

Computational Models and Simulations,

MDSC 689.11

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Lecture Overview



- Introduction to Numerical Simulations
 - Brief overview of numerical simulations
 - Importance in solving complex problems
 - Brief history and evolution
 - Physics-based vs data-driven
- General Principles in Computational Modelling
 - Complexity, Scaling, Hierarchical modelling, Mathematical principles (Differential equations)
- Finite Element Analysis (FEA)
 - Idea behind FEA modelling, Process of conducting FEA, Challenges, Examples, Tools, Common Mistakes
- Case Study: Stress shielding in total hip replacements
- Q&A and Discussion

Brief Overview of (numerical) Simulations



1. Definition

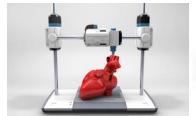
"Numerical simulations are computer-based models that solve complex mathematical problems to predict the behaviour of systems in the real world."

2. Key Components

- Mathematical Modelling: Real-world problems to mathematical form
- Computational Algorithms: Methods to numerically solve mathematical models
- Visualization: Graphical representation of simulation results

3. Other types of Simulations:

Physical models (e.g. mock-ups, 3D printing, animal models)





4. Applications

physical sciences, mathematics, economics, engineering, and biomedical fields

Simulation process

Real-World-Problem



Mathematical Model



Computation



Quantification/ Visualisation





Solving the Unsolvable

Solve complex problems that are (currently) analytically too complicated

Cost-Effectiveness

Reduce physical prototypes and experiments

3. Precision and Predictability

 System behaviours based on physical principles, e.g. different temperatures, material properties, external loads

Innovation and Design

Rapid prototyping, e.g. devices, implants, stents, surgeries,

5. Decision Making

 Providing data-driven insights, e.g. simulation of failure load of implants

Navier-Stokes Millennium Problem

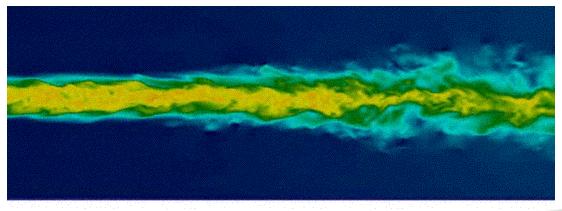
The existence of a strong solution to the Navier-Stokes equations

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ISSN 1682-0525. Mathematical Journal. 2013. Vol 13, Num 4 (50). Translated by Mikhail Wolfson, Ph.D., January 12, 2014

Otelbaev, 2013

Fluid Dynamics Simulation

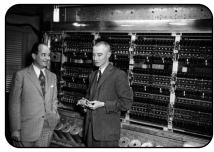


https://vbt.ebi.kit.edu/

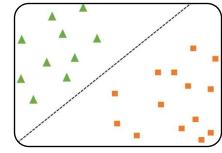
Brief history and evolution













1940s: Birth of Computer Simulations

 Monte Carlo simulation by von Neumann and Ulam during the Manhatten Project

1960s: Rise of Digital Computing

 Use of computers to solve differential equations

1970s: Physics-Based Modelling

 Simulations become standard for engineering systems from aerospace to biomedical applications

1990s: Data-Driven Models

• Emergence of Machine Learning

Present: Generative Al

 Generative Adversarial Networks, Transformer Architecture (ChatGPT), Large Language Models (Llama, PaLM, Gemini), Diffusion Models (Sora)





	Data-Driven: Machine Learning	Physics-Based: Numerical Modelling
Foundation	Data patterns	Physical laws
Data Need	Large datasets	Minimal to none
Predictive Scope	Within training data range	Beyond observed data
Insight	Limited to data patterns	Deep causal mechanisms
Complex Conditions	Limited by training data	Adaptable to new scenarios
Efficiency	Data-dependent costs	High initial cost, efficient long-term
Applications	Data-rich applications, explore patterns and data correlations, e.g. lung cancer detection in CT or MRI scans, fracture risk assessment in bone	Data-scarce applications, understand complex systems, predict and explore new scenarios, e.g. bone strength calculations, implant integration in bone

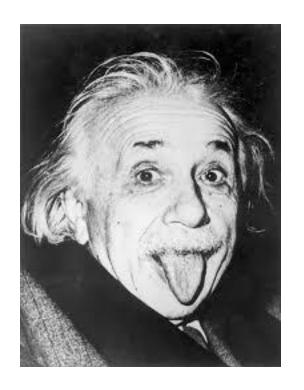
Underlying principle of Simulations



• Einstein's razor:

"The supreme goal of all theory is to make the irreducible basic elements as simple and as few as possible without having to surrender the adequate representation of a single datum of experience."

