

PHYS 225

Fundamentals of Physics: Mechanics

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Lecture 26: Collision

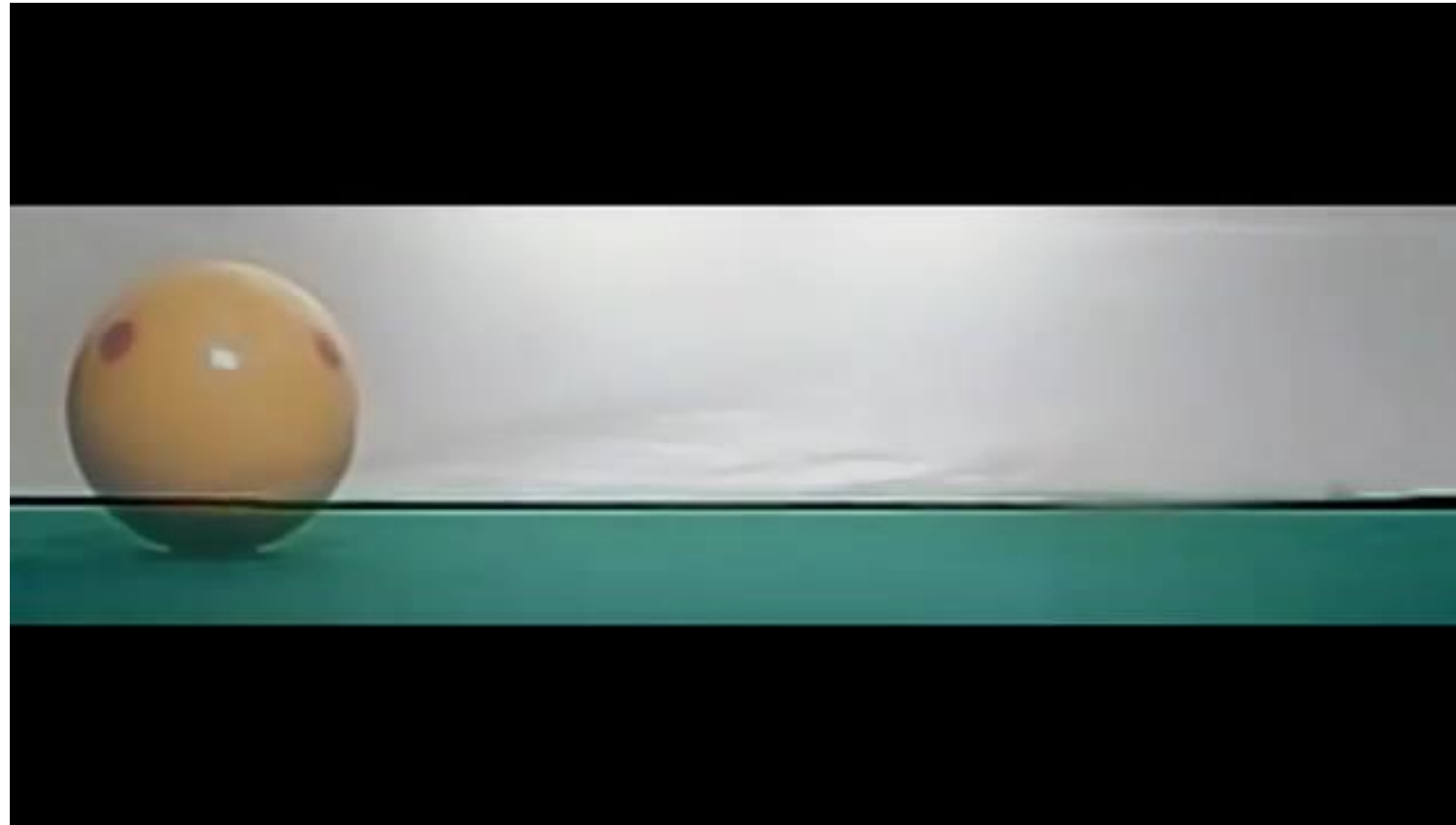
Learning goals for today

- Collision
 - Inelastic collision
 - Elastic collision

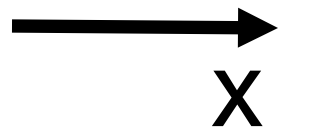
Recap:

- Impulse: $\vec{I} = \int_{t_i}^{t_f} \vec{F} dt \approx \vec{F}_{ave} \Delta t$
- Impulse and change of linear momentum: $\vec{I}_{net} = \Delta \vec{P} = \vec{P}_f - \vec{P}_i$
- Conservation of linear momentum: If $\vec{I}_{net} = 0$, then $\vec{P}_{tot,final} = \vec{P}_{tot,init}$.

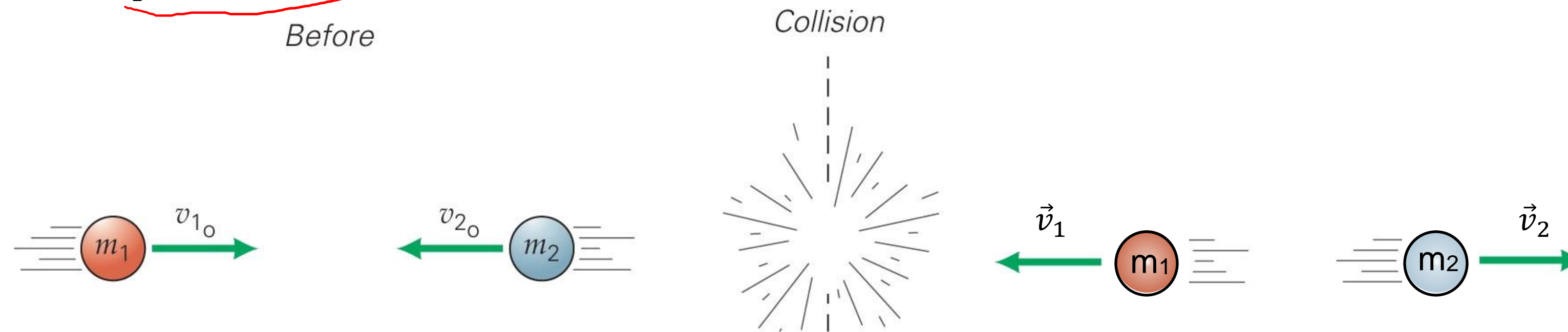
Chapter 9.3: Collision



1. Collisions



- Collision: An event in which two or more bodies exert forces on each other in a relatively **short time**.



$$\Delta t \sim 0$$
$$\vec{I}_{net} \sim 0$$

Since $\Delta t \rightarrow 0$, Therefore, $\vec{I}_{net} = 0$

- Collision happens so quickly that the **total momentum is conserved**:

$$\vec{P}_{tot,f} - \vec{P}_{tot,i} = \vec{I}_{net} \approx 0$$

$$\vec{P}_{f,tot} = \vec{P}_{i,tot}$$

Clicker question 1

Given: $m_A, m_B, \vec{v}_{A0} = 0, \vec{v}_{B0} = -5 \text{ m/s} \hat{i}$

Goal: $\vec{v}_{f,A} = -4 \text{ m/s} \hat{i}$

$\vec{v}_{f,B}$

\xrightarrow{x}

- In the top figure (before part), car A (mass $m_A = 1000 \text{ kg}$) is stopped at a traffic light, and car B (mass $m_B = 1000 \text{ kg}$) is moving with an initial velocity \vec{v}_0 at **5 m/s** to the left. In bottom figure (after part), the rear end of car A is hit by car B. Immediately after the collision, Car A gains a velocity of velocity $\vec{v}_{f,A}$ of **4 m/s** to the left. What is the velocity of Car B immediately after collision?

