

$$\vec{E} = -\vec{\nabla} V - \frac{\partial \vec{A}}{\partial t}$$

$$\vec{\nabla} V = \frac{qc}{4\pi\epsilon_0} \frac{-1}{(rc - \vec{r} \cdot \vec{v})^2} \vec{\nabla} (rc - \vec{r} \cdot \vec{v})$$

$$\vec{\nabla} (\vec{r} \cdot \vec{v}) = \vec{r} \times \vec{\nabla} \times \vec{v} + \vec{v} \times \vec{\nabla} \times \vec{r} + (\vec{r} \cdot \vec{\nabla}) \vec{v} + (\vec{v} \cdot \vec{\nabla}) \vec{r}$$

$$\textcircled{1} (\vec{r} \cdot \vec{\nabla}) \vec{v} = \left(r_x \frac{\partial}{\partial x} + r_y \frac{\partial}{\partial y} + r_z \frac{\partial}{\partial z} \right) \vec{v}$$

$$\frac{\partial \vec{v}}{\partial x} = \frac{\partial \vec{v}}{\partial t_r} \frac{\partial t_r}{\partial x} \quad \text{etc.}$$

$$\frac{\partial \vec{v}}{\partial t_r} \left(r_x \frac{\partial t_r}{\partial x} + r_y \frac{\partial t_r}{\partial y} + r_z \frac{\partial t_r}{\partial z} \right)$$

$$\vec{a} (\vec{r} \cdot \vec{\nabla} t_r)$$

$$\textcircled{2} (\vec{v} \cdot \vec{\nabla}) \vec{r} = \left(v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} + v_z \frac{\partial}{\partial z} \right) \vec{r}$$

$$\frac{\partial \vec{r}}{\partial x} = \frac{\partial \vec{r}}{\partial x} + \frac{\partial \vec{r}}{\partial t_r} \frac{\partial t_r}{\partial x} = \frac{\partial \vec{r}}{\partial x} - \frac{\partial \vec{w}(t_r)}{\partial t_r} \frac{\partial t_r}{\partial x}$$

$$= \hat{x} - \frac{\partial \vec{w}(t_r)}{\partial t_r} \frac{\partial t_r}{\partial x} = \hat{x} - \vec{v} \frac{\partial t_r}{\partial x}$$

$$\begin{aligned}
 (\vec{v} \cdot \vec{\nabla}) \vec{r} &= v_x \hat{x} - v v_x \frac{\partial t_r}{\partial x} + v_y \hat{y} - v v_y \frac{\partial t_r}{\partial y} \\
 &\quad + v_z \hat{z} - v v_z \frac{\partial t_r}{\partial z} \\
 &= \vec{v} - \vec{v} (\vec{v} \cdot \vec{\nabla} t_r)
 \end{aligned}$$

$$③ \quad \vec{r} \times \vec{\nabla} \times \vec{v}(t_r)$$

$$(\vec{\nabla} \times \vec{v}(t_r)) = \left(\frac{\partial v_z}{\partial t_r} \frac{\partial t_r}{\partial y} - \frac{\partial v_y}{\partial t_r} \frac{\partial t_r}{\partial z} \right) \hat{x}$$

$$+ \left(\frac{\partial v_x}{\partial t_r} \frac{\partial t_r}{\partial z} - \frac{\partial v_z}{\partial t_r} \frac{\partial t_r}{\partial x} \right) \hat{y} + \left(\frac{\partial v_y}{\partial t_r} \frac{\partial t_r}{\partial x} - \frac{\partial v_x}{\partial t_r} \frac{\partial t_r}{\partial y} \right) \hat{z}$$

$$= \left(a_z \frac{\partial t_r}{\partial y} - a_y \frac{\partial t_r}{\partial z} \right) \hat{x} + \left(a_x \frac{\partial t_r}{\partial z} - a_z \frac{\partial t_r}{\partial x} \right) \hat{y}$$

$$+ \left(a_y \frac{\partial t_r}{\partial x} - a_x \frac{\partial t_r}{\partial y} \right) \hat{z} = -\vec{a} \times \vec{\nabla} t_r$$

