range of X as $R_X = \{x_1, x_2, \ldots\}$. Then

$$\sum_{i=1}^{\infty} p_X(x_i) = 1.$$

For any subset A of real numbers, we may express $P(X \in A)$ as

$$P(X \in A) = \sum_{x \in A \cap R_X} p_X(x).$$

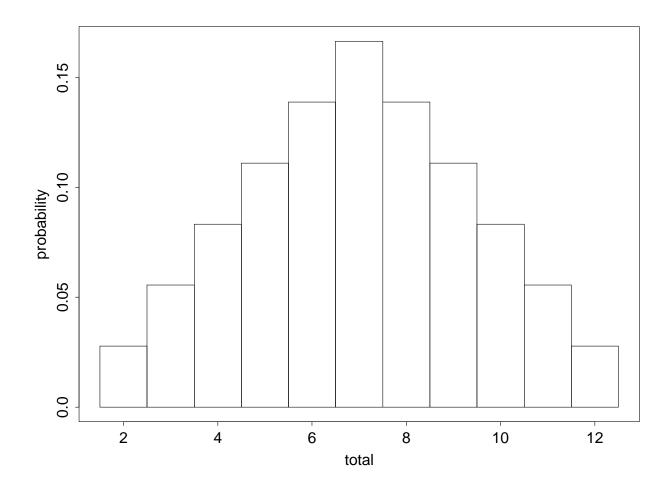
Example 4 revisited Consider again our dice experiment. If the dice are balanced, then the probability of each of the 36 different outcomes is the same. In this case, for each (i,j)

$$P(\{(i,j)\}) = \frac{1}{36}$$
. Why?

We define the random variable X to be total on the two dice. We can compute the probability mass function for X from the probabilities on the original sample space. For example,

$$p_X(6) = P(X = 6) = P(\{(1, 5), (2, 4), (3, 3), (4, 2), (5, 1)\}) = \frac{5}{36}.$$

We can likewise find the probability of any other possible total. A graph of the probability mass function is given below.



Example 4 continued

Suppose now we let $A=\{x:x\leq 4\}$. We are interested in $P(X\in A)$. We note that

$$R_X = \{2, 3, 4, \dots, 11, 12\}$$
 and $A \cap R_X = \{2, 3, 4\}$.

We have two ways of finding $P(X \in A)$.

1. We can use the original probability space:

$$P(X \in A) = P(\{(1,1), (1,2), (2,1), (1,3), (2,2), (3,1)\}) = \frac{6}{36} = \frac{1}{6}$$

2. We can use the probability mass function of X:

$$P(X \in A) = \sum_{x=2}^{4} p_X(x) = p_X(2) + p_X(3) + p_X(4) = \frac{1}{36} + \frac{2}{36} + \frac{3}{36} = \frac{6}{36} = \frac{1}{6}$$

A function that is often useful in defining and proving properties of a random variable is an *indicator function*.

The *indicator function* of an event A is defined as

$$I_A(s) = \begin{cases} 1 & \text{if } s \in A \\ 0 & \text{if } s \notin A \end{cases}$$

Example: Exercise 2.1.6 (modified a little) Let $\mathcal{S} = \{1,2,3,4\}$, $X = I_{\{1,2\}}, \ Y = I_{\{2,3\}}, \ Z = I_{\{3,4\}}$, and W = X - 2Y + Z.

$$W(1) = X(1) - 2Y(1) + Z(1) = 1 - 2(0) + 0 = 1$$

 $W(2) = X(2) - 2Y(2) + Z(2) = 1 - 2(1) + 0 = -1$
 $W(3) = X(3) - 2Y(3) + Z(3) = 0 - 2(1) + 1 = -1$
 $W(4) = X(4) - 2Y(4) + Z(4) = 0 - 2(0) + 1 = 1$

We'll discuss several probability mass functions (pmfs) that are important in statistical applications. These are the pmfs for the **Bernoulli distribution**, **discrete uniform distribution**, the **binomial distribution**, the **negative binomial distribution**, the **Poisson distribution**, and the **hypergeometric distribution**.

2.1 Bernoulli distribution

The simplest discrete random variable X takes on only two values, 0 and 1. Suppose that $0 < \theta < 1$. The probability mass function (pmf) of X is

$$p_X(1) = \theta$$
 $p_X(0) = 1 - \theta$
 $p_X(x) = 0$, otherwise.

