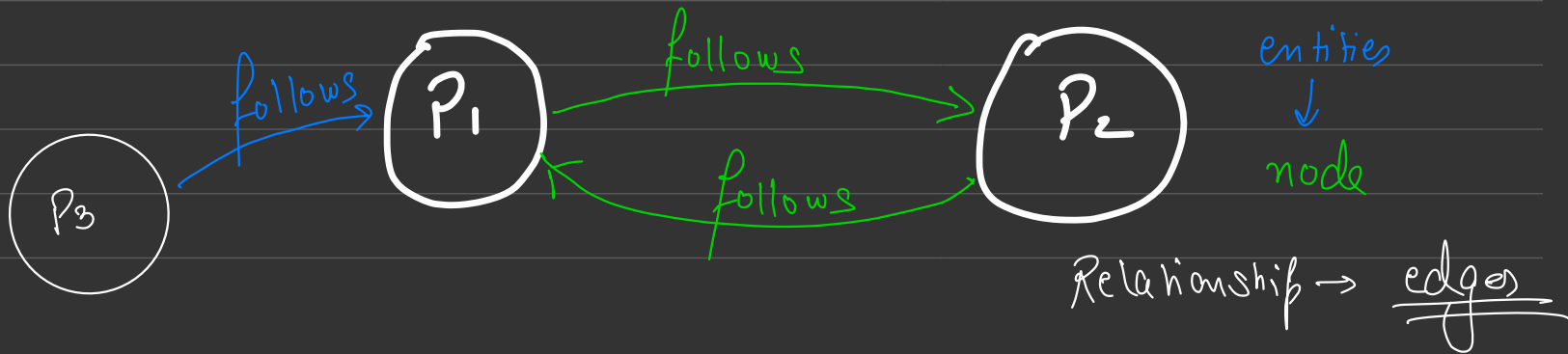


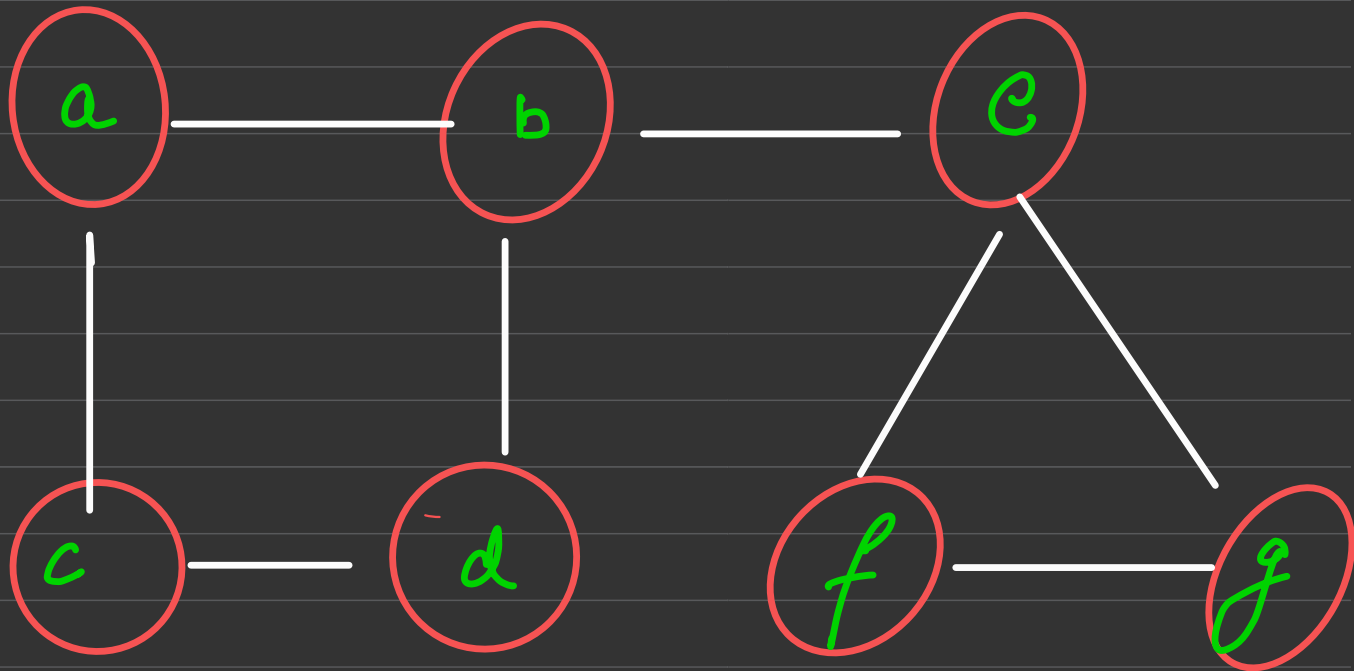
Graphs

Q₂ What is a graph??

Graph is a non linear Data Structure

which represents relationship btw 2 entities

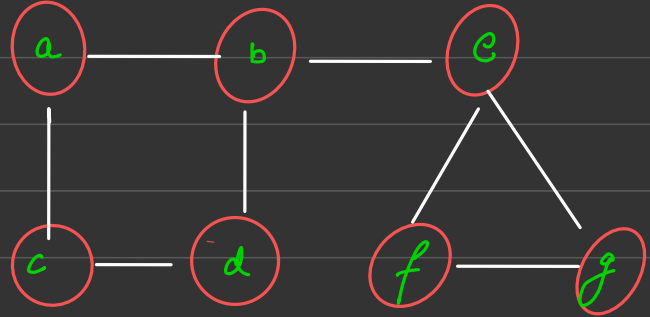




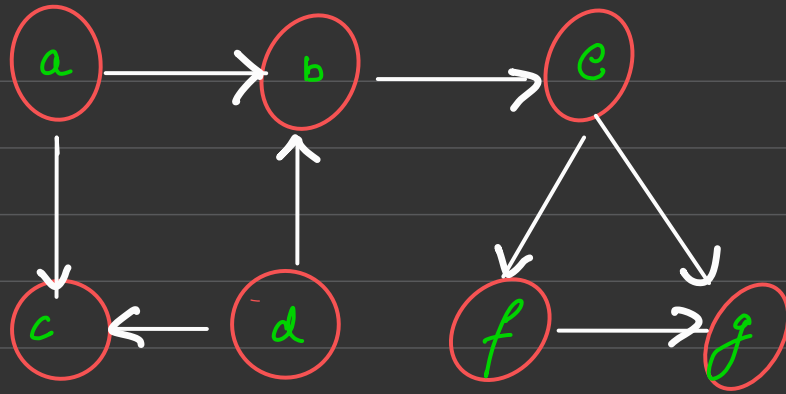
