How to Emulate Web Traffic Using Standard Load Testing Tools *

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Abstract

Conventional load-testing tools are based on a fifty-year old time-share computer paradigm where a finite number of users submit requests and respond in a synchronized fashion. Conversely, modern web traffic is essentially asynchronous and driven by an unknown number of users. This difference presents a conundrum for testing the performance of modern web applications. Even when the difference is recognized, performance engineers often introduce modifications to their test scripts based on folklore or hearsay published in various Internet fora, much of which can lead to wrong results. We present a coherent methodology, based on two fundamental principles, for emulating web traffic using a standard load-test environment.

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1 Introduction

Conventional load testing tools, e.g., Apache JMeter and HP LoadRunner, are simulators. More particularly, they are workload simulators that generate real-life application loads on a representative computing platform. These simulations are based on the paradigm that a fixed, finite, set of load-generator threads mimic the actions of a finite population of human users who submit requests to the test platform: the System Under Test (SUT). With the advent of web applications, however, this paradigm has shifted because the number of active users on the Internet is no longer fixed. At any point in time that number is dynamic and the workload mix is changing. This stands in stark contrast to the fifty-year old monolithic, time-share, computer paradigm inherent in standard load-testing tools.

Many performance engineers are polarized over how best to represent web-users with existing load-test tools. Some believe there is no significant issue, as long the number of load-generators is relatively large with the think time often set to zero (see Sect. 3.3), while others who recognize the problem are confused about how to correctly represent web requests [GOOG14]. It should be emphasized that this subject is fraught with confusion due to a lack of clear terminology and rigorous methods. See, e.g., [GOOG14, HASH10, NING09, SCHR06]. We attempt to correct that in this paper by developing two new web testing principles. As far as we are aware, this is the first time a consistent framework for simulating web-users has been presented in the context of performance engineering.

Our starting point is to recognize that typical test workloads and web workloads are very different and therefore need to be formalized very differently. Next, we establish the formal criteria needed to generate web requests. We then show how to verify the load generators actually produce web-like requests during a test. Finally, we present a detailed case study based on our methodology. The approach is similar to that implemented by AT&T Bell Laboratories to size telephone network components. There, fundamental queue-theoretic principles [GUNT11] formed the foundation and measurements were used to confirm it [HAYW82]. Our approach can be viewed as the historical descendent of the methods first devised one hundred years ago by Agner Erlang to do capacity planning for the telephone network belonging to the Copenhagen Telephone Company: the Internet of his day [ERLA17].

This paper is organized as follows. Section 2 establishes the difference between real web-based users and so-called *virtual users* in conventional load-test tools. Section 3 presents the first of the principles that define our methodology, viz., web testing Principle A. Section 4 presents the second of the principles that define our methodology, viz., web testing Principle B, and demonstrates the application of those two principles to load testing a large-scale website. Section 5 summarizes our conclusions. The reader is encouraged to click on technical terms in the text that are linked to definitions in a Glossary (Appendix B), particularly because various authors employ many of the same terms differently from us—another potential source of confusion.

2 Load Testing Simulations

To commence from a very broad perspective, the key difference between the workload generated using conventional load-test tools and the workload generated by actual web-based users can be characterized as the difference in the pattern of requests arriving at the SUT. Virtual users in a conventional load-testing environments generate a *synchronous* arrival pattern, whereas web-based users generate an *asynchronous* arrival pattern. Similarly, the queue-theoretic terms, closed system and open system [GUNT11], have also been used respectively in this connection [DIAO01, SCHR06]. We show how all these terms are related in Section 3.

2.1 Synchronous vs. asynchronous arrivals

Figure 1 is a graphical representation of the difference between synchronous arrivals in a closed system and asynchronous arrivals in a open system. Figure 1a shows how the average arrival rate into a typical (closed) test system *decreases* linearly with the level of concurrency because the rate of requests arriving from the load generators depends *synchronously* on the queueing state in the SUT.

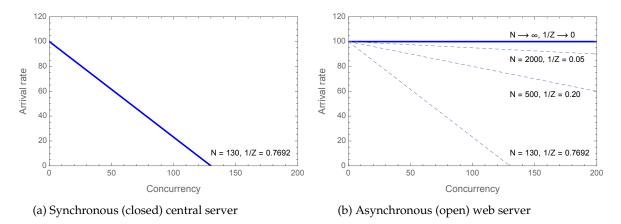


Figure 1: Comparison of arrival rates as a function of concurrent requests

Figure 1a represents the case of a load test system with up to N=130 virtual users, each with a mean think time setting of Z=1.3 seconds. The maximum arrival rate of 100 HTTP GETs/second occurs at near-

zero concurrency in the SUT, i.e., when there are few active virtual users. Conversely, at maximal load with all N=130 virtual users active, the arrival rate at the SUT falls to zero. The level of concurrency in the SUT cannot be greater than the number of active load generators. The slope of the load line corresponds to 1/Z: the mean request rate of each virtual user.

This retrograde effect—higher concurrency causes a lower request rate—seems counterintuitive but is easily explained. The logic in a typical load generation script only allows one outstanding request at a time, i.e., each virtual user cannot issue its next request until the current request has completed and returned a result. In other words, the more outstanding requests there are in the SUT, the fewer new requests can be initiated by the load generators. In this way, the driver-side of the test environment is synchronously coupled to the state of the SUT and produces the self-throttling characteristic seen in Fig. 1a. We shall revisit this effect in more detail in Section 3.

No such self-throttling is possible in a purely asynchronous or open system. To understand this difference consider the standard load test system in Fig. 1a where the number of active virtual users becomes extremely large $(N \to \infty)$. This situation is depicted in Fig. 1b with the load progressively increased as $N=130,500,2000,\ldots$ virtual users. Notice that the slope of the corresponding load line also decreases (due to the decreasing value of 1/Z) until it would ideally become constant at infinite load: the horizontal dashed line with zero slope in Fig. 1b. In the infinite load limit there is no dependency between the arrival rate and the level of concurrency in the SUT. The arrival rate becomes completely asynchronous or decoupled from the state of the SUT. A more detailed explanation is provided in Section 3.3.

This is most like the situation in real web sites. Requests, such as an HTTP GET, arrive into the web server from what appears to be an infinite or indeterminate number of users on the Internet. The only quantities that can be measured directly are the time at which requests arrive into the TCP listen-queue and the number of the requests in each measurement interval. The arithmetic mean of those samples can then be used to calculate summary statistics, such as the average arrival rate of requests. The number of requests residing in the web server is a measure of the level of concurrency in the system and is largely independent of the arrival rate. Sect. 3.2 contains a more detailed discussion about concurrency.

The goal of our methodology is to find a way to reduce synchronization effects in the SUT so that requests appear to be generated asynchronously, or nearly so. Put more visually, we want to "rotate" the load line in Fig. 1a counterclockwise until its slope approaches the horizontal line in Fig. 1b. Moreover, we want to achieve that result without necessitating any exotic modifications to the conventional load-test environment.

2.2 Web simulation tools

To give some perspective for our later discussion, we provide a brief overview of other tools that claim to simulate web traffic. Commercial load testing products come with their own inherent constraints for web-scale workloads due to licensing fees being scaled to the number of cloned load generators. For example, a relatively modest 500 client LoadRunner license can cost around \$100,000 [QUOR10]. Open source JMeter, however, can be extended to more than 1000 users by resorting to a JMeter cluster to provide enough driver capacity. But that approach also comes with its own limitations [FOAL15]. JMeter can also be configured to do distributed testing, including on *Amazon Web Services*. Commercial web-based simulation tools are provided by SOASTA, BrowserMob, Neustar, and Load Impact.

Some cautionary remarks about these tools are in order. It can be confusing to understand whether tests are being run in their entirety on a cloud-based platform, like AWS EC2 instances or, whether the EC2 instances are being used merely as load generators to drive the web site SUT across the Internet. In other words, the performance engineer needs to understand whether the load generators are *local* or *remote*, relative to the SUT. Those questions notwithstanding, none to these approaches would make any difference if the scripts still produce synchronous arrivals as defined in Sect. 2.1.

2.3 Virtual users and web users

In the conventional language of load testing, the load generators represent virtualized human users or *virtual users*, for short. It is these virtual users that provide the test workload. In fact, virtual users are just a fixed set of process threads that run on separate computational resources that are distinct from the SUT. As well as emitting HTTP GET and HTTP POST requests into the SUT, virtual-user threads typically incur a parameterized delay between receiving the response to the previous request and issuing the next request. Since this delay is intended to represent the time a human user spends "thinking" about what to do next, and therefore what kind of request is issued next, it is commonly known as the think time and is often denoted by Z in queue-theoretic parlance [GUNT11].

The conventional load testing methodology has all the virtual-user threads that belong to a given group perform the same sequence of requests repeatedly for the entire period of each load test.

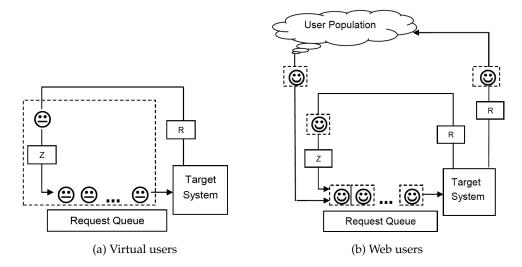


Figure 2: Comparison of virtual users in a test rig and web users on the Internet

Figure 2a depicts this fixed virtual-user simulation schematically with each virtual-user thread, represented by a straight face \bigcirc , repeatedly cycling through five phases:

- Make a web request into the target SUT
- Wait for and measure the time of the response (with mean time *R*)
- Sleep for a think time (with mean time Z)
- Wake up and wait in the OS run-queue (with mean time W)
- Compute the requested results and return them (with mean service time S)

The activity of real web users, however, differ significantly from this scenario. Figure 2b depicts these web users as smiley faces ©. Although Figs. 2a and 2b look similar, the following differences are important to understand.

