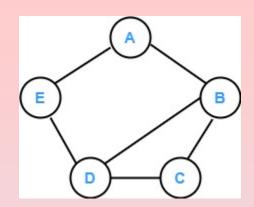
Spanning Tree and Minimum Cost Spanning Tree

Spanning Tree

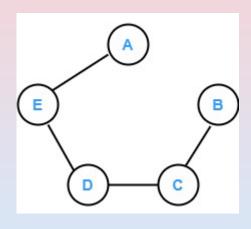
- * The spanning tree is a subgraph of an undirected connected graph.
- ❖ Spanning tree includes all the vertices in the graph and the least number of edges that can connect every vertex without forming a loop or cycle.
- **❖** Spanning tree has n vertices and n-1 edges.

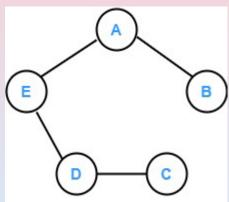
Spanning Tree

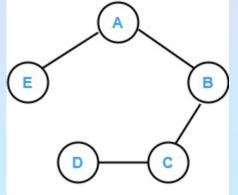
Given graph is

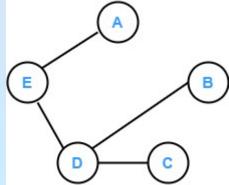


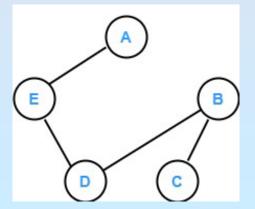
Possible Spanning trees are









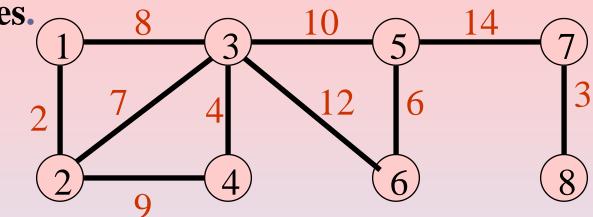


Minimum-Cost Spanning Tree

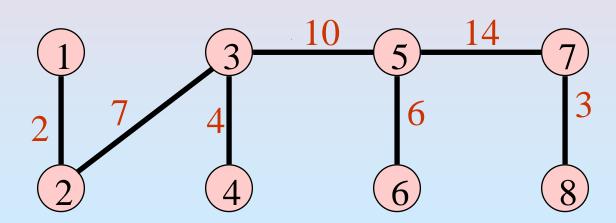
- Weighted connected undirected graph
- Spanning tree
- Cost of spanning tree is sum of edge costs
- Find spanning tree that has minimum cost

MST- Example

♦ Graph/Network has n = 8 Vertices and e = 10 edges. 8 10 14 14



Spanning tree has only n - 1 = 7 edges.



Strategy to either select 7 edges or discard 3. ???

Edge Selection Strategies

- *Start with an n-vertex, 0-edge forest. Consider edges in ascending order of cost. Select edge if it does not form a cycle together with already selected edges.
 - Kruskal's Algorithm.
- Start with a 1-vertex tree and grow it into an n-vertex tree by repeatedly adding a vertex and an edge. When there is a choice, add a least cost edge.
 - Prim's Algorithm.

Edge Selection Strategies

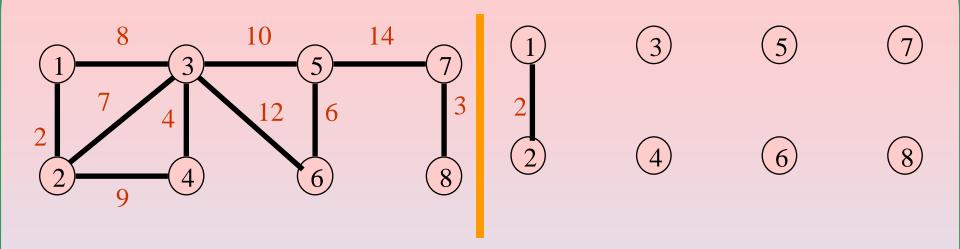
♦ Start with an n-vertex forest. Each component/tree selects a least cost edge to connect to another component/tree. Eliminate duplicate selections and possible cycles. Repeat until only 1 component/tree is left.