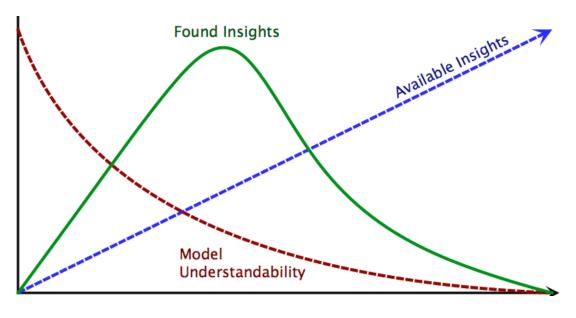
Make things as simple as possible, but no simpler.







- Complex models are more expensive...
 - 1. as they take longer to simulate,
 - as they are harder to interpret (cognitive costs),
 - 3. as they may not generalise well (e.g. overfitting in data-driven simulations)

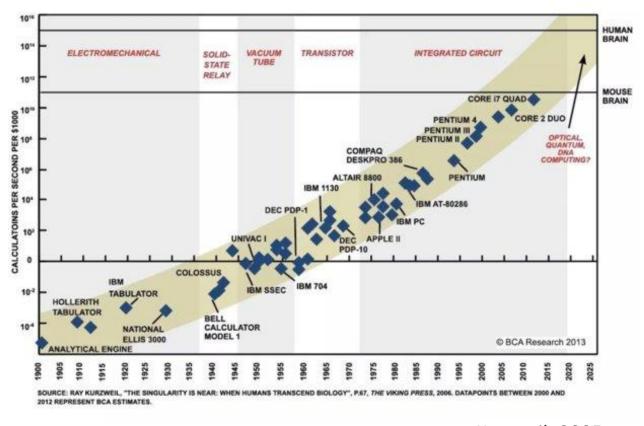


realkm.com





 Increasing computing power → increased model complexity and problem size

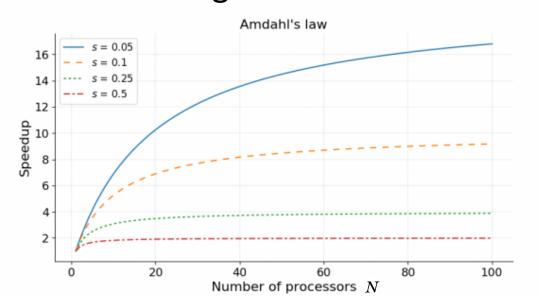


Kurzweil, 2005

Weak and strong scalability

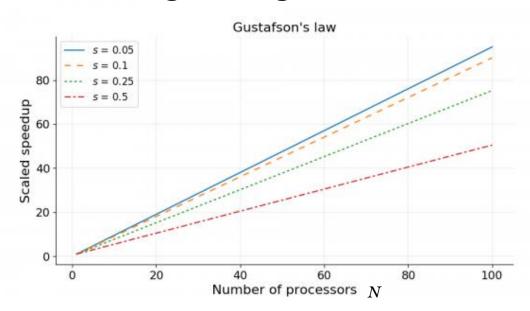


Weak scaling



$$speedup = 1 / (s + p / N)$$

Strong scaling



scaled speedup =
$$s + p \times N$$

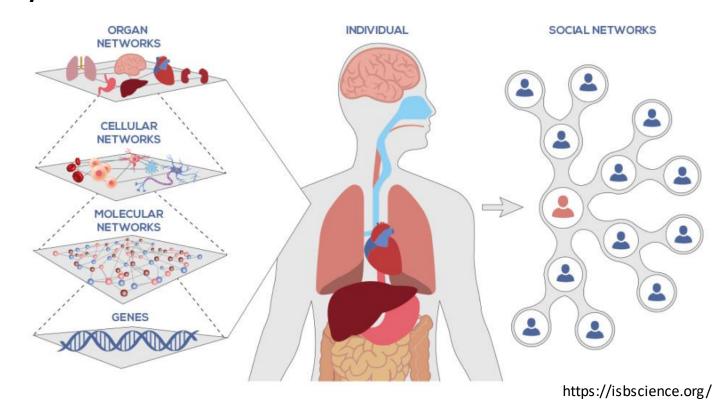
Parallelisation of mathematical models is key for large scale simulations!

p = parallel proportions = serial proportion





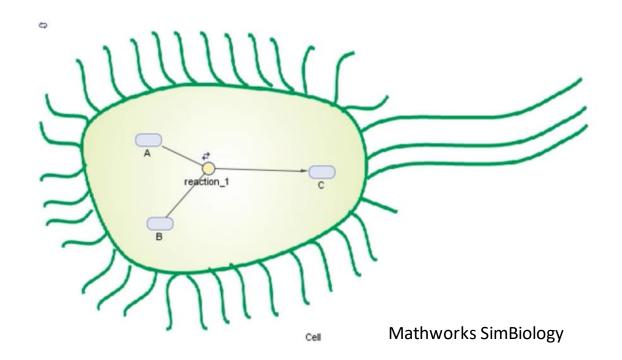
Biological systems: Network of Networks







- Hierarchical Modelling: Dividing a complex system into simpler subsystems
- Two approaches:
 - Top-down: Begins with the broad overview or system-level perspective, breaking it down into smaller parts
 - Bottom-up: Starts at the most detailed and basic level, assembling these components to build more complex systems



Choosing the right approach



Bottom-Up Approach

- Mechanistic Understanding
 - **Example**: To understand how diseases affect bones, researchers model individual cells, uncovering the disease's impact from the cellular level upwards.
- Synthetic Biology
 - Example: Constructing new biological systems or organisms from the ground up, often without a prior understanding of the system.

Top-Down Approach

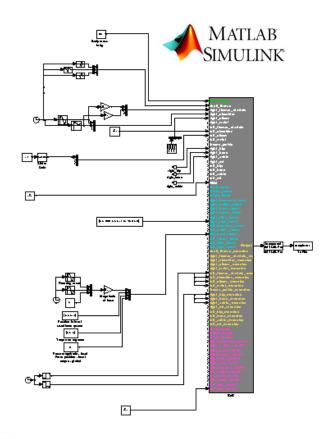
- Ecology and Evolutionary Biology
 - **Example**: Examining how climate change affects certain organisms, starting from an ecosystem-wide perspective.
- Systems Biology
 - Example: Simulating the dynamic interactions within biological systems to understand how different components interact on a systemic level.

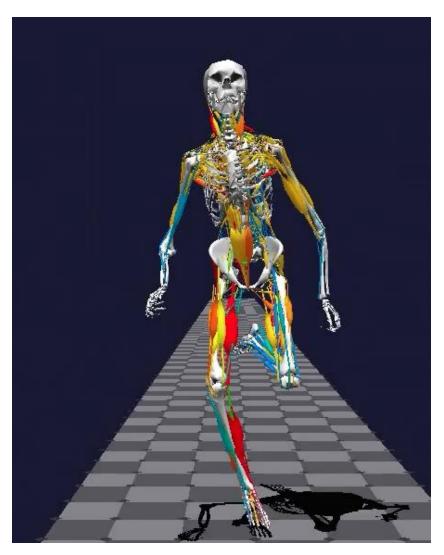
real-world scenarios approaches are typically hybrid (no clear separation possible)