Driver operating system: The dotted box in Fig. 2a represents a single operating system instance. In a standard load-test environment, all the virtual users share that same operating system. Conversely, the real web-users in Fig. 2b have a face because each of them runs in their own private operating system. In other words, the activity of a real user cannot be limited by an exhausted thread pool. Failure to recognize this potential driver-side constraint is a classic gottcha in load testing scenarios. See, e.g., [BUCH01] and [GUNT11, Chap. 12].

Heterogeneous requests: Each \bigcirc virtual user generally issues only one HTTP GET or HTTP POST request at a time. Each \bigcirc web user, on the other hand, can issue more than one type of HTTP request to retrieve multiple web objects that may comprise a complete web page.

Cycling population: Real web users are not restricted by the closed-loop structure of the standard test environment in Fig. 2a. Rather, web-users can come and go from a much larger but inactive population of users. This difference provides a pivotal insight for our approach.

Overall, these distinctions tell us that real web users act like a variable sized set of threads that move in and out of the active thread pool to initiate HTTP requests. Accordingly, we want to find a way to have the fixed virtual users in Fig. 2a emulate the real web users in Fig. 2b.

3 Web Testing Methodology

The key insight into producing an asynchronous request pattern with otherwise synchronous load-test tools comes from a comparison of the load-test simulation models with the appropriate queue-theoretic models [GUNT10a, GUNT10b, GUNT11, GUNT15, BRAD14, SCHR06]. Queueing metrics best capture the nonlinear relationship between well-known performance metrics. For our purposes, we only need to undertand two basic types of queues:

Open queue: An open queueing system involves asynchronous requests where the number of users generating those requests is unknown.

Closed queue: A closed queueing system involves synchronized requests where the number of users generating requests is finite and fixed.

The dynamics of these queues differ dramatically and therefore they need to be characterized in completely different ways. We consider asynchronous request patterns first because they are associated with a simpler queueing structure than synchronous request patterns, which we deal with in Sect. 3.2.

3.1 Asynchronous open users

The asynchronous workload referred to in Section 2 is called an open system in queueing theory parlance [GUNT11, KLEI75]. The term "open" is meant to indicate that requests arrive from an unknown number of users existing *outside* the queueing facility—indicated by the cloud in Fig. 3, which should be compared with Fig. 2b.

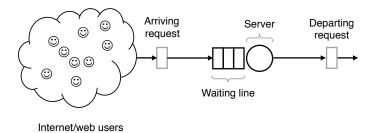


Figure 3: Open queue schematic representing asynchronous web requests

An open queueing center, shown schematically in Fig. 3, is the simplest to characterize with queueing metrics that represent averages or statistical means. Requests arrive from the left at a measurable rate λ , wait in line for some time, W, incur a time, S, to get serviced and finally depart the facility. The total time spent in the queueing facility is given by

$$R = W + S \tag{1}$$

and is called the residence time. It is the time spent in the queueing facility from arrival to departure. R can also be regarded as the response time for a single queue.

This open queue can be thought of as a very simple representation of a web site where the arrivals are HTTP GET requests generated by an unknown, and possibly large, number of Internet-based users. Some proportion of those users will be actively sending requests to the web site while others are perusing the content resulting from previous web server responses. In queueing theory parlance, these latter users are said to be in a "think state."

Although the actual number of users submitting requests is indeterminate, the *number of requests* resident in the web server, Q, is simply the sum of those requests that are waiting for service (λW) plus those that are already in service (λS) . From eqn. (1):

$$Q = \lambda W + \lambda S = \lambda R \tag{2}$$

This is one version of Little's law [GUNT14b]. The steady-state arrival rate can be measured directly with a probe or calculated using the definition [GUNT11]

$$\lambda = A/T. \tag{3}$$

where A is the counted number of arrivals and T is measurement period. The corresponding departure rate is X=C/T, where C a count of the number of completed requests. During any suitably long measurement period, the open queue will be in *steady state* such that arrivals count will closely match the number of completed requests, i.e., A=C. It follows from this that $\lambda=X$ in steady state. The departure rate is more commonly known as the *throughput* and is a system metric that is measured by all load test tools.

In many practical situations, the periods between arriving requests are found to be exponentially distributed [BRAD12]. See also, *Are Your Data Poissonian?* in [GUNT11, Chap. 3]. When the service periods are also exponentially distributed with mean time, S, the queue in Fig. 3 is denoted M/M/1, where 'M' denotes "memoryless" (or Markovian, more formally). This memoryless feature is a property of the exponential distribution which, in turn, is associated with a Poisson process. Essentially, it means that history is no guide to the future when the time periods are exponentially distributed. We will make use of this feature in Sect. 4.

Our use of the term asynchronous also seems particularly appropriate in light of Erlang's original development of the M/M/m queue to predict the waiting times at telephone switches. The 'A' in ATM stands for 'asynchronous' and Asynchronous Transfer Mode switches form the backbone of the modern Internet.

The important point for our discussion is that the explicit relationship between the asynchronous arrival rate, λ , and the number of active Internet users is unknown. Consequently, there can be an unbounded (but not infinite) number of requests in the system, independent of λ . (See Fig. 1b)

3.2 Synchronous closed users

As noted earlier, virtual users in a standard load-test system cycle through the SUT in the sense that no new request can be issued by a virtual user until the currently outstanding request in the SUT has been serviced. This loop structure depicted in Fig. 2a will now be reflected in a corresponding closed queueing model.

In contrast to an open queue, a closed queue is actually comprised of two queues connected by the flow of requests and responses circulating between them. For historical reasons in the development of queueing theory, this system is sometimes referred to as the *central server* or the *repairman* model [GUNT11]. The two queues are:

- 1. N sources of requests (top queue in Fig. 4). These sources correspond to the load-test generators representing virtual users. Since each source effectively has its own service center (shown as if faces corresponding to those in Fig. 2a), no waiting line forms at this queue.
- 2. The system under test (bottom queue in Fig. 4). Although there are potentially many queueing facilities associated with actual computing resources in the SUT, for simplicity and without loss of generality, we show the SUT here as a single queue.

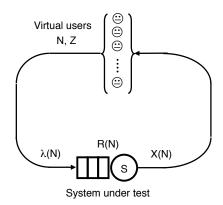


Figure 4: Closed queue schematic representing synchronous load-test requests

Since there are no requests arriving from outside this system (the meaning of "closed"), the flow in Fig. 4 appears as a loop.

For a given load test, each of N generators executes a script that issues a request into the SUT. Unlike the open queue of Sect. 3.1, with a potentially unbounded number of requests in the system, there can never be more than N requests in the closed system. The corresponding queue-theoretic notation is M/M/1/N/N [GUNT11]. In actual test environments, the number of active generators may be restricted by the cost of licensing fees for commercial test tools, and the number of available threads. (See Sections 4.3 and 4.4)

The response of the SUT is measured in terms of the overall throughput, X and residence time, R. When the response is received by the associated generator, it will generally incur a predetermined delay, Z, before issuing the next request. This behavior is identical to the perusal time associated with the human users in the open queue and is called the think time. The average think time, Z, is a programmable parameter in the generator script. During test execution, each script draws a random think-time variate from a known statistical distribution, e.g., a uniform or exponential distribution having a mean equal to Z.

A key distinction between an open queue and a closed queue is that there cannot be more than one request outstanding from each generator. This constraint has the consequence that if all N generators have issued requests into the SUT, there cannot be any more arrivals until at least one of those requests has completed service, and also possibly incurred a think delay, Z. The effective arrival rate has fallen to zero!

In this sense, a closed queue is *self-throttling* due to the negative feedback loop in Fig. 4. The more requests in the SUT, the lower the instantaneous arrival rate at the SUT, and vice versa. Moreover, the mean arrival rate is no longer constant but must therefore depend functionally on the N users. We present function, $\lambda(N)$ in eqn. (8) of Sect. 3.3.

The total round-trip time, R_{TT} , for a request in Fig. 4 is the sum of the time spent in the SUT and the time spent "thinking" in the generator script:

$$R_{TT} = R + Z \tag{4}$$

When a serviced request returns to its corresponding generator script, the think time, Z, can be regarded as a special kind of service time—the service time on the driver side of the test platform (top queue in Fig. 4). Then, λZ represents the total number of generators that are in a think state.

Similarly, the total number of requests in the system is given by Little's law [GUNT11]

$$N = \lambda R_{TT} \tag{5}$$

which is the counterpart of eqn. (2). Expanding eqn. (5) produces

$$N = \lambda R + \lambda Z \tag{6}$$

In steady state, the total number of requests active in the closed system is the sum of those in the SUT, i.e., λR , together with those in a think state, λZ , on the generator side of the testing environment. We will make use of eqn. (6) to determine the number of real web-users in Sect. 4.5. Substituting the expression for Q from eqn. (2) into eqn. (6) shows how the total number of requests in the test system is related to the queue length (i.e., requests that are waiting together with requests that are already in service) on the SUT.

$$N = Q + \lambda Z \tag{7}$$

Equation (7) provides an opportunity to disambiguate the term "concurrency" in the context of a load-test environment (see e.g., [GOOG14, WARR13]). Broadly speaking, the level of concurrency refers to the number of processes or threads that are *acting* simultaneously. But, like the term *latency*, concurrency is often too generic to be really helpful for accurate performance analysis. For example, it could refer to:

- 1. the size of the generator thread-pool
- 2. the number of active threads
- 3. the number of virtual users
- 4. the number of active processes on the SUT

This is where our notation is helpful. We can immediately reduce the options to choosing between N and Q. The difference between these quantities is the number of processes or threads that are in a think state, viz., λZ . We know that N represents the maximal number of users that can possibly generate requests into the SUT. In a closed queueing system, this number is split between the number of outstanding requests, Q, that are actively residing on the SUT and the number of users that are thinking, λZ . We note that [COOP84] calls these thinking processes, "idle" with respect to the SUT in that they will eventually issue requests but have not done so, yet. Clearly, if all the generators were in such an idle state then, Q=0 and no load would be impressed on the SUT. If we take "acting" to mean executing on the computational resources of the SUT then, the level of concurrency is Q in eqn. (7). Indeed, Q is the metric represented on the x-axis in Fig. 1.