Sollin's method.

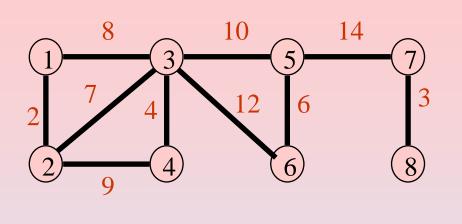
Edge Rejection Strategies

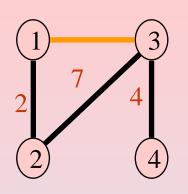
- 1. Start with the connected graph.

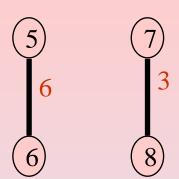
 Repeatedly find a cycle and eliminate the highest cost edge on this cycle. Stop when no cycles remain.
- 2. Consider edges in descending order of cost. Eliminate an edge provided this leaves behind a connected graph.



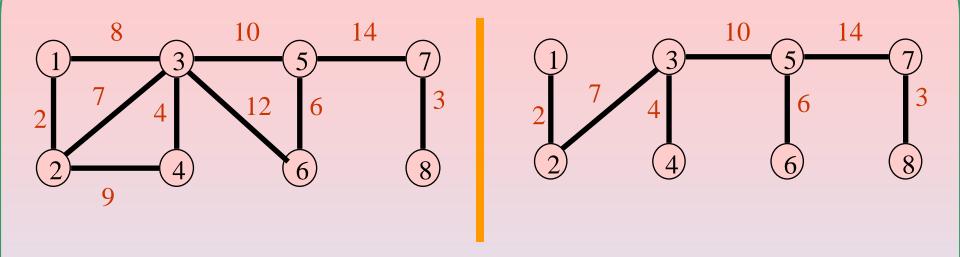
- Start with a forest that has no edges.
- Consider edges in ascending order of cost.
- Edge (1,2) is considered first and added to the forest.



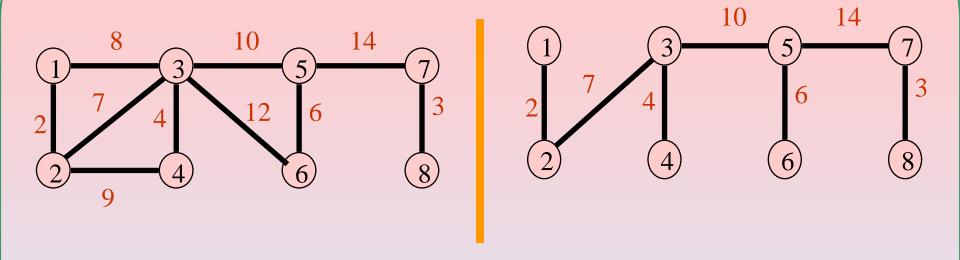




- **Edge** (7,8) is considered next and added.
- **Edge (3,4) is considered next and added.**
- **Edge (5,6)** is considered next and added.
- **Edge (2,3)** is considered next and added.
- **❖** Edge (1,3) is considered next and rejected because it creates a cycle.

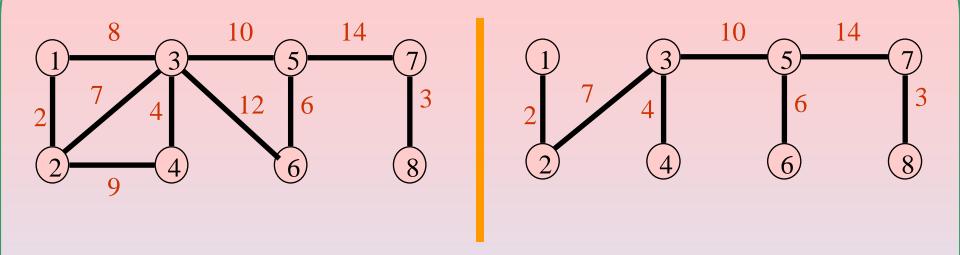


- **❖** Edge (2,4) is considered next and rejected because it creates a cycle.
- Edge (3,5) is considered next and added.
- Edge (3,6) is considered next and rejected.
- Edge (5,7) is considered next and added.



