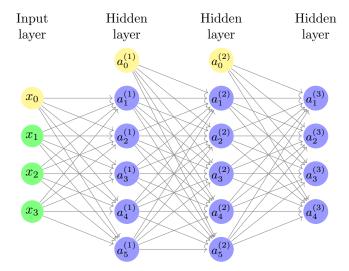
# Week 9

July 17, 2021

# Types of classification problems with NNs

- Training set is  $(x^1, y^1), (x^2, y^2), ..., (x^n, y^n)$ .
- L = number of layers in the network.
- $s_l$  = number of units (not counting bias unit) in layer l.



So here we have:

- L = 4.
- $s_1 = 3$ .
- $s_2 = 5$ .
- $s_3 = 5$ .
- $s_4 = 4$ .

# Binary classification

- 1 output (0 or 1).
- So single output node value is going to be a real number.
- k = 1.
- $s_l = 1$

#### Multi-class classification

- k distinct classifications.
- y is a k-dimensional vector of real numbers.
- $s_l = k$

#### Cost function

Logistic regression cost function is as follows:

$$J(\theta) = -\frac{1}{m} \left[ \sum_{i=1}^{m} y^{(i)} log h_{\theta}(x^{(i)}) + (1 - y^{(i)}) log (1 - h_{\theta}(x^{(i)})) \right] + \frac{\lambda}{2m} \sum_{j=1}^{m} \theta_{j}^{2}$$

For neural networks our cost function is a generalization of this equation above, so instead of one output we generate k outputs:

$$J(\Theta) = -\frac{1}{m} \left[ \sum_{i=1}^{m} \sum_{k=1}^{K} y_k^{(i)} log(h_{\Theta}(x^{(i)}))_k + (1 - y_k^{(i)}) log(1 - (h_{\Theta}(x^{(i)}))_k) \right] + \frac{\lambda}{2m} \sum_{l=1}^{K-1} \sum_{i=1}^{s_l} \sum_{j=1}^{s_l+1} (\Theta_{ji}^{(l)})^2$$

- Our cost function now outputs a k dimensional vector.
- Costfunction  $J(\Theta)$  is -1/m times a sum of a similar term to which we had for logic regression.
- But now this is also a sum from k = 1 through to K (K is number of output nodes).
- Summation is a sum over the k output units i.e. for each of the possible classes.
- We don't sum over the bias terms (hence starting at 1 for the summation).

#### Partial derivative terms

- $\Theta^{(1)}$  is the matrix of weights which define the function mapping from layer 1 to layer 2.
- Θ<sub>10</sub><sup>(1)</sup> is the real number parameter which you multiply the bias unit (i.e.
  1) with for the bias unit input into the first unit in the second layer.
- $\Theta_{11}^{(1)}$  is the real number parameter which you multiply the first (real) unit with for the first input into the first unit in the second layer.
- $\Theta_{21}^{(1)}$  is the real number parameter which you multiply the first (real) unit with for the first input into the second unit in the second layer.

### Gradient computation

- One training example.
- Imagine we just have a single pair (x,y) entire training set.
- The following is how the forward propagation method works:
- Layer 1:  $a^{(1)} = x$  and  $z^{(2)} = \Theta^{(1)}a^{(1)}$ .
- Layer 2:  $a^{(2)} = g(z^{(2)}) + a_0^{(2)}$  and  $z^{(3)} = \Theta^{(2)}a^{(2)}$ .
- Layer 3:  $a^{(3)} = g(z^{(3)}) + a_0^{(3)}$  and  $z^{(4)} = \Theta^{(3)}a^{(3)}$ .
- Ouptut:  $a^{(4)} = h_{\Theta}(x) = g(z^{(4)}).$

Layer 1 Layer 2 Layer 3 Layer 4  $a_0^{(1)}$   $a_0^{(2)}$   $a_0^{(3)}$   $a_0^{(3)}$   $a_0^{(4)}$   $a_2^{(4)}$   $a_2^{(4)}$   $a_3^{(1)}$   $a_3^{(2)}$   $a_3^{(3)}$   $a_3^{(4)}$   $a_4^{(4)}$   $a_4^{(4)}$   $a_4^{(4)}$ 

# Calculate backpropagation

- $\delta_j$  is Lx1 vector.
- First we compute the LAST element:  $\delta_j^{(L)} = a_j^{(L)} y_j$ .
- Value of each element is based on the value of the next element:

$$\delta_{j}^{(l)} = (\Theta_{j}^{(l)})^{T} \delta_{j}^{(l+1)} \cdot g'(z_{j}^{(l)})$$

 $\bullet$  Finally, use  $\Delta$  to accumulate the partial derivative terms:

$$\Delta_{ij}^{(l)} := \Delta_{ij}^{(l)} + a_j^{(l)} \delta_i^{(l+1)}$$

- l = layer.
- j = node in that layer.
- $\bullet$  i = the error of the affected node in the target layer

$$\frac{\partial}{\partial \Theta_{ij}^{(l)}} J(\Theta) = \begin{cases} \frac{1}{m} \Delta_{ij}^{(l)} + \lambda \Theta_{ij}^{(l)} & \text{if } j \neq 0 \\ \frac{1}{m} \Delta_{ij}^{(l)} & \text{if } j = 0 \end{cases}$$

## Gradient checking

Backpropagation contains a lot of details, and tiny flaws can break it. As a result, employing a numerical approach to verify the gradient can aid in the quick diagnosis of a problem.

- Have a function  $J(\Theta)$ .
- Compute  $\Theta + \epsilon$ .
- Compute  $\Theta \epsilon$ .
- Join them by a straight line.
- Use the slope of that line as an approximation to the derivative.