MathWorks Simulink

UNIVERSITY OF CALGARY

Can be used for hierarchical modelling



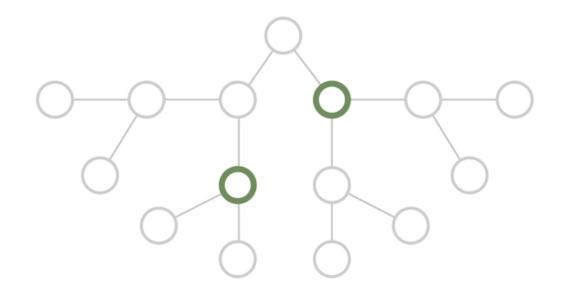


https://www.bob-biomechanics.com/



Key Mathematical Principles in Numerical Simulations

Differential equations



$$\frac{dI(t)}{dt} = k * I(t)$$

- Equations that describe how quantities change over time or space, involving derivatives with respect to a variable
- **Applications**: modelling the dynamics of systems, including motion, growth, decay, and changes in physical properties.



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Solving differential equations using Simulink

Robertson Problem

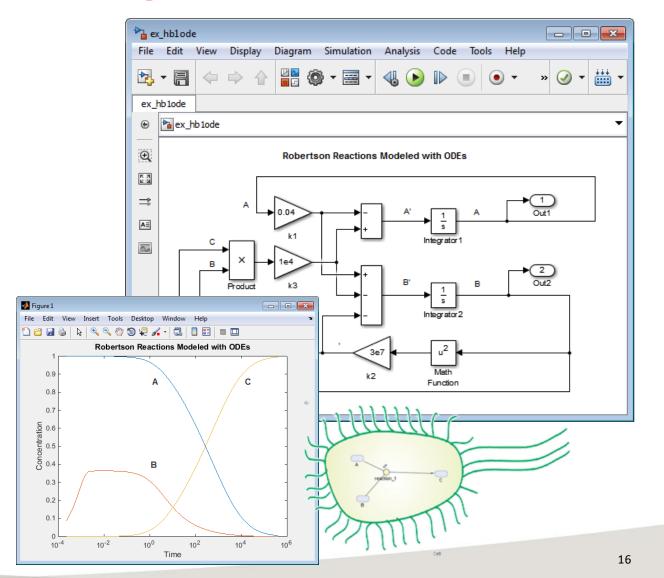
Set of chemical reactions among

$$A \xrightarrow{k_1} B \qquad k_1 = 0.04 \qquad V_1 = k_1[A]$$

$$B + B \xrightarrow{k_2} C + B \qquad k_2 = 3 \cdot 10^7 \quad V_2 = k_2[B][B]$$

$$k_3 \qquad B + C \xrightarrow{k_3} A + C \qquad k_3 = 1 \cdot 10^4 \quad V_3 = k_3[B][C]$$

1. Initial conditions: A=1, B=0, and C=0.







Solid Mechanics

$$\begin{split} &\frac{\partial \sigma_{xx}}{\partial x_1} + \frac{\partial \tau_{xy}}{\partial x_2} + \frac{\partial \tau_{xz}}{\partial x_3} + F_x = 0, \\ &\frac{\partial \tau_{xy}}{\partial x_1} + \frac{\partial \sigma_{yy}}{\partial x_2} + \frac{\partial \tau_{yz}}{\partial x_3} + F_y = 0, \\ &\frac{\partial \tau_{xz}}{\partial x_1} + \frac{\partial \tau_{xz}}{\partial x_2} + \frac{\partial \sigma_{zz}}{\partial x_3} + F_z = 0, \end{split}$$

Thermodynamics/Biology

$$rac{\partial c}{\partial t} =
abla \cdot (D
abla c - \mathbf{v}c) + R$$

Fluid Mechanics

$$rac{D\mathbf{u}}{Dt} = rac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot
abla) \mathbf{u} =
u \,
abla^2 \mathbf{u} - rac{1}{
ho}
abla p + \mathbf{g}.$$

