

# Advanced Graph Algorithms

Conf. dr. ing. Guillaume Ducoffe

`guillaume.ducoffe@fmi.unibuc.ro`

## Sets in Graphs

- The families of all modules in a graph  $G$  admits a representation as a tree with  $\mathcal{O}(n)$  nodes.
- Since there are  $2^n$  possible vertex subsets, there are  $2^{2^n}$  possible families of sets on a graph  $G$ . In particular, not all such families can be encoded using only  $\mathcal{O}(n)$  bits (nor even  $\mathcal{O}(n^c)$  bits, for some  $c > 1$ ).
- Objective: identify the families of sets which admit an efficient (tree) encoding. Deduce from the latter new graph decompositions.

## Partitive families

A family  $\mathcal{F}$  of subsets of  $V$  is called **partitive** if:

- $\emptyset, V \in \mathcal{F}$ ;
- for all  $v \in V$ ,  $\{v\} \in \mathcal{F}$ ;
- for all  $X, Y \in \mathcal{F}$  such that  $X, Y$  overlap:
  - $X \cap Y \in \mathcal{F}$ ;
  - $X \cup Y \in \mathcal{F}$ ;
  - $X \setminus Y \in \mathcal{F}$ ;
  - $Y \setminus X \in \mathcal{F}$ ;
  - $X \Delta Y \in \mathcal{F}$ .

Reminder: Modules form a partitive family.

## Rooted tree-like families

A family  $\mathcal{F}$  of subsets of  $V$  is called **rooted tree-like** if:

- $\emptyset, V \in \mathcal{F}$ ;
- for all  $v \in V$ ,  $\{v\} \in \mathcal{F}$ ;
- for all  $X, Y \in \mathcal{F}$ ,  $X$  and  $Y$  do not overlap (i.e., they are disjoint or comparable for inclusion).

Rooted tree-like families are partitive, but the converse is false in general.

**Proposition:** every rooted tree-like family has an inclusion tree, where the nodes represent sets of  $\mathcal{F}$ . In particular,  $V$  is the root, the leaves are  $\{v\}$  for every  $v \in V$ , and for every  $X \neq V$ , its father is the smallest  $Y$  such that  $X \subset Y$ .

# Strong members

## Definition

A strong member  $X$  of a partitive family  $\mathcal{F}$  is a set which does not overlap any other set  $Y \in \mathcal{F}$ .

Remark: the sets  $\emptyset$ ,  $V$  and  $\{v\}$ ,  $v \in V$  are strong.

The notion of strong members generalises that of strong modules.

**Proposition:** the family of strong members of  $\mathcal{F}$  is rooted tree-like (and so, it admits an inclusion tree).

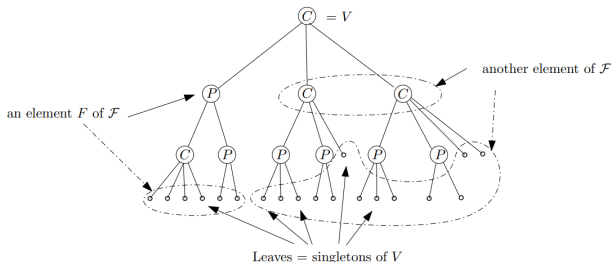
# Decomposition theorem

## Theorem

*For every partitive family  $\mathcal{F}$ , the nodes in the inclusion tree  $T$  of its strong members can be labelled either complete or prime, in such a way that:*

- The union of any children of a complete node must be in  $\mathcal{F}$ .*
- Every not strong member of  $\mathcal{F}$  is the union of some children of a complete node.*

Consequence: the modular decomposition tree can be generalized to any partitive family  $\mathcal{F}$ . It is sometimes called the representative tree of  $\mathcal{F}$ .