Example

Types of graph \rightarrow

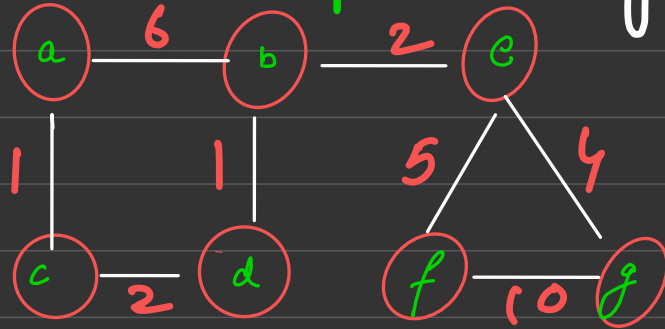
1) Undirected Graph \rightarrow where edges do not have directions



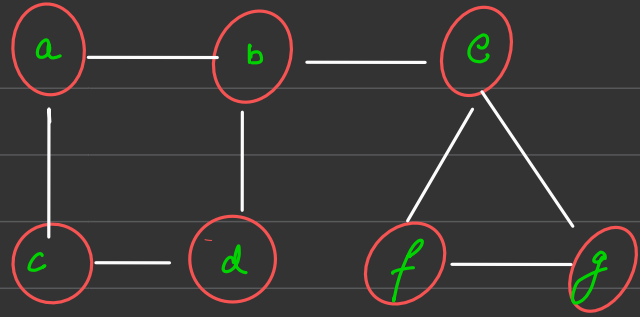
2) Directed Graphs \rightarrow edges have directions