Electromagnetics

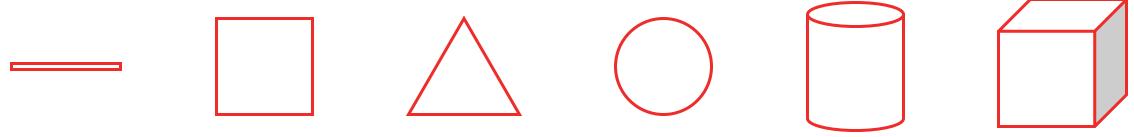
$$egin{aligned}
abla imes \mathbf{E} &= -rac{\partial \mathbf{B}}{\partial t} &
abla \cdot \mathbf{E} &= rac{
ho}{arepsilon_0} \
abla imes \mathbf{B} &= \mu_0 \left(\mathbf{J} + arepsilon_0 rac{\partial \mathbf{E}}{\partial t}
ight) &
abla \cdot \mathbf{B} &= 0 \end{aligned}$$

- Along with these equations with additional constraints called the boundary conditions (BCs)
- Differential equations + BC → Boundary value problem

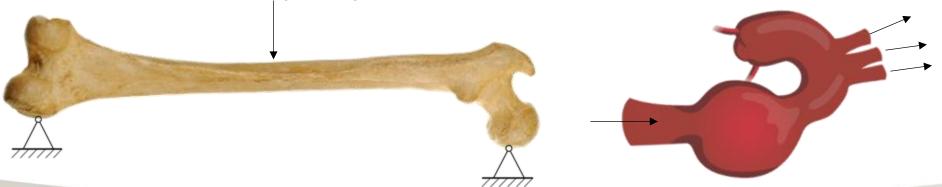




 Analytical methods (Integration, Laplace transform, etc.) are only valid for certain geometries



• How do we handle complex problems?



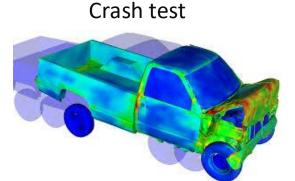




• FEA is a numerical method used to obtain an approximate solution for a given boundary value problem