# Computation of the representative tree

## Theorem

*For every rooted tree-like family  $\mathcal{F}$ , its inclusion tree can be computed in  $\mathcal{O}(\sum_{X \in \mathcal{F}} |X|) =_{\text{def}} \mathcal{O}(\|\mathcal{F}\|)$  time.*

- 1) We compute  $|X|$  for every  $X \in \mathcal{F}$ .
- 2) We sort the sets of  $\mathcal{F}$  by nondecreasing size. Using counting sort, it can be done in  $\mathcal{O}(|V| + |\mathcal{F}|)$  time.
- 3) For every  $v \in V$ , we compute the ordered family  $\mathcal{F}_v$  of all sets that contain  $v$ , ordered by decreasing size. Then, for every  $X \in \mathcal{F}_v$  such that  $X \neq V$ , its father in the inclusion tree must be the set  $Y \in \mathcal{F}_v$  that comes immediately before  $X$ .

## Corollary

*For every partitive family  $\mathcal{F}$ , its representative tree can be computed in  $\mathcal{O}(\|\mathcal{F}\|^2)$  time.*

# Orthogonal family

**Notation:**  $X \perp Y$  if  $X, Y$  do not overlap.

## Definition

For any family  $\mathcal{F}$ , we define  $\mathcal{F}^\perp = \{Y \mid \forall X \in \mathcal{F}, X \perp Y\}$ .

Remark: If  $\mathcal{F}$  is partitive, then we always have  $\mathcal{F} \cap \mathcal{F}^\perp \neq \emptyset$ , because of the strong members of  $\mathcal{F}$ .

## Theorem

*For every  $\mathcal{F}$  (not necessarily partitive),  $\mathcal{F}^\perp$  is partitive.*

*Furthermore, if  $\mathcal{F}$  is also partitive, then  $(\mathcal{F}^\perp)^\perp = \mathcal{F}$ . The representation trees of  $\mathcal{F}$  and  $\mathcal{F}^\perp$  are the same, up to switching the complete and prime labels at every node.*



## Strong members of $\mathcal{F}^\perp$

- The overlap graph of  $\mathcal{F}$  is the graph with vertex  $\mathcal{S}$  and an edge  $XY$  for every overlapping sets  $X$  and  $Y$ .
- An **overlap component** is a connected component of the overlap graph.
- A **block** is a set of vertices which are exactly in the same sets  $X$  of some overlap component.

### Theorem (McConnell, 2004)

*The strong members of  $\mathcal{F}^\perp$  are exactly:*

- $V$  and  $\{v\}$  for all  $v \in V$ ;
- $\bigcup \mathcal{C}$  for every overlap component  $\mathcal{C}$ ;
- The blocks in  $\bigcup \mathcal{C}$  for every overlap component  $\mathcal{C}$ .

## Computation of overlap components

- The overlap graph may have  $\mathcal{O}(|\mathcal{F}|^2)$  edges. Nevertheless, we can compute a graph on  $\mathcal{F}$  with much fewer edges and the same connected components!
- In what follows, let  $\mathcal{F} = (X_1, X_2, \dots, X_k)$  be totally ordered so that  $|X_1| \leq |X_2| \leq \dots \leq |X_k|$ .

### Definition

For every  $i$ , let  $MAX(X_i) = X_j$  be such that:

- $j < i$ ;
- $X_i, X_j$  overlap;
- for all  $t < j$ ,  $X_i \perp X_t$ .

**Proposition:** For every  $Y$  such that  $Y \cap X \neq \emptyset$  and  $|X| \leq |Y| \leq MAX(X)$ ,  $Y$  must overlap either  $X$  or  $MAX(X)$ .

## Computation of $MAX(X)$

- 1) We initialize a **partition refinement** data structure, with one group equal to  $V$ .
- 2) (**new**) all groups in the partition, past and present, are nodes of some rooted tree  $T$ . The root of the tree corresponds to  $V$ , the initial group. The leaves represent groups of the current partition.
- 3) We consider each set  $X_j$ ,  $j = k \dots 1$  sequentially. We refine according to  $X_j$ . For every group  $V_r$  in the data structure, if  $V_r$  and  $X_j$  overlap, then we create new nodes  $V_r \cap X_j$  and  $V_r \setminus X_j$  as children of  $V_r$ . **We label the edges between  $V_r$  and its children by  $X_j$**

## Computation of $MAX(X)$

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**Proposition:**  $MAX(X_j)$  exists if and only if, before we consider set  $X_j$ , not all the elements in  $X_j$  are contained in the same group of the partition.