We can also write the pmf as

$$p_X(x) = \begin{cases} \theta^x (1-\theta)^{1-x} & \text{if } x = 0 \text{ or } x = 1 \\ 0, & \text{otherwise.} \end{cases}$$

2.2 Discrete uniform distribution

The discrete uniform probability mass function p_{X} is defined for a positive integer k by

$$p_X(x) = \begin{cases} 1/k, & x = 1, 2, \dots, k \\ 0, & \text{otherwise.} \end{cases}$$

This probability function is the distribution of a random variable X that has range $\{1,\ldots,k\}$ and is equally likely to take on any value in this range.

The uniform distribution arises in the analysis of ranks in statistics. Suppose that k numbers are drawn randomly from an infinite population (to be defined later).

Let R be the rank of the first number drawn among all k numbers. So, R=1 if the first number drawn is the smallest one, R=2 if the first number drawn is the next to the smallest, and so on.

It turns out that R has a discrete uniform distribution in this case.

2.3 Binomial distribution

Binomial experiment

- 1. Observe a sequence of n trials, where n is fixed in advance.
- 2. Each trial results in one of two possible outcomes; call them "success" and "failure" (S and F).
- 3. The trials are independent of each other.
- 4. The probability of S on any one trial is θ where $0<\theta<1$. (Note: θ remains the same from trial to trial.)

Define X to be the number of successes among the n trials of a binomial experiment. Then the probability mass function of X has the following form:

$$p_X(x) = \begin{cases} \binom{n}{x} \theta^x (1-\theta)^{n-x}, & x = 0, 1, 2, \dots, n \\ 0, & \text{otherwise.} \end{cases}$$

This pmf is called the binomial pmf.

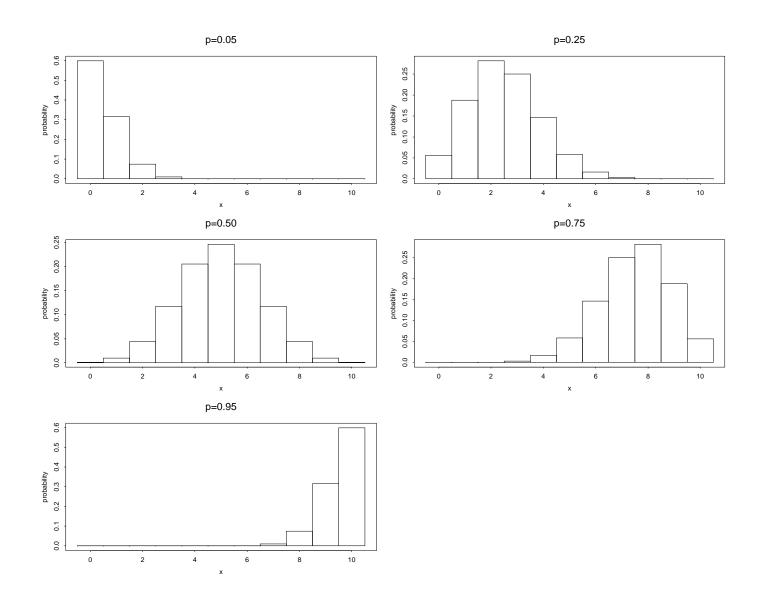
We can use ideas from Chapter 1 to prove that p_X is the pmf of the number of successes X in a binomial experiment.

There is a statistical application for the binomial distribution in sampling from a finite population. Suppose a population consists of N items, M of which are defective and N-M nondefective.

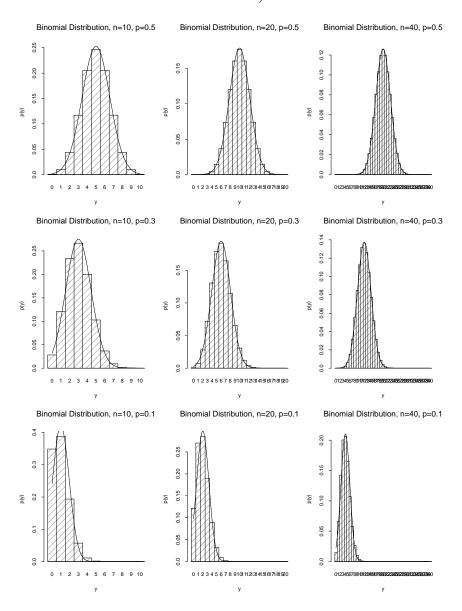
Suppose we randomly select n items from the population with replacement. Let X be the number of defective items among the n selected. Then X has the binomial distribution with $\theta=M/N$.

To argue that the distribution is binomial, just verify the conditions of the binomial experiment in this setting.