$$- (\vec{r} \times \vec{a} \times \vec{\nabla} t_r) = -\vec{a} (\vec{r} \cdot \vec{\nabla} t_r) + \vec{\nabla} t_r (\vec{r} \cdot \vec{a})$$

using triple product rule

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B} (\vec{A} \cdot \vec{C}) - \vec{C} (\vec{A} \cdot \vec{B})$$

$$(4) \quad \vec{v} \times (\vec{\nabla} \times \vec{r}) =$$

$$\vec{\nabla} \times (\vec{r} - \vec{\omega}(t_r)) = \vec{\nabla} \times \vec{r} - \vec{\nabla} \times \vec{\omega}(t_r) = -\vec{\nabla} \times \vec{\omega}(t_r)$$

$$\vec{\nabla} \times \vec{\omega}(t_r) = \left(\frac{\partial \omega_z}{\partial t_r} \frac{\partial t_r}{\partial y} - \frac{\partial \omega_y}{\partial t_r} \frac{\partial t_r}{\partial z} \right) \hat{x}$$

$$\left(\frac{\partial \omega_x}{\partial t_r} \frac{\partial t_r}{\partial z} - \frac{\partial \omega_z}{\partial t_r} \frac{\partial t_r}{\partial x} \right) \hat{y} + \left(\frac{\partial \omega_y}{\partial t_r} \frac{\partial t_r}{\partial x} - \frac{\partial \omega_x}{\partial t_r} \frac{\partial t_r}{\partial y} \right) \hat{z}$$

$$= \left(v_z \frac{\partial t_r}{\partial y} - v_y \frac{\partial t_r}{\partial z} \right) \hat{x} + \left(v_x \frac{\partial t_r}{\partial z} - v_z \frac{\partial t_r}{\partial x} \right) \hat{y}$$

$$+ \left(v_y \frac{\partial t_r}{\partial x} - v_x \frac{\partial t_r}{\partial y} \right) \hat{z} = -\vec{v} \times \vec{\nabla} t_r$$

$$\vec{v} \times \vec{v} \times \vec{\nabla} t_r =$$

$$\vec{v} (\vec{v} \cdot \vec{\nabla} t_r) - \vec{\nabla} t_r (\vec{v} \cdot \vec{v}) = \vec{v} (\vec{v} \cdot \vec{\nabla} t_r) - v^2 \vec{\nabla} t_r$$

Add these results to get $\vec{\nabla}(\vec{r} \cdot \vec{v})$

$$\vec{a}(\vec{r} \cdot \vec{\nabla} t_r) + \vec{v} - \vec{v}(\vec{v} \cdot \vec{\nabla} t_r) - \vec{a}(\vec{r} \cdot \vec{\nabla} t_r)$$

$$+ \vec{\nabla} t_r (\vec{r} \cdot \vec{a}) + \vec{v}(\vec{v} \cdot \vec{\nabla} t_r) - v^2 \vec{\nabla} t_r$$

$$= \vec{v} + (\vec{r} \cdot \vec{a} - v^2) \vec{\nabla} t_r$$

Putting it together:

$$\begin{aligned}\vec{\nabla} V &= \frac{qc}{4\pi\epsilon_0} \frac{1}{(rc - \vec{r} \cdot \vec{v})^2} \left[\vec{\nabla} (\vec{r} \cdot \vec{v}) + c^2 \vec{\nabla} t_r \right] \\ &= \frac{qc}{4\pi\epsilon_0} \frac{1}{(rc - \vec{r} \cdot \vec{v})^2} \left[\vec{v} + (c^2 - v^2 + \vec{r} \cdot \vec{a}) \vec{\nabla} t_r \right]\end{aligned}$$

$$-c \vec{\nabla} t_r = \vec{\nabla} r$$

Find $\vec{\nabla} t_r$ the tricky book way

$$\begin{aligned}\vec{\nabla} (\vec{r} \cdot \vec{r})^{1/2} &= \frac{1}{2r} \vec{\nabla} (\vec{r} \cdot \vec{r}) \\ &= \frac{1}{2r} 2 \left[\vec{r} \times \vec{\nabla} \times \vec{r} + (\vec{r} \cdot \vec{\nabla}) \vec{r} \right]\end{aligned}$$