A 1 m/s, to the left.

B 1 m/s, to the right.

C 0

Step 1: $\vec{P}_{f,tot} = \vec{P}_{i,tot}$

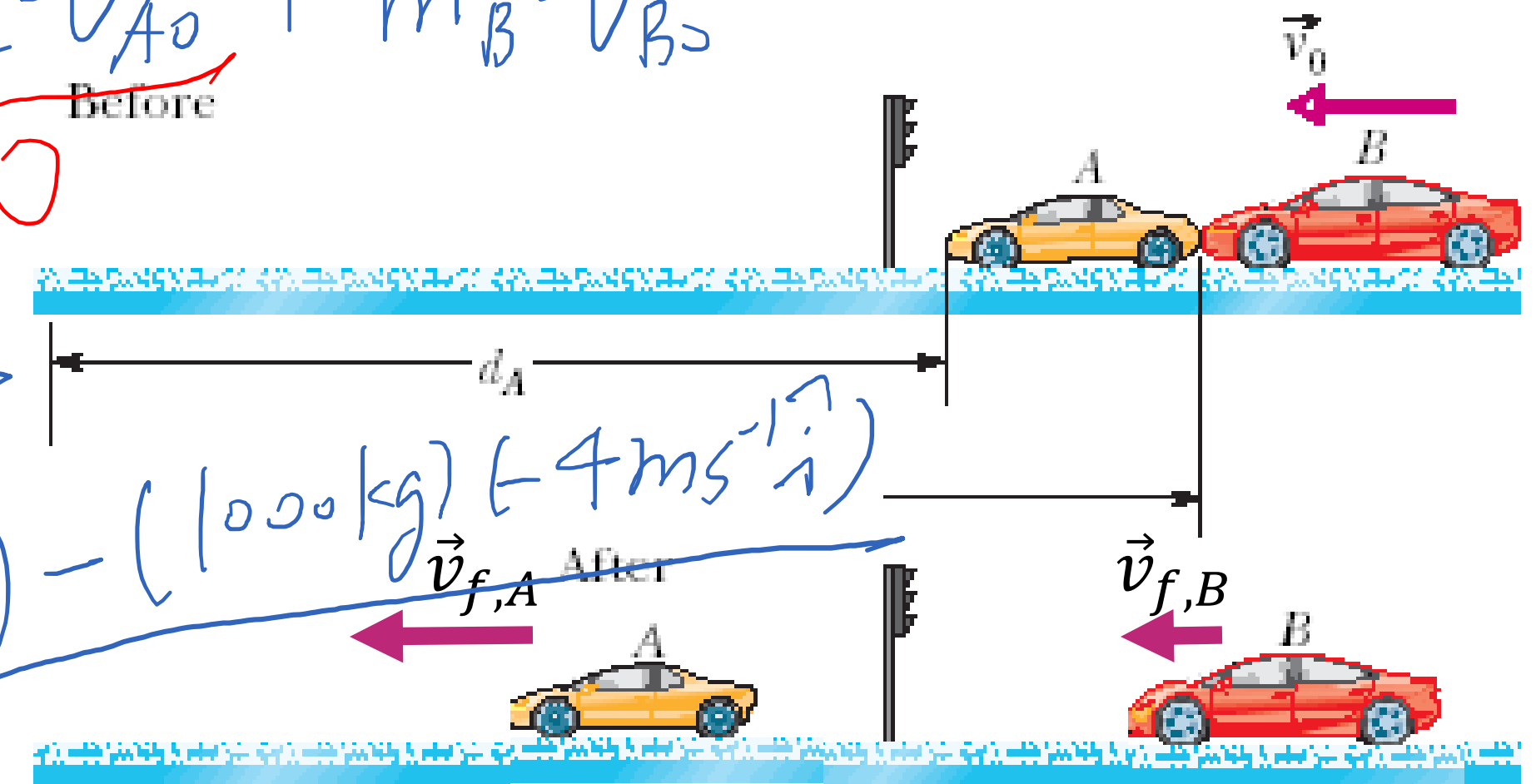
$$m_A \vec{v}_{Af} + m_B \vec{v}_{Bf} = m_A \vec{v}_{A0} + m_B \vec{v}_{B0}$$

Before

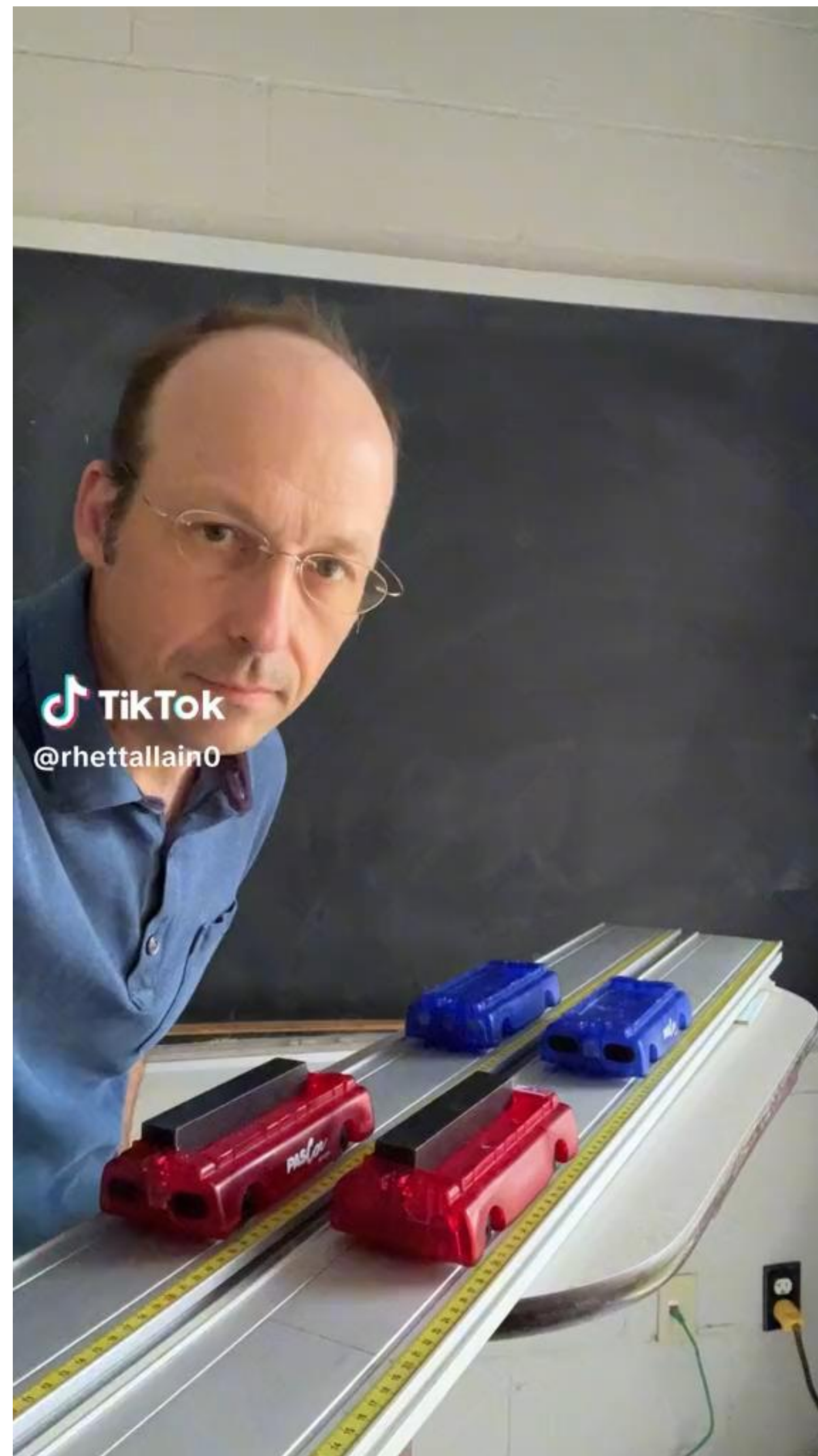
Step 2: $\vec{v}_{Bf} = \frac{m_B \vec{v}_{B0} - m_A \vec{v}_{Af}}{m_B}$

