

Vladimir Nekrasov

[linkedin/vladimir-nekrasov-6549a4a7/](https://www.linkedin.com/in/vladimir-nekrasov-6549a4a7/) | [github/DrSleep](https://github.com/DrSleep) | <https://drsleepp.github.io>

A deep learning and computer vision expert focused on simplifying existing end-to-end pipelines in order to create practical solutions and applications. Extensive experience building real-time deep learning networks optimised for embedded devices.

EDUCATION

Ph.D. in Computer Science

Adelaide, Australia | Aug, 2017 - Nov, 2020

THE UNIVERSITY OF ADELAIDE, SCHOOL OF COMPUTER SCIENCE

Thesis: Semantic Image Segmentation and Other Dense Per-Pixel Tasks: Practical Approaches

Dean's Commendation for Thesis Excellence

Specialist D. in Mechanics

Moscow, Russia | Sep, 2010 - Jun, 2015

LOMONOSOV MOSCOW STATE UNIVERSITY, FACULTY OF MATHEMATICS AND MECHANICS

GPA: 4.6 / 5.0

Majors: Indoor Navigation, Stability & Control Theory

SELECTED PUBLICATIONS

CVPR

Long Beach, USA, 2019

FAST NEURAL ARCHITECTURE SEARCH OF COMPACT SEMANTIC SEGMENTATION MODELS VIA AUX. CELLS

V. Nekrasov, H. Chen, C. Shen, and I. Reid

<https://github.com/DrSleep/nas-segm-pytorch>

ICRA

Montreal, Canada, 2019

REAL-TIME JOINT SEMANTIC SEGMENTATION AND DEPTH ESTIMATION USING ASYMMETRIC ANNOTATIONS

V. Nekrasov et al.

<https://github.com/DrSleep/multi-task-refinenet>

BMVC

Newcastle-upon-Tyne, UK, 2018

LIGHT-WEIGHT REFINE NET FOR REAL-TIME SEMANTIC SEGMENTATION

V. Nekrasov, C. Shen, and I. Reid

<https://github.com/DrSleep/light-weight-refinenet>

BMVC

York, UK, 2016

GLOBAL DECONVOLUTIONAL NETWORKS FOR SEMANTIC SEGMENTATION

V. Nekrasov, J. Ju, and J. Choi

<https://github.com/DrSleep/GDN>

WORK EXPERIENCE (LAST 3)

NEARMAP | SR. DATA SCIENTIST, AI TEAM

Remote, AU | Jun, 2022 - present

SKYDIO | SR. DEEP LEARNING RESEARCH ENGINEER, AUTONOMY TEAM

Remote, AU | Aug, 2020 - Mar, 2022

- Built and improved end-to-end reproducible deep learning pipelines and processes
- Led and managed a team of 5 deep learning engineers

SKYDIO | COMPUTER VISION RESEARCH INTERN, AUTONOMY TEAM

Redwood City, USA | Jun, 2019 - Nov, 2019

- Improved the obstacle avoidance system of an autonomous flying robot, Skydio 2

WEB DEMOS & OPEN-SOURCE PROJECTS

DENSE PER-PIXEL TASKS IN YOUR BROWSER VIA JAVASCRIPT

2019

<https://drsleepp.github.io/demos/>

DIAGNOSTICS IN SEMANTIC SEGMENTATION - SUPPLEMENTARY

2018

<https://cv-conf.shinyapps.io/diag-sem-segm/>

DEEPLAB-RESNET-V2 IN TENSORFLOW

2017

<https://github.com/DrSleep/tensorflow-deeplab-resnet>

NCI-60 CANCER CELL INTERACTIVE EXPLORATIVE APPLICATION

2016

https://drsleepp.shinyapps.io/bio_data/