

### **0.0.1 What is Influence**

Broadly defined, influence is understood as the ability of a single or multiple data points, through their presence or absence in the data, to alter important aspects of the analysis, yield qualitatively different inferences, or violate assumptions of the statistical model. The goal of influence analysis is not primarily to mark data points for deletion so that a better model fit can be achieved for the reduced data, although this might be a result of influence analysis (Schabenberger,20XX).

## **0.1 Introduction**

In classical linear models model diagnostics have been become a required part of any statistical analysis, and the methods are commonly available in statistical packages and standard textbooks on applied regression. However it has been noted by several papers that model diagnostics do not often accompany LME model analyses. Model diagnostic techniques determine whether or not the distributional assumptions are satisfied, and to assess the influence of unusual observations.

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### **0.1.2 Quantifying Influence**

The basic procedure for quantifying influence is simple as follows:

- Fit the model to the data and obtain estimates of all parameters.

- Remove one or more data points from the analysis and compute updated estimates of model parameters.
- Based on full- and reduced-data estimates, contrast quantities of interest to determine how the absence of the observations changes the analysis.

? introduces powerful tools for local-influence assessment and examining perturbations in the assumptions of a model. In particular the effect of local perturbations of parameters or observations are examined.

### 0.1.3 Model Data Agreement

Schabenberger(20XX) describes the examination of model-data agreement as comprising several elements;

- residual analysis,
- goodness of fit,
- collinearity diagnostics
- influence analysis.

### 0.1.4 Influence Diagnostics: Basic Idea and Statistics

The general idea of quantifying the influence of one or more observations relies on computing parameter estimates based on all data points, removing the cases in question from the data, refitting the model, and computing statistics based on the change between full-data and reduced-data estimation.

### 0.1.5 Overall Influence

An overall influence statistic measures the change in the objective function being minimized. For example, in OLS regression, the residual sums of squares serves that

purpose. In linear mixed models fit by maximum likelihood (ML) or restricted maximum likelihood (REML), an overall influence measure is the likelihood distance [Cook and Weisberg ].

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### **0.1.9 Residual diagnostics**

For classical linear models, residual diagnostics are typically implemented as a plot of the observed residuals and the predicted values. A visual inspection for the presence of trends inform the analyst on the validity of distributional assumptions, and to detect outliers and influential observations.

## Extension of techniques to LME Models

Model diagnostic techniques, well established for classical models, have since been adapted for use with linear mixed effects models. Diagnostic techniques for LME models are inevitably more difficult to implement, due to the increased complexity.

Beckman, Nachtsheim and Cook (1987) applied the local influence method of Cook (1986) to the analysis of the linear mixed model.

While the concept of influence analysis is straightforward, implementation in mixed models is more complex. Update formulae for fixed effects models are available only when the covariance parameters are assumed to be known.

If the global measure suggests that the points in  $U$  are influential, the nature of that influence should be determined. In particular, the points in  $U$  can affect the following

- the estimates of fixed effects,
- the estimates of the precision of the fixed effects,
- the estimates of the covariance parameters,
- the estimates of the precision of the covariance parameters,
- fitted and predicted values.

## Influence Diagnostics Basic Idea and Statistics

The general idea of quantifying the influence of one or more observations relies on computing parameter estimates based on all data points, removing the cases in question from the data, refitting the model, and computing statistics based on the change between full-data and reduced-data estimation.

Influence statistics can be coarsely grouped by the aspect of estimation that is their primary target:

- overall measures compare changes in objective functions: (restricted) likelihood distance (Cook and Weisberg 1982, Ch. 5.2)
- influence on parameter estimates: Cooks (Cook 1977, 1979), MDFFITS (Belsley, Kuh, and Welsch 1980, p. 32)
- influence on precision of estimates: CovRatio and CovTrace
- influence on fitted and predicted values: PRESS residual, PRESS statistic (Allen 1974), DFFITS (Belsley, Kuh, and Welsch 1980, p. 15)
- outlier properties: internally and externally studentized residuals, leverage

For linear models for uncorrelated data, it is not necessary to refit the model after removing a data point in order to measure the impact of an observation on the model. The change in fixed effect estimates, residuals, residual sums of squares, and the variance-covariance matrix of the fixed effects can be computed based on the fit to the full data alone. By contrast, in mixed models several important complications arise. Data points can affect not only the fixed effects but also the covariance parameter estimates on which the fixed-effects estimates depend.