→ If we compute the LCA of all groups that intersect  $X_j$ , then  $MAX(X_j)$  must label the edges toward its two children.

## Definition of an auxiliary graph

- 1) For every  $v \in V$ , let  $\mathcal{F}_v = (X_1^v, X_2^v, \dots, X_q^v)$  be the family of all sets in  $\mathcal{F}$  containing  $v$  (ordered by nondecreasing size).
- 2) Compute by dynamic programming  $m_i^v = \max\{|MAX(X_j^v)| \mid 1 \leq j \leq i\}$ .
- 3) If  $|X_{i+1}^v| \leq m_i^v$ , then add an edge  $X_i^v X_{i+1}^v$ .

**Proposition:** the connected components of the resulting graph are exactly the overlap components.

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**Proposition:** the connected components of the resulting graph are exactly the overlap components.

Theorem (Dahlaus, 2000)

*For every  $\mathcal{F}$ , the overlap components can be computed in  $\mathcal{O}(\|\mathcal{F}\|)$  time.*

## Optimal computation of the representative tree

**Proposition:** Being given an overlap component of  $\mathcal{C}$ , we can compute all its blocks in  $\mathcal{O}(\|\mathcal{C}\|)$  time.

Proof: we compute twins in the incidence graph, with respective partite sets  $\mathcal{C}$  and  $\bigcup \mathcal{C}$ .

Consequence: By McConnell's theorem, all strong elements of  $\mathcal{F}^\perp$  can be computed in  $\mathcal{O}(\|\mathcal{F}\|)$  time.

Reminder: the inclusion tree of a rooted tree-like family can be computed in linear time.

### Theorem

*We can compute the representative tree of  $\mathcal{F}^\perp$  in  $\mathcal{O}(\|\mathcal{F}\|)$  time.*

## Weakly partitive families

A family  $\mathcal{F}$  of subsets of  $V$  is called **weakly partitive** if:

- $\emptyset, V \in \mathcal{F}$ ;
- for all  $v \in V$ ,  $\{v\} \in \mathcal{F}$ ;
- for all  $X, Y \in \mathcal{F}$  such that  $X, Y$  overlap:
  - $X \cap Y \in \mathcal{F}$ ;
  - $X \cup Y \in \mathcal{F}$ ;
  - $X \setminus Y \in \mathcal{F}$ ;
  - $Y \setminus X \in \mathcal{F}$ ;
  - ~~$X \Delta Y \in \mathcal{F}$ .~~

Remark: partitive = weakly partitive + closed under symmetric difference



# Decomposition theorem

## Theorem (Chein et al.)

*If  $\mathcal{F}$  is weakly partitive, then the nodes in the inclusion tree  $T$  of its strong members can be labelled either complete, prime or linear, so that:*

- *Any union of children of a complete node is in  $\mathcal{F}$ ;*
- *Any union of consecutive children of a linear node is also in  $\mathcal{F}$ ;*
- *Every non strong member of  $\mathcal{F}$  can be represented as such a union of (consecutive) children.*

A representative tree may still exist under fewer properties (e.g., union-difference), but its number of nodes becomes  $\mathcal{O}(n^2)$ .

## From sets to bipartitions

- The theory goes on for the families of **bipartitions**  $(X, V \setminus X)$  on  $V$ .
- Two bipartitions  $(X, V \setminus X)$  and  $(Y, V \setminus Y)$  overlap if the four subsets  $X \cap Y, X \setminus Y, Y \setminus X$  and  $V \setminus (X \cup Y)$  are nonempty.

Remark: this is a stronger condition than just having  $X, Y$  overlapping.

