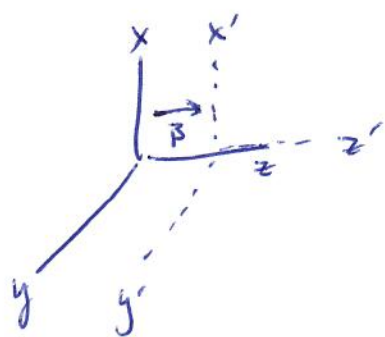


Covariance of the Electromagnetic Field

We've assumed some familiarity with Special relativity, especially that particle energies & momenta transform like a Lorentz 4-vector: $cp^\mu = (E, \vec{p}c) = (\gamma mc^2, \gamma mc \vec{v})$.

How does the electromagnetic field "transform", or appear differently for different observers in relative motion?

First some notation. Recall: if one observer uses coordinates



$x^\mu \equiv (ct, \vec{x})$ then the observer moving with constant velocity βc along the \hat{z} direction would label the same events by coordinates:

$$t' = \gamma(t - \beta z/c)$$

$$z' = \gamma(z - \beta ct)$$

$$x' = x$$

$$y' = y$$

In matrix notation, $x^{\mu'} = \Lambda^{\mu}_{\nu} x^\nu$

$$\Lambda^{\mu}_{\nu} \equiv \begin{pmatrix} \gamma & 0 & 0 & -\beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\beta\gamma & 0 & 0 & 1 \end{pmatrix}$$

implements a
"z-boost"

A more general form of the boost matrix is given in Jackson 11.98. All 4-vectors transform this way.
(definition)

We can define the proper time along a given trajectory

$$\text{as } \tau = \int_{\text{trajectory}} d\tau = \int_{\text{trajectory}} \sqrt{dt^2 - \frac{1}{c^2} dx^2}, \text{ i.e. } d\tau = dt/\gamma$$

where γ is associated with the trajectory.

This is Lorentz invariant.

Then the "4-velocity" $U^\mu \equiv \frac{dx^\mu}{d\tau} = \left(c \frac{dt}{d\tau}, \frac{d\vec{x}}{d\tau} \frac{dt}{d\tau} \right)$
 $= \gamma(c, \vec{v})$

is a 4-vector, since x^μ is a 4-vec and τ is invariant.

If we multiply this by m , we get $(\gamma mc, \gamma mc \vec{\beta})$

which is just p^μ ! So p^μ is also a 4-vector
 $"(E/c, \vec{p})"$

For the z boost, $E' = \gamma(E - \beta c p_z)$

$$p_z' = \gamma(p_z - \beta E/c)$$

$$p_x' = p_x$$

$$p_y' = p_y$$

$$\text{or } \Lambda^\mu{}_\nu p^\nu = p^{\mu'}$$

So $\frac{d\vec{p}}{d\tau}$ is a 4-vector and $\frac{d\vec{p}}{d\tau}$ is its spatial 3-vector part. Now look at the Lorentz force law:

$$\frac{d\vec{p}}{dt} = q(\vec{E} + \underbrace{\frac{\vec{v}}{c} \times \vec{B}}_{\text{Jackson normalizes } \vec{B} \text{ with a } 1/c \text{ here. Sometimes I absorb this in } \vec{B}, \text{ so that } \vec{F} = q(\vec{E} + \vec{v} \times \vec{B})})$$

We take this equation as given by experiment and use it to try to work out the necessary transformation properties of \vec{E} and \vec{B} , so that the equation is Lorentz invariant.

Jackson normalizes \vec{B} with a $1/c$ here. Sometimes I absorb this in \vec{B} , so that $\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$

$$\Rightarrow \gamma \frac{d\vec{p}}{dt} = \frac{d\vec{p}}{d\tau} = q \left(\gamma \vec{E} + \frac{\gamma \vec{v} \times \vec{B}}{c} \right) = \frac{q}{c} (u^0 \vec{E} + \vec{u} \times \vec{B})$$

This tells us the RHS transforms like a 3-vector.

The corresponding "time" is

$$\begin{aligned} \frac{dp^0}{d\tau} &= \frac{d}{d\tau} \sqrt{m^2 c^2 + \vec{p}^2} = \frac{1}{p^0} \vec{p} \cdot \frac{d\vec{p}}{d\tau} \\ &= \frac{q}{c} m \vec{u} \cdot (u^0 \vec{E} + \vec{u} \times \vec{B}) \\ &= \frac{q}{c} \vec{u} \cdot \vec{E} \end{aligned}$$

Therefore $\frac{1}{c} (\vec{U} \cdot \vec{E}, U^0 \vec{E} + \vec{U} \times \vec{B})$ must be a 4-vector.

$$= \frac{dp^\mu}{d\tau}$$

this must determine the transformation properties of E and B ...

The way to do it is to arrange \vec{E} and \vec{B} in

a rank 2 antisymmetric tensor, the

"Maxwell field strength tensor":

$$F^{\alpha\beta} = \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -B_z & +B_y \\ E_y & B_z & 0 & -B_x \\ E_z & -B_y & B_x & 0 \end{pmatrix}$$

$$\text{Then } F^{\mu\nu} U_\nu = \begin{pmatrix} \quad \quad \quad \end{pmatrix} \begin{pmatrix} -\gamma c \\ +\gamma v_x \\ +\gamma v_y \\ +\gamma v_z \end{pmatrix}$$

$$= \begin{pmatrix} \vec{U} \cdot \vec{E} \\ U^0 E_x + (\vec{U} \times \vec{B})_x \\ U^0 E_y + (\vec{U} \times \vec{B})_y \\ U^0 E_z + (\vec{U} \times \vec{B})_z \end{pmatrix}$$

If we chose the "West Coast" metric convention, $\eta = \text{diag}(1, -1, -1, -1)$, the minus sign would not be here.