3.3 Web testing principle A

Rearranging eqn. (7) and dividing both sides by Z yields

$$\lambda(N,Z) = \frac{N}{Z} - \frac{Q(N)}{Z} \tag{8}$$

which tells us how the arrival rate varies as a function of both choice for the user load N and the think time Z setting in a closed system. For any chosen value of Z, eqn. (8) remains a nonlinear function of N because the concurrency, Q, in the SUT is a nonlinear function of N. (See Fig. 5)

The arrival rate, $\lambda(N,Z)$ in eqn. (8), forms the basis of the methodology to be presented in the subsequent sections and to illustrate how it contains the performance characteristics of both virtual user and web user workloads, we developed a theoretical model in PDQ [GUNT15] the results of which are shown in Table 1.

Table 1a corresponds to a typical load-test environment where the think time is held constant at Z=10 seconds while the number of virtual users is increased by almost an order of magnitude in an attempt to emulate web users. Naturally, as N increases, the ratio N/Z increases. Similarly, the number of concurrent requests, Q, in the SUT also increases dramatically due to the increasing number of load generators. Hence, the Q/Z ratio increases. Recall that the synchronization of a closed system comes from the requirement that each virtual user can have no more than one outstanding request, and Q is a measure of the total number of outstanding requests. The difference between these two ratios in eqn. (8) is the average arrival rate into the SUT, λ , which clearly is not constant. This already suggests that increasing N alone cannot accurately mimic web traffic.

Table 1: Theoretical comparison of (a) constant Z and (b) scaled Z load models

(a) Constant Z virtual users

(b) Scaled Z web users

N	Z	N/Z	λ	Q	Q/Z
100	10	10.00	9.80	2.01	0.20
200	10	20.00	18.46	15.37	1.54
400	10	40.00	19.95	200.52	20.05
600	10	60.00	19.98	400.17	40.02
800	10	80.00	19.99	600.09	60.01
1000	10	100.00	19.99	800.05	80.01

N	Z	N/Z	λ	Q	Q/Z
100	5	20.00	17.80	11.02	2.20
200	10	20.00	18.46	15.37	1.54
400	20	20.00	18.93	21.38	1.07
600	30	20.00	19.14	25.95	0.86
800	40	20.00	19.26	29.78	0.74
1000	50	20.00	19.34	33.15	0.66

Table 1b shows what happens when the N/Z ratio is held constant at 20 HTTP GETs/second. This is achieved by scaling the think time, Z by the same proportion as the increase in the number of generators, N. Notice the dramatic difference in the SUT concurrency. Compared with Q in Table 1a, it grows relatively slowly. This effect is explained as follows. Although the number of load generators is increased, as in the constant-Z case, the delay between the completion of one request and the start of the next is also increased in the same proportion. Consequently, the number of concurrent requests in the SUT increases only very slowly. In this scaled-Z case, the contribution from the Q/Z ratio diminishes rapidly such that the effective arrival rate into the SUT quickly approaches the constant ratio N/Z. (See Fig. 5)

That both scenarios in Table 1 exhibit saturation effects is noteworthy because each is due to a very different cause. The plateauing in λ of Table 1a, starting around N=800 virtual users, is the result of physical resource saturation in the SUT. It is a physical bottleneck determined by the longest of the service demand, S_{max} , such that [GUNT11, Chap. 7]

$$\lambda_{sat} = \frac{1}{S_{max}} \tag{9}$$

The bound in eqn. (9) represents the maximum possible throughput that the SUT can achieve. In this case, $S_{max}=50$ milliseconds so, $\lambda_{sat}=20$ HTTP GETs/second. In contrast, the plateauing in Table 1b is a result of constraining N and Z to scale as a fixed ratio

$$\lambda_{rat} = \frac{N}{Z} \tag{10}$$

Since N and Z can be chosen arbitrarily, λ_{rat} can take on any value as long as it satisfies the condition

$$\lambda_{rat} \le \lambda_{sat}$$
 (11)

as exhibited in column 4 of Table 1b. The choice of $\lambda_{rat} = \lambda_{sat}$ in Table 1 was made for simplicity. In general, however, since λ_{rat} can be chosen by the performance engineer, we shall refer to it as a *soft bottleneck*. This throughput bound is depicted as a (*blue*) horizontal line in Fig. 5 of Sect. 3.4.

Asynchronous requests, as defined in Sect. 3.1, create a constant mean arrival rate that corresponds to the horizontal line in Fig. 1b. In that case, the goal should be to have $\lambda = \lambda_{rat}$ to reflect the independence of the request rate from Q in eqn. (8). However, the presence of the Q/Z term means λ is not independent of Q and that is responsible for the slope in the load line seen in Fig. 1a. If the magnitude of Q could be made relatively small, that slope would become shallower which would indicate the synchronization of virtual-user requests had become weaker. In other words, the synchronous requests would look more and more like the asynchronous requests of the web users we want to mimic: the load line with near-zero slope in Fig. 1b. The most efficient way to achieve that result is shown numerically in Table 1b. There, the ratio N/Z is held constant while increasing the load N. It is the *royal road* to producing asynchronous requests with arrival rate λ_{rat} . But how is this trick actually achieved in a real test environment?

Equation (8) assumes that the level of concurrency is smaller than the number of generators, i.e., Q < N. If it were the case that Q > N, the arrival rate at the SUT would be negative, which is not physically possible. If both parameters were very close in value, i.e., $Q \simeq N$, the arrival rate would become

impractically small for load testing purposes. In other words, it is the relative magnitudes of each of N, Q, and Z that determine the value of λ .

To help ensure Q < N (actually, much smaller, $Q \ll N$, as we shall see) in a real test environment, the value of Z can be *increased* in the test script. In Table 1a, each virtual user thinks for a mean period of Z=10 time units (i.e., seconds). Suppose, however, that instead of treating Z as a think time, we treat it as free parameter in the load-test simulator, i.e., use Z as a control knob to tune the web-user approximation to whatever accuracy we desire. In that vein, it is more useful to consider the inverse quantity, 1/Z: the mean emission rate of user requests. If we retard the virtual user emission-rate by increasing Z, the number of concurrent requests in the SUT will also be reduced, i.e., Q will become small. This effect can be seen clearly in Table 1b and a real example is presented in Sect 4.3.

Now, this is where the magic happens. Little's law in eqn. (2) tells us that the response time, R, is directly proportional to the number of requests, Q, residing in the SUT. If Q is long, then an arriving request will have to reside in the SUT for a longer time than if Q were short. The size of Q is determined by how many other requests are still outstanding in the SUT. Therefore, the expected R of an arriving request from the nth virtual user depends on the state of the other n-1 virtual users. This dependency or interaction between users occurs in the queues of the SUT. In this way, virtual users are correlated in time and therefore lack statistical independence. As Q becomes small, so does the time spent in the SUT. If R is small (e.g., R < Z) then, the time for which each virtual user request remains outstanding also becomes small. In the limit, if Q=0 or, equivalently R=0, there would be no outstanding requests at all (there would also be no work for the SUT to do) and each virtual user would no longer be constrained by the synchronization of the closed feedback loop in Fig. 4. Moreover, there would be no interaction in the SUT, so virtual users would also become statistically independent. In other words, in that limit, requests would become asynchronous and virtual users would be transformed into statistically independent web users, each having a very low request rate, 1/Z, because Z is now relatively large. Since there are N of these web users making requests,

$$\lambda = \underbrace{\frac{1}{Z} + \frac{1}{Z} + \ldots + \frac{1}{Z}}_{N \text{ web users}} = \frac{N}{Z},$$
(12)

which is their aggregate request rate into the SUT. And since λ would be independent of Q, it would also be consistent with Fig. 1b.

Real web users, however, do induce work in the SUT, so the idealized requirement Q=0 is too severe. In fact, eqn. (8) only requires that the ratio Q/Z be small, i.e., Q can be non-zero as long as Z is relatively large. This more relaxed condition means N can also be relatively large without causing request synchronization to re-emerge, and that is what we see in Table 1b.

With this intuitive explanation of how virtual users are transformed into web users by eqn. (8), we can state the first guiding principle of our test methodology.

Principle A

To efficiently emulate web traffic the mean think-time, Z, in each of the N load generators should be scaled with N such that the ratio N/Z remains constant thereby ensuring the request rate λ approaches the soft bottleneck rate λ_{rat} .

Principle A is the royal road for attaining statistical independence by reducing the per-user request rate into the SUT. It also makes clear why the common practice among performance engineers of setting Z=0 in the generator scripts is actually fallacious when it comes to emulating web traffic. The intuition behind setting zero think time is that it increases the mean request rate into the SUT and that corresponds to the much larger number of real web users. In fact, it is counterproductive for emulating web users, where the goal is to *reduce* the per-user request rate so as to keep R small in the SUT relative to Z. That is how the requirement of statistically independent web requests is achieved.

