All the code can be accessed here and executed in google colab or any Jupyter Notebook environment: https://github.com/DragonBoy25830/caltech-cs-156

I) In general, H' will have a lower complexity than H, so H' won't be able to explain more of f and the deterministic noise will increase, so the answer is b.

```
def calc_error(classification, w, z_transform):
    yn = classification
    counter = 0
    for i in range(len(z_transform)):
    z = z_transform[i]
    w_val = np.sign(np.dot(w, z))
    if w_val != yn[i]:
        counter += 1
    return counter / len(classification)

def get_x_values(dataset):
    dataset = np.array(dataset)
    x1 = dataset[i, 0]
    x2 = dataset[i, 1]
    return np.column_stack((x1, x2))

def run_linear_regression_experiment():
    train_xn = np_training_set[i, 2]
    test_xn = get_x_values(training_set)
    train_yn = np_testing_set[i, 2]
    test_yn = np_testing_set[i, 2]
    train_xn_transform = [transform_data(x1, x2) for (x1, x2) in train_xn]
    test_xn_transform = [transform_data(x1, x2) for (x1, x2) in test_xn]
    w = np.matmul(np.linalg.pinv(train_xn_transform)
    t_in = calc_error(train_yn, w, train_xn_transform)
    E_in = calc_error(train_yn, w, test_xn_transform)
    return E_in, E_out

MagicPython
```

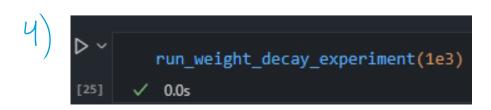
The code above outputs an Ein of 0.0286 and Eout of 0.084 which is closest in Euclidean distance to 0.03 & 0.08, so the answer is a.

3) The functions from before are used for this part as well. All I did was change the code for calculating

as well. All I did was change the code for calculating the weights.

```
def calculate_w_reg(Z, ZT, lambda_value, y):
            step_1 = np.matmul(ZT, Z)
            step_2 = step_1 + 1 (variable) step_3: Any /(len(step_1))
            step_3 = np.linalg.
            w_reg = np.matmul(step_4, y)
            return w_reg
                                                                                              MagicPython
        def run_weight_decay_experiment(lambda_value):
            train_xn = get_x_values(training_set)
            train_yn = np_training_set[:, 2]
            test_xn = get_x_values(testing_set)
            test_yn = np_testing_set[:, 2]
            train_xn_transform = np.array([transform_data(x1, x2) for (x1, x2) in train_xn])
            test_xn_transform = np.array([transform_data(x1, x2) for (x1, x2) in test_xn])
            w_reg = calculate_w_reg(train_xn_transform, np.transpose(train_xn_transform), lambda_value
            E_out = calc_error(test_yn, w_reg, test_xn_transform)
[23] 		 0.0s
                                                                                              MagicPython
        run_weight_decay_experiment(1e-3)
                                                                                              MagicPython
    (0.02857142857142857, 0.08)
```

The code above outputs an Ein of 0.0286 and Eout of 0.08 which is closest in Euclidean distance to 0.03 & 0.08, so the answer is d.



The code above outputs an Ein of 0.371 and Eout of 0.436 which is closest in Euclidean distance to 0.4 & 0.4, so the answer is e.

The above code shows that the smallest $E_{out} = 0.056$ occurs when K = -1, so the answer is d.

```
k_values = np.arange(-100, 100)
min_Eout = float('inf')

for k in k_values:
    Ein, Eout = run_weight_decay_experiment(np.power(10.0, k))

if Eout < min_Eout:
    min_Eout = Fout</pre>
```

6)

The code above calculates Eout for integer values of K from -100 to 100. The minimum Eout is equal to 0.056 which is closest to 0.06, so the answer is b

7) If a < b, then $Ha \in H_0$. Using this fact, we can write that based off the given constraint, $\mathcal{H}(Q,C,Q_0) = \mathcal{H}_{a_0-1} \text{ if } C=0 \text{ since the constraint zeroes}$ but all the terms of La after for $a > a_0$. As such, $\mathcal{H}(10,0,3) = \mathcal{H}_z \quad \& \quad \mathcal{H}(10,0,4) = \mathcal{H}_3 \quad . \text{ Since } \mathcal{H}_z \in \mathcal{H}_3,$ we can say that $\mathcal{H}(10,0,3) \cap \mathcal{H}(10,0,4) = \mathcal{H}_z \cdot .$ As Such, the answer is $c \cdot .$

8)
$$W_{ij}^{(r)} \times_{i}^{(r-1)} = \text{calculate } \times_{j}$$
 $W_{ij}^{(r)} \times_{i}^{(r-1)} = \text{calculate } \times_{j}$
 $W_{ij}^{(r)} \times_{j}^{(r)} = \text{calculate } \times_{j}$
 $X_{i}^{(r-1)} \times_{j}^{(r)} = \text{update weights}$
 O
 O
 O
 O
 O
 O

We calculate the total # of operations by looking at how many times each type of operation is performed:

0

1) Calculate X;

$$\frac{d^{c_1}}{\sum_{i=0}^{c_2} w_{ij}^{(e)} \times_{i}^{(e-1)}} = \frac{d^0}{\sum_{i=0}^{c_2} w_{ij}^{(1)} \times_{i}^{(o)}} + \frac{d^1}{\sum_{i=0}^{c_2} w_{ij}^{(o)} \times_{i}^{(o)}}$$

$$\frac{d^0}{\sum_{i=0}^{c_2} w_{ij}^{(o)} \times_{i}^{(o)}} + \frac{d^0}{\sum_{i=0}^{c_2} w_{ij}^{(o)} \times_{i}^{(o)}} \times_{i}^{(o)}}$$

$$\frac{d^0}{\sum_{i=0}^{c_2} w_{ij}^{(o)} \times_{i}^{(o)}} + \frac{d^0}{\sum_{i=0}^{c_2} w_{ij}^{(o)}} \times_{i}^{(o)}}$$

$$\frac{d^0}{\sum_{i=0}^{c_2} w_{ij}^{(o)} \times_{i}^{(o)}} + \frac{d^0}{\sum_{i=0}^{c_2} w_{ij}^{(o)}} \times_{i}^{(o)}} + \frac{d^0}{\sum_{i=0}^{c_2} w_{ij}^{(o)}} \times_{i}^{(o)}}$$

$$\frac{d^0}{\sum_{i=0}^{c_2} w_{ij}^{(o)} \times_{i}^{(o)}$$

2) Calculate 8; - Backpropagation

$$\frac{d^{(R)}}{\sum_{j=1}^{(R)} W_{ij}^{(R)} \otimes S_{j}^{(R)}} = \frac{d^{(1)}}{\sum_{j=1}^{(R)} W_{ij}^{(1)} \otimes S_{j}^{(1)}} + \frac{d^{(2)}}{\sum_{j=1}^{(R)} W_{ij}^{(2)} \otimes S_{j}^{(2)}}$$

$$\frac{3 \text{ weights for}}{\text{each node in}} = \frac{1 \text{ weight for}}{3 \text{ nodes in}}$$

$$\frac{d^{(0)}}{d^{(0)}} \otimes S_{j}^{(0)} = \frac{d^{(1)}}{\sum_{j=1}^{(R)} W_{ij}^{(2)} \otimes S_{j}^{(2)}}$$

$$\frac{d^{(1)}}{d^{(0)}} \otimes S_{j}^{(1)} = \frac{d^{(1)}}{\sum_{j=1}^{(R)} W_{ij}^{(2)} \otimes S_{j}^{(2)}}$$

$$\frac{d^{(1)}}{\sum_{j=1}^{(R)} W_{ij}^{(2)} \otimes S_{j}^{(2)}}$$

$$\frac{d^{(1)}}{\sum_{j=1}^{(R)} W_{ij}^{(2)} \otimes S_{j}^{(2)}}$$

$$\frac{d^{(1)}}{\sum_{j=1}^{(R)} W_{ij}^{(2)} \otimes S_{j}^{(2)}}$$

$$\frac{d^{(1)}}{\partial S_{j}^{(1)}} \otimes S_{j}^{(1)} = \frac{d^{(1)}}{\sum_{j=1}^{(R)} W_{ij}^{(2)} \otimes S_{j}^{(2)}}$$

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$$\frac{d^{(1)}}{\partial S_{j}^{(1)}} \otimes S_{j}^{(1)} \otimes S_{j}^{(1)} \otimes S_{j}^{(1)}$$

$$\frac{d^{(1)}}{\partial S_{j}^{(1)}} \otimes S_{j}^{(1)}$$

$$\frac{d^{(1)}}{\partial S_{j$$

$$d^{(0)}$$
, so 3 ops 15 ops

3) Update Weights

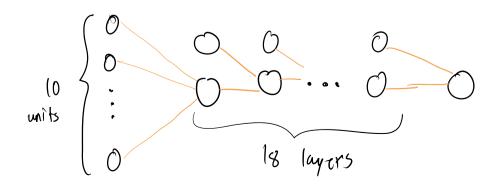
every Wij is updated and there are 8 total ups.

fotal # of operations =
$$(5x3+3x1)+(5x3+3x1)+(5+3)$$

= $44 \approx 45$

The answer is d.

9) The simplest way to reduce the number of weights is to only have two unit in each hidden layer.



We have 10 weights from the imput layer to the first hidden layer, 34 weights within the hidden layers and two weights from the last hidden layer to the output layer, so the minimum # of weights is 10+34+2=46.

The answer is a.

```
№ № № 日… 🛍
(0)
                     for i in range(1, 36):
                   ✓ 0.0s
                  4 186
                  6 254
                  8 314
                  10 366
                  11 389
                  14 446
                  15 461
                  16 474
                  17 485
                  18 494
                  19 501
                  21 509
                  22 510
                  24 506
                  ...
32 410
                  33 389
                  34 366
                  35 341
```

After some trial & error, it seems that two hidden layers maximizes the number of weights

in the network. After writing some python code, we see that 22 units in the first layer and 14 in the second layer results in a maximum # of weights of 510. The answer is e.

10(21) + 22(13) + 14 = 510