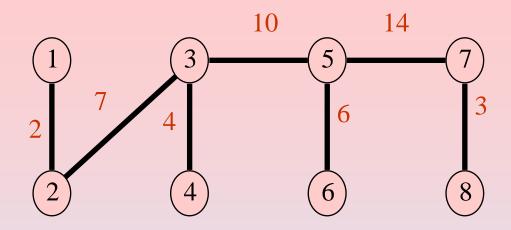
- ❖ n 1 edges have been selected and no cycle formed.
- **So we must have a spanning tree.**
- **Min-cost spanning tree is unique when all edge costs are different.**

Prim's Method



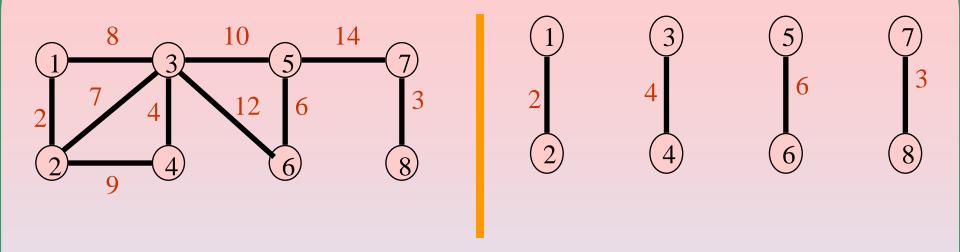
- Start with any single vertex tree.
- Get a 2-vertex tree by adding a cheapest edge.
- Get a 3-vertex tree by adding a cheapest edge.
- Grow the tree one edge at a time until the tree has n 1 edges (and hence has all n vertices).

Prim's Method



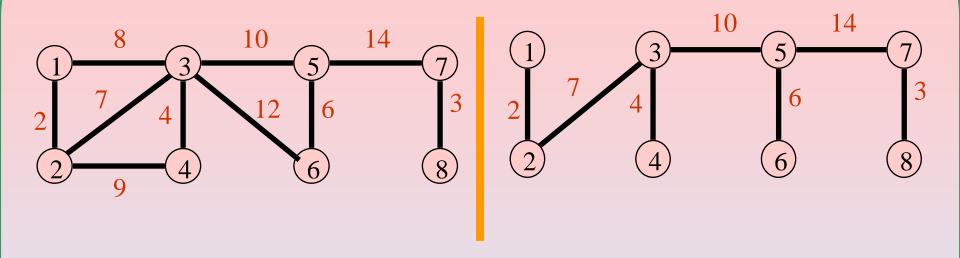
- **Start with any single vertex tree.**
- Get a 2-vertex tree by adding a cheapest edge.
- Get a 3-vertex tree by adding a cheapest edge.
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 edges (and hence has all n vertices).

