

Geometry

Kaizhao Liu

October 15, 2025

Contents

1	Smooth Manifold	5
1.1	Tensor Algebra	5
2	Riemannian Manifold	7
2.1	Riemannian Metrics	7
2.2	Affine Connections	7
2.2.1	Levi-Civita Connection	7
2.2.2	Tensor Leibniz Rule	7
2.2.3	Along a Curve	7
2.3	Curvature	7
2.3.1	Symmetries	8

Chapter 1

Smooth Manifold

Lie derivative

1.1 Tensor Algebra

Chapter 2

Riemannian Manifold

2.1 Riemannian Metrics

2.2 Affine Connections

An affine connection $\nabla(\cdot)$ is a map from $\Gamma(M) \times \Gamma(M)$ to $\Gamma(M)$

Definition 2.2.1. 1. $C(M)$ -linear in the lower slot

2. \mathbb{R} -linear in the upper slot

3. $C(M)$ -Leibniz rule in the upper slot

2.2.1 Levi-Civita Connection

Let ∇ be an affine connection, then by the basis theorem there are locally defined functions Γ_{ij}^k such that

$$\nabla_{\partial_i} \partial_j = \sum_k \Gamma_{ij}^k \partial_k. \quad (2.1)$$

A connection is symmetric if
metric compaibility

Theorem 2.2.2. *Given a metric g , there is a unique connection ∇ that is symmetric and metric compatible. This connection is called the **Levi-Civita connection**, and is given by*

2.2.2 Tensor Leibniz Rule

$$\nabla_{E_i} E_j = \Gamma_{ij}^k E_k$$

Proposition 2.2.3.

$$F_{j_1 \dots j_l; m}^{i_1 \dots i_k} = E_m(F_{j_1 \dots j_l}^{i_1 \dots i_k}) + \sum_{s=1}^k \Gamma_{mp}^{i_s} F_{j_1 \dots j_l}^{i_1 \dots p \dots i_k} - \sum_{s=1}^l \Gamma_{mj_s}^p F_{j_1 \dots p \dots j_l}^{i_1 \dots i_k}$$

higher order covariant derivative can be computed by iterating

2.2.3 Along a Curve

2.3 Curvature

The covariant derivative of a (r, s) tensor can be thought of as an $(r, s+1)$ tensor in a natural way. For example, if

Repeating this, we get a $(1, 2)$ tensor $\nabla \nabla V$, which will abbreviate as $\nabla^2 V$.

Using the Leibniz rule, we see that

$$\nabla_X(\nabla_Y V) = \nabla_{X,Y}^2 V + \nabla_{\nabla_X Y} V$$

The tensor is not necessarily symmetric in the two lower slots. In fact, the curvature comes in

$$\begin{aligned}
\nabla_{X,Y}^2 V - \nabla_{Y,X}^2 V &= \nabla_X(\nabla_Y V) - \nabla_Y(\nabla_X V) - \nabla_{\nabla_X Y - \nabla_Y X} V \\
&= \nabla_X(\nabla_Y V) - \nabla_Y(\nabla_X V) - \nabla_{[X,Y]} V \\
&= R(Y, X)V
\end{aligned}$$

This is known as the **Ricci identity**.

Definition 2.3.1 (Riemann curvature).

2.3.1 Symmetries