# Distributed Systems – Fault Tolerance

#### Lab 2

#### 2021/2022

## **Quorum replication**

Use quorums for consistent replication with the lin-kv service. Store data as  $key \rightarrow (value, timestamp)$ , a set of locked keys, and implement the following operations:

- **Read** Collect (*value*, *timestamp*) from a read quorum, disregarding locking state, and return the *value* with the highest *timestamp*.
- Write In two steps:
  - Step 1: Pick a write quorum and collect *timestamp* from them, acquiring locks and returning an error if the lock is already taken.
  - If the quorum is not available, return error 11 to client and give up, informing replicas to release the locks.
  - Step 2: Select the highest timestamp and send (value, timestamp + 1) to the write quorum.
  - In each server, update (value, timesamp) and return an acknowledgment.
  - Wait for all acknowledgments and reply to client.
- CAS Similar to write, but use  $read \cup write$  quorum; collect values in step 1 to validate that from matches previous value.

### **Steps**

- 1. Implement the quorum protocol.
- 2. Test with different quorum combinations (ROWA, majority, ...).
- 3. Retest with increasing request rate (--rate) and network latency (--latency).
- 4. Discussion topics: Do reads need to respect locking? Why do writes need to be acknowledged? Does the protocol tolerate crashes?

**Learning Outcomes** Apply quorum replication for build a concurrent linearizable register. Recognize the relevance of quorums for fault tolerance.