Automotive Industry

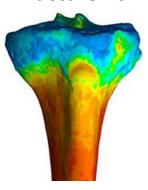


Aerospace Industry



Biomedical Engineering

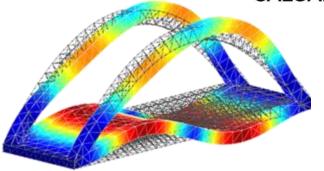
Fracture risk



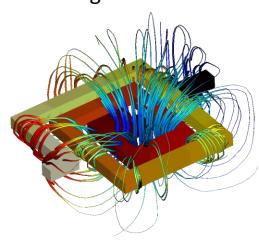
Civil Engineering

Bridge modes

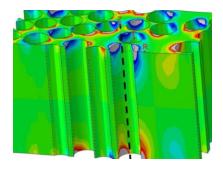




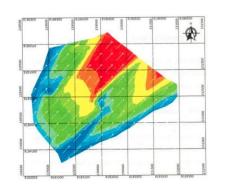
Manufacturing Magnetic Fields



Material Science
Carbon Fibre



Environmental EngineeringAir Pollution



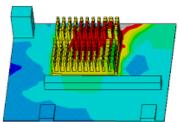
The Power of Finite Element Analysis

Energy SectorNuclear Reactor



Consumer Electronics

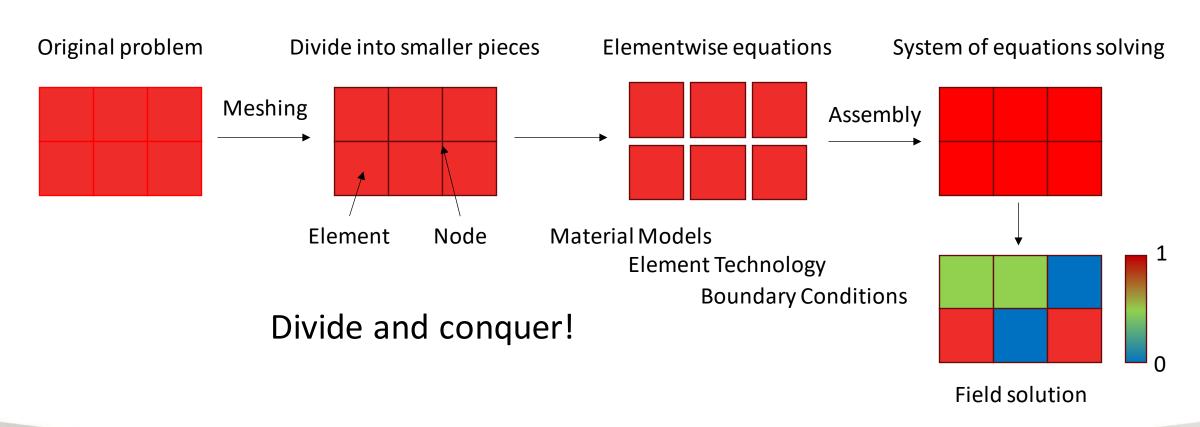
Heat Transfer



Process of Finite Element Analysis



Objective is to find the approximate solution to the boundary value problem!





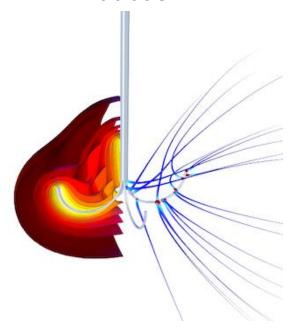


- **1. Define Problem** Objectives, Scope (e.g. Predict bone fracture load)
- **2. Create Model** Geometry Simplification (e.g. Use CT scans for 3D bone structure)
- **3. Select Materials** Properties, Behaviour (e.g. Bone material properties from literature)
- 4. **Meshing** Element Type, Density (e.g. tetrahedral, hexahedral)
- 5. Apply Conditions Constraints, Loads (e.g. Apply physiological loads and constraints mimicking joint forces)
- **6. Solve** FEA Solver (e.g. Linear static analysis to estimate failure load)
- **7. Analyse Results** Convergence, Sensibility (e.g. Evaluate stress distribution to predict potential fracture sites)

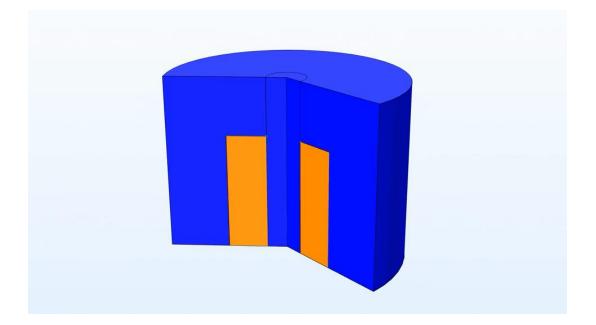




Heat generated during a tumor ablation



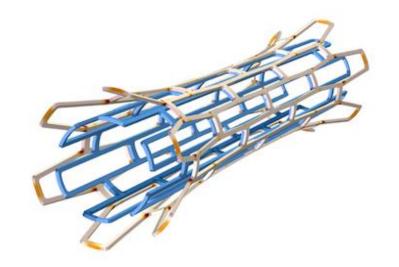
Drug delivery from a biomatrix



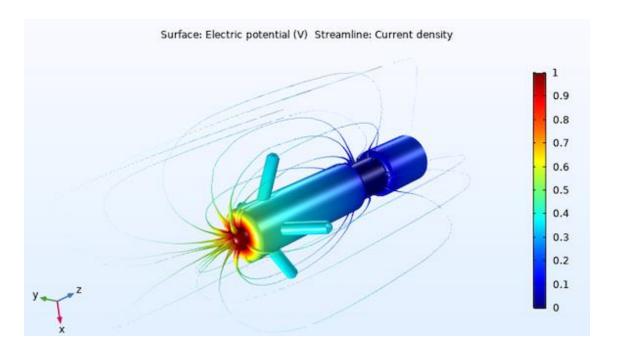
Simulations to accelerate Product Development