$$= \frac{1000 \text{ kg} (-5 \text{ m/s} \hat{i}) - (1000 \text{ kg}) (-4 \text{ m/s} \hat{i})}{1000 \text{ kg}}$$

$$= -1 \text{ m/s} \hat{i}$$



Demo



<https://www.tiktok.com/@rhettallain0/video/7223476245500038442>

2. Two types of collisions: Elastic and inelastic collision

- 1. Elastic collision

- Linear momentum is conserved:

$$P_{i,tot} = P_{f,tot}$$

- Kinetic energy is conserved:

$$K_{i,tot} = K_{f,tot}$$

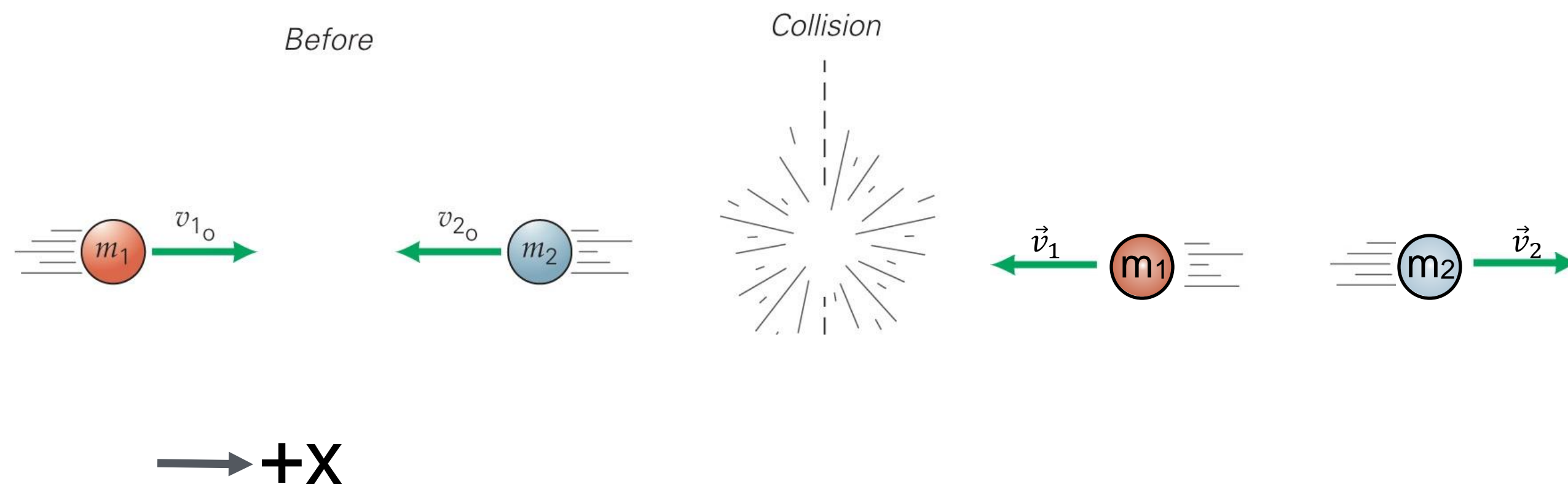
- 2. Inelastic collision

- Linear momentum is conserved:

$$P_{i,tot} = P_{f,tot}$$

- Kinetic energy is **NOT** conserved:

$$K_{i,tot} \neq K_{f,tot}$$



Clicker question 2

Given: $m_A, m_B, \vec{v}_{A0} = 0, \vec{v}_{B0}, \vec{v}_{Af}, \vec{v}_{Bf}$

Goal: $K_{i,tot} \neq K_{f,tot}$

- In the "before" part of the figure, car A (mass $m_A = 1000\text{kg}$) is stopped at a traffic light, and car B (mass $m_B = 1000\text{kg}$) is moving with an initial velocity \vec{v}_0 to the left at **5 m/s**. In the "after" part of the figure, the rear end of car A is hit by car B. Immediately after the collision, Car A moves at a velocity of velocity $\vec{v}_{A,f}$ of **4 m/s** to the left, and Car B moves at a velocity of $\vec{v}_{B,f}$ of **1 m/s** to the left. What type of collision is it?

A

It's an elastic collision.

