DUBLIN INSTITUTE OF TECHNOLOGY KEVIN STREET, DUBLIN 8

B.Sc. in Mathematics (Ordinary)

SAMPLE PAPER

Numerical Methods 2

Full marks for complete answers to **five** questions.

Use at least three significant digits and show all your calculations clearly.

Mathematics Tables, Graph Paper

1 The Lagrange polynomial which interpolates the data (x_i, f_i) , where $f_i = f(x_i)$ for $i = 0, 1, 2 \dots n$, is given by

$$P_n(x) = \sum_{i=0}^n L_{n,i}(x) f_i$$
 where $L_{n,i}(x) = \prod_{\substack{i=0 \ i \neq j}}^n \frac{x - x_i}{x_j - x_i}$.

and the interpolation error is given by the formula

$$f(x) - P_n(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x - x_0) \cdots (x - x_n)$$

Consider the function $f(x) = \sin(x)$.

(a) Construct the Lagrange form of the interpolating polynomial for f passing through the points $(0, \sin(0))$, $(\pi/4, \sin(\pi/4))$ and $(\pi/2, \sin(\pi/2))$.

[8 marks]

(b) Use this polynomial to estimate $\sin(\pi/3)$. What is the error in this approximation?

[4 marks]

- (c) Establish the theoretical error bound for using the polynomial found in part (a) to approximate $\sin(\pi/3)$. How does this error compare with that in part (b)? [8 marks]
- 2 The Newton form of the interpolating polynomial is

$$P(x) = f(x_0) + f[x_0, x_1](x - x_0) + f[x_0, x_1, x_2](x - x_0)(x - x_1) + \cdots + f[x_0, x_1, \dots, x_n](x - x_0)(x - x_1) \cdots (x - x_{n-1})$$

where

$$f[x_0, x_1] = \frac{f(x_1) - f(x_0)}{x_1 - x_0};$$
 $f[x_0, x_1, x_2] = \frac{f[x_1, x_2] - f[x_0, x_1]}{x_2 - x_0}$ etc.

are the divided differences of f(x) with respect to the interpolating points.

Consider the function $f(x) = e^x$.

(a) Construct the Newton interpolating polynomial for f passing through the points $(-1, e^{-1})$, $(0, e^{0})$ and $(1, e^{1})$.

[8 marks]

- (b) Use this polynomial to estimate $e^{0.1}$. What is the error in this approximation? [4 marks]
- (c) Establish the theoretical error bound for using the polynomial found in part (a) to approximate e^{0.1}. How does this error compare with that in part (b)?

 [8 marks]
- 3 (a) Consider the Cholesky factorization of a matrix, $A = LL^T$. What conditions must A and L satisfy? In the case of a 3×3 matrix, derive the equations satisfied by the entries of L and indicate the order in which these should be solved.

[6 marks]

(b) Find the Cholesky factorization for the matrix

$$B = \begin{pmatrix} 6 & -2 & 3 \\ -2 & 8 & 1 \\ 3 & 1 & 7 \end{pmatrix}$$

[6 marks]

(c) Use the result of part (b) to solve the system

$$6x_1 - 2x_2 + 3x_3 = 4$$
$$-2x_1 + 8x_2 + x_3 = -2$$
$$3x_1 + x_2 + 7x_3 = 8.$$

[8 marks]

4 Consider the matrix

$$A = \begin{pmatrix} 16 & 7 & -7 \\ -1 & 2 & 1 \\ 11 & 7 & -5 \end{pmatrix}$$

(a) Sketch the Gerschgorin circles for the matrix A. What information do they give regarding the eigenvalues of A?

[4 marks]

(b) Using exact arithmetic, calculate the matrix $B = (A - 3I)^{-1}$. How are the eigenvalues and eigenvectors of B related to those of A?

[8 marks]

(c) Using 3 iterations of the inverse power method, approximate the eigenvalue of A closest to the number 3, as well as an associated eigenvector. Use $\mathbf{x}^{(0)} = [1, 1, 1]^T$ as your initial approximation.

[8 marks]

5 (a) Using the Euler method and a step size of h=0.25, find an approximate solution for the initial value problem

$$\frac{dx}{dt} = 3t - \frac{x}{t}, \qquad 1 \le t \le 3,$$
$$x(1) = 2.$$

Given that the exact solution is $x(t) = t^2 + \frac{1}{t}$, calculate the approximation error at each step.

[10 marks]

(b) Approximate the solution of the problem in part (b) using the fourth order Runge-Kutta method with a step size of h=0.25. How do the absolute errors in this case compare with those obtained from the Euler's method?

[10 marks]

Hint: The fourth-order Runge-Kutta formula is given by $w_{i+1} = w_i + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)$ where $k_1 = hf(t_i, w_i)$, $k_2 = hf(t_i + \frac{h}{2}, w_i + \frac{k_1}{2})$, $k_3 = hf(t_i + \frac{h}{2}, w_i + \frac{k_2}{2})$, $k_4 = hf(t_i + h, w_i + k_3)$, where w_i is the approximate solution at time $t_i = t_0 + ih$.

6 (a) Determine the weights w_1 , w_2 , w_3 , and the quadrature points x_1 , x_2 , x_3 for the three-point Gaussian quadrature rule

$$\int_{-1}^{1} f(x) dx \approx w_1 f(x_1) + w_2 f(x_2) + w_3 f(x_3)$$

knowing that this approximation formula has degree of precision equal to 5.

[12 marks]

(b) Use the three-point Gaussian quadrature rule to approximate the value of the integral

$$\int_{-1}^{1} \frac{1}{1+x^2} \, dx.$$

What is the absolute error in this approximation?

[8 marks]

7 The composite trapezoidal rule for approximating the value of the integral $I(f) = \int_a^b f(x) dx$ is given by

$$T_h(f) = \frac{h}{2} \left[f(a) + 2 \sum_{i=1}^{n-1} f(x_i) + f(b) \right] - \frac{(b-a)h^2}{12} f''(\bar{\xi})$$

where $a < \bar{\xi} < b$, h = (b - a)/n and $x_i = a + ih$ for all $i = 0, \dots n$.

(a) Consider the integral

$$I(f) = \int_0^{\pi} \sin(x) \, dx$$

Compute a sequence of approximations $T_h(f)$ which shows clearly the convergence to I(f) and the rate of convergence corresponding to this method.

[12 marks]

(b) Determine the number of intervals needed in the composite trapezoidal rule such that, when approximating the value of the integral in part (b) the error is less than 10⁻⁴. (Do not attempt to determine this approximation.)

[8 marks]

8 (a) Define the Chebyshev polynomials, $T_n(x)$, and prove the recurrence formula

$$T_{n+1}(x) + T_{n-1}(x) = 2xT_n(x),$$

for $n \ge 0$ and $-1 \le x \le 1$. (Hint: Use the substitution $\theta = \cos^{-1}(x)$.)

[5 marks]

(b) Using the definition or the recurrence formula in part (a), calculate the polynomials $T_0(x)$, $T_1(x)$, $T_2(x)$, $T_3(x)$ and $T_4(x)$.

[5 marks]

(c) Starting with the fourth-order Maclaurin polynomial and using the modified Chebyshev polynomials $\widetilde{T}_n(x) = T_n(x)/2^{n-1}$, find the polynomial of least degree which best approximates the function $f(x) = e^x$ on [-1,1], while keeping the error less than 0.05.

[10 marks]