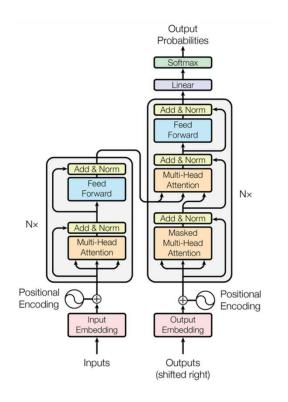
# LARGE LANGUAGE MODEL AS REINFORCEMENT LEARNING AGENT

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## TWO STAGES OF LARGE LANGUAGE MODEL DEVELOPMENT

#### **Pre-Training: Base LLM (GPT3)**

predict next word, based on text training data

Self-supervised

# Once upon a time, there was a unicorn that lived in a magical forest with all her unicorn friends

#### What is the capital of France?

What is France's largest city? What is France's population? What is the currency of France?

#### Post-Training: Instruction Tuned LLM (ChatGPT)

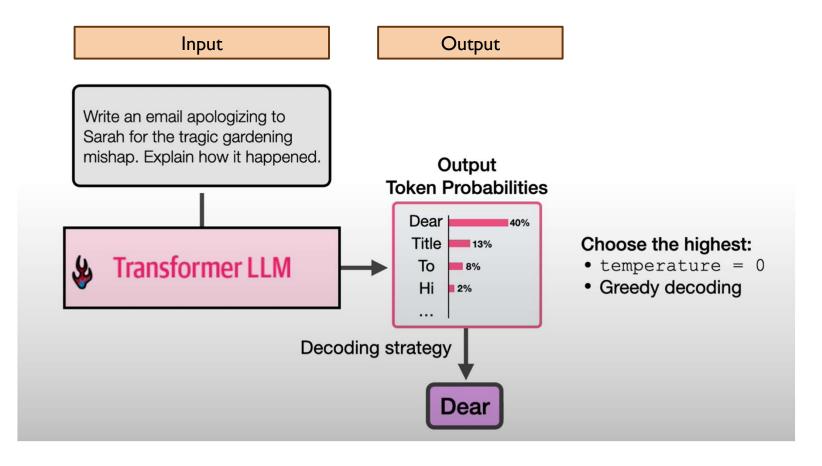
Tries to follow instructions

Fine-tune on instructions and good response pairs

- Human labeled data: Instruction Response Pair
- SFT: Supervised Fine-tuning
- RLHF (Reinforcement Learning with Human Feedback) or DPO (Direct Preference Optimization)

What is the capital of France?
The capital of France is Paris.

## TRANSFORMER LLM: INPUT AND OUTPUT



#### **AUTOREGRESSIVE LANGUAGE MODELS: PROBABILITY KERNEL**

- A language model is a **probability kernel**  $\mu$  given a prefix of words:  $\mu: X \to Pr(Y)$ 
  - Stochastic in nature: **A same prefix** X can give a **random output** sampled from a probability distribution  $\mu_X$  (i.e., generative)  $\to$  A key reason for factual inaccuracy, inconsistency or hallucination (making stuff up)
- A language model calculates Pr(s) given a sequence of words:  $s = (w_1, w_2, \dots, w_{T-1}, w_T)$
- An autoregressive language model calculates this <u>conditional on a previous sequence of words</u>:

$$Pr(s) = Pr(w_1, w_2, ..., w_{T-1}, w_T)$$
  
=  $\prod_{t=1}^{T} Pr(w_t | w_1, w_2, ..., w_{t-1})$ 

- Next-word prediction: Given a prefix  $(w_1, w_2, \ldots, w_{t-1})$ , calculate the probability of the next word  $w_t$  (Conceptually same to time series with path dependence)

