

Assignment 9 Analysis

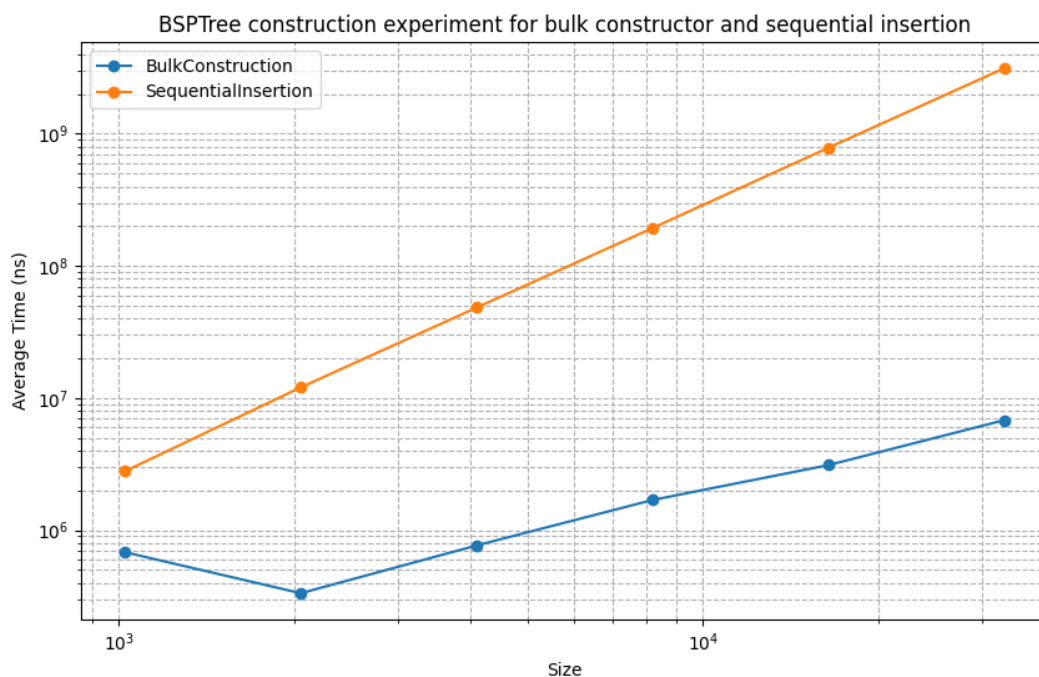
Ray Ding

Construction

What is the "worst case" order to insert them? Plot the runtimes of the 2 methods for building the tree. Do your experiments match the Big O growth rates you expected?

The worst case could be that segments are sorted by their x-coordinate in ascending order. Each new segment could potentially split all the segments that have been inserted before it.

As shown by the figure, the log-log scale plot provided illustrates the relationship between the size of segments and the average time taken to construct a BSP tree using both bulk construction (blue curve) and sequential insertion (orange curve) methods. In a log-log scale plot, a linear relationship indicates a power-law correlation between the two variables. The steepness of the orange curve is consistent with the $O(N^2)$ complexity often associated with the sequential insertion method in worst-case scenarios. The shallower slope of the bulk construction suggests an algorithmic complexity better than $O(N^2)$, potentially close to $O(N\log N)$, which is typically desired for a BSP tree construction. Thus, the results match theoretical expectations: bulk construction should generally perform better than sequential insertion in the worst-case scenario due to its ability to maintain a more balanced tree.



Collision Detection

Does our optimized collision detection routine run in the big O you expected? Be sure to describe the details of your experiment.

Yes, the routine behaves as expected.

The expected Big O complexity for the optimized collision detection routine in a well-balanced BSP tree is $O(\log N)$, where n is the number of segments in the tree. This is because the collision detection should only need to check a subset of segments along a path from the root to a leaf. The naive method has an expected complexity of $O(N)$ since it checks every segment.