- Let  $\mathcal{F}$  be a family of bipartitions. A **bipartition tree** is a tree  $T$  whose leaves are labelled by  $V$  and such that, for every  $(X, V \setminus X) \in \mathcal{F}$ , there is an edge  $e \in E(T)$  such that the leaf-sets in the two components of  $T - e$  are exactly  $X, V \setminus X$ . Conversely, every edge of  $T$  can be associated to some bipartition of  $\mathcal{F}$ .

→ equivalent of the inclusion tree.

# Unrooted tree-like families

## Definition

A family  $\mathcal{F}$  of bipartitions on  $V$  is called unrooted tree-like if the following conditions hold:

- $(\emptyset, V) \notin \mathcal{F}$ ;
- for all  $v \in V$ ,  $(\{v\}, V \setminus \{v\}) \in \mathcal{F}$ ;
- Two bipartitions of  $\mathcal{F}$  do not overlap.

**Proposition:** every unrooted tree-like family admits a bipartition tree.

# Bipartitive families

## Definition

A family  $\mathcal{F}$  of bipartitions on  $V$  is called bipartitive if the following conditions hold:

- $(\emptyset, V) \notin \mathcal{F}$ ;
- for all  $v \in V$ ,  $(\{v\}, V \setminus \{v\}) \in \mathcal{F}$ ;
- for all overlapping  $(X, V \setminus X), (Y, V \setminus Y) \in \mathcal{F}$ :
  - $(X \cap Y, V \setminus (X \cap Y)) \in \mathcal{F}$ ;
  - $(X \cup Y, V \setminus (X \cup Y)) \in \mathcal{F}$ ;
  - $(X \setminus Y, (V \setminus X) \cup Y) \in \mathcal{F}$ ;
  - $(Y \setminus X, (V \setminus Y) \cup X) \in \mathcal{F}$ ;
  - $(X \Delta Y, V \setminus (X \Delta Y)) \in \mathcal{F}$ .

The strong members of  $\mathcal{F}$  are unrooted tree-like, and we can label nodes in their bipartition tree either complete or prime, with similar meaning as for partitive families.

# Splits

## Definition

A **split** is a bipartition  $(X, V \setminus X)$  such that the cut  $E(X, V \setminus X)$  induces a complete bipartite subgraph.

Remark: If  $M$  is a module, then  $(M, V \setminus M)$  is a split.



# Split decomposition

Theorem (Cunningham, 1982)

*The family of all splits in a graph is bipartitive.*

The representative bipartition tree of strong splits is called the **split decomposition tree**.

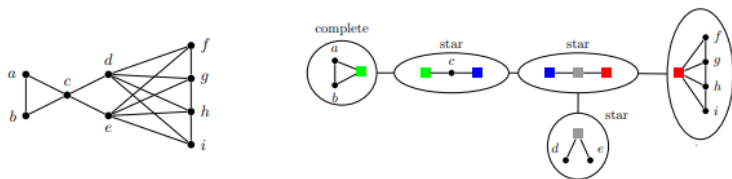


Figure 3: A graph and its split decomposition.

To every node, we associate a *split component*: where we add new nodes to represent incident strong splits. A split component is either a clique, a star, or prime for split decomposition.

## Computation of a split

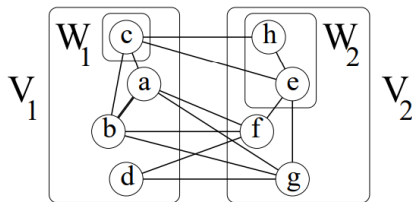
- For an edge  $xy$ , we try to compute a split  $(X, V \setminus X)$  such that  $x \in X, y \notin X$ .
- The edges of the split (if it exists) must have their respective ends in  $N(x), N(y)$ . By removing all edges of  $E \cap (N(x) \times N(y))$ , we obtain connected components  $C_1, \dots, C_q$ . Wlog  $x \in C_1, y \in C_q$ .
- We must have  $C_1 \subseteq X, C_q \cap X = \emptyset$ . In particular, we check whether  $E(C_1, C_q)$  induces a complete bipartite subgraph.
- We construct a graph  $H$  whose vertices are  $c_1, c_2, \dots, c_q$ . For every  $1 \leq i < j \leq q$ , if  $E(C_i, C_j)$  does not include a complete bipartite graph, then  $C_i, C_j$  must be on the same partite set. We add an edge  $c_i c_j$ .
- We are done computing the connected components of  $H$ .