Source: Prof. Kyunghyun Cho

#### **AUTOREGRESSIVE LANGUAGE MODELS: SIMPLE EXAMPLE**

4-word sentence example: "I am a student"

$$Pr(s) = Pr(w_1, w_2, w_3, w_4) = Pr(w_1) \times Pr(w_2|w_1) \times Pr(w_3|w_1, w_2) \times Pr(w_4|w_1, w_2, w_3)$$

• All you need is "counting" (if there are large amounts of data)

$$Pr(w_2|w_1) = \frac{count(w_1, w_2)}{count(w_1)}$$
 2-grams (Bigrams)
$$Pr(w_3|w_1, w_2) = \frac{count(w_1, w_2, w_3)}{count(w_1, w_2)}$$
 3-grams (Trigrams)
$$Pr(w_4|w_1, w_2, w_3) = \frac{count(w_1, w_2, w_3, w_4)}{count(w_1, w_2, w_3)}$$
 4-grams

- Problems:
  - This requires a lot of space (RAM)
  - Count-based language models cannot generalize: A certain sentence does not appear in the corpus

Source: Prof. Kyunghyun Cho

#### PRE-TRAINING: SELF-SUPERVISED LEARNING

Input

• A sequence of tokens (encoded words)

**Loss Function** 

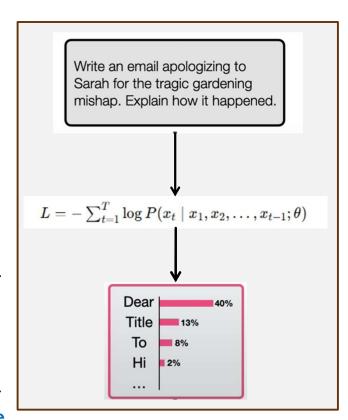
- Minimize the negative log-likelihood of the predicted token given the preceding tokens:
   Cross-entropy Loss
- Mathematically, the loss L for a sequence of tokens  $(x_1, x_2, \ldots, x_T)$  is:

Output

- Probability distribution over the vocabulary (~30,000)
- Deterministic

**Dataset Size** 

- Neural scaling law: The dataset size (D) should scale proportionally with the model size (i.e., linear)
  - e.g., GPT-3: 175B parameters, 300B tokens



# PRE-TRAINED LLM EVAL - PERPLEXITY: PREDICTIVE ACCURACY (2/2)

#### **Example Calculation:** "The cat sat on the mat"

- P("The") = 0.2
- P("cat"|"The") = 0.1
- P("sat"|"The cat") = 0.15
- P("on"|"The cat sat") = 0.3
- P("the"|"The cat sat on") = 0.25
- P("mat"|"The cat sat on the") = 0.05

$$\operatorname{Perplexity}(PP) = \exp\left(-rac{1}{N}\sum_{i=1}^{N}\log P(w_i\mid w_{< i})
ight)$$

First, calculate the average negative log probability:

$$-\frac{1}{6}\left(\log(0.2) + \log(0.1) + \log(0.15) + \log(0.3) + \log(0.25) + \log(0.05)\right) \approx 1.8992$$

Then, exponentiate to find perplexity:

$$PP = \exp(1.8992) \approx 6.68$$

This means the model, on average, considers about 6.68 possible next words, indicating its uncertainty in prediction.

#### POST-TRAINING: SUPERVISED FINE TUNING

Input

Prompt-Desired Response Pair Dataset: {Prompt I, Desired Response I}, {Prompt 2, Desired Response 2}

Loss Function

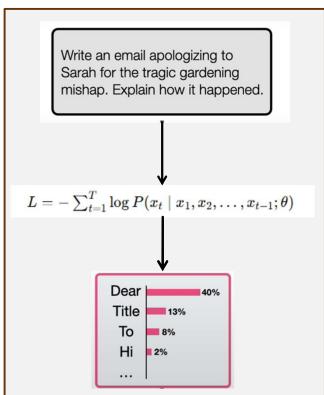
- Cross-entropy Loss
- Generated output is compared to the desired response using a loss function

