0.0.1 Replicate Measurements

Thus far, the formulation for comparison of two measurement methods is one where one measurement by each method is taken on each subject. Should there be two or more measurements by each methods, these measurement are known as 'replicate measurements'. Carstensen et al. (2008) recommends the use of replicate measurements, but acknowledges that additional computational complexity.

Bland and Altman (1986) address this problem by offering two different approaches. The premise of the first approach is that replicate measurements can be treated as independent measurements. The second approach is based upon using the mean of the each group of replicates as a representative value of that group. Using either of these approaches will allow an analyst to estimate the inter method bias.

However, because of the removal of the effects of the replicate measurements error, this would cause the estimation of the standard deviation of the differences to be unduly small. Bland and Altman (1986) propose a correction for this.

Carstensen et al. (2008) takes issue with the limits of agreement based on mean values, in that they can only be interpreted as prediction limits for difference between means of repeated measurements by both methods, as opposed to the difference of all measurements. Incorrect conclusions would be caused by such a misinterpretation. Carstensen et al. (2008) demonstrates how the limits of agreement calculated using the mean of replicates are 'much too narrow as prediction limits for differences between future single measurements'. This paper also comments that, while treating the replicate measurements as independent will cause a downward bias on the limits of agreement calculation, this method is preferable to the 'mean of replicates' approach.

0.1 Repeated Measurements

In cases where there are repeated measurements by each of the two methods on the same subjects, Bland Altman suggest calculating the mean for each method on each subject and use these pairs of means to compare the two methods. The estimate of bias will be unaffected using this approach, but the estimate of the standard deviation of the differences will be too small, because of the reduction of the effect of repeated measurement error. Bland Altman propose a correction for this. Carstensen attends to this issue also, adding that another approach would be to treat each repeated measurement separately.

In this model, the variances of the random effects must depend on m, since the different methods do not necessarily measure on the same scale, and different methods naturally must be assumed to have different variances. Carstensen (2004) attends to the issue of comparative variances.

0.2 Repeated measurements in LME models

In many statistical analyzes, the need to determine parameter estimates where multiple measurements are available on each of a set of variables often arises. Further to Lam et al. (1999), Hamlett et al. (2004) performs an analysis of the correlation of replicate measurements, for two variables of interest, using LME models.

Let y_{Aij} and y_{Bij} be the jth repeated observations of the variables of interest A and B taken on the ith subject. The number of repeated measurements for each variable may differ for each individual. Both variables are measured on each time points. Let n_i be the number of observations for each variable, hence $2 \times n_i$ observations in total.

It is assumed that the pair y_{Aij} and y_{Bij} follow a bivariate normal distribution.

$$\left(egin{array}{c} y_{Aij} \ y_{Bij} \end{array}
ight) \sim \mathcal{N}(oldsymbol{\mu}, oldsymbol{\Sigma}) ext{ where } oldsymbol{\mu} = \left(egin{array}{c} \mu_A \ \mu_B \end{array}
ight)$$

The matrix Σ represents the variance component matrix between response variables at a given time point j.

$$oldsymbol{\Sigma} = \left(egin{array}{cc} \sigma_A^2 & \sigma_{AB} \ \sigma_{AB} & \sigma_B^2 \end{array}
ight)$$

 σ_A^2 is the variance of variable A, σ_B^2 is the variance of variable B and σ_{AB} is the covariance of the two variable. It is assumed that Σ does not depend on a particular time point, and is the same over all time points.

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