We can also use Principle A to explain Fig. 1. In the synchronous queueing system of Fig. 1a, for a given load value N, the level of concurrency, Q, controls the arrival rate via the second term in eqn. (8). Larger Q value means longer queues so, the time spent in the SUT will also be longer. That also means requests remain outstanding for longer so, fewer new requests can be generated. That is the basis for the synchronous feedback loop in Figs. 4 and 2a. That the synchronous arrival rate decreases in direct proportion to Q is reflected by the minus sign in eqn. (8). The negative sign is responsible for the negative slope in Fig. 1a.

Conversely, in the asynchronous queueing system of Fig. 1b, the arrival rate is independent of Q and therefore appears as a horizontal line at height N/Z on the y-axis. This situation is tantamount to setting Q=0 in the second term of eqn. (8), as already explained above. The interested reader will find a different, but related, argument based on taking the continuum limit of a Binomial distribution in [COOP84].

Although we have used very simple queueing models in this section to establish Principle A of our methodology, the same results hold for more elaborate queueing models that reflect realistic systems. For example, a multi-tier web site can be modeled by replacing the single queue representing the SUT in Fig. 4 by a set of single queues arranged in series and parallel with respect to their flows [GUNT11, GUNT15].

3.4 Visualizing principle A

Figure 5 presents a visual interpretation of eqn. (8) that underlies Principle A. The theoretical curve is the arrival rate, $\lambda(N)$ for any continuous value of N, corresponding to the discrete load points in Table 1b, which are indicated by the blue dots sitting on that curve.

 $\lambda(N)$ increases monotonically with N and approaches the bound λ_{rat} in eqn. (10), depicted by the dashed horizontal line. In this case, the soft-bottleneck is located at $\lambda_{rat}=20$ HTTP GETs per second, as can be read off from the right-hand vertical axis. Notice that the plot actually has four axes:

- 1. A conventional x-axis (positioned as a *midline*) showing generator load in the range $N \in [0,1000]$
- 2. A left-side y-axis showing both positive response time values in the range $R \in [0, +50]$ above the x-axis and negative values $R \in [0, -50]$ below the x-axis
- 3. A right-side y-axis showing positive arrival rate values $\lambda \in [0,25]$
- 4. Three diagonal lines passing through red circles at N=200,400,1000 that also intersect the left-side y-axis at R=-10,-20,-50, respectively

Therefore, to fully appreciate the dense information contained in Fig. 5 requires a little orientation.

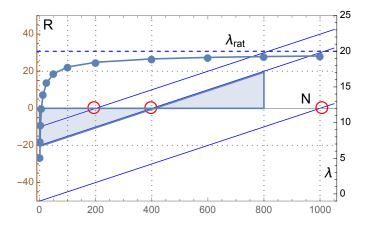


Figure 5: Convergence of $\lambda(N)$ toward $\lambda_{rat} = 20$ (triangle slope) according to Principle A

The continuous curve $\lambda(N)$ is computed for all possible theoretical load levels in the range $N \in (0,1000]$ and therefore includes the specific data points of Table 1b. However, the curve is not determined uniquely by N. Equation (8) is really a function of both N and Z, i.e., $\lambda = \lambda(N,Z)$, which simply expresses the fact that the test workload intensity is controlled by the number of load generators (N) and the think delay (Z) set in the test script. Normally, Z is a fixed constant so, there is no need to mention it explicitly. Principle A, however, requires that we do pay close attention to the Z value because it is not fixed in eqn. (8).

The x-position of each data point (solid dot) corresponds to its load value N. The subset of data values in Table 1b corresponds to the six dots starting on the left side of the plot at N=100 and ending on the right side at N=1000. To explain the procedure for finding the associated Z values from the diagonals, we consider the data points at N=200,400 and 1000 virtual users as examples.

Example 1 (N=200 ratio). Consider the solid dot corresponding to $\lambda(200,Z)$ located at N=200. Identify the red circle below it and locate the diagonal that passes through that circle. Follow that diagonal downward to where it intersects the y-axis on the left side of Fig. 5. The magnitude of that number corresponds to the associated Z value. In this case, the diagonal intersects in the negative part of the y-axis (below the x-axis) at the value -R=10. Since by definition the y-axis is the vertical line located at x=0, the R-axis is located at N=0 in Fig. 5. With zero active users, there are no requests in circulation and the round trip time is $R_{TT}=0$ at zero load. By eqn. (4) that is equivalent to R+Z=0. Consequently, if R=-10 then Z=10, and the ratio N/Z=200/10=20 HTTP GETs/second.

Note that the magnitude of the ratio N/Z=20 is equivalent to the value of λ_{rat} (the horizontal blue line) as indicated on the λ -axis of Fig. 5. It is the maximum possible arrival rate that can be achieved in this system that is consistent with the soft bottleneck defined by Principle A.

Example 2 (N=400 ratio). Repeating the same steps as Example 1 for the solid dot corresponding to $\lambda(400,Z)$ located at N=400, we see that the associated diagonal line intersects at R=-20 or Z=20. Again, N/Z=400/20 or equivalently, $\lambda_{rat}=20$ HTTP GETs/second.

Example 3 (N = 1000 ratio). Similarly, for the solid dot corresponding to $\lambda(1000, Z)$ located at N = 1000 the associated diagonal intersects at R = -50 yielding N/Z = 1000/50 or $\lambda_{rat} = 20$ HTTP GETs/second.

As noted in Sect. 3.3, the sharp nonlinearity in the curve arises from the rapid diminishment of the queueing term, Q/Z, in eqn. (8). The difference between the two terms in eqn. (8) can also be visualized using Fig. 5. The difference is the vertical gap between the curve and the soft bottleneck bound at λ_{rat} with the gap size equal to the magnitude of Q/Z. As N is increased (to the right), the size of the gap gets smaller, which shows why λ_{rat} is an asymptotic bound. The following examples provide numerical verification.

Example 4 (Vertical difference $\Delta\lambda(200)$). From Example 1 we have $\lambda_{rat}=20$ HTTP GETs/second and from Table 1b we note that Q/Z=1.54 at N=200 (row 2). The vertical difference between the horizontal line and the solid dot at N=200 is given by $\Delta\lambda=20-1.54=18.46$. This is precisely the height of the dot on the right-hand λ -axis, i.e., $\lambda(200,10)=18.46$ HTTP GETs/second, in agreement with column 4 of Table 1b.

Example 5 (Vertical difference $\Delta\lambda(400)$). From Table 1b we have Q/Z=1.07 at N=400 (row 3). The vertical difference between the horizontal line and the solid dot at N=400 is given by $\Delta\lambda=20-1.07=18.93$ or $\lambda(400,20)=18.93$ HTTP GETs/second, in agreement with Table 1b.

Example 6 (Vertical difference $\Delta\lambda(1000)$). From Table 1b we have Q/Z=0.66 at N=1000 (row 6). The vertical difference is given by $\Delta\lambda=20-0.66=19.34$ or $\lambda(1000,50)=19.34$ HTTP GETs/second, as seen in Table 1b.

Referring now to the shaded triangles in Fig. 5, the associated red circle at N=400 sits at the vertex of an upside-down right-angled triangle (*left shaded area*). The base of this triangle therefore has length of 400. Its hypotenuse lies on the diagonal that intersects the R-axis at R=-20, as mentioned in Example 2. This just corresponds to an upside-down height |R|=20. The conjugate right-angled triangle with positive

height R=+20 is shown between the grid lines at N=400 and 800 (right shaded area). The hypotenuse of both triangles lie on the common diagonal line. The slope of the diagonal line is given by the rise over the run of either triangle, viz., Z/N=20/400, which is the inverse of λ_{rat} analogous to λ_{sat} in eqn. (9).

The same logic can be applied to the smaller triangle formed by the first red circle at N=200, as well as the much larger triangle formed by the rightmost red circle at N=1000. Because all such triangles are similar triangles, they explain why the ratio N/Z=20 is held constant in eqn. (8). Scaling the ratio N/Z in Principle A is the same as maintaining the triangular proportions associated with each value of N in Fig. 5.

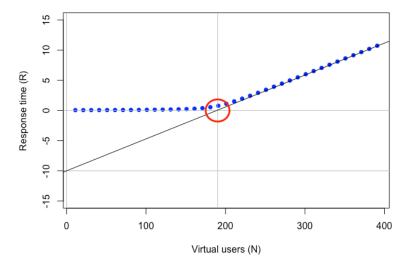


Figure 6: Typical response-time data (*solid dots*) for a closed queueing system with Z=10 showing the classic hockey-stick shape. The hockey-stick handle is always asymptotic to the diagonal line (R_{∞}) given by eqn. (14) with slope S_{max} . Extending the asymptote below the x-axis (horizontal line at R=0) always intersects the y-axis (vertical line at R=0) at R=-Z

Of course, the reader is likely wondering where the diagonal lines come from in the first place. In closed queueing models, the think time, Z is usually considered as part of the round-trip time, R_{TT} in eqn. (4), not the arrival rate, λ . However, in a load-test model (Fig. 4), N and Z are the two parameters on the driver side that control the rate of requests associated with the synchronous workload. The diagonal lines in Fig. 5 belong to the response-time (R) for a closed queueing system: previously identified with the load test environment in Sect. 3.2. Each diagonal line is the asymptote that controls the slope of the classic "hockey stick" shape of response time measurements (cf. Fig. 10 top-left) in a closed system [GUNT11, see Fig. 7.3 there]. Figure 6 is provided as a reminder of how this works.

The response-time data (*solid dots*) in Fig. 6 start out approximately horizontally (i.e., roughly parallel to the x-axis) because the queue lengths are typically small at low loads, so the response times are approximately constant or slowly increasing. The general expression for the response time in a closed queueing system is given by

$$R(N) = \frac{N}{X(N)} - Z \tag{13}$$

The explicit loop structure in Fig. 4 is contained implicitly in eqn. (13) since both the response time R and the throughput X are dependent on N so, in general, this equation cannot be solved analytically and one must resort to computational tools like PDQ [GUNT11].