Output

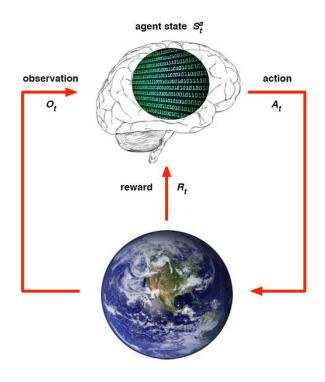
 Modified Probability Distribution over the vocabulary (~30,000)

**Dataset Size** 

- Task-specific models: Less than 0.5% of the original dataset: Generalize to other data, not just in fine-tuning data
- InstructGPT: I 3,000 prompt-response pairs human labelers



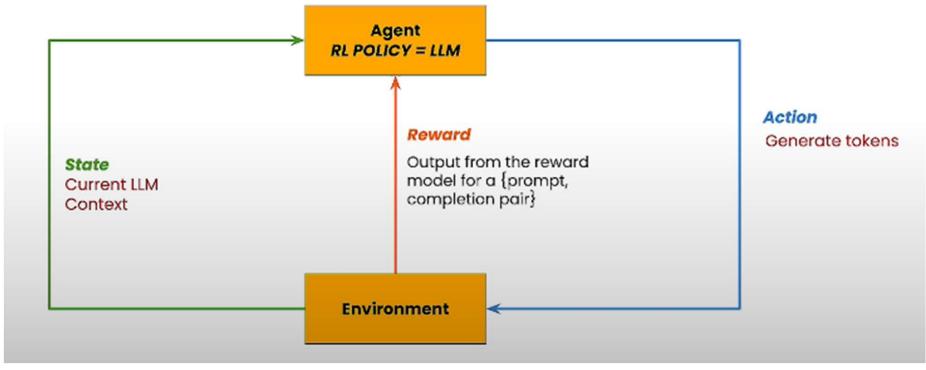
## REINFORCEMENT LEARNING: AGENT AND ENVIRONMENT



- At each step t, the agent:
  - Execute action A(t)
  - Receives observation O(t)
  - Receives scalar reward R(t)
- The environment:
  - Receives action A(t)
  - Emits observation O(t+1)
  - Emits scalar reward R(t+1)
- t increment at environment step

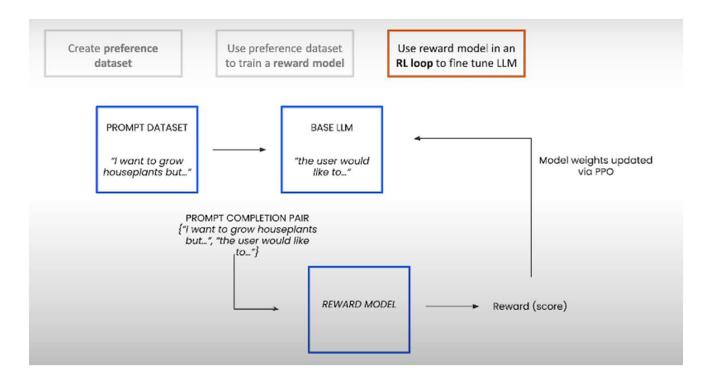
- Sequential Decision Making
- Reward Hypothesis: All goals can be described by the maximization of expected cumulative reward (scalar)

## POST-TRAINING: RLHF TO FINE TUNE LLM



- Proximal Policy Optimization (PPO)
- DeepSeek: GRPO

## **POST-TRAINING: RLHF**



- Sequential Decision Making
- Reward Hypothesis: All goals can be described by the maximization of expected cumulative reward (scalar)

# POST-TRAINING: RLHF – REWARD MODEL – TRAINING (1/3)

Input

- Preference Dataset Pairwise (Prompt, Winning Candidate, Losing Candidate, Choice)
- Annotated by Human (Subjective)

**Loss Function** 

Minimize Pairwise Loss

$$\mathcal{L}( heta) = -rac{1}{{K \choose 2}} \sum_{(x,y_w,y_l)} \log \left(\sigma \left(r_ heta(x,y_w) - r_ heta(x,y_l)
ight)
ight)$$

Here:

- x is the prompt.
- $y_w$  and  $y_l$  are the preferred and less preferred responses, respectively.
- $r_{ heta}(x,y)$  is the reward model's score for a given prompt-response pair.
- ullet  $\sigma$  denotes the sigmoid function.
- ullet K is the number of responses ranked by human annotators for each prompt.