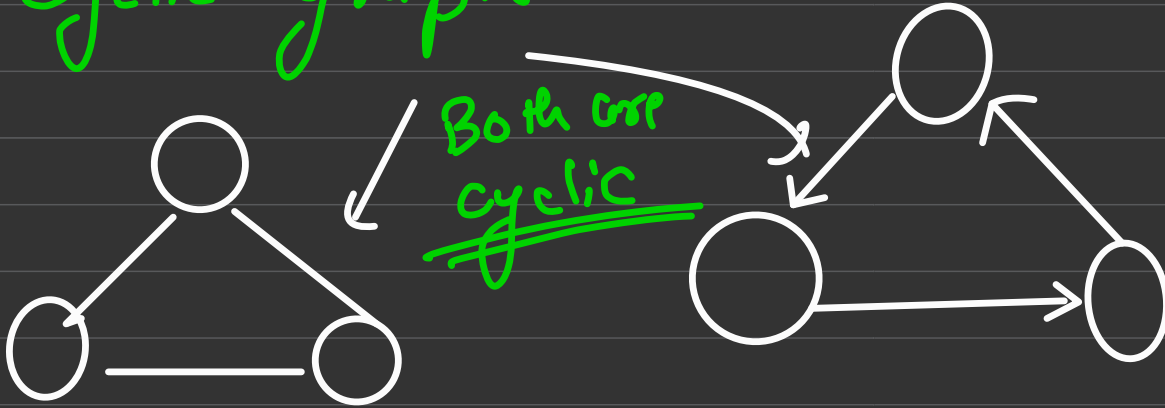
3) Weighted Graph \rightarrow every edge has a weight



4) unweighted graphs

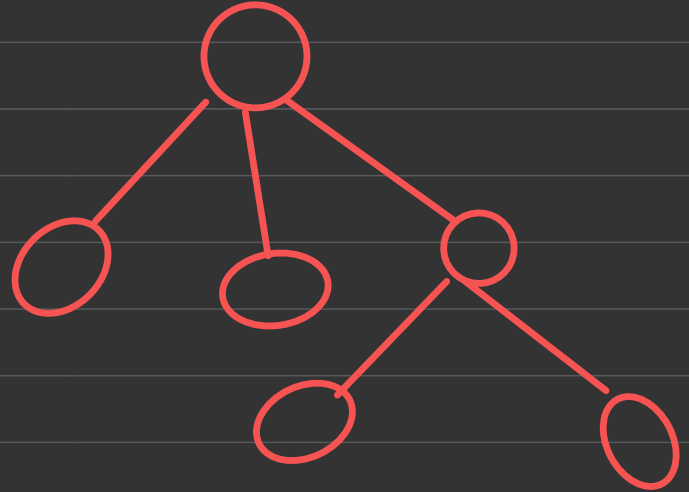


5) Cyclic graphs →



TREE \rightarrow It is an undirected acyclic

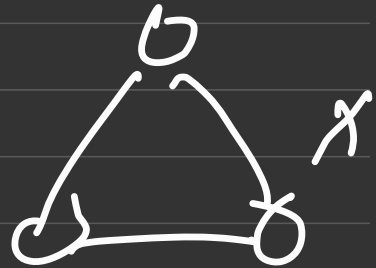
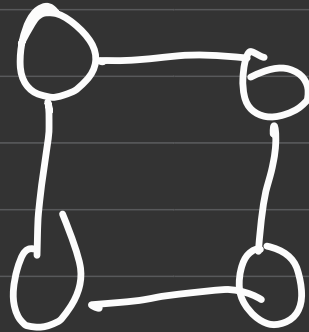
graph where any 2 nodes are connected
by only one path