# Bijoins

**Observation:** If  $(X, V \setminus X)$  is a split of  $G$ , then in general it is not a split of its complement  $\overline{G}$ .

## Definition

A **bijoin** is a bipartition  $(X, V \setminus X)$  such that (i)  $N(X) = V \setminus X$ , and (ii) the cut  $E(X, V \setminus X)$  induces the disjoint union of two complete bipartite subgraphs.



**Proposition:**  $(X, V \setminus X)$  is a bijoin of  $G$  if and only if it is a bijoin of  $\overline{G}$ .



# Bijoin decomposition

## Theorem (de Montgolfier & Rao)

*The family of all bijoins of a graph is bipartitive.*

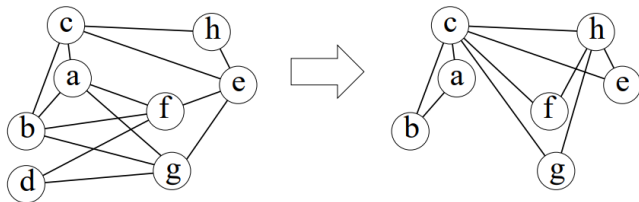
The representative bipartition tree of strong bijoins is called the **bijoin decomposition tree**.

# Seidel switch

## Definition

The Seidel switch of a graph  $G$  with respect to  $W$  is the graph obtained from  $G$  by removing all edges from the cut  $E(W, V \setminus W)$ , and replacing them with  $\overline{E}(W, V \setminus W)$  (cut in the complement  $\overline{G}$ ).

The Seidel reduction  $\tilde{G}_v$  is the graph obtained from the Seidel switch with respect to  $N(v)$  by removing vertex  $v$ .



# Fundamental bijoin lemma

## Lemma

*Let  $(X, V \setminus X)$  be an arbitrary bipartition and let  $x \in X$ . Then,  $(X, V \setminus X)$  is a bijoin of  $G$  if and only if  $V \setminus X$  is a module of  $\tilde{G}_x$ .*

Apply the lemma to some  $x$  such that  $d(x) \leq 2m/n$ .

## Theorem

*The bijoin decomposition of any graph can be computed in  $\mathcal{O}(n + m)$  time.*

The same is true for split decomposition, but the algorithm is much more intricate:

## Theorem

*The split decomposition tree of any graph can be computed in  $\mathcal{O}(n + m)$  time.*

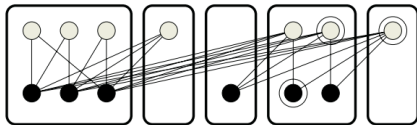
# Bimodules

Observation: modules in a bipartite graphs are always twin classes. . .

## Definition

Let  $B = (V_0 \cup V_1, E)$  be a bipartite graph. A bimodule is a pair  $(M_0, M_1)$  such that the following holds for  $i \in \{0, 1\}$ :

- $M_i \subseteq V_i$ ;
- for every  $x_i, y_i \in M_i$ ,  $N(x_i) \setminus M_{1-i} = N(y_i) \setminus M_{1-i}$ .



There are canonical bimodules and degenerate ones. The canonical bimodules form a weakly bipartitive family.  $\implies$  **bimodular decomposition**

## 2-Modules

### Definition

$M$  is a 2-module of  $G$  if there exists a bipartition  $(M_0, M_1)$  of  $M$  such that, for  $i \in \{0, 1\}$ ,  $M_i$  is a module of  $G \setminus M_{i-1}$ .

Special cases of 2-modules:

- modules
- splits
- bijoins
- bimodules

Unfortunately, there is no more a nice tree-like structure for representing all 2-modules in a graph.

# Questions

