Vladimir Nekrasov

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A deep learning and computer vision expert focused on simplifying existing end-to-end pipelines in order to create practical solutions and applications. Extensive experience building real-time deep learning networks optimised for embedded devices.

WORK EXPERIENCE (LAST 3)

NEARMAP | SR. DATA SCIENTIST, AI TEAM

Remote, AU | Jun, 2022 - present

• Built high-quality, scalable and platform-agnostic temporal deep learning model on aerial imagery

♣Tools used: Python • PyTorch Lightning • Hydra • WandB • Streamlit • QGIS • S3 • Folium • torchscript

SKYDIO | Sr. Deep Learning Research Engineer, Autonomy Team Remote, AU | Aug. 2020 - Mar. 2022

- Built and established easy to use and extend end-to-end reproducible deep learning pipelines and processes
- Led and managed a team of 5 deep learning engineers

♣Tools used: Python • C++ • CUDA • PyTorch • WandB • Streamlit • TensorRT • Slurm • ONNX • torchscript

SKYDIO | Comp. Vision Research Intern, Autonomy Team Redwood City, USA | Jun, 2019 - Nov, 2019

• Improved performance and runtime of the on-device obstacle avoidance system of the Skydio 2 drone

♣Tools used: Python • C++ • CUDA • PyTorch • TensorFlow • TensorRT • ONNX • Keras

SELECTED PUBLICATIONS

CVPR Long Beach, USA, 2019

FAST NEURAL ARCHITECTURE SEARCH OF COMPACT SEMANTIC SEGMENTATION MODELS VIA AUX. CELLS

V. Nekrasov , H. Chen, C. Shen, and I. Reid

https://github.com/DrSleep/nas-segm-pytorch

ICRA Montreal, Canada, 2019

REAL-TIME JOINT SEMANTIC SEGMENTATION AND DEPTH ESTIMATION USING ASYMMETRIC ANNOTATIONS

V. Nekrasov et al. https://github.com/DrSleep/multi-task-refinenet

BMVC Newcastle-upon-Tyne, UK, 2018

LIGHT-WEIGHT REFINENET FOR REAL-TIME SEMANTIC SEGMENTATION

V. Nekrasov , C. Shen, and I. Reid https://github.com/DrSleep/light-weight-refinenet

BMVC York, UK, 2016

GLOBAL DECONVOLUTIONAL NETWORKS FOR SEMANTIC SEGMENTATION

V. Nekrasov . J. Ju. and J. Choi

https://github.com/DrSleep/GDN

EDUCATION

Ph.D. in Computer Science

Adelaide, Australia | Aug. 2017 - Nov. 2020

THE UNIVERSITY OF ADELAIDE, SCHOOL OF COMPUTER SCIENCE

Thesis: Semantic Image Segmentation and Other Dense Per-Pixel Tasks: Practical Approaches

Dean's Commendation for Thesis Excellence

Specialist D. in Mechanics

Moscow, Russia | Sep. 2010 - Jun. 2015

LOMONOSOV MOSCOW STATE UNIVERSITY, FACULTY OF MATHEMATICS AND MECHANICS

GPA: 4.6 / 5.0

Majors: Indoor Navigation, Stability & Control Theory