Biomedical stent



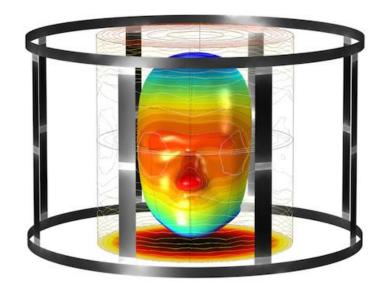
Pacemaker electrode



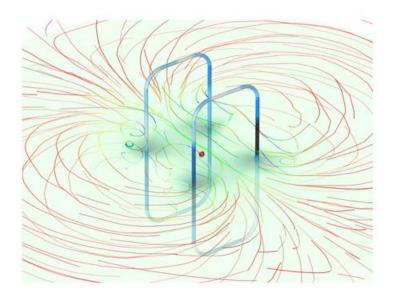




Electromagnetic field MRI birdcage coil



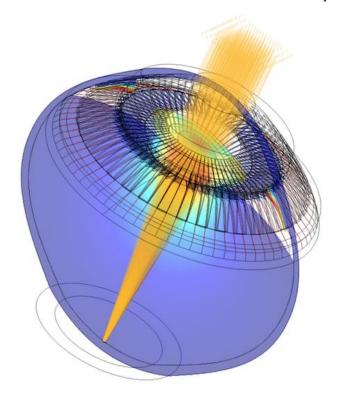
Electromagnetic interference RFID tag



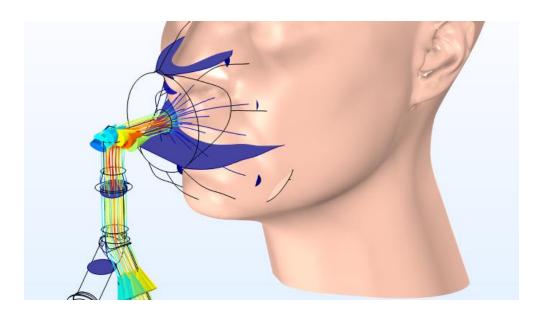




Optomechanical model of the human eye



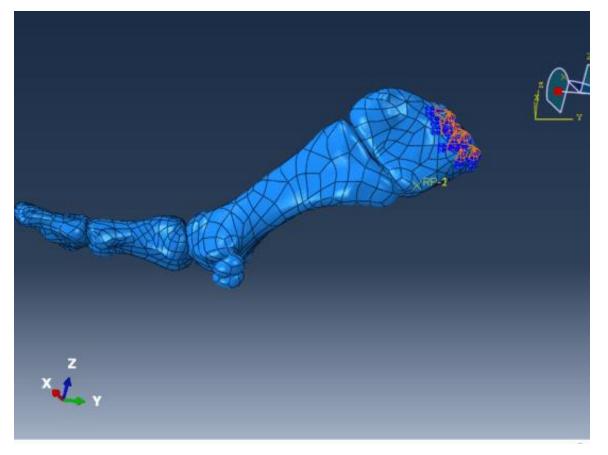
Non-invasive ventilation (NIV) mask



Tools for Finite Element Analysis



- ANSYS
 - Advanced simulations across multiple physics.
- Abaqus
 - Specialized in nonlinear problems, material failure.
- COMSOL Multiphysics
 - Multiphysics problems, user-friendly interface.
- SolidWorks Simulation
 - Integrated with CAD, user-friendly for designers.
- Custom Solvers:
 - For: Bone (FAIM, ParOsol), Soft tissue (BACI)



Connected bones using Abaqus

Common problems in FEA



- 1. Watch Out for Stress Concentrations
 - Are there any artefacts? High stress at the boundary conditions or sharp corners may be artefacts!
- Ensure Adequate Mesh Quality
 - Is my solution accurate enough? Conduct mesh convergence studies!
- 3. Account for Material and Geometric Nonlinearities
 - Was the right material model chosen? Consider nonlinear models for large deformations (e.g. soft tissues)
- 4. Apply Boundary Conditions and Loads Correctly
 - Do boundary conditions accurately mimic the physical setup?
- Validate FEA Results
 - 1. Always compare FEA outcomes with experimental data





Problem

Model

Materials

Meshing

Boundary Conditions

Solver

Results

Wolff's law¹:

Bone adapts to the loads under which it is placed

Problem:

Simulate stress shielding in a femoral implant



wallematthias.github.io/teaching

¹Wolff, J. 1892

Questions?



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https://wallematthias.github.io/