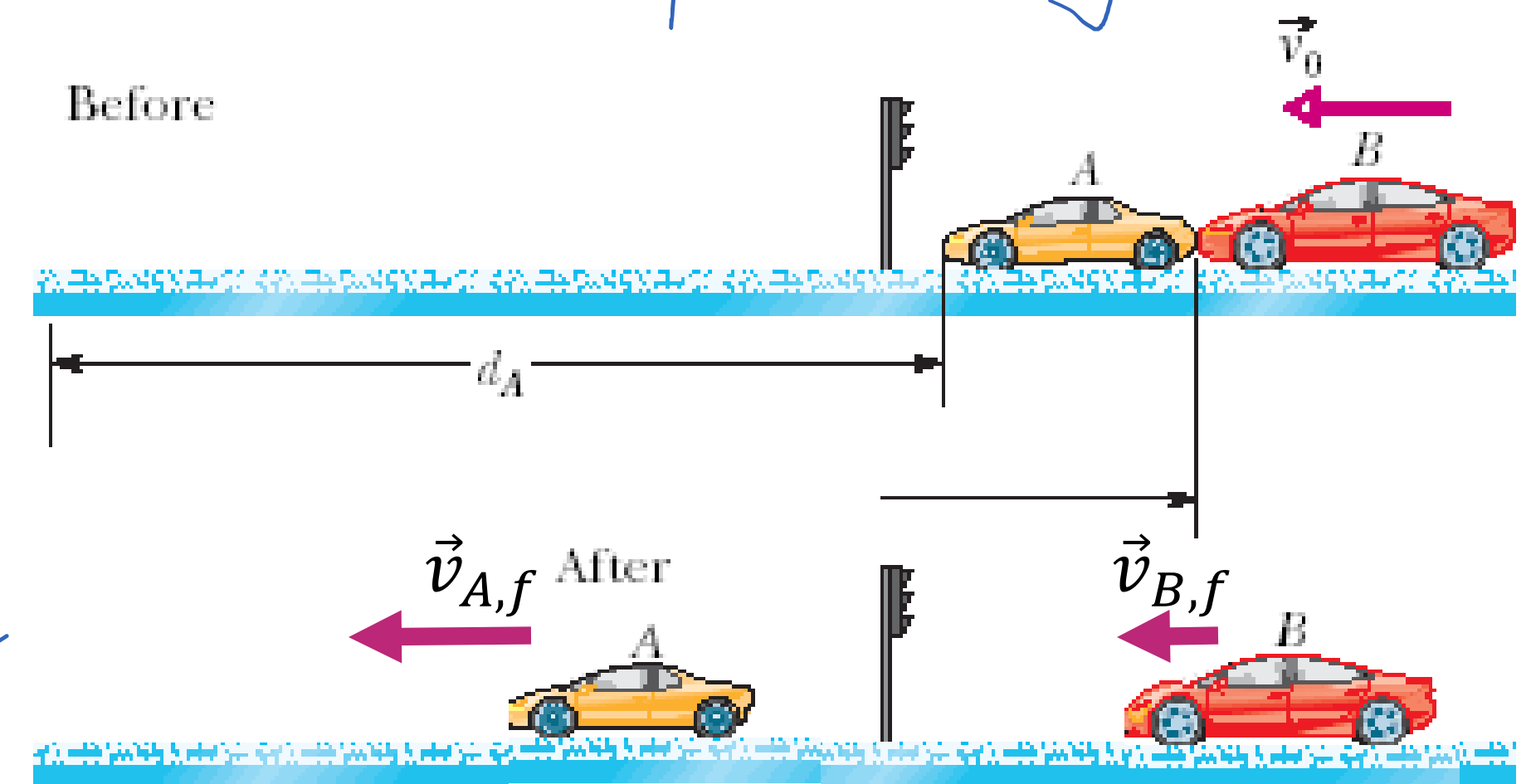
B

It's an inelastic collision.

$$K_{i,tot} = \frac{1}{2} m_A \underbrace{v_{A0}^2}_0 + \frac{1}{2} m_B v_{B0}^2 = \frac{1}{2} \times 1000\text{kg} \times (-5\text{m/s})^2 = 12500\text{J}$$

$$K_{f,tot} = \frac{1}{2} m_A v_{Af}^2 + \frac{1}{2} m_B v_{Bf}^2 = \frac{1}{2} \times 1000\text{kg} (-4\text{m/s})^2 + \frac{1}{2} \times 1000\text{kg} (-1\text{m/s})^2 = 8500\text{J}$$

$$K_{i,tot} \neq K_{f,tot}$$



2.1. Inelastic collision and totally inelastic collision



- Inelastic collision *in general*

- Linear momentum is conserved:

$$\vec{P}_{tot,i} = \vec{P}_{tot,f}$$

- Kinetic energy is NOT conserved

$$\underline{K_{tot,i} \neq K_{tot,f}}$$

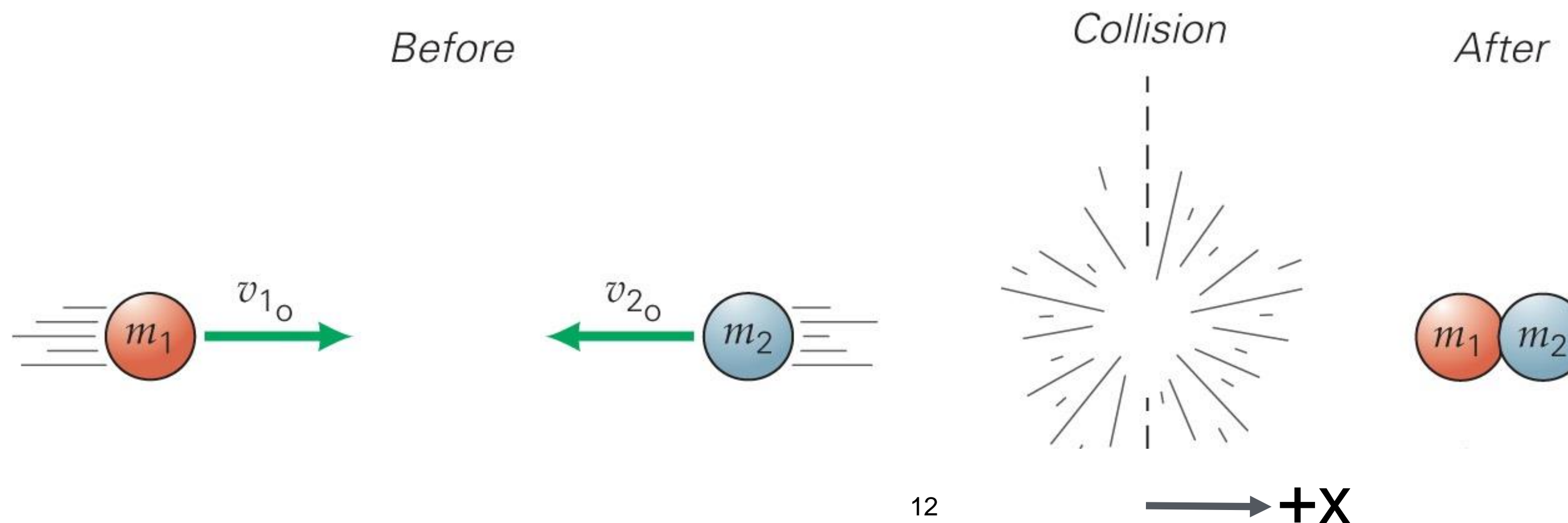
- Totally inelastic collision:

- After the collision, the two objects move at the same velocity:

$$\vec{v}_{1f} = \vec{v}_{2f}$$

obj. 1 *obj. 2*

*Stick together
after
collision*



Clicker question 3



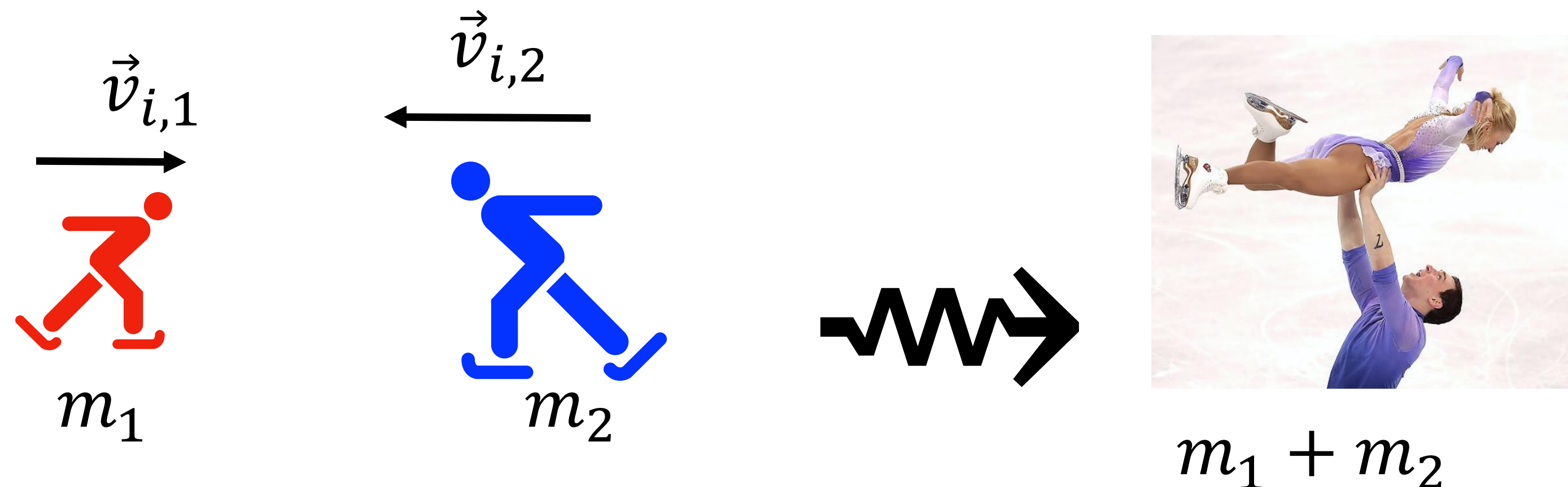
- Skater 1 and Skater 2 are moving towards each other during figure skating. Initially, Skater 1 (mass 50kg) is skating to the right at 2 m/s, and Skater 2 (70 kg) is skating to the left at 5 m/s. After they collide with each other, they skate together at the same velocity. Neglect the net impulse on them, what type of collision is it?

$$\vec{v}_{f1} = \vec{v}_{f2}$$

A Elastic collision

B Totally inelastic collision

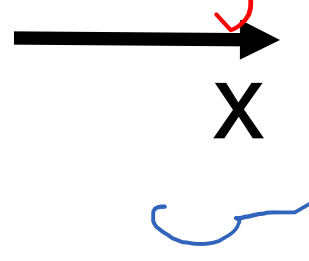
C Undetermined.



Example 1

Given: m_c , \vec{v}_{c0} , m_j , \vec{v}_{j0} , $\vec{v}_{cf} = \vec{v}_{jf} = \vec{v}_f$

Goal: \vec{v}_f



- Two athletes, John and ~~Jane~~ ^{Carley} are moving towards each other during figure skating. Initially, Carley (mass 50kg) is skating to the right at 2 m/s, and John (70 kg) is skating to the left at 5 m/s. After they collide with each other, they skate together at the same velocity. Neglect the net impulse on them, please calculate their common velocity after the collision.

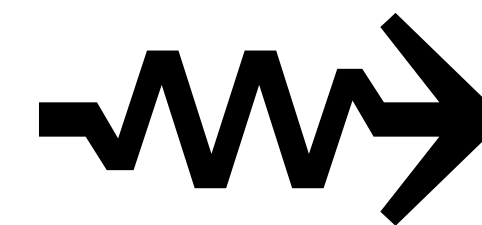
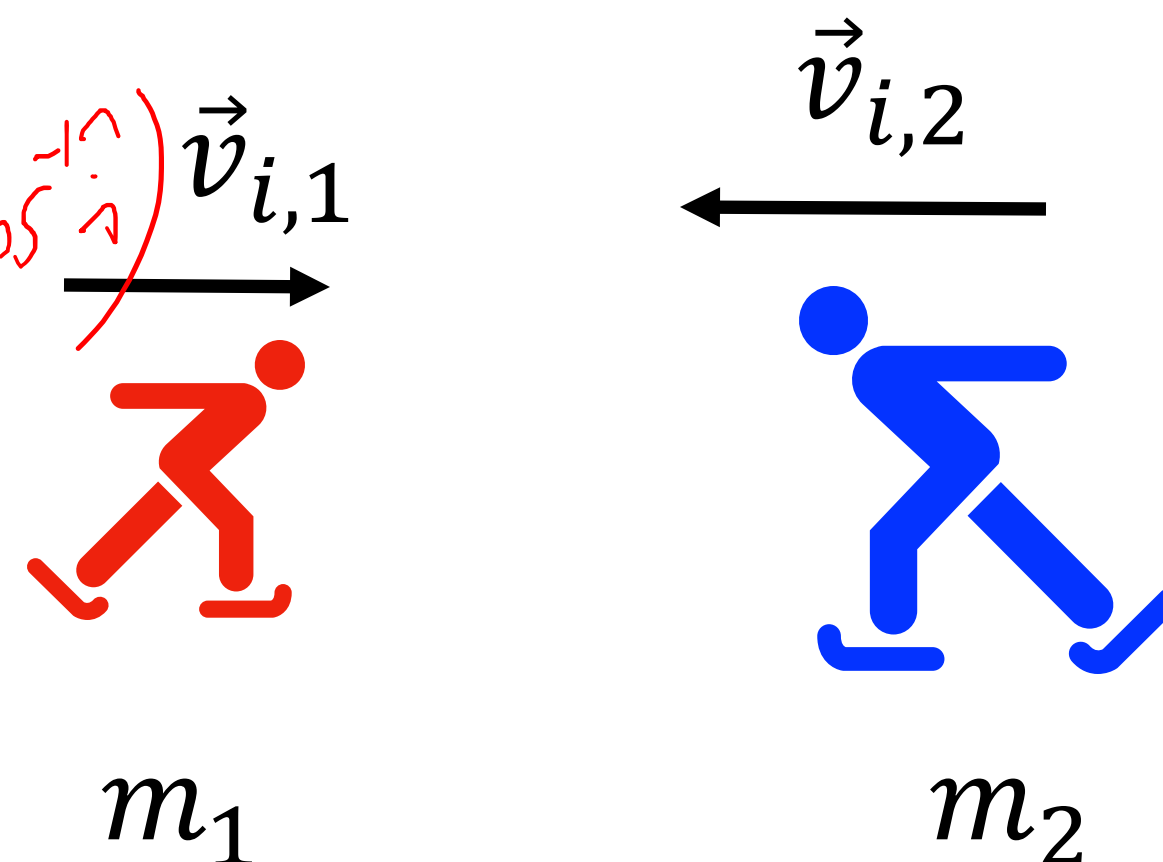
Step 1: $\vec{P}_{i,tot} = \vec{P}_{f,tot} \rightarrow m_c \vec{v}_{c0} + m_j \vec{v}_{j0} = m_c \vec{v}_f + m_j \vec{v}_f$

$$\vec{v}_f = \frac{m_c \vec{v}_{c0} + m_j \vec{v}_{j0}}{m_c + m_j}$$

Step 2:

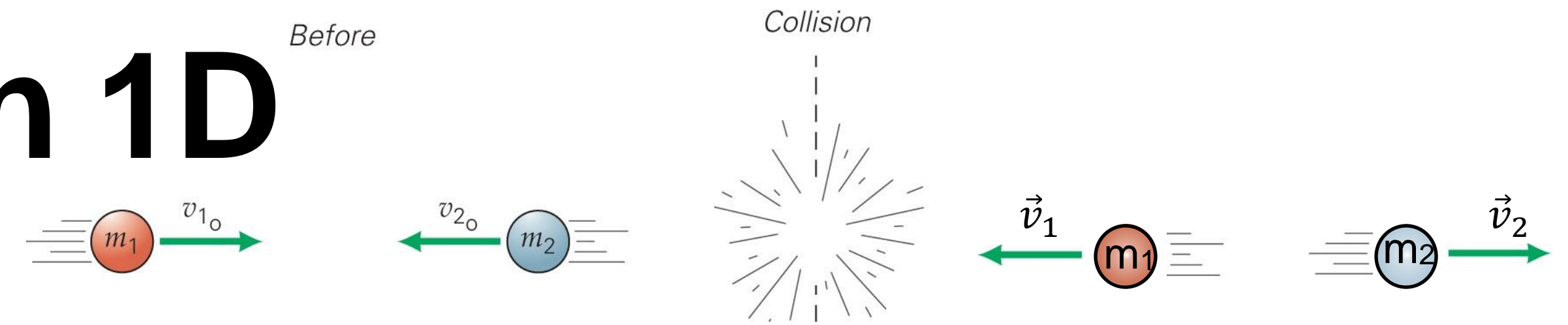
$$\vec{v}_f = \frac{50 \text{ kg} (2 \text{ m s}^{-1} \hat{i}) + 70 \text{ kg} (-5 \text{ m s}^{-1} \hat{i})}{50 \text{ kg} + 70 \text{ kg}}$$

$$\approx -2.08 \text{ m s}^{-1} \hat{i}$$



$m_1 + m_2$

2.2. Elastic collisions in 1D



- Elastic collisions: Both linear momentum and kinetic energy are conserved

- Conservation of momentum

$$\vec{p}_{1,i} + \vec{p}_{2,i} = \vec{p}_{1,f} + \vec{p}_{2,f}$$

- Conservation of kinetic energy

$$\frac{1}{2}m_1v_{1,i}^2 + \frac{1}{2}m_2v_{2,i}^2 = \frac{1}{2}m_1v_{1,f}^2 + \frac{1}{2}m_2v_{2,f}^2$$

$$K_{i,tot} = K_{f,tot}$$

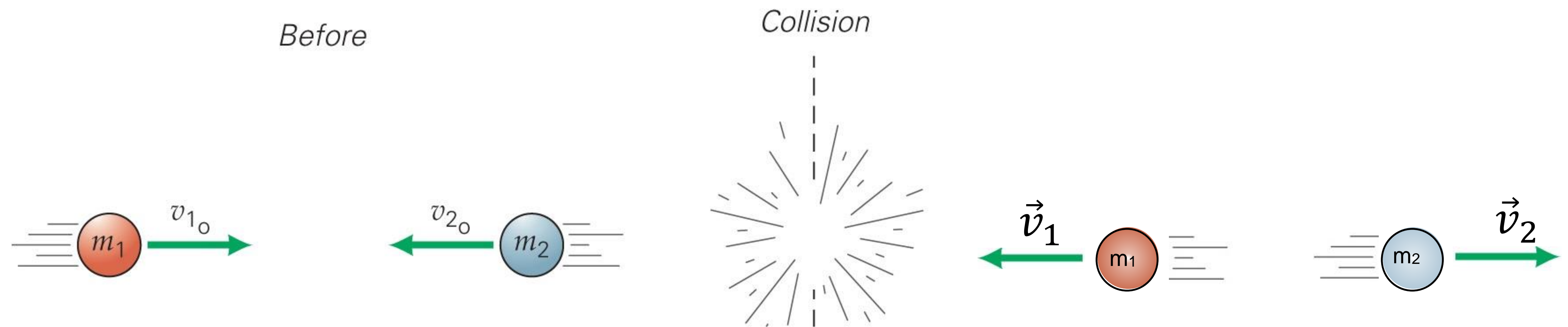
If Given $m_1, m_2, \vec{v}_{1,i}, \vec{v}_{2,i}$, then

$$\begin{cases} \vec{p}_{i,tot} = \vec{p}_{f,tot} \\ K_{i,tot} = K_{f,tot} \end{cases}$$

In 1D
Elastic
collisions

Clicker question 4

A ball of mass m_1 and initial velocity $\vec{v}_{10} = v_{10}\hat{i}$ collides elastically with another ball of mass m_2 and initial velocity $\vec{v}_{20} = v_{20}\hat{i}$. What principles would you use to find the final velocities, \vec{v}_1 and \vec{v}_2 ?

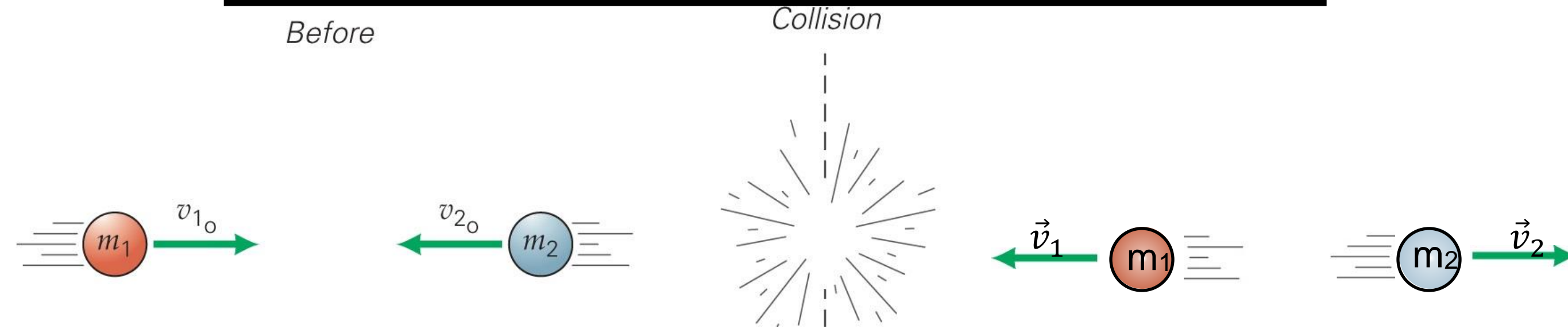


- ☐ A Conservation of momentum
- ☐ B Conservation of kinetic energy
- ☒ C Both

Elastic collisions in 1D: Special conditions

Given: $m_1, m_2, \vec{v}_{10}, \vec{v}_{20}$, elastic collision

Goal: \vec{v}_1, \vec{v}_2 v_1, v_2, v_{10} and v_{20} are vector components.