Eventually, the bottleneck resource (i.e., the resource with the longest mean service period, S_{max}) saturates in accordance with eqn. (9) and that causes queues to grow dramatically. This rapid increase in queue length (due to the number of concurrent requests in the SUT) causes the response-time data (solid dots) to increase along the diagonal "handle" of the hockey stick. This follows from the fact that the

asymptotic form of eqn. (13), i.e., for large N, is given by [GUNT11, Sect. 7.4]

$$R_{\infty} = N S_{max} - Z \tag{14}$$

This is simply the equation for a straight line with the general form y=mx+c where m is the gradient of the line and the constant c is the point of intersection with the y-axis, i.e., the value of y at x=0. By analogy, the slope $m=S_{max}$ and the intersection with the R-axis occurs at N=0 in eqn. (14), i.e., at $R_{\infty}=-Z$. In Fig. 6 it corresponds to R=-10 or Z=10 at N=0. This is the justification for introducing the diagonal axes or Z-lines in Fig. 5 to indicate the associated value of Z required by eqn. (8).

Figure 5 shows why N or Z must be varied as a pair of values (N,Z) in order to mimic the asynchronous workload in Table 1b. The typical load-testing scenario in Table 1a, with $N \to \infty$, is tantamount to letting the SUT choose λ_{rat} for you, viz., $\lambda_{rat} = \lambda_{sat}$, which might not be appropriate. Conversely, the scaled-Z approach offers the performance engineer an infinite variety of choices for running load-test simulations with λ_{rat} matched to measured values of real-world asynchronous web traffic. We make use of similar opportunities in Sect. 4.4.

4 Applying the Methodology

Sect. 3.3 has provided the conceptual basis of the methodology embodied in Principle A. It tells us how to adjust the think time setting in the load generators so that synchronous virtual users are transformed into asynchronous web users. In this section, we want to verify that Principle A indeed produces the correct statistical traffic pattern associated with asynchronous web users. This is a necessary step because all the quantities in eqn. (8) are relative magnitudes, not absolutes, so we always need to check that we have not inadvertently chosen an incompatible set of magnitudes for N, Q, and Z. This step will become Principle B, which we will then apply to testing a real website in Sect. 4.2.

What kind of statistical test should be contained in Principle B? Here, we can look to A. K. Erlang as a role model. Erlang's first published work [ERLA09] was mostly about measuring telephone traffic and demonstrating that phone calls arrived randomly into the switch (a female operator) according to a Poisson process. (See Fig. 12) Applying probability theory to an engineering problem was considered a novel idea a hundred years ago.

Following Erlang, we ask, do random web-user requests arriving into a web site also follow a Poisson process? To some extent the answer to this question has already been pre-empted by the queue-theoretic analysis in Sect. 3.1. The memoryless property of Markovian queues is an attribute of a Poisson process. Since we already know that a Poisson process is the correct statistical model for web users, we just need a way to validate it in the context of load test measurements.

4.1 Poisson properties

We use the following properties of a Poisson process in the subsequent sections.

- 1. The *number* of arrivals in each fixed interval of time is a random variable that is Poisson distributed. This is shown as the *Count per interval* at the bottom of Fig. 7. The Poisson distribution is revealed by plotting the corresponding histogram. (See discussion in Appendix A)
- 2. The *periods* between arrivals has a random spacing that is exponentially distributed. This is shown as the *Inter-arrival times* at the top of Fig. 7. The exponential distribution is revealed by plotting the corresponding histogram. (See Appendix A)
- 3. Combining arrivals from N Poisson processes (e.g., web users), each having mean request rate λ , produces a single aggregated Poisson process having a mean request rate $N\lambda$ [KARL75, GUNT11].
- 4. Combining N non-Poisson processes asymptotically approaches an aggregated Poisson process provided N is large and each λ is very small. This follows from the Palm-Kintchine theorem, which

explains why so many natural and engineering phenomena can be well described by an aggregated Poisson process [KLEI75].

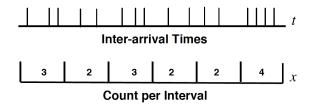


Figure 7: Sample arrival pattern generated by a Poisson process

The clicks of a Geiger counter (YouTube audio) follow a Poisson process due the random arrival of nuclear decay fragments at the detector. The clicks are analogous to requests arriving at the SUT. An intuitive demonstration of the Poisson process, based on random numbers generated in an Excel spreadsheet that are then mapped to points on a meter ruler, is provided in Appendix A and discussed in [BRAD09].

4.2 Web testing principle B

The second principle that forms part of our methodology follows from Poisson property 2 in the previous section, viz., the mean and standard deviation of an exponential distribution are equal. More particularly, the ratio of the mean and standard deviation is called the coefficient of variation, or CoV, and therefore CoV=1 for an exponential distribution. Since the measured times between web requests are expected to be exponentially distributed, statistical analysis should produce a CoV close to unit value. This statistic forms the basis of Principle B for verifying that asynchronous web traffic generated according to Principle A is in fact produced during the load tests.

Principle B

Verify that the requests generated by applying Principle A (i.e. large N with low rate 1/Z) closely approximate a Poisson process by measuring the coefficient of variation of the inter-arrival periods and demonstrating that $CoV \simeq 1$ within acceptable measurement error.

A synchronous or closed workload will exhibit a coefficient of variation CoV < 1 (see, e.g., Fig. 9) because the random variations or fluctuations in the Poisson arrival pattern are damped out by the negative-feedback loop discussed in Section 3. A closed workload is therefore hypo-exponential. According to Principle A, as the ratio $Q/Z \to 0$ and $\lambda \to N/Z$ in eqn. (8), it follows that $CoV \to 1$ because the period between arrivals becomes exponentially distributed. This is how Principles A and B are connected.

Equation (8) assumes that the inter-arrival periods are exponentially distributed whereas Principle B verifies that assumption is not violated during the actual test. It is worth noting that our approach stands in contrast to [SCHR06] where the focus is on the *CoV* of the service times in the SUT; not the inter-arrival times. Service demand statistics are also generally more difficult to measure.

4.3 Website case study

We now show how the principles developed in Sects. 3.3 and 4.2 are applied to the actual load-testing of a real government website using JMeter as the test harness. The purpose of the government website is to allow state residents to obtain various kinds of government statistics. We abbreviate the website name to WEB.gov for both simplicity and protection. Because WEB.gov was about to go live, all tests had to be performed in a single day, and the only test equipment available on such short notice was a relatively

small load-driver capable of handling a JMeter thread group of two hundred user threads, at most. Despite these physical limitations in the test environment, the broader performance question of interest was, how many web users will the real WEB.gov website be able to support? We address that question in Sect. 4.5. Overall, this exercise became a balancing act between accurately emulating web traffic and assessing website scalability beyond the data that could be captured within the limited testing time. We address scalability projections in Sect. 4.6.

Table 2: WEB.gov test web pages and test web objects

(a) Web site test objects

Object	Definition
010_Home	Home page
012_Home_jpg	Background image
020_Dept	Department data
022_Dept_jpg	Department image
030_Demographics	Demographic data
040_Statistics	Government user data

(b) Mapping between pages and objects

Web Page	Objects
Home	010_Home + 012_Home_jpg
Department	020_Dept + 022_Dept_jpg
Demographics	030_Demographics
Statistics	040_Statistics

In this scenario, the intent was for the WEB.gov website to be reconfigured from standalone dedicated servers to a virtual-server environment. The load tests were based on a list of web-page objects specified by name and purpose in Table 2. Each heterogeneous object is retrieved by an HTTP GET request. Based on the methodology described in Sections 2 and 3, one goal of these load tests was to ensure that the web objects in Table 2a were retrieved in a manner consistent with real web users on the Internet.

The left side of Fig. 8 is a topological view of the load testing environment showing load generator, network interfaces, F5 load balancer, and the virtualized blade server setup with WEB.gov virtual servers GOV1 and GOV2. The right side of Fig. 8 is the JMeter test script.

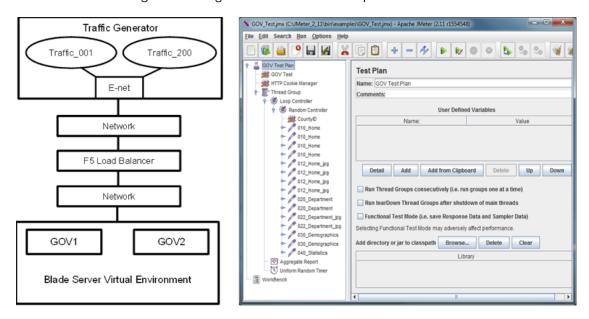


Figure 8: WEB.gov web site test configuration and JMeter script

In addition to estimating how many web users can be supported, there was interest in determining the scalability of the virtual servers GOV1 and GOV2 as well as evaluating how well the F5 balanced the load between them. The testing was performed under the following conditions:

ullet As the traffic-generator layout of Fig. 8 implies, a maximum of N=200 JMeter threads (indicated

by the Traffic_200 bubble) was used due to driver-side operating system limits

- Web pages are accessed in random order with multiple instances of them implemented to bias the
 event count. For example, there are four 010_Home page object-instances compared with just one
 040_Statistics object-instance.
- There is one *Uniform Random Timer* used to produce think times spanning the entire thread group.
 A uniform distribution is a bounded distribution so it terminates more gracefully at the end of each test run. Generator threads typically draw a think time without checking to see if that time exceeds the wall-clock time of the test.
- Traffic is increased from test to test by reducing the mean think time between tests.
- The seven 25-minute tests of increasing load are numbered 1800, 1830, 1900, 1930, 2000, 2030, 2100, according to the start time of a 24-hour clock.
- Steady state measurements are ensured by excluding the first two and last three minutes of each
 test run. This also mitigates any negative effects of the ramp-up and ramp-down phases in the data
 analysis.