Sollin's Method



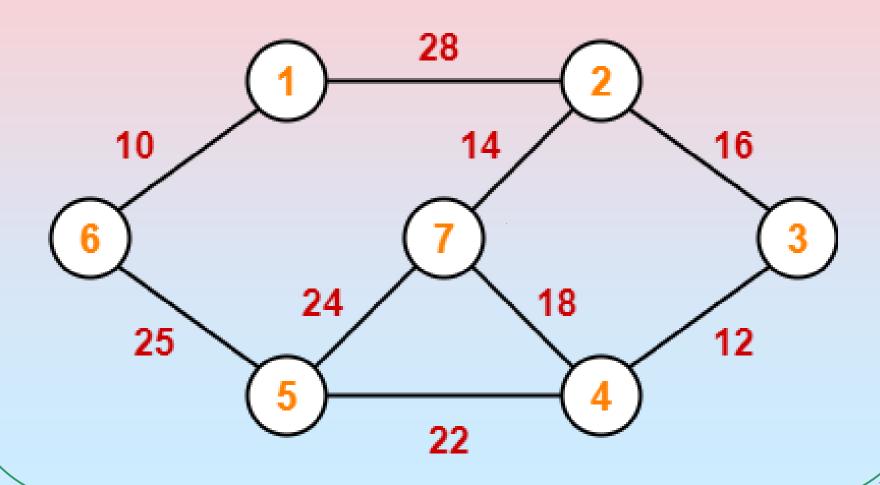
- Start with a forest that has no edges.
- Each component selects a least cost edge with which it can connect to another component.
- Duplicate selections are eliminated.
- Cycles are possible when the graph has some edges that have the same cost.