Dense graph

Sparse graph

Connected graph



How To Represent A Graph

→ Adjacency Matrix

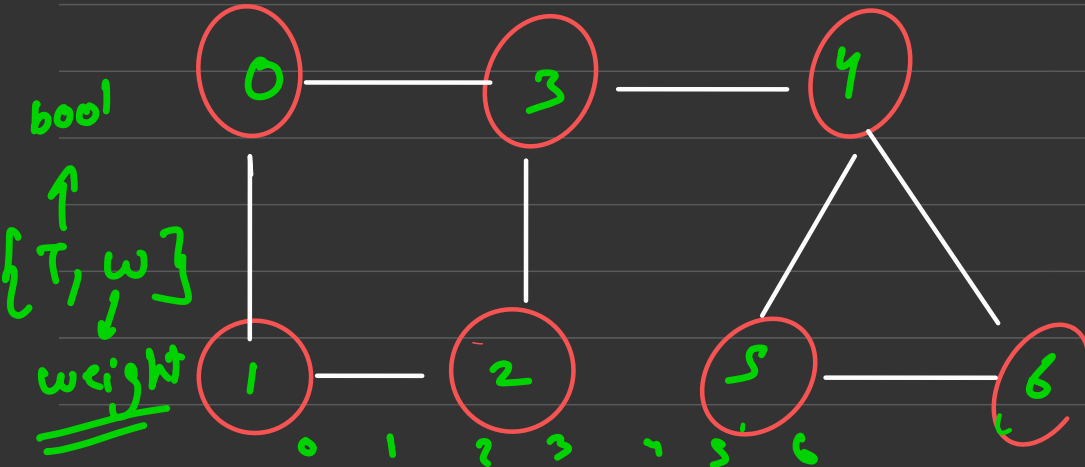
→ Adjacency List

→ Adjacency Map

→ Edge list

① Adjacency Matrix → V vertices

↓
VxV matrix



bool
↑
{T, w}
↓
weight

	0	1	2	3	4	5	6
0		T	T	T			
1	T						
2	T			T			
3	T		T		T		
4				T		T	T
5					T	T	
6							T

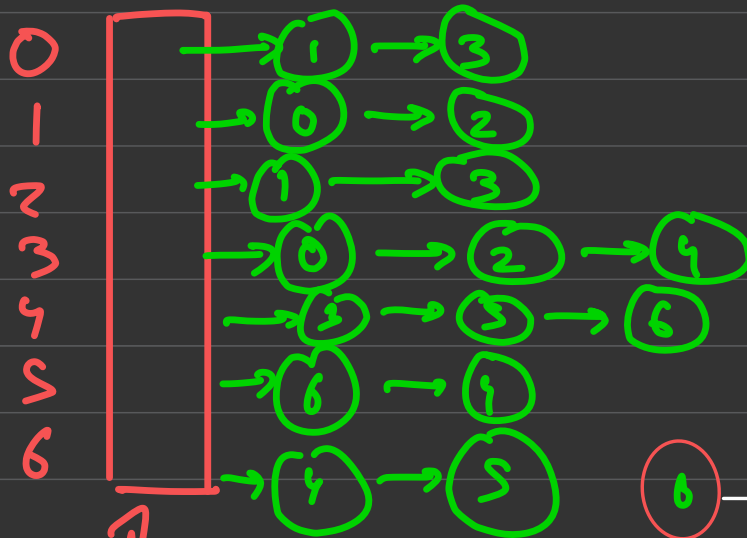
$(i, j) \rightarrow$ there is an edge btw i^{th} node & j^{th} node or not