The traffic generator and the test script are structured so as to maintain a consistent traffic mix for scalability testing. Objects are selected in random order to mimic the stateless HTTP protocol that supports an application that has no set sequence of page accesses.

Table 3 summarizes the JMeter test parameters and inter-arrival statistics. Rows 1–7 correspond to seven 25-minute test runs. Each test run employs the maximal number of JMeter generator threads. Hence, N=200 in our notation. Successive runs correspond to increasing the simulated web-user load which, in turn, increases the steady-state throughput measured by JMeter, i.e., $X=\lambda$ objects per second in column 4. Since the maximal N is constrained by the number of available driver threads, traffic into the SUT is actually increased by successively decreasing Z in column 3. As discussed in Sect. 3.3, this is tantamount to increasing the emission rate 1/Z of each load generator. Note that the number of concurrent requests in the SUT is very small (i.e., $Q \ll N$ in column 6) so, the key condition of Principle A is met. Also note that the total number of web objects in the test system, N (obj) in column 7, can be estimated as a decimal number using eqn. (6) and is consistent with the integral number of actual JMeter threads, N in column 2. Even though the inter-arrival statistics appear to diverge from CoV=1 at the highest traffic levels in this thread-limited environment, they are still within an acceptible range to conform to Principle B and prove that we are indeed simulating web-user traffic in accordance with Principle A.

					Ü					
	JMet	er Para	meters	JMeter N	Aetrics	Queue	Metrics	Inter-arri	val Time Statis	tics
	Run	N	Z (ms)	λ (obj/s)	R (ms)	Q (obj)	N (obj)	Mean (ms)	StdDev (ms)	CoV
1	1800	200	12500	15.91	53.17	0.85	199.72	62.81	61.75	0.98
2	1830	200	6250	31.73	52.74	1.67	199.99	31.52	31.59	1.00
3	1900	200	4200	46.79	54.06	2.53	199.05	21.37	21.54	1.01
4	1930	200	3250	60.26	59.64	3.59	199.44	16.60	16.78	1.01
5	2000	200	2500	77.56	74.97	5.81	199.71	12.89	13.22	1.03
6	2030	200	1563	118.03	132.67	15.66	200.14	8.47	9.12	1.08
7	2100	200	1000	150.16	252.20	40.22	100.40	6.20	7 27	1 17

Table 3: WEB.gov simulated web user loads

Clearly, the CoV of the inter-arrival times is an important statistic needed to confirm that asynchronous web traffic is being produced by the load tests in Table 3. Unfortunately, that statistic is not provided by JMeter or any other load-test harnesses, to our knowledge. Consequently, one of us (JFB) developed an analysis script to calculate the empirical CoV by sorting logged JMeter requests into correct temporal order and taking differences.

4.4 Simulated web users

The CoV of inter-arrival periods in Table 3 is based on a maximum pool of N=200 threads (column 2) allowed by the operating system that supports the load generators. Taking test-run number 1830 (row 2) as the example being closest to the required CoV, we can ask, how many threads are actually needed to reach unit value? Figure 9 provides the answer.

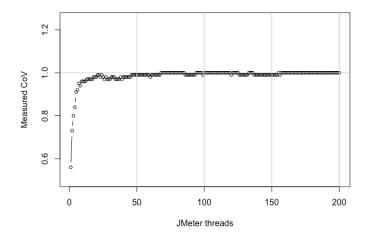


Figure 9: Inter-arrival time CoV for JMeter threads up to N = 200 with Z = 6.25 seconds

At around 50 threads, the monitored values start to settle down around CoV=1 all the way up to the maximum 200 threads. In other words, by applying Principle A of Sect. 3.3 in these tests, we see that the hypoexponential arrival pattern of the closed test environment is converted into the desired exponential arrival pattern using just 25% of the total thread pool. Note also that the data profile in Fig. 9 is consistent with the rapid onset predicted by PDQ [GUNT15] in Fig. 5.

Poisson property 3, in Sect. 4.1, supports the derivation of eqn. (12) which assumed N independent virtual users, each issuing requests with a mean rate 1/Z, can be added together at the SUT and treated as though they are requests coming from a single user at a mean rate N/Z. This Poisson property is guaranteed to be satisfied when the think-time periods are exponentially distributed with mean time Z (i.e., Poisson property 2).

However, JMeter, like many load-test tools, does not offer an exponential-timer option [GUNT10b, BRAD12]. The test configuration specified in the previous section used uniformly distributed think-time periods. In other words, the actual load generators appear to be in violation of our assumed Poisson property 3. Poisson property 4 provides the escape hatch. As long as 1/Z corresponds to a very low rate of requests and N is relatively large, an aggregate Poisson process will still be well approximated [KARL75, ALB182]. As seen in Fig. 8, the JMeter Uniform Random Timer was used in this case study and Fig. 9 confirms that Poisson property 4 applies to a uniform think-time distribution.

4.5 Internet web users

Since the main question of interest to management was the predicted number of real web users that WEB.gov could be expected to support, we leveraged the results of Sect. 4.4 to move from simulated web users in the test environment to real web users on the Internet. To avoid any confusion with our earlier notation, we denote real web users by N' and retain N for simulated web users. Since we cannot measure N' directly (cf. the clouds in Figs. 2b and 3), we calculate it as a statistical quantity using

$$N' = \lambda(R + Z') \tag{15}$$

which is the analog of eqn. (6). We already know λ and R from the simulated web-user measurements in Table 3. The think time Z' is chosen to reflect real-world delays, e.g., Internet latencies and the time taken

by human users when perusing actual web pages. Since N' is a statistical mean, it appears as a decimal number (rather than an integer that would normally be used to specify the number of load generators) in Table 4.

							No	minal Inte	rnet Think	κ Time, Z'	(ms)
		JMeter Me	asuremen	ts	Conversion		10,000	20,000	30,000	40,000	50,000
	Run	λ (obj/s) R (ms) Q (obj) λ (pgs/s) Q (pgs)				Calculated Internet Web Users, N'					
1	1800	15.91	53.17	0.85	9.5460	0.51	95.97	191.43	286.89	382.35	477.81
2	1830	31.73	52.74	1.67	19.0380	1.00	191.38	381.76	572.14	762.52	952.90
3	1900	46.79	54.06	2.53	28.0740	1.52	282.26	563.00	843.74	1124.48	1405.22
4	1930	60.26	59.64	3.59	36.1560	2.16	363.72	725.28	1086.84	1448.40	1809.96
5	2000	77.56	74.97	5.81	46.5360	3.49	468.85	934.21	1399.57	1864.93	2330.29
6	2030	118.03	132.67	15.66	70.8180	9.40	717.58	1425.76	2133.94	2842.12	3550.30
7	2100	159.16	253.38	40.33	95.4960	24.20	979.16	1934.12	2889.08	3844.04	4799.00

Table 4: WEB.gov estimated Internet web users

Rows 1–7 in Table 4 correspond to the same seven tests shown in Table 3. Some web objects are requested as an aggregate by the browser when a real user performs a web-page query. See *Heterogeneous requests* of Sect. 2.3. Table 2b lists the mapping of web pages to web objects for the WEB.gov web site and shows that the Home web page and the Department web page each contain two web objects. Because λ (obj/s), as measured by JMeter, is actually the arrival rate of web objects (see column 2 of Table 4), and not web pages, the web-page per web-object ratio needs to be determined. The JMeter script in Fig. 8 contains 15 web objects. When these objects are consolidated, the result is 4 *Home pages* + 2 *Department pages* + 2 *Demographics pages* + 1 *Statistics pages* = 9 web pages. The measured arrival rate λ (obj/s) is multiplied by this 9:15 ratio to convert it into the necessary web-page arrival rate, λ (pgs/s). This pro-rated arrival rate is used to calculate the average of number of Internet web users, N', in Table 4.

Example 7 (Test Run 2100). Consider the load test data in row 7 of Table 4. The arrival rate $\lambda = 159.16$ web-objects per second in column 2 comes from row 7 of Table 3. Applying the 9:15 conversion ratio yields $9 \times 159.16/15 = 95.50$ web-pages per second as the request rate in the 5th column. The measured response time is 253.38 milliseconds (column 3). Substituting an Internet user think time of Z' = 30,000 milliseconds (from column 9) into eqn. (15), we find $N' = 95.4960 \times (0.25338 + 30) = 2889.08$ mean Internet web users.

In Sect. 3.3 it was pointed out that $Q \ll N$ is a condition for eqn. (8) to be a valid approximation to web traffic. We see that condition reflected as Q < N' in Table 4. Similarly, by virtue of Little's law, R < Z' in eqn. (15). We can also verify that our estimates of N' and Z' scale in conformance with Principle A.

Example 8 (Scaled-Z arrival rate). Consider test run 1930 (row 4 of Table 4) for Internet user think times Z' = 10, 20, ..., 50 seconds (top of columns 7–11). Applying eqn. (8), the expected arrival rate into WEB.gov is

$$\lambda_{10} = \frac{363.72}{10} - \frac{2.16}{10} = 36.16$$

$$\lambda_{20} = \frac{725.28}{20} - \frac{2.16}{20} = 36.16$$

$$\lambda_{30} = \frac{1086.84}{30} - \frac{2.16}{30} = 36.16$$

$$\lambda_{40} = \frac{1448.40}{40} - \frac{2.16}{40} = 36.16$$

$$\lambda_{50} = \frac{1809.96}{50} - \frac{2.16}{50} = 36.16$$

all of which are the same constant mean rate and in agreement with the value shown in column 5.