- 1. Final velocities for 1D elastic collision: In general

$$\begin{cases} \vec{p}_{1,i} + \vec{p}_{2,i} = \vec{p}_{1,f} + \vec{p}_{2,f} \\ \frac{1}{2}m_1v_{1,i}^2 + \frac{1}{2}m_2v_{2,i}^2 = \frac{1}{2}m_1v_{1,f}^2 + \frac{1}{2}m_2v_{2,f}^2 \end{cases}$$

Equal masses, $m_2 = m_1$ $v_{1f} = v_{2i}$ & $v_{2f} = v_{1i}$

Massive m_2 , $m_2 \gg m_1$ $v_{1f} \approx -v_{1i} + 2v_{2i}$ & $v_{2f} \approx v_{2i}$

If Head-on elastic collision, $m_2 \gg m_1$,
 v_{1i} is opposite to v_{2i} lighter obj. is speed up by $2v_{2i}$

Demo

The screenshot shows the PhET Collision Lab simulation interface. At the top, a horizontal track with a scale bar labeled "0.5 m" contains two spheres. Sphere 1 is cyan and labeled "1", moving to the right with a green velocity vector. Sphere 2 is magenta and labeled "2", moving to the left with a blue velocity vector. Below the track, a timer displays "0.00 s". To the right of the timer are playback controls: a grey "Previous" button, a blue "Play" button, a blue "Pause" button, a legend with "Normal" (filled circle) and "Slow" (empty circle) options, and a blue "Reset" button. Below these controls is a checkbox labeled "More Data". At the bottom, a "Mass (kg)" panel shows two sliders. Slider 1 is set to 0.50 kg, and slider 2 is set to 1.50 kg.

0.5 m

0.00 s

Normal
Slow

☐ More Data

Mass (kg)