→ wastage of space

Adjacency List \rightarrow array of LL

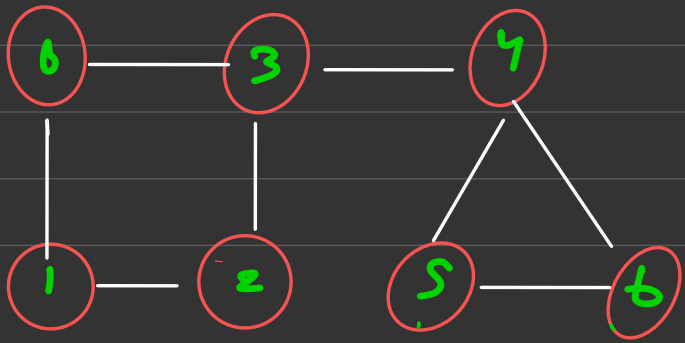
vector of vector

$\rightarrow \underline{\underline{O(V+E)}}$



array

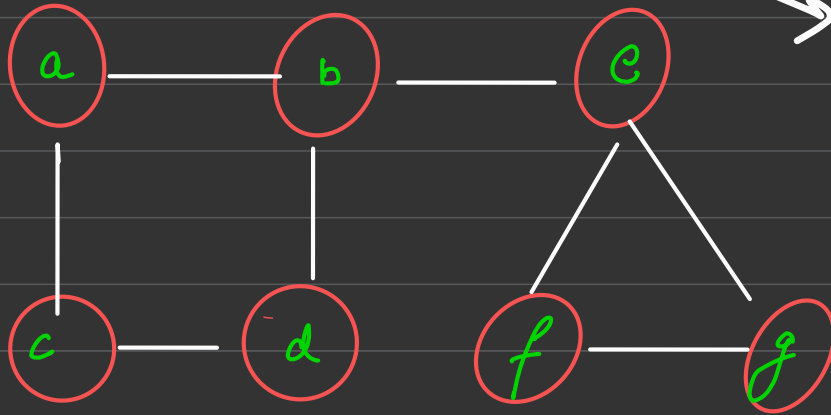
LL



Adjacency Map \rightarrow array of map



Edge List \rightarrow array of edge object



storing the info of
edge

src
dest
wt

$[(a,b), (a,c), (b,d), (c,d), (b,e) \dots]$

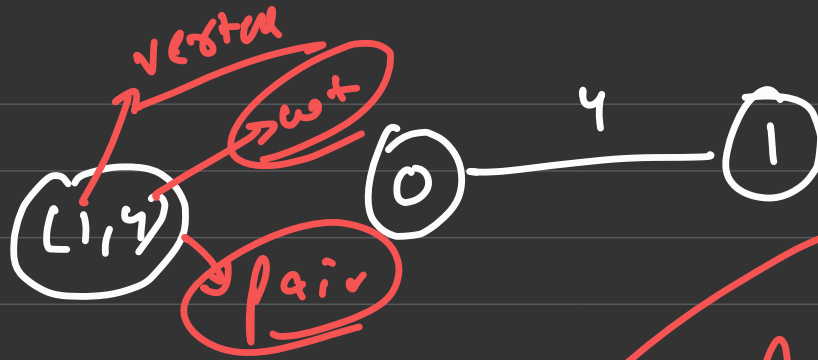
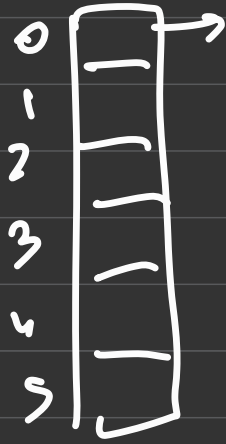