$$\begin{aligned}(\vec{r} \cdot \vec{\nabla}) \vec{r} &= \left(r_x \frac{\partial}{\partial x} + r_y \frac{\partial}{\partial y} + r_z \frac{\partial}{\partial z} \right) (\vec{r} - \vec{w}(t_r)) \\ &= \left(r_x \frac{\partial x}{\partial x} + r_y \frac{\partial y}{\partial y} + r_z \frac{\partial z}{\partial z} \right) - r_x \frac{\partial \vec{w}}{\partial t_r} \frac{\partial t_r}{\partial x} - r_y \frac{\partial \vec{w}}{\partial t_r} \frac{\partial t_r}{\partial y} \\ &\quad - r_z \frac{\partial \vec{w}}{\partial t_r} \frac{\partial t_r}{\partial z} = \vec{r} - \vec{v} (\vec{r} \cdot \vec{\nabla} t_r)\end{aligned}$$

$$\vec{\nabla} \times \vec{A} = \vec{\nabla} \times \vec{F} - \vec{\nabla} \times \vec{W}(t_r)$$

we did this one earlier,

$$\vec{\nabla} \times \vec{A} = \vec{v} \times \vec{\nabla} t_r$$

$$\vec{A} \times \vec{v} \times \vec{\nabla} t_r = \vec{v} (\vec{A} \cdot \vec{\nabla} t_r) - \vec{\nabla} t_r (\vec{A} \cdot \vec{v})$$

$$\vec{\nabla} A = \frac{1}{A} \left[\vec{v} (\vec{A} \cdot \vec{\nabla} t_r) - \vec{\nabla} t_r (\vec{A} \cdot \vec{v}) + \vec{A} - \vec{v} (\vec{A} \cdot \vec{\nabla} t_r) \right]$$

$$-c \vec{\nabla} t_r = \frac{1}{A} \left[\vec{A} - (\vec{A} \cdot \vec{v}) \vec{\nabla} t_r \right]$$

$$\vec{\nabla} t_r = \frac{-\vec{A}}{Ac - \vec{A} \cdot \vec{v}}$$

$$\vec{\nabla} V = \frac{qc}{4\pi\epsilon_0} \frac{1}{(Ac - \vec{A} \cdot \vec{v})^3} \left[(Ac - \vec{A} \cdot \vec{v}) \vec{v} - (c^2 - v^2 + \vec{A} \cdot \vec{a}) \vec{A} \right]$$

Alternative (longer) way of finding $\vec{\nabla} t_r$

$$\vec{\nabla} \mathcal{L} = -c \vec{\nabla} t_r$$

Also

$$\begin{aligned} \vec{\nabla} \mathcal{L} &= \vec{\nabla} [r^2 - 2\vec{r} \cdot \vec{\omega}(t_r) + \omega^2(t_r)]^{1/2} \\ &= \frac{1}{2} \frac{1}{r} \vec{\nabla} [\vec{r} \cdot \vec{r} - 2\vec{r} \cdot \vec{\omega}(t_r) + \vec{\omega} \cdot \vec{\omega}] \end{aligned}$$

Look at $\frac{\partial}{\partial x}$ term of $\vec{\nabla} = \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z}$

$$\frac{\partial}{\partial x} [\vec{r} \cdot \vec{r} - 2\vec{r} \cdot \vec{\omega}(t_r) + \vec{\omega}(t_r) \cdot \vec{\omega}(t_r)] =$$

$$2\vec{r} \cdot \frac{\partial \vec{r}}{\partial x} - 2 \frac{\partial \vec{r}}{\partial x} \cdot \vec{\omega}(t_r) - 2\vec{r} \cdot \frac{\partial \vec{\omega}(t_r)}{\partial t_r} \frac{\partial t_r}{\partial x} + 2\vec{\omega} \cdot \frac{\partial \vec{\omega}}{\partial t_r} \frac{\partial t_r}{\partial x} =$$

$$2\vec{r} \cdot \hat{x} - 2\hat{x} \cdot \vec{\omega}(t_r) - 2\vec{r} \cdot \vec{v} \frac{\partial t_r}{\partial x} + 2\vec{\omega} \cdot \vec{v} \frac{\partial t_r}{\partial x} =$$

$$2x - 2\omega_x(t_r) - 2(\vec{r} \cdot \vec{v} - \vec{\omega} \cdot \vec{v}) \frac{\partial t_r}{\partial x}$$