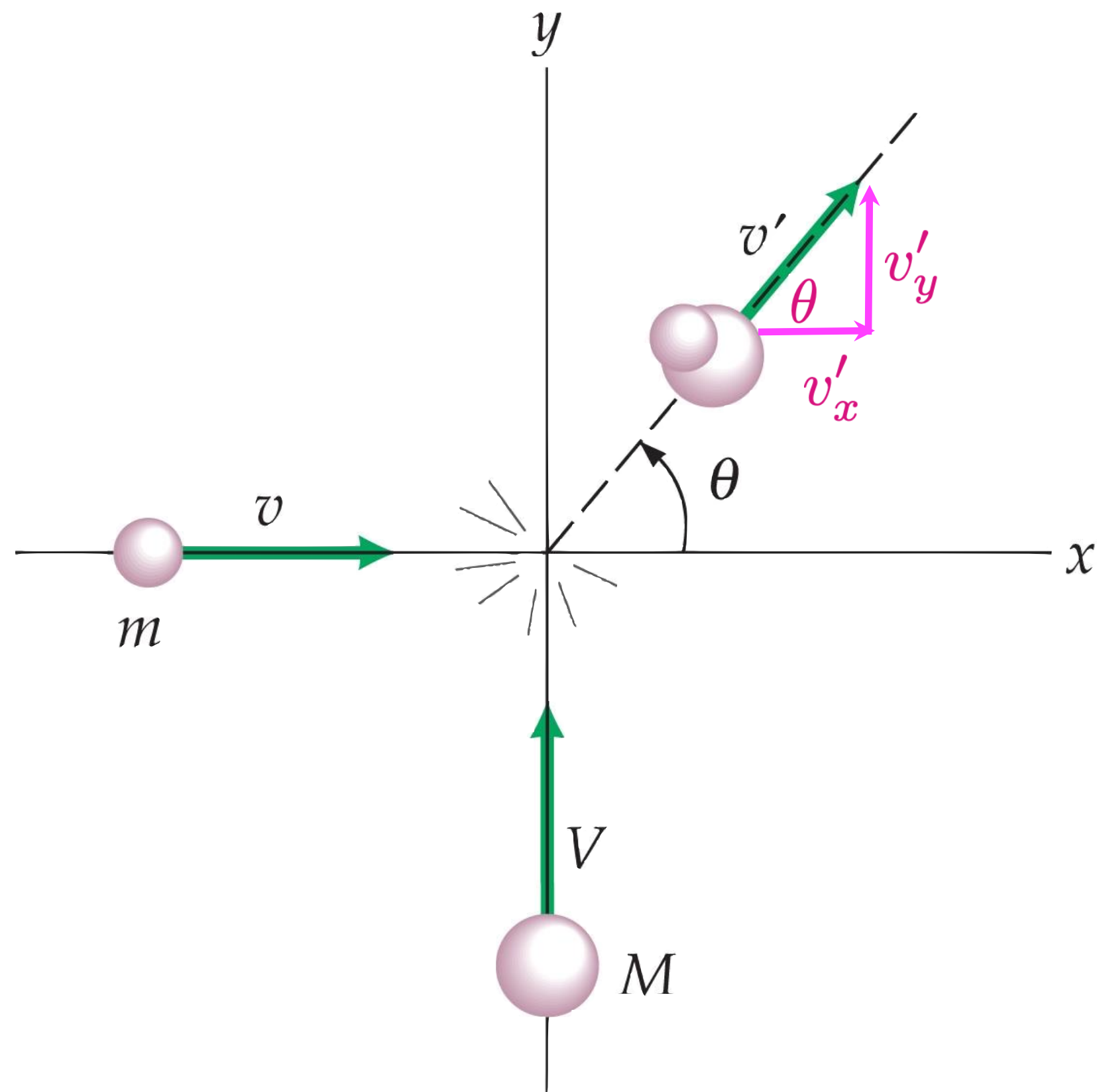
1	0.50
2	1.50

https://phet.colorado.edu/sims/html/collision-lab/latest/collision-lab_all.html

More examples of collision

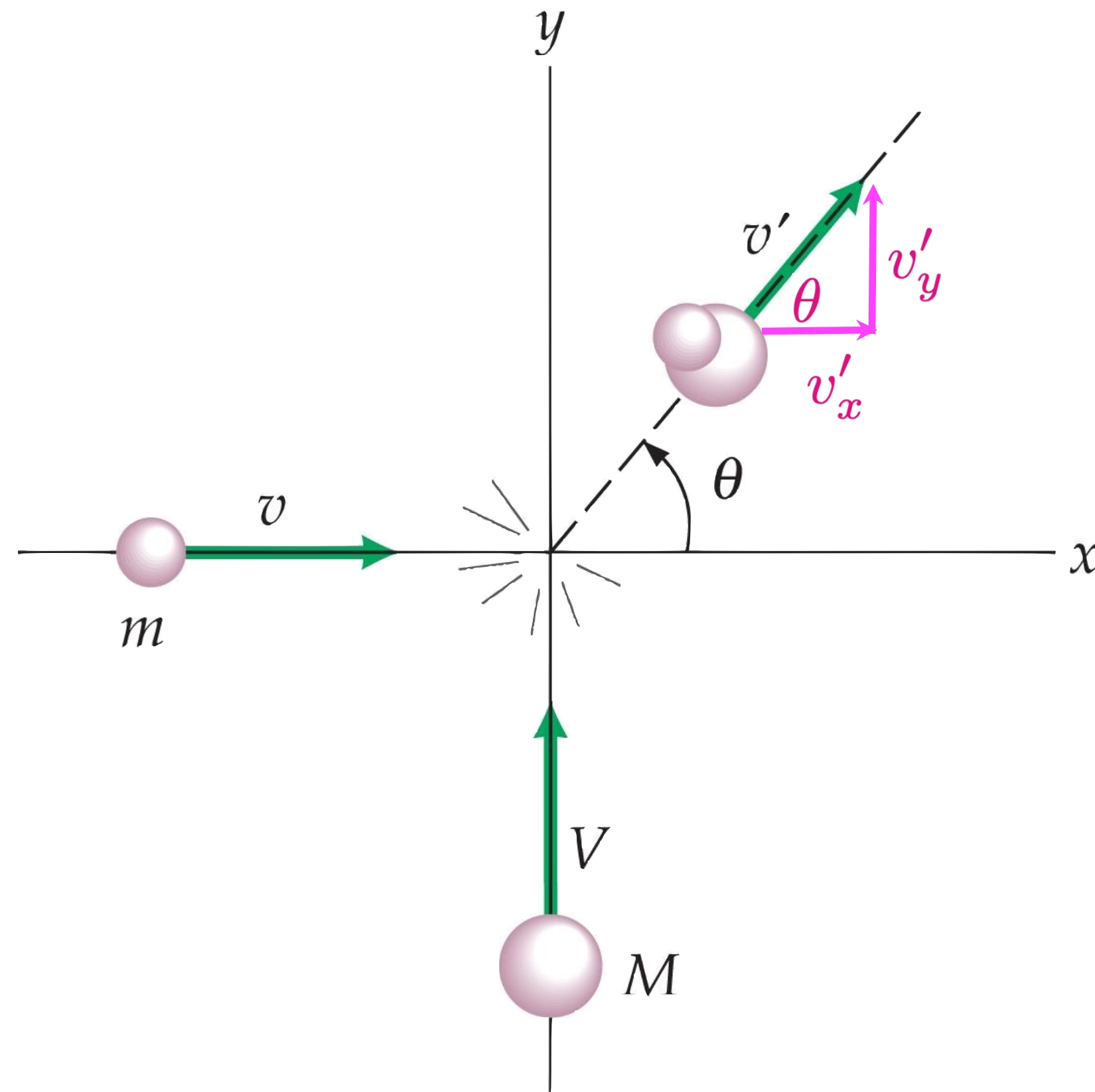
Example 2: Totally inelastic collision in 2D

Ex.: Ball 1 has a mass of m , Ball 2 has a mass of M . Ball 1 moves to the $+x$ direction at v , ball 2 moves in the $+y$ direction at V . They collide and **stick together**. What is their common final velocity, $\vec{v}' = \vec{v}_f$?



$$\vec{p}_{i,tot} = \vec{p}_{f,tot}$$
$$\vec{v}_{mf} = \vec{v}_{Mf} = \vec{v}_f$$

Clicker question 5



Given: m, M ; initial velocities: $v\hat{i}, V\hat{j}$; totally inelastic collision

Goal: Final velocity, \vec{v}'

Question: What principle(s) to use?

A

Conservation of momentum

B

Conservation of kinetic energy

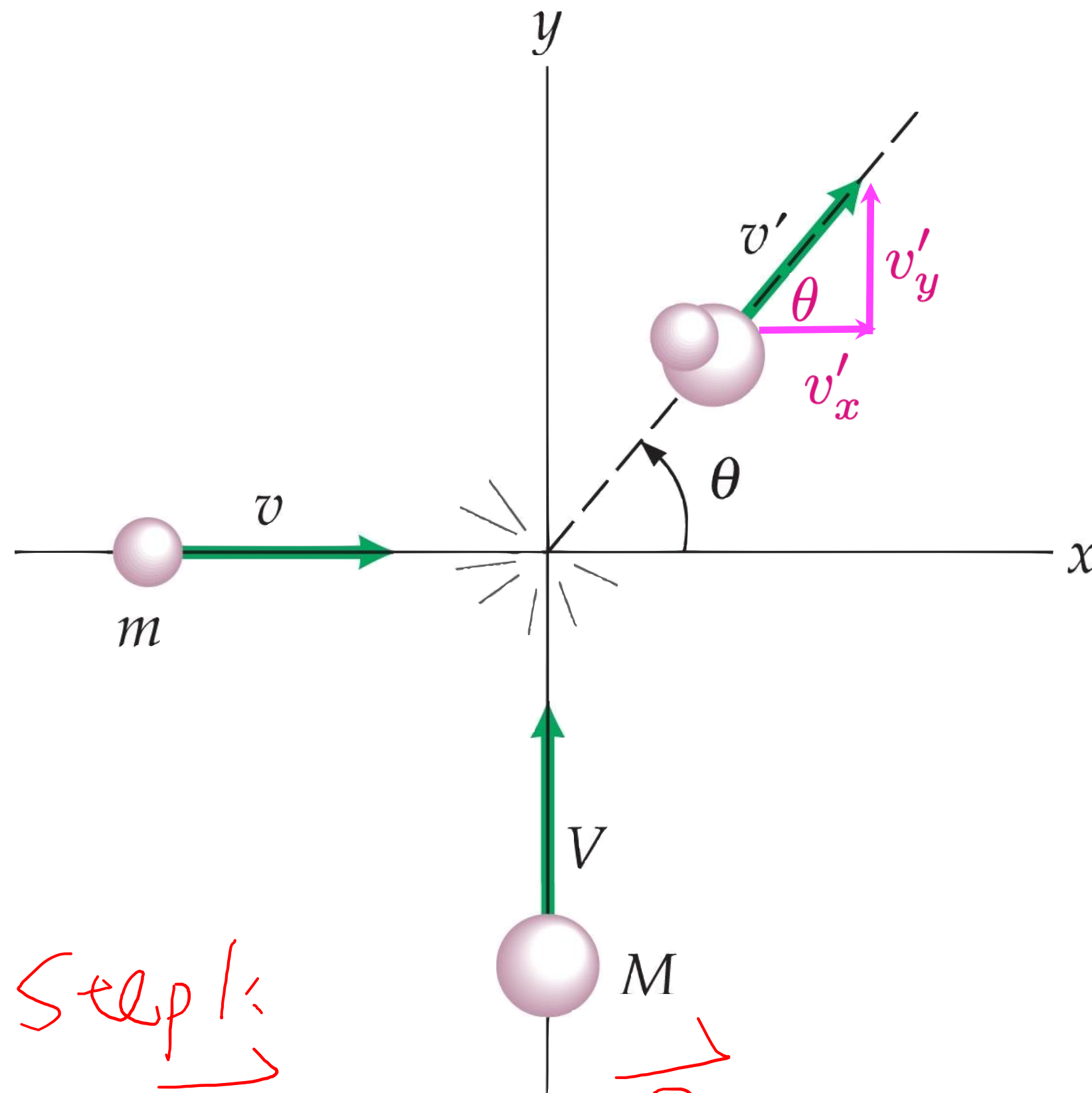
C

Both

Clicker question 6

Given: totally inelastic collision

in 2D



Given:

Mass	Before collision	After collision
m	$\vec{v}_{10} = v\hat{i}$	$\vec{v}_{1f} = \vec{v}_f = ?$
M	$\vec{v}_{20} = V\hat{j}$	$\vec{v}_{2f} = \vec{v}_f = ?$

Goal: Final velocity, \vec{v}_f

$\vec{v}_{1f} = \vec{v}_{2f} = \vec{v}_f$

Question: What is the x component of final velocity, v_{fx} ?

A $v_{fx} = v$