Furthermore, closed-form expressions for computing the change in important model quantities might not be available. This section provides background material for the various influence diagnostics available with the MIXED procedure. See the section Mixed Models Theory for relevant expressions and definitions. The parameter vector

denotes all unknown parameters in the  $\beta$  and  $\Sigma$  matrix. The observations whose influence is being ascertained are represented by the set  $S$  and referred to simply as "the observations in  $S$ ." The estimate of a parameter vector, such as  $\beta$ , obtained from all observations except those in the set  $S$  is denoted  $\hat{\beta}_{-S}$ . In case of a matrix  $\Sigma$ , the notation  $\Sigma_{-S}$  represents the matrix with the rows in  $S$  removed; these rows are collected in  $\Sigma_S$ . If  $\Sigma$  is symmetric, then notation  $\Sigma_{-S}$  implies removal of rows and columns. The vector  $y_{-S}$  comprises the responses of the data points being removed, and  $\Sigma_{-S}$  is the variance-covariance matrix of the remaining observations. When  $S$  is a single point, lowercase notation emphasizes that single points are removed, such as  $\hat{\beta}_i$ .



## SUMMARY AND CONCLUSIONS

Standard residual and influence diagnostics for linear models can be extended to linear mixed models. The dependence of fixed-effects solutions on the covariance parameter estimates has important ramifications in perturbation analysis. To gauge the full impact of a set of observations on the analysis, covariance parameters need to be updated, which requires refitting of the model.

The experimental INFLUENCE option of the MODEL statement in the MIXED procedure (SAS 9.1) enables you to perform iterative and noniterative influence analysis for individual observations and sets of observations. The conditional (subject-specific) and marginal (population-averaged) formulations in the linear mixed model enable you to consider conditional residuals that use the estimated BLUPs of the random effects, and marginal residuals which are deviations from the overall mean. Residuals using the BLUPs are useful to diagnose whether the random effects components in the model are specified correctly, marginal residuals are useful to diagnose the fixed-effects components. Both types of residuals are available in SAS 9.1 as an experimental option of the MODEL statement in the MIXED procedure. It is important to note that influence analyses are performed under the assumption that the chosen model is correct. Changing the model structure can alter the conclusions. Many other variance models have been fit to the data presented in the repeated measures example. You need to see the conclusions about which model component is affected in light of the model being fit. For example, modeling these data with a random intercept and random slope for each child or an unstructured covariance matrix will affect your conclusions about which children are influential on the analysis and how this influence manifests itself.

### 0.1.10 Summary of Paper

Standard residual and influence diagnostics for linear models can be extended to LME models. The dependence of the fixed effects solutions on the covariance parameters has important ramifications on the perturbation analysis. Calculating the studentized

residuals-And influence statistics whereas each software procedure can calculate both conditional and marginal raw residuals, only SAS Proc Mixed is currently the only program that provide studentized residuals Which are preferred for model diagnostics. The conditional Raw residuals are not well suited to detecting outliers as are the studentized conditional residuals. (schabenbege r)

LME are flexible tools for the analysis of clustered and repeated measurement data. LME extend the capabilities of standard linear models by allowing unbalanced and missing data, as long as the missing data are MAR. Structured covariance matrices for both the random effects  $G$  and the residuals  $R$ . missing at Random.

A conditional residual is the difference between the observed value and the predicted value of a dependent variable- Influence diagnostics are formal techniques that allow the identification observation that heavily influence estimates of parameters. To alleviate the problems with the interpretation of conditional residuals that may have unequal variances, we consider scaling. Residuals obtained in this manner are called studentized residuals.

### **0.1.11 ITERATIVE VS. NONITERATIVE INFLUENCE ANALYSIS**

While the basic idea of influence analysis is straightforward, the implementation in mixed models can be tricky. For example, update formulas for the fixed effects are available only when the covariance parameters are assumed to be known. At most the profiled residual variance can be updated without refitting the model. A measure of total influence requires updates of all model parameters, and the only way that this can be achieved in general is by removing the observations in question and refitting the model. Because this brute-force method involves iterative reestimation of the covariance parameters, it is termed iterative influence analysis. Reliance on closed-form update formulas for the fixed effects without updating the (un-profiled) covariance parameters is termed a noniterative influence analysis. An iterative analysis seems like a costly,

computationally intensive enterprise. If you compute iterative influence diagnostics for all  $n$  observations, then a total of  $n + 1$  mixed models are fit iteratively. This does not imply, of course, that the procedures execution time increases  $n$ -fold. Keep in mind that

- iterative reestimation always starts at the converged full-data estimates. If a data point is not influential, then its removal will have little effect on the objective function and parameter estimates. Within one or two iterations, the process should arrive at the reduced-data estimates.
- if complete reestimation does require many iterations, then this is important information in itself. The likelihood surface has probably changed drastically, and the reduced-data estimates are moving away

from the full-data estimates.