Then,

$$(\vec{\nabla} \mathcal{L})_x = \frac{1}{r} \left[\hat{x} x - \hat{x} \omega_x - [\vec{r} \cdot \vec{v} - \vec{\omega} \cdot \vec{v}] \hat{x} \frac{\partial t_r}{\partial x} \right]$$

Then $\vec{\nabla} \lambda = -c \vec{\nabla} t_r =$

$$\frac{1}{\lambda} \left[\hat{x}x + \hat{y}y + \hat{z}z - (\hat{x}\omega_x + \hat{y}\omega_y + \hat{z}\omega_z) - [\vec{r} \cdot \vec{v} - \vec{\omega} \cdot \vec{v}] \left(\hat{x} \frac{\partial t_r}{\partial x} + \hat{y} \frac{\partial t_r}{\partial y} + \hat{z} \frac{\partial t_r}{\partial z} \right) \right]$$

$$= \frac{1}{\lambda} \left[\vec{r} - \vec{\omega}(t_r) - \left((\vec{r} - \vec{\omega}(t_r)) \cdot \vec{v} \right) \vec{\nabla} t_r \right]$$

Solving for $\vec{\nabla} t_r$

$$- \lambda c \vec{\nabla} t_r + [(\vec{r} - \vec{\omega}(t_r)) \cdot \vec{v}] \vec{\nabla} t_r = \vec{\lambda}$$

$$\vec{\nabla} t_r = \frac{-\vec{\lambda}}{\lambda c - \vec{\lambda} \cdot \vec{v}}$$

$$\vec{E} = -\vec{\nabla}V - \frac{\partial \vec{A}}{\partial t} \quad \left(\begin{array}{l} \text{use results} \\ \text{of problem 10.17} \end{array} \right)$$

$$= -\frac{1}{4\pi\epsilon_0} \frac{qc}{(rc - \vec{r} \cdot \vec{v})^3} \left\{ (rc - \vec{r} \cdot \vec{v}) \vec{v} \right.$$

$$- (c^2 - v^2 + \vec{r} \cdot \vec{a}) \vec{r} + (rc - \vec{r} \cdot \vec{v}) (-\vec{v} + r\vec{a}/c)$$

$$\left. + \frac{r}{c} (c^2 - v^2 + \vec{r} \cdot \vec{a}) \vec{v} \right\}$$

$$= -\frac{1}{4\pi\epsilon_0} \frac{qc}{(rc - \vec{r} \cdot \vec{v})^3} \left\{ - (c^2 - v^2) \hat{r} \frac{r}{c} + (c^2 - v^2) \frac{r}{c} \vec{v} \right.$$

$$- (\vec{r} \cdot \vec{a}) \hat{r} \frac{r}{c} + (\vec{r} \cdot \vec{a}) \vec{v} \frac{r}{c} + r^2 \vec{a} - (\vec{r} \cdot \vec{v}) \vec{a} \frac{r}{c} \left. \right\}$$

$$= \frac{qr}{4\pi\epsilon_0} \frac{1}{(rc - \vec{r} \cdot \vec{v})^3} \left\{ (c^2 - v^2) (\hat{r} - \vec{v}) \right.$$

$$(\vec{r} \cdot \vec{a}) (\hat{r} - \vec{v}) - r \vec{a} + (\vec{r} \cdot \vec{v}) \vec{a} \left. \right\}$$

$$= \frac{qr}{4\pi\epsilon_0} \frac{1}{(rc - \vec{r} \cdot \vec{v})^3} \left\{ (c^2 - v^2) (\hat{r} - \vec{v}) + (\hat{r} - \vec{v}) (\vec{r} \cdot \vec{a}) \right.$$

$$\left. - \vec{a} (\vec{r} \cdot \hat{r} - \vec{r} \cdot \vec{v}) \right\}$$

Let $\vec{u} \equiv c\vec{\hat{n}} - \vec{v}$, then this is:

$$\vec{E} = \frac{q\lambda}{4\pi\epsilon_0} \frac{1}{[\vec{\hat{n}} \cdot (c\vec{\hat{n}} - \vec{v})]^3} \left\{ (c^2 - v^2) \vec{u} + \vec{u} (\vec{\hat{n}} \cdot \vec{a}) - \vec{a} (\vec{\hat{n}} \cdot \vec{u}) \right\}$$

$$\vec{E} = \frac{q\lambda}{4\pi\epsilon_0 [\vec{\hat{n}} \cdot \vec{u}]^3} \left\{ (c^2 - v^2) \vec{u} + \vec{\hat{n}} \times (\vec{u} \times \vec{a}) \right\}$$

using $\vec{\hat{n}} \times \vec{u} \times \vec{a} = \vec{u} (\vec{\hat{n}} \cdot \vec{a}) - \vec{a} (\vec{\hat{n}} \cdot \vec{u})$

Since $\vec{A} = \frac{\vec{v}}{c^2} V$, $\vec{B} = \frac{1}{c^2} \vec{\nabla} \times (\vec{v} V)$

$$\vec{\nabla} \times (f \vec{A}) = f (\vec{\nabla} \times \vec{A}) - \vec{A} \times \vec{\nabla} f \quad \left. \vphantom{\vec{\nabla} \times (f \vec{A})} \right\} \text{Product Rule}$$

$$\vec{B} = \frac{1}{c^2} \left[V (\vec{\nabla} \times \vec{v}) - \vec{v} \times \vec{\nabla} V \right]$$

From before:

$$\vec{\nabla} V = \frac{1}{4\pi\epsilon_0} \frac{qc}{(\lambda(c - \vec{\hat{n}} \cdot \vec{v}))^3} \left[(\lambda c - \vec{\hat{n}} \cdot \vec{v}) \vec{v} - (c^2 - v^2 + \vec{\hat{n}} \cdot \vec{a}) \vec{\hat{n}} \right]$$

Also from before,

$$\begin{aligned}\vec{\nabla} \times \vec{v} &= -\vec{a} \times \vec{\nabla} t_r \\ &= -\vec{a} \times \left(\frac{-\vec{n}}{rc - \vec{n} \cdot \vec{v}} \right)\end{aligned}$$

$$\begin{aligned}\vec{B} &= \frac{1}{c^2} \left[\frac{1}{4\pi\epsilon_0} \frac{qc}{(rc - \vec{n} \cdot \vec{v})} \left(\vec{a} \times \frac{\vec{n}}{(rc - \vec{n} \cdot \vec{v})} \right) - \vec{v} \times \frac{1}{4\pi\epsilon_0} \frac{qc}{(rc - \vec{n} \cdot \vec{v})^3} \left((rc - \vec{n} \cdot \vec{v}) \vec{v} - (c^2 - v^2 + \vec{n} \cdot \vec{a}) \vec{n} \right) \right] \\ &= \frac{q}{c 4\pi\epsilon_0} \left[\frac{-1}{(rc - \vec{n} \cdot \vec{v})^2} (\vec{n} \times \vec{a}) + \frac{(c^2 - v^2 + \vec{n} \cdot \vec{a})}{(rc - \vec{n} \cdot \vec{v})^3} (\vec{v} \times \vec{n}) \right] \\ &= \frac{-q}{c 4\pi\epsilon_0} \frac{1}{(\vec{a} \cdot \vec{n})^3} \left[(\vec{a} \cdot \vec{n}) (\vec{n} \times \vec{a}) - (c^2 - v^2 + \vec{n} \cdot \vec{a}) (\vec{v} \times \vec{n}) \right] \\ &= -\frac{q}{c 4\pi\epsilon_0} \frac{1}{(\vec{a} \cdot \vec{n})^3} \vec{n} \times \left[\vec{a} (\vec{a} \cdot \vec{n}) + \vec{v} (c^2 - v^2 + \vec{n} \cdot \vec{a}) \right] \\ &= -\frac{q}{c 4\pi\epsilon_0} \frac{1}{(\vec{n} \cdot \vec{a})^3} \vec{n} \times \left[(c^2 - v^2) \vec{v} + (\vec{n} \cdot \vec{a}) \vec{v} + (\vec{n} \cdot \vec{a}) \vec{a} \right]\end{aligned}$$