

汽车航迹推算研究进展

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① 研究内容

② 研究计划

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文献
试验

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国内外研究现状

① 研究内容

文献

试验

② 研究计划

数据集

- **Awesome GINS Dataset¹.**
- **RoNIN Dataset².**
- **KITTI Dataset³.**

¹Hailiang Tang et al. "Impact of the Earth Rotation Compensation on MEMS-IMU Preintegration of Factor Graph Optimization". In: *IEEE Sensors Journal* 22 (17 Sept. 2022), pp. 17194–17204. ISSN: 15581748. DOI: 10.1109/JSEN.2022.3192552.

²Sachini Herath, Hang Yan, and Yasutaka Furukawa. "RoNIN: Robust Neural Inertial Navigation in the Wild: Benchmark, Evaluations, & New Methods". In: 2020, pp. 3146–3152. ISBN: 9781728173955. DOI: 10.1109/ICRA40945.2020.9196860.

³Andreas Geiger et al. "Vision meets robotics: The KITTI dataset". In: *The International Journal of Robotics Research* 32 (11 Sept. 2013), pp. 1231–1237. ISSN: 0278-3649. DOI: 10.1177/0278364913491297. URL: <http://journals.sagepub.com/doi/10.1177/0278364913491297>.

深度神经网络模型

- 数据集和模型间的交叉验证

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参考文献 I

- [1] Hailiang Tang et al. “Impact of the Earth Rotation Compensation on MEMS-IMU Preintegration of Factor Graph Optimization”. In: *IEEE Sensors Journal* 22 (17 Sept. 2022), pp. 17194–17204. ISSN: 15581748. DOI: 10.1109/JSEN.2022.3192552.
- [2] Sachini Herath, Hang Yan, and Yasutaka Furukawa. “RoNIN: Robust Neural Inertial Navigation in the Wild: Benchmark, Evaluations, & New Methods”. In: 2020, pp. 3146–3152. ISBN: 9781728173955. DOI: 10.1109/ICRA40945.2020.9196860.

参考文献 II

- [3] Andreas Geiger et al. “Vision meets robotics: The KITTI dataset”. In: *The International Journal of Robotics Research* 32 (11 Sept. 2013), pp. 1231–1237. ISSN: 0278-3649. DOI: 10.1177/0278364913491297. URL: <http://journals.sagepub.com/doi/10.1177/0278364913491297>.

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