Various Binomial Distributions for n=10



Some Binomial Distributions for $n=10,20\ \mathrm{and}\ 40$



2.4 Negative Binomial Probability Distribution

Consider the following simple experiment:

We flip a coin until we have tossed 5 heads.

Note:

- 1. The experiment consists of a sequence of independent trials.
- 2. Each trial is identical and can result in one of two outcomes (S or F).
- 3. The probability of S equals θ ($0 < \theta < 1$) for each trial.
- 4. We continue the experiment until r successes have been observed.

Any experiment meeting all of the above conditions is called a

Negative Binomial Experiment.

If Y is our random variable representing the number of failures obtained before obtaining r successes, then Y has a negative binomial distribution:

$$Y \sim \mathsf{Negative\ Binomial}(r, \theta)$$

r = number of S

 θ = probability of S

The probability mass function of a negative binomial rv is given by

$$p_Y(y) = P(Y = y) = {r - 1 + y \choose r - 1} \theta^r (1 - \theta)^y, \quad y = 0, 1, 2, \dots$$

ullet If r=1 and X= the number of failures until the first success, we have a *geometric* distribution with pmf

$$P(X = x) = p_X(x) = \theta(1 - \theta)^x, \quad x = 0, 1, 2, 3, \dots$$

ullet Some books define the negative binomial distribution as the number of trials it takes to obtain the r^{th} success. This changes the formulas a little.

2.5 Hypergeometric Distribution

The hypergeometric distribution applies to "sampling without replacement" from a finite population containing two types of items.

We have a population of size N containing M defective items and N-M nondefective items. We randomly select n items ($n \leq N$) without replacement.

Define X to be the number of defectives in the sample. Then X has the probability mass function

$$p_X(x) = \begin{cases} \frac{\binom{M}{x} \binom{N-M}{n-x}}{\binom{N}{n}}, & x = M_1, \dots, M_2, \\ 0 & \text{otherwise,} \end{cases}$$

where
$$M_1 = \max(0, n - (N - M))$$
, and $M_2 = \min(n, M)$.

This is the pmf of the *hypergeometric distribution*.

2.6 Poisson Distribution

Consider these random variables:

- Number of phone calls received per hour by AAA emergency service.
- Number of customers logging onto Amazon Prime in a 5 minute interval.
- Number of trees in an area of forest.
- Number of bacteria in a culture.

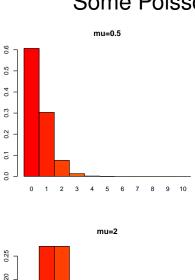
A random variable X, the number of successes occurring during a given time interval or in a specified region, is called a *Poisson* random variable. The corresponding distribution of

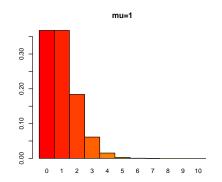
$$Y \sim \mathsf{Poisson}(\lambda)$$

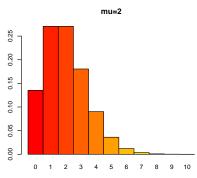
where λ is the rate for the given time or area, has pmf

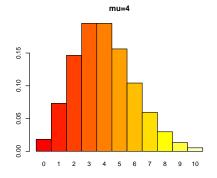
$$p_Y(y) = P(Y = y) = \frac{e^{-\lambda} \lambda^y}{y!}, \quad y = 0, 1, 2, \dots, \ \lambda > 0.$$

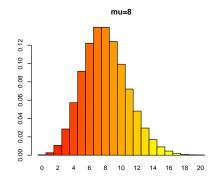
Some Poisson Distributions

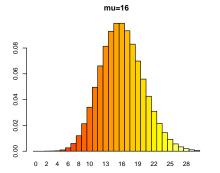












2.7 Some Relationships among the Distributions

• If we sample without replacement and n is small relative to N and M, we can approximate the hypergeometric distribution by using the binomial distribution with $\theta=\frac{M}{N}$:

$$X \sim \operatorname{Hypergeometric}(N,M,n) \ \rightarrow \ X \sim \operatorname{Binomial}(n,\theta = \frac{M}{N})$$

• Let X be a binomial random variable with probability distribution $X\sim \mathrm{Binomial}(n,\theta).$ When $n\to\infty$ and $\theta\to 0$ and $\lambda=n\theta$ remains fixed at $\lambda>0$, then

$$X \sim \mathsf{Binomial}(n, \theta) \to X \sim \mathsf{Poisson}(\lambda = n\theta)$$

As a rule of thumb, this approximation can be safely applied if:

$$n \ge 100$$
 $\theta \le .01$ $n\theta \le 20$