## Chapter 1

## A Simplified LME Framework for Method Comparison

## 1.1 Model Terms for Roy's Techniques

 $\boldsymbol{b}_i$  is a m-dimensional vector comprised of the random effects.

$$\boldsymbol{b}_i = \begin{pmatrix} b_{1i} \\ b_{21} \end{pmatrix} \tag{1.1}$$

V represents the correlation matrix of the replicated measurements on a given method.  $\Sigma$  is the within-subject VC matrix.

 ${\pmb V}$  and  ${\pmb \Sigma}$  are positive definite matrices. The dimensions of  ${\pmb V}$  and  ${\pmb \Sigma}$  are  $3\times 3(=p\times p)$  and  $2\times 2(=k\times k)$ .

It is assumed that V is the same for both methods and  $\Sigma$  is the same for all replications.  $V \otimes \Sigma$  creates a  $6 \times 6 (= kp \times kp)$  matrix.  $\mathbf{R}_i$  is a sub-matrix of this.

## 1.2 Model terms

It is important to note the following characteristics of this model. Let the number of replicate measurements on each item i for both methods be  $n_i$ , hence  $2 \times n_i$  responses. However, it is assumed that

there may be a different number of replicates made for different items. Let the maximum number of replicates be p. An item will have up to 2p measurements, i.e.  $\max(n_i) = 2p$ .

Later on  $X_i$  will be reduced to a  $2 \times 1$  matrix, to allow estimation of terms. This is due to a shortage of rank. The fixed effects vector can be modified accordingly.  $Z_i$  is the  $2n_i \times 2$  model matrix for the random effects for measurement methods on item i.  $b_i$  is the  $2 \times 1$  vector of random-effect coefficients on item i, one for each method.  $\epsilon$  is the  $2n_i \times 1$  vector of residuals for measurements on item i. G is the  $2 \times 2$  covariance matrix for the random effects.  $R_i$  is the  $2n_i \times 2n_i$  covariance matrix for the residuals on item i. The expected value is given as  $E(y_i) = X_i\beta$ . (?) The variance of the response vector is given by  $Var(y_i) = Z_iGZ'_i + R_i$  (?).