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Under different circumstances and test requirements, load tools like those identified in Sect. 2.2 could be used to validate these estimates. In the meantime, our methodology provides a low-cost alternative.

4.6 Website scalability

Figure 10 indicates that the WEB.gov virtual environment is load balanced and capable of handling 159.16 web HTTP GET or HTTP POST requests per second with all CPUs running around 70% busy. Viewing the 200 JMeter threads as asynchronous transaction generators, instead of canonical virtual users, shifts the focus of SUT load balance and scalability analysis from users to the traffic they produce. Hence, the x-axes of the plots are labelled by transactions per second (TPS), not users. This relabeling is also consistent with the typical units of rate that are used in the context of open queueing systems [GUNT11].

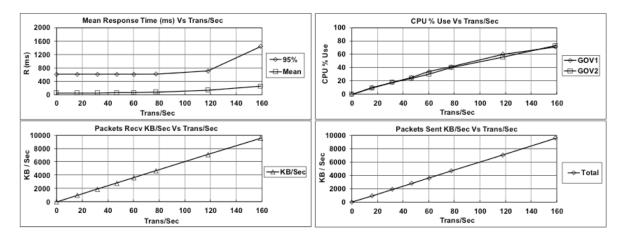


Figure 10: WEB.gov load balancing and scalability data

The plot in the upper-left quadrant of Fig. 10 contains the mean and 95th percentile of response time (as measured by JMeter) plotted as a function of TPS for the seven test runs performed in Sect. 4.4. Both response-time curves are relatively flat until test run 2100, when the hockey-stick handle corresponding to Fig. 6, begins to appear at a mean R of 253 milliseconds and an R_{95} of 1440 milliseconds. Although these levels are larger than baseline, they were considered to be acceptable for this particular application.

The plot in the lower-left quadrant of Fig. 10 shows network packets received in KB/s, as measured by JMeter. These values are higher than send-traffic volumes because the data size of the web server responses are almost always larger than HTTP GET or HTTP POST requests. The plot shows that the approximately 10,000 KB/s network link (i.e., 100 Mbps packet bandwidth) is nearly saturated as test run 2100 reaches a throughput of 9,552 KB/s.

The plot in the upper-right quadrant of Fig. 10 shows CPU utilization as a function of TPS for each of the two virtual servers. The two plots essentially lie on top of each other for all seven tests, indicating a load balanced environment. Moreover, both plots are linear through the 71% CPU busy, achieved at test run 2100, thus indicating excellent scalability up to that utilization level.

The plot in the lower-right quadrant of Fig. 10 represents combined SUT network packets sent in KB/s. The virtualized servers, GOV1 and GOV2 (see Fig. 8), sent network packets at an aggregate rate of 9,538 KB/sec in test run 2100 on two 10,000 KB/s (or 100 Mbps) network links. These data provide a statistical cross-check that packet traffic leaving the SUT is the same as the 9552 KB/s received by JMeter.

5 Conclusion

Interactive computing has evolved over the past fifty years from a relatively small number of centralized users issuing commands into a monolithic application via their fixed terminals, to a much larger number of

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remote users issuing requests into web services via a plethora of personal computing devices. Conventional load-test tools are designed to mimic the former rather than the latter and that creates a problem for performance engineering when it comes to accurately load-testing web applications. In Sections 3 and 4, we presented a methodology to address that problem.

Our methodology is based on two fundamental principles. Principle A, in Sect. 3.3, tells us how to scale the parameters N and Z so that the test environment is optimized for producing requests that mimic the Poisson process associated with web-user workloads. Principle B, in Sect. 4.2, tells us how to confirm that the test parameter settings did actually mimic a Poisson process during the course of each test by analyzing the CoV of the measured inter-arrival times. In practice, the request rate λ into the SUT can be increased in any of three ways: (i) increase N while holding N fixed (see Table 1a), (ii) decrease N while holding N fixed (see Table 1b). Of these, the third option offers the royal road to emulating web-user traffic.

The development of Principle B also extends the work of [ALBI82], who analyzed a $\sum_N GI_N/M/1$ queue using an event-based simulator with up to 1024 aggregated iid arrival processes. The aggregated non-Poisson arrivals potentially represent a more realistic queueing model of a web server than the M/M/1 queue discussed in Sect. 3.1 or the M/M/1/N/N queue discussed in Sect. 3.2. However, the simulation suite did not include uniformly distributed inter-arrival times. Consistent with the Palm-Kintchine theorem in Sect. 4.1, $\sum_N GI_N/M/1$ diverges from M/M/1 for server utilizations greater than 50% but, as we have shown using JMeter as a more realistic workload simulator in Sect. 4.4, the slowest divergence occurs for aggregated non-Poisson arrivals that are uniformly distributed with a low 1/Z rate.

Our results offer a different perspective on the choice of queueing system for modeling asynchronous arrivals. To model M/M/1 exactly, in a load-test environment, would require significant modification to the generator scripts so that they issue requests randomly in time and are independent of any outstanding requests in the SUT. However, as we showed in Sect. 4.3, real Internet-based web users do actually submit synchronous requests into the website, but the synchronization is relatively weak: precisely as Principle A prescribes. Somewhat surprisingly then, M/M/1/N/N with low 1/Z rate is a better queue-theoretic approximation to real web users than an explicit M/M/1 model, and R < Z is consistent with HTTP being a stateless protocol. On the other hand, one might choose to use the less realistic M/M/1 approximation simply because the actual values of N and Z are not known, as in Sect. 4.5.

We applied our methodology to load testing a major web site in Section 4. In practice, as discussed in Sect. 4.5, an estimation of actual N' Internet users—rather than the number of test generators, N—may need to be reported as the performance metric of interest. In Sections 2.3, 3.2, and 4.5, we attempted to clarify the meaning of user-concurrency in this context. As a further aid to performance engineers, the statistical analysis tools we developed are available online.

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Appendices

A Meter Ruler Illustration

Figure 11 is a one meter ruler spreadsheet illustration of random arrivals where 200 samples are drawn using the Excel rand() function and mapped to millimeter values shown as marks on the ruler. The spreadsheet lists the first 30 out of the 200 samples drawn as well as contains graphs and statistics for "Marks per Interval (cm)" and "Distance Between Marks (mm)." Both the "Marks Per Interval" and "Distance Between Marks" bar charts are accompanied by their theoretical distributions, viz., the Poisson and negative-exponential.

The spreadsheet columns (left to right) contain random numbers along with corresponding ruler mark values, mark per centimeter frequency statistics and associated histogram ordinates. This information is followed by histogram statistics and Poisson distribution ordinate values. The distance between mark ordinates, histogram, histogram statistics, and exponential distribution ordinates are developed by first sorting the mark values in ascending order and recording the difference between adjacent marks.

An inspection of the one meter ruler reveals 13 one centimeter intervals with 0 marks, f(x) = 13, and an analysis of the distance between marks section of the full spreadsheet yields 26 places with 0 millimeters between marks, f(t) = 26.

The 'Marks Per Interval' bar chart on the left below the one meter ruler contains frequency data in yellow and theoretical distribution values in blue yielding a mean = 2.00 cm and Var = 2.00 cm. The Distance Between Marks bar chart on the right shows a mean = 4.98 mm and an SD = 4.76 mm. These graphs indicate the mean and variance are equal for "Marks Per Interval" and the mean and standard deviation are statistically the same for "Distance Between Marks". Both are properties of a Poisson process or a random arrivals environment.

B Glossary

Arrival rate: The rate $\lambda = A/T$ where A is the <u>count</u> of arrivals and T is the measurement period. The same rate is used to parameterize a <u>Poisson process</u>.

Bernoulli process: A random sequence of events where the outcome is either a "success" or a "failure", e.g., a head or a tail in the toss of a fair coin. Each coin toss—often called a *Bernoulli trial*—is assumed to be a *statistically independent* event in that the resultant head or tail of one toss has no influence or bearing on the outcome of the next toss. The probability of getting a run of k heads, for example, is given by the Binomial distribution. Real coins are not fair and real coin tosses are not entirely statistically independent. A Bernoulli process can also be characterized as a sequence of iid geometrically distributed inter-arrival intervals. (See Fig. 12) Other important stochastic processes are shown in Fig. 12.

Binomial distribution: The distribution associated with discrete events that have a binary outcome with probability of success, p and probability of failure, q = 1 - p. For a fair coin toss (a Bernoulli process:), p = q = 1/2.