**Dataset Size** 

- 10K 100K range
- InstructGPT:
  - Reward Model Dataset: ~ 33,000 examples. Human labelers ranked multiple responses to the same prompt

# POST-TRAINING: RLHF – REWARD MODEL – INFERENCE (2/3)

Input

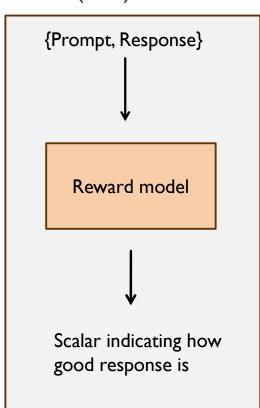
Prompt Dataset - {Prompt, Response}

Model

Reward Model (LLM), trained with Preference Dataset:
 {Prompt, Winning Candidate, Losing Candidate, Choice}

Output

Scalar indicating how good response is



# POST-TRAINING: RLHF – PROXIMAL POLICY OPTIMIZATION (3/3)

Input

• **Proximal Policy Optimization (PPO) Dataset**: InstructGPT ~31,000 prompts used to generate responses without human intervention during training, {Prompt}

**Loss Function** 

Policy Optimization: The language model is fine-tuned using reinforcement learning to maximize the rewards predicted by the reward model. A common approach is to use Proximal Policy Optimization (PPO) with a loss function that balances achieving high reward and maintaining the model's output distribution close to the original model to prevent divergence:

$$L(\phi) = \mathbb{E}_{(x,y) \sim D_{\pi_\phi}} \left[ r_{ heta}(x,y) - eta \log \left( rac{\pi_\phi(y|x)}{\pi_{ ext{SFT}}(y|x)} 
ight) 
ight]$$

In this equation:

- $\pi_{\phi}$  is the policy of the fine-tuned model.
- π<sub>SFT</sub> is the policy of the supervised fine-tuned model before reinforcement learning.
- β is a scaling factor that controls the strength of the penalty for deviating from the original policy.

# CONNECTING RL AND LLMS (1/2)

#### Connection in LLM

Sequential
Decision Making

• Next token prediction to maximize prediction accuracy (pre-training) and rewards (post-training) over vocabulary (discrete set)

State

Input prompt and previous generated tokens

Action

Token chosen from the vocabulary

Reward

Prediction accuracy + rewards from aligning with preference (weighted)

$$r(s_t, y_t) = \lambda_1 \log \pi(y_t \mid s_t) + \lambda_2 \operatorname{Metric}(s_t, y_t),$$

Source: <u>Large Language Models as Reinforcement Learning Agents in Token Space: A Theoretical Framework by Miquel Noguer I Alonso :: SSRN</u>

# CONNECTING RLAND LLMS (2/2): APPLICABILITY OF RL RESEARCH

#### Description

Hierarchical Decision

- Motivated by AlphaStar's multi-scale decision-making
- High-level planning and detailed token generation

Self-dialogue

- Motivated by self-play training in AlphaGo, AlphaStar
- Self-dialogue: Models can engage in dialogue, critiquing and improving each other's outputs

Adaptive decoding

Develop decoders that balance exploration and exploitation based on state uncertainty

Hybrid Models

Combine maximum likelihood training with RL-based fine-tuning

Source: Large Language Models as Reinforcement Learning Agents in Token Space: A Theoretical Framework by Miquel Noguer I Alonso :: SSRN

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