$(F^{\mu\nu})' \equiv \Lambda^\mu_\rho \Lambda^\nu_\sigma F^{\rho\sigma}$ is the transformation law, so that $F^{\mu\nu} U_\nu$ is manifestly a 4-vector:

$$\begin{aligned} (F^{\mu\nu} U_\nu)' &= F^{\mu\nu'} g_{\nu\beta} U^{\beta'} \\ &= \Lambda^\mu_\rho \Lambda^\nu_\sigma F^{\rho\sigma} g_{\nu\beta} \Lambda^\beta_\gamma U^\gamma \end{aligned}$$

and since $\Lambda^\nu_\sigma g_{\nu\beta} \Lambda^\beta_\gamma = g_{\sigma\gamma}$

(Minkowski space is Lorentz invariant!)

we get $\Lambda^\mu_\rho (F^{\rho\sigma} U_\sigma)$

\Rightarrow 4-vector.

So $\frac{dp^\mu}{d\tau} = -\frac{q}{c} F^{\mu\nu} U_\nu$ is the "covariant form"

of the force law, and we can read off the transformation properties of \vec{E} and \vec{B} :

$$E_1' = E_1$$

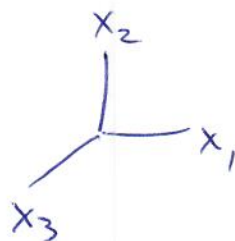
$$E_2' = \gamma(E_2 - \beta B_3)$$

$$E_3' = \gamma(E_3 + \beta B_2)$$

$$B_1' = B_1$$

$$B_2' = \gamma(B_2 + \beta E_3)$$

$$B_3' = \gamma(B_3 - \beta E_2)$$



from boosts along the x_1 axis:

$$\underbrace{\begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}}_{\Lambda} \underbrace{\begin{pmatrix} 0 & -E_1 & -E_2 & -E_3 \\ E_1 & 0 & -B_3 & +B_2 \\ E_2 & B_3 & 0 & -B_1 \\ E_3 & -B_2 & B_1 & 0 \end{pmatrix}}_F \underbrace{\begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}}_{\Lambda^T}$$

More generally,

$$\vec{E}' = \gamma(\vec{E} + \vec{\beta} \times \vec{B}) - \frac{\gamma^2}{\gamma+1} \vec{\beta} (\vec{\beta} \cdot \vec{E})$$

$$\vec{B}' = \gamma(\vec{B} - \vec{\beta} \times \vec{E}) - \frac{\gamma^2}{\gamma+1} \vec{\beta} (\vec{\beta} \cdot \vec{B})$$

if $\vec{B} = 0$, then $\vec{B}' = -\gamma \vec{\beta} \times \vec{E}$

Maxwell equations:

$$\partial_\mu F^{\mu\nu} = \mu_0 J^\nu$$

$$\epsilon^{\alpha\beta\gamma\delta} \partial_\beta F_{\gamma\delta} = 0$$

$$\epsilon^{\alpha\beta\gamma\delta} = \begin{cases} +1 & 0123, \text{ even perms} \\ 0 & \text{else} \\ -1 & \text{odd perms} \end{cases}$$

$$\square A^\mu = \mu_0 J^\mu \text{ (Lorentz gauge)}$$

$$J = (c\rho, \vec{j})$$

$$(\star F)^{\alpha\beta} \equiv \frac{1}{2} \epsilon^{\alpha\beta\gamma\delta} F_{\gamma\delta}$$

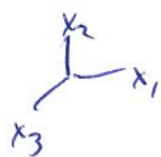
eg $\partial_0 F^{00} + \partial_i F^{i0} = \mu_0 c \rho$

$\nabla \cdot \vec{E} = \rho / \epsilon_0$ Gauss law

$$\partial_0 F^{0i} + \partial_j F^{ji} = \mu_0 \vec{j}$$

$$\frac{1}{c} \vec{E} - \nabla \times \vec{B} = \mu_0 \vec{j} \quad \text{signs, c's.}$$

Finally, let's use this to recover (in a simpler way!)
the fields of a moving point charge, as used
in the Weizsäcker-Williams analysis (later)



• observer

← • observer

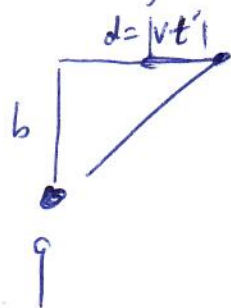


rest frame of
observer (x^μ)



rest frame of
charge (x'^μ)

In the x'^μ coordinate system,



$$E_1 = \frac{vt'}{\sqrt{b^2 + (vt')^2}} \frac{q}{4\pi\epsilon_0} \frac{1}{b^2 + (vt')^2}$$

$$E_2 = \frac{b}{\sqrt{b^2 + (vt')^2}} \frac{q}{4\pi\epsilon_0} \frac{1}{b^2 + (vt')^2}$$

$$E_3 = \vec{B} = 0.$$

In the x^μ coordinate system, $E_1' = E$, $E_2' = \gamma E_2$, $B_3' = -\gamma \beta E_2$
all others = 0.

In terms of $t = t'/\gamma$,

$$E_1' = \frac{\gamma vt}{[b^2 + (\gamma vt)^2]^{3/2}} \frac{q}{4\pi\epsilon_0}$$

$$E_2' = \frac{b\gamma}{[b^2 + (\gamma vt)^2]^{3/2}} \frac{q}{4\pi\epsilon_0}$$

$$B_3' = -\beta E_2'$$