- 1. Discrete random variable k = 0, 1, 2, ...
- 2. PMF $f(k) = \binom{n}{k} p^k q^{n-k}$ where q = (1-p)
- 3. CDF $F(k) = \sum_{i=0}^{k} {n \choose i} p^{i} q^{n-i}$
- 4. Mean E(k) = np
- 5. Variance Var(k) = npq

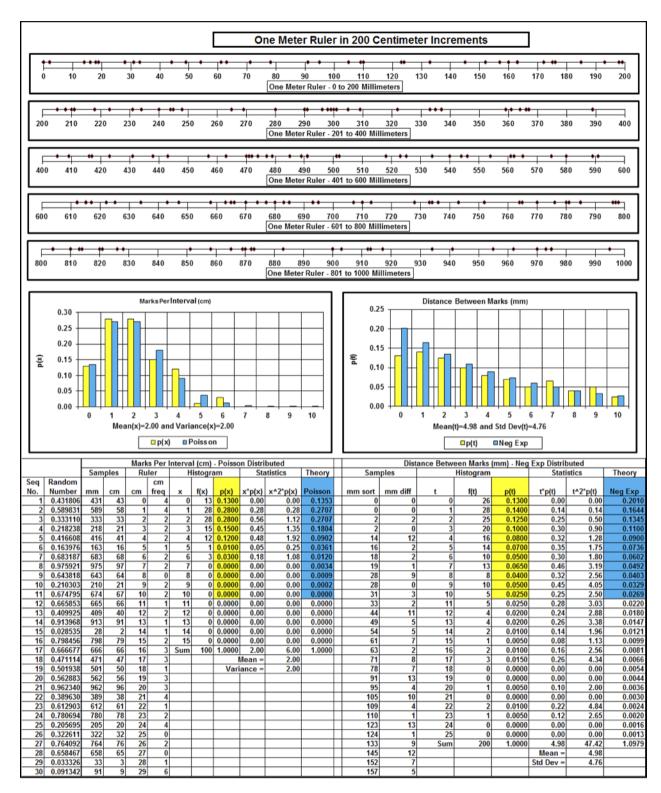


Figure 11: One meter ruler spreadsheet illustration

- 6. Standard deviation $SD = \sqrt{npq}$
- 7. Coefficient of variation $CoV = \frac{q}{\sqrt{npq}}$

Closed system: A queueing system with a finite number of requesters. No additional requests are allowed to enter from outside the system. (cf. open queues) Provides an elementary performance model of a load-test system. Since no more than a single request can be outstanding, the limited number of requests come from the finite number of load generators. This means a closed system is actually comprised of two queues: generators (with no waiting line) and a queueing facility (the system under test). See Figs. 2a and 4.

Coefficient of variation: Denoted by CoV, it is the ratio of the standard deviation and the mean. For an analytic distribution $CoV = \sigma/\mu$, where σ is the standard deviation and μ is the mean of the distribution. For measurements, of the type performed in this paper, CoV = SD/M, where SD is the sample standard deviation and M the sample mean.

Concurrency level: Denoted by Q, it is the combined number of requests waiting and the number of requests in service.

Exponential distribution: The distribution associated with the inter-arrival times from a Poisson process as well as the service periods of an M/M/m queue. It has the following properties:

- 1. Continuous random variable x
- 2. PDF $f(x) = \lambda e^{-\lambda x}$
- 3. CDF $F(x) = 1 e^{-\lambda x}$
- 4. Mean $E(x) = 1/\lambda$
- 5. Variance $Var(x) = 1/\lambda^2$
- 6. Standard deviation $SD = 1/\lambda$
- 7. Coefficient of variation CoV = 1

Geometric distribution: The probability distribution of the number of Bernoulli trials needed to obtain a single success.

- 1. Discrete random variable $k = 0, 1, 2, \ldots$ with probability of success $p \in (0, 1]$
- 2. PMF $f(k) = p q^{k-1}$ where q = (1 p)
- 3. CDF $F(k) = 1 q^k$
- 4. Mean E(k) = 1/p
- 5. Variance $Var(k) = q/p^2$
- 6. Standard deviation $SD = \sqrt{q}/p$
- 7. Coefficient of variation $CoV = \sqrt{q}$

Independence (statistical): The innocent looking word "independent" appears in different guises throughout the literature on probability and statistics (including this paper) and has several special meanings. Broadly speaking, it refers to the assumption that there are no correlations between values of the random variable of interest, e.g., arrival events of a Poisson process. The more technical phrase is: random variables are *iid* or independently and identically distributed.

For example, the number of arrival events contained in each uniformly spaced bin of Fig. 7 is assumed to be *iid* according to a Poisson distribution. Note, it does not mean they are identically distributed, otherwise

the numbers in each bin would all be the same. Rather, it means they are distributed with the same (identical) probability.

The term *independent* is often used as a proxy for the word *random* (which is a much deeper subject). Another way to think of statistical independence for a Poisson process is to imagine that the width of the uniform bins in Fig. 7 is made smaller and smaller until any bin can contain just a single arrival, at most. Many of these small bins will be empty. If a bin contains an arrival, that is like a Bernoulli success. The sequence of randomly occupied time-bins is like the random heads in a sequence of Bernoulli coin tosses, each of which is assumed to be independent.

Open system: A queueing system where an unlimited number of requests are allowed to enter from outside the system. Provides an elementary performance model of a web-based HTTP server where "outside" refers to the Internet. See Figs. 2b and 3. Example open queueing models discussed in this paper include M/M/1, M/G/1 [KLEI75, GUNT11] and $\sum_N GI_N/M/1$ [ALBI82].

Poisson distribution: The distribution associated with the number of arrivals from a Poisson process as well as the service periods of an M/M/m queue. It has the following properties:

1. Discrete random variable k = 0, 1, 2, ...

2. PMF
$$f(k,\alpha) = \frac{\alpha^k}{k!} e^{-\alpha}$$

3. CDF
$$F(x,\alpha) = \sum_{i=0}^{k} \frac{\alpha^i}{i!} e^{-\alpha}$$

- 4. Mean $E(k) = \alpha$
- 5. Variance $Var(k) = \alpha$
- 6. Standard deviation $SD = \sqrt{\alpha}$
- 7. Coefficient of variation $CoV = 1/\sqrt{\alpha}$

A simple mnemonic for the Poisson distribution is given in [GUNT14a].

Poisson process: A stochastic process is a dynamical map in either space or time that is generated by the values of a random variable. Some important stochastic processes are shown in Fig. 12. As employed in this paper, a Poisson process refers to the generation of random events that are counted in continuous time, N(t). The counts are commonly referred to as *arrivals* and since they accumulate, N(t) is an increasing stochastic function of time. More formally the following three conditions need to be met:

- 1. N(0) = 0.
- 2. N(t) has independent increments.
- 3. The number of arrivals in any time interval has a Poisson distribution.

The number of arrivals in any time interval depends only on the length of the chosen interval, not on its location on the continuous time-line.

The relationship to the exponential distribution can be seen as follows. A Poisson process creates arrivals at random time-intervals A_1, A_2, \ldots seen as the vertical lines in the top part of Fig. 7. We want to know the distribution of these times A_i . If there are no arrivals during the interval [0,t], then the first arrival must occurs after time t, i.e.,

$$Pr(A_1 > t) \equiv Pr(N(t) = 0)$$

otherwise, it would not be the first arrival. From the Poisson distribution with $\alpha = \lambda t$ and k = 0 (i.e., no event), this probability is given by the Poisson CDF:

$$\Pr(A_1 > t) = \frac{(\lambda t)^0}{0!} e^{-\lambda t} = e^{-\lambda t}$$

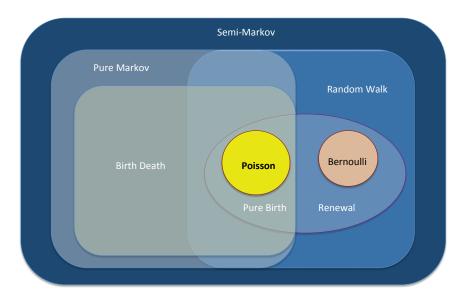


Figure 12: Venn diagram of the relationship between some stochastic processes

The complementary probability, $Pr(A_1 \le t)$, that an arrival did occur in [0,t], is then given by

$$1 - P(A_1 > t) = 1 - e^{-\lambda t}$$

which is just the exponential CDF with x replaced by t. Other key features of a Poisson process are discussed in Section 4.1.

Residence time: Denoted by R=W+S is the total average time spent in a single queue. (cf. response time)

Response time: The sum of the residence times, $\sum_k R_k$, belonging to a sequence of k queueing centers. The response time is identical to the residence time for a single queueing center (i.e., k=1).

Round trip time: Denoted by $R_{TT} = \sum_k R_k + Z$, it is the average time spent in the SUT together with the average time a virtual user spends thinking before issuing the next request. It can also be regarded as a special case of response time.

Service time: Denoted by S, it is the average time spent in service, e.g., executing on a CPU or core. When there are repeated visits to the same resource for service, the cumulative time is called the service demand. In the teletraffic context, S is called the *holding time*. The first queue solved by Erlang was M/D/1 because he assumed a constant holding time [ERLA09].

Think time: Denoted by Z it is the average delay (often associated with a human) between the completion of the previous request and the next.

Threads: Denoted by N, it represents the number of active load generation processes initiated by the driver-side operating system.

Waiting time: Denoted by W, it is the mean time spent in waiting, e.g., in the scheduler run-queue, prior to receiving service. The terminology for waiting and queueing if often ambiguous across different but related disciplines, e.g., queueing theory vs. operating system architectures. In conventional queue-theoretic parlance [ERLA09, ERLA17, KLE175, COOP84, GUNT11], a queue is comprised of two parts: a service facility, which may contain multiple service resources, e.g., multiple cores, and a separate waiting line or buffer. In this sense, the "run-queue" in a scheduler is actually the waiting-line or run-buffer for threads that are ready to be executed, but not yet executing.

Uniform distribution: The uniform distribution (sometimes referred to as a Rectangular Distribution) can be defined for either a discrete or a continuous random variable. The continuous uniform distribution is the most applicable for load generation.

1. Continuous random variable defined on the real-valued interval $x \in [a,b]$

2. PMF
$$f(x) = \frac{1}{b-a}$$
 for $x \in [a,b]$ and zero elsewhere

- 3. CDF $F(x) = \frac{x-a}{b-a}$ for $x \in [a,b)$, but zero for x < a and 1 for $x \ge b$
- 4. Mean $E(x) = \frac{1}{2}(a+b)$
- 5. Variance $Var(x) = \frac{1}{12}(b a)^2$
- 6. Standard deviation $SD=\frac{1}{\sqrt{12}}(b-a)$
- 7. Coefficient of variation $CoV = \frac{1}{\sqrt{3}} \left(\frac{b-a}{a+b} \right)$