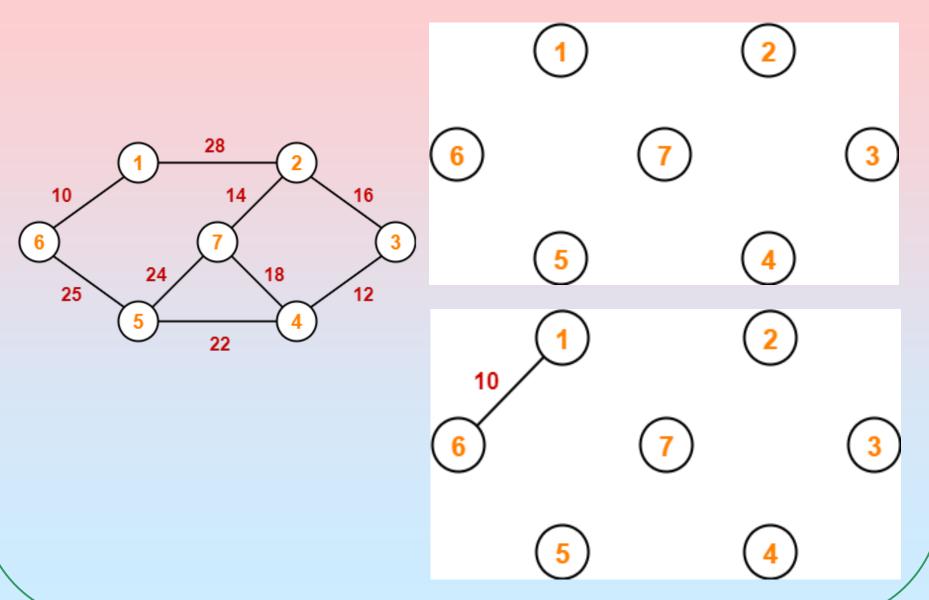
Sollin's Method

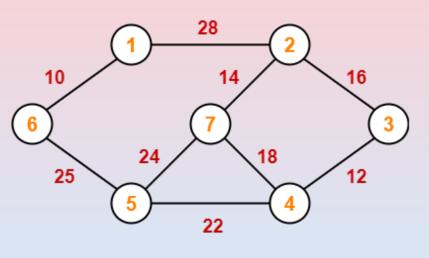


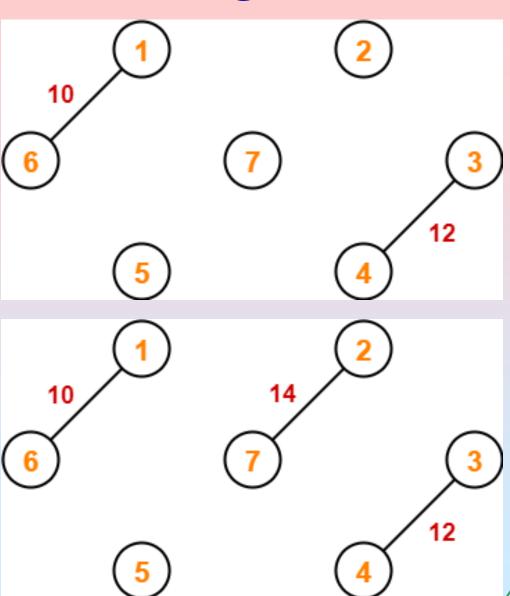
- Each component that remains selects a least cost edge with which to connect to another component.
- Beware of duplicate selections and cycles.

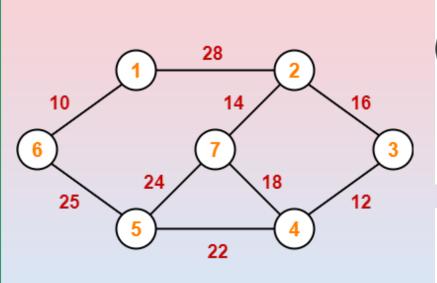
Construct the minimum spanning tree (MST) for the following graph using Kruskal's Algorithm

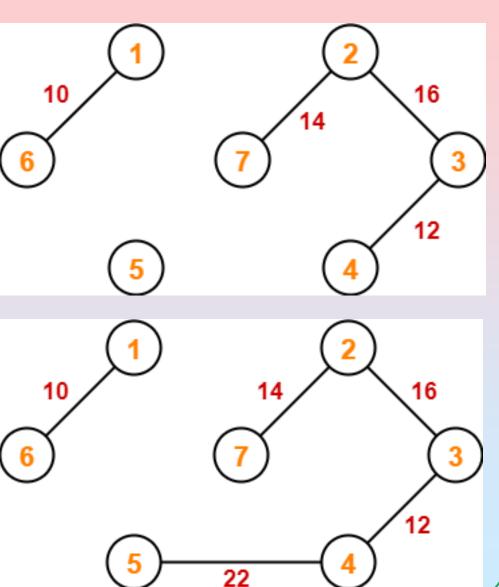


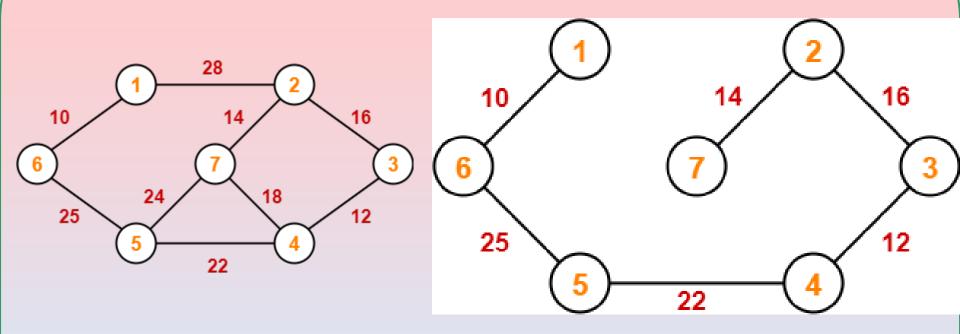








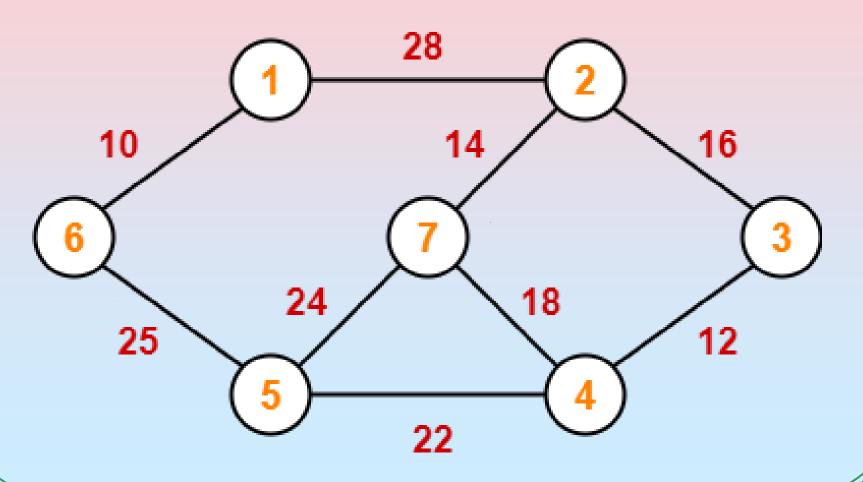




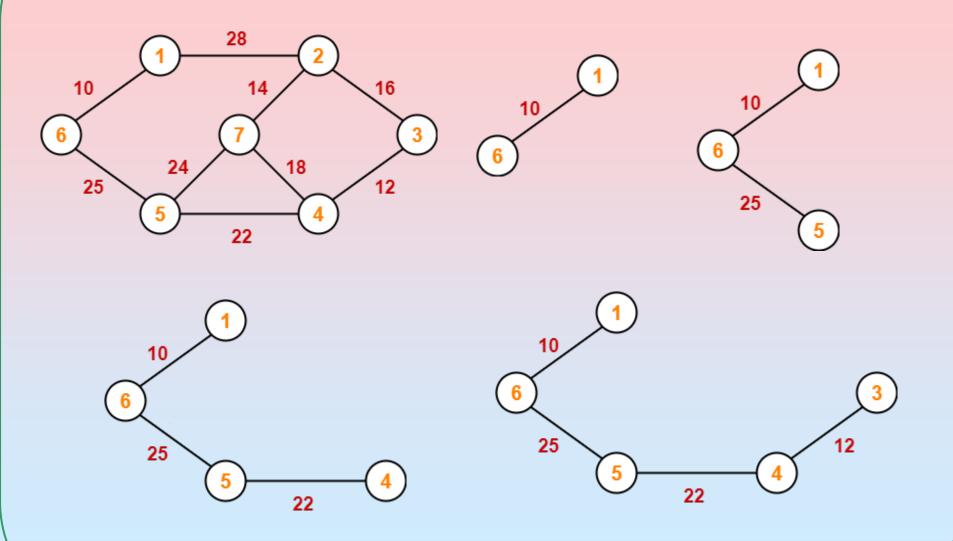
All the vertices have been included in the MST. Now, Cost of Minimum Spanning Tree

- = Sum of all edge weights
- = 10 + 25 + 22 + 12 + 16 + 14
- **= 99 units**

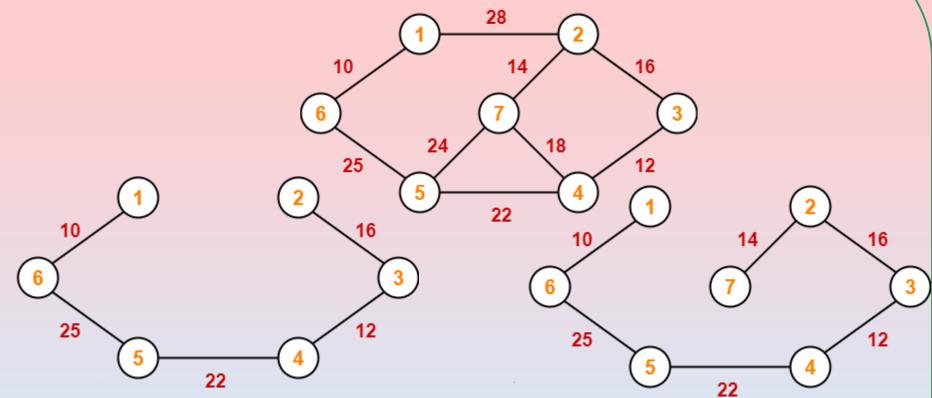
Construct the minimum spanning tree (MST) for the following graph using Prim's Algorithm



MST using Prim's Algorithm



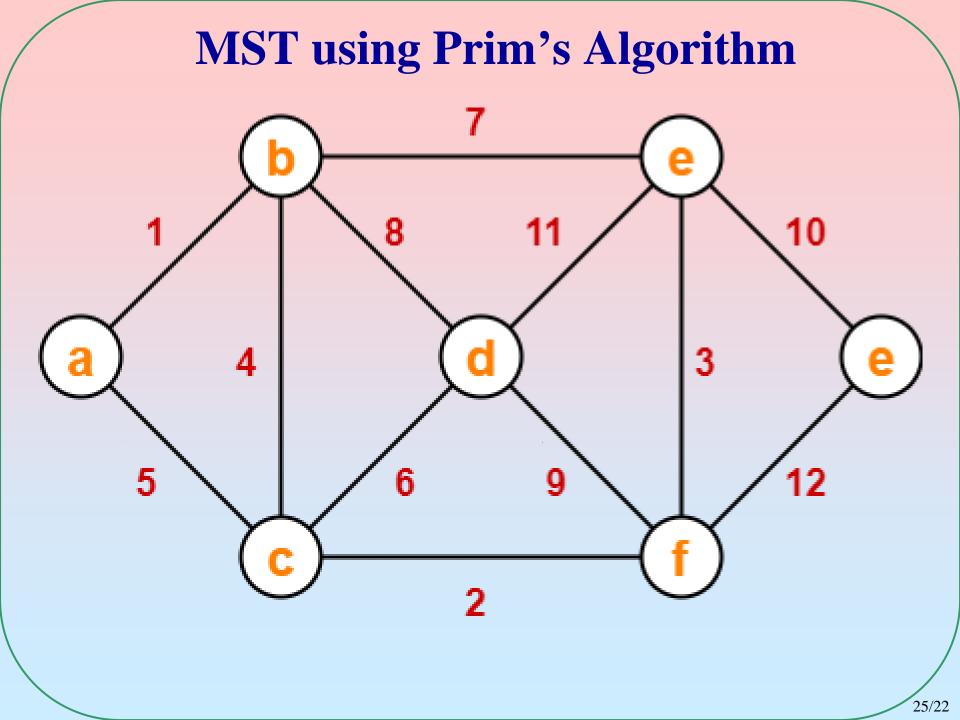




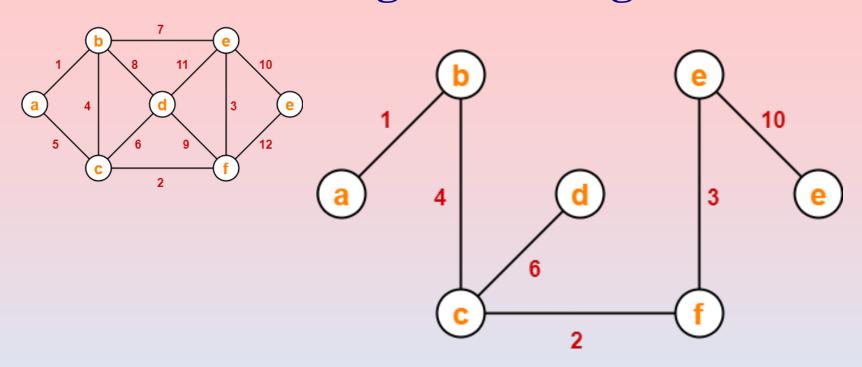
All the vertices have been included in the MST.

Now, Cost of Minimum Spanning Tree

- = Sum of all edge weights
- = 10 + 25 + 22 + 12 + 16 + 14
- **= 99 units**



MST using Prim's Algorithm



Cost of Minimum Spanning Tree

- = Sum of all edge weights
- = 1 + 4 + 2 + 6 + 3 + 10
- **= 26 units**

Minimum-Cost Spanning Tree Methods

- * Can prove that all stated edge selection/rejection result in a minimum-cost spanning tree.
- Prim's method is fastest.
 - O(n²) using an implementation similar to that of Dijkstra's shortest-path algorithm.
 - O(e + n log n) using a Fibonacci heap.
- ❖ Kruskal's uses union-find trees to run in O(n + e log
 e) time.

Pseudocode For Kruskal's Method

```
Start with an empty set T of edges.
while (E is not empty && |T| != n-1)
   Let (u,v) be a least-cost edge in E.
   E = E - \{(u,v)\}.
   if ((u,v) does not create a cycle in T)
    Add edge (u,v) to T.
if (|T| == n-1) T is a min-cost spanning tree.
else Network has no spanning tree.
```

Edge set E.

Operations are:

- Is E empty?
- Select and remove a least-cost edge.

Use a min heap of edges.

- Initialize. O(e) time.
- Remove and return least-cost edge. O(log e) time.

Set of selected edges T.

Operations are:

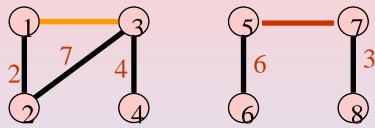
- Does T have n 1 edges?
- Does the addition of an edge (u, v) to T result in a cycle?
- Add an edge to T.

Use an array for the edges of T.

- Does T have n 1 edges?
 - Check number of edges in array. O(1) time.
- Does the addition of an edge (u, v) to T result in a cycle?
 - Not easy.
- Add an edge to T.
 - Add at right end of edges in array. O(1) time.

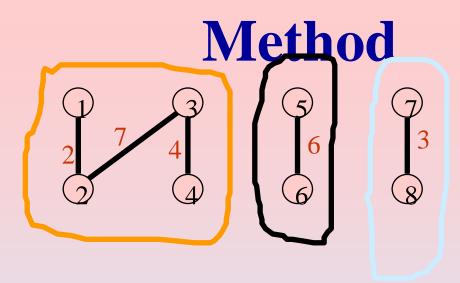
Does the addition of an edge (u, v) to T result

in a cycle?



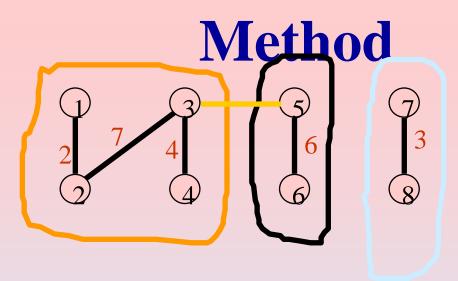
- Each component of T is a tree.
- When u and v are in the same component, the addition of the edge (u,v) creates a cycle.
- When u and v are in the different components, the addition of the edge (u,v) does not create a cycle.

Data Structures For Kruskal's



- Each component of T is defined by the vertices in the component.
- Represent each component as a set of vertices.
 - **1**, 2, 3, 4}, {5, 6},
- Two vertices are in the same component iff they are in the same set of vertices.

Data Structures For Kruskal's



- When an edge (u, v) is added to T, the two components that have vertices u and v combine to become a single component.
- In our set representation of components, the set that has vertex u and the set that has vertex v are united.
 - \blacksquare {1, 2, 3, 4} + {5, 6} => {1, 2, 3, 4, 5, 6}

• Initially, T is empty.

```
    3
    5
    2
    4
    8
```

- Initial sets are:
 - **•** {1} {2} {3} {4} {5} {6} {7} {8}
- Does the addition of an edge (u, v) to T result in a cycle? If not, add edge to T.

```
s1 = find(u); s2 = find(v);
if (s1 != s2) union(s1, s2);
```

- Use fast solution for disjoint sets.
- Initialize.
 - O(n) time.
- At most 2e finds and n-1 unions.
 - Very close to O(n + e).
- Min heap operations to get edges in increasing order of cost take O(e log e).
- Overall complexity of Kruskal's method is O(n + e log e).