Kruskal's

$p \leftarrow \{ \text{first: } x$
 $\text{second: } y$

}

$p.\text{first} \rightarrow x$
 $p.\text{second} \rightarrow y$

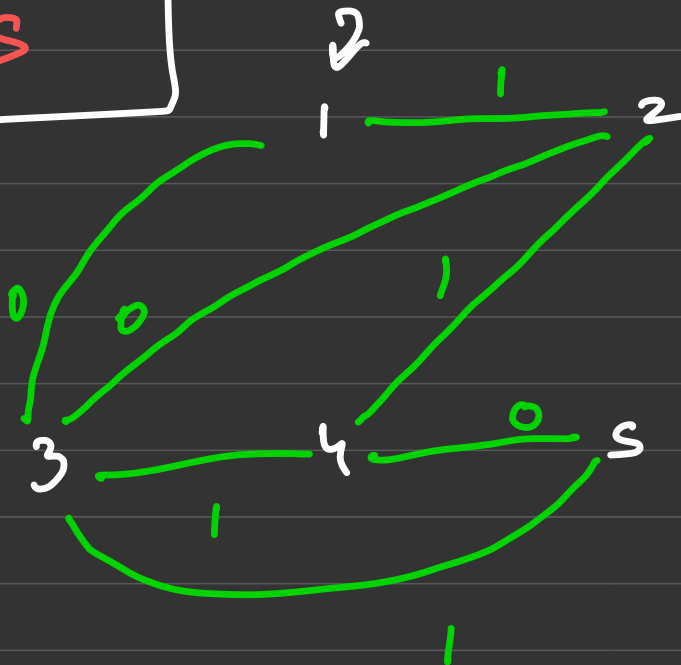


#include <vector>

1, 2, 3, 4, 5

visited

1, 2, 3, 4, 5

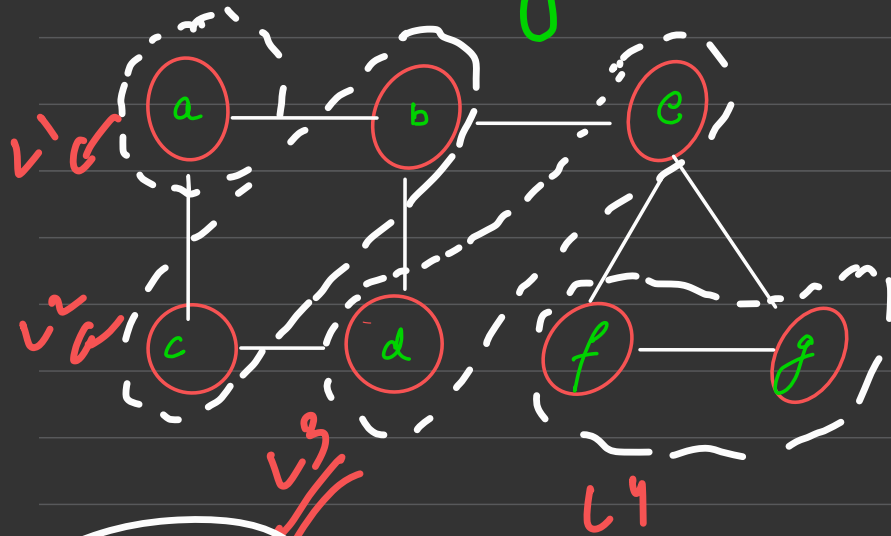


Graph Traversal

1) BREADTH FIRST TRAVERSAL/SEARCH
(BFS)

2) DEPTH FIRST TRAVERSAL/SEARCH
(DFS)

BFS \rightarrow In this traversal, we select a node and traverse the graph layer wise (level wise) thus exploring the neighbour nodes first

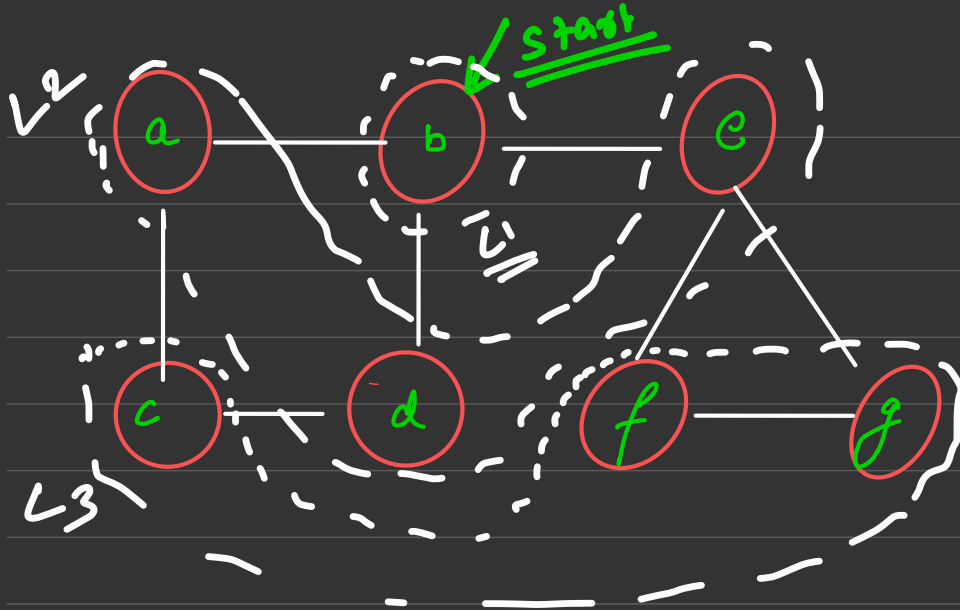


queues

a, b, c, e, d, f, g

BFS

neighbour first



queue

b, a, d, e, c, f, g

visited

set

bool array

b, a, d, c, c, f, g

$O(V + E)$

