# Formula Sheet for Linear Algebra Final

#### 6.3 Orthonormal bases; Gram-Schmidt process; QR-decomposition

• Apply the Gram-Schmidt process to a set  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$  of vectors to obtain an orthonormal set  $\{\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_r\}$  of vectors with the same span as the original set. If the original set was a basis, then the final set will be an orthonormal basis. To find the vector  $\mathbf{q}_i$ , subtract from  $\mathbf{v}_i$  its projections onto the vectors  $\mathbf{q}_1, \dots, \mathbf{q}_{i-1}$  (to get  $\mathbf{w}_i$ ) and then normalize this vector to get  $\mathbf{q}_i$ :

$$\mathbf{w}_i = \mathbf{v}_i - \langle \mathbf{v}_i, \mathbf{q}_1 \rangle \mathbf{q}_1 - \langle \mathbf{v}_i, \mathbf{q}_2 \rangle \mathbf{q}_2 - \dots - \langle \mathbf{v}_i, \mathbf{q}_{i-1} \rangle \mathbf{q}_{i-1},$$
$$\mathbf{q}_i = \frac{\mathbf{w}_i}{\|\mathbf{w}_i\|}.$$

ullet Use the results of Gram-Schmidt orthogonalization to write a matrix A with linearly independent columns as a product

$$A = QR$$

where Q has orthonormal columns and R is an invertible upper triangular matrix. With

$$A = [\mathbf{v}_1 \ \mathbf{v}_2 \ \cdots \ \mathbf{v}_n],$$

we set

$$Q = [\mathbf{q}_1 \ \mathbf{q}_2 \ \cdots \ \mathbf{q}_n]$$

and

$$R = \begin{bmatrix} \|\mathbf{w}_1\| & \langle \mathbf{v}_2, \mathbf{q}_1 \rangle & \langle \mathbf{v}_3, \mathbf{q}_1 \rangle & \cdots & \langle \mathbf{v}_n, \mathbf{q}_1 \rangle \\ 0 & \|\mathbf{w}_2\| & \langle \mathbf{v}_3, \mathbf{q}_2 \rangle & \cdots & \langle \mathbf{v}_n, \mathbf{q}_2 \rangle \\ 0 & 0 & \|\mathbf{w}_3\| & \cdots & \langle \mathbf{v}_n, \mathbf{q}_3 \rangle \\ \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & 0 & \cdots & \|\mathbf{w}_n\| \end{bmatrix}.$$

Note that  $\|\mathbf{w}_i\| = \langle \mathbf{w}_i, \mathbf{q}_i \rangle = \langle \mathbf{v}_i, \mathbf{q}_i \rangle$ .

### 6.4 Least squares approximation

- If W is a finite-dimensional subspace of an inner product space V, and if  $\mathbf{v}$  is a vector in V, then the vector in W closest to  $\mathbf{v}$  is  $\operatorname{proj}_W \mathbf{v}$ .
- Given a matrix  $A \in M_{m \times n}$ , the set of all vectors of the form  $A\mathbf{x}$  is the span of the column vectors  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  of A. Thus  $A\mathbf{x} = \mathbf{b}$  has a solution  $\mathbf{x}$  if and only if

$$\mathbf{b} \in \operatorname{span}{\{\mathbf{v}_1, \dots, \mathbf{v}_n\}}.$$

• If  $\mathbf{b} \notin \text{span}\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ , then  $A\mathbf{x} = \mathbf{b}$  does not have any solutions  $\mathbf{x}$ . However, the associated normal system

$$A^T A \mathbf{x} = A^T \mathbf{b}$$

always has a solution  $\mathbf{x}$ . A solution  $\mathbf{x}$  of the normal system satisfies  $\operatorname{proj}_W \mathbf{b} = A\mathbf{x}$ , so that  $A\mathbf{x}$  is as close to  $\mathbf{b}$  as possible. If  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  are linearly independent, then  $A^T A$  will be invertible, so we have

$$\mathbf{x} = (A^T A)^{-1} A^T \mathbf{b}.$$

• It follows that

$$\operatorname{proj}_{W} \mathbf{b} = A\mathbf{x} = A(A^{T}A)^{-1}A^{T}\mathbf{b},$$

so the standard matrix for the linear transformation  $\operatorname{proj}_W:\mathbb{R}^m \to \mathbb{R}^m$  is

$$[\text{proj}_W] = A(A^T A)^{-1} A^T.$$

### 6.5 Change of basis (for vectors)

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$$\mathbf{x} = P_B[\mathbf{x}]_B$$

Solving for  $[\mathbf{x}]_B$ , we have

$$[\mathbf{x}]_B = P_B^{-1} \mathbf{x}.$$

ullet To change directly from a nonstandard basis B to a nonstandard basis B', we have the formula

$$[\mathbf{x}]_{B'} = P_{B'}^{-1} P_B[\mathbf{x}]_B.$$

• The same formulas hold in a general vector space V, as long as we set  $P_B = \left[ [\mathbf{v}_1]_E \cdots [\mathbf{v}_n]_E \right]$  and replace  $\mathbf{x}$  by  $[\mathbf{x}]_E$  for some basis E of V (usually chosen to be "standard").

#### 8.4 Matrices of general linear transformations

• The matrix  $[T]_{B'}^B$  can be computed as

$$[T]_{B'}^B = \begin{bmatrix} [T(\mathbf{v}_1)]_{B'} & [T(\mathbf{v}_2)]_{B'} & \cdots & [T(\mathbf{v}_n)]_{B'} \end{bmatrix},$$

where  $B = {\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n}.$ 

 $[T(\mathbf{x})]_{B'} = [T]_{B'}^B[\mathbf{x}]_B$ 

 $[T_2 \circ T_1]_{B''}^B = [T_2]_{B''}^{B'} [T_1]_{B'}^B$ 

# 8.5 Similarity (change of basis for linear operators)

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$$[T] = P_B [T]_B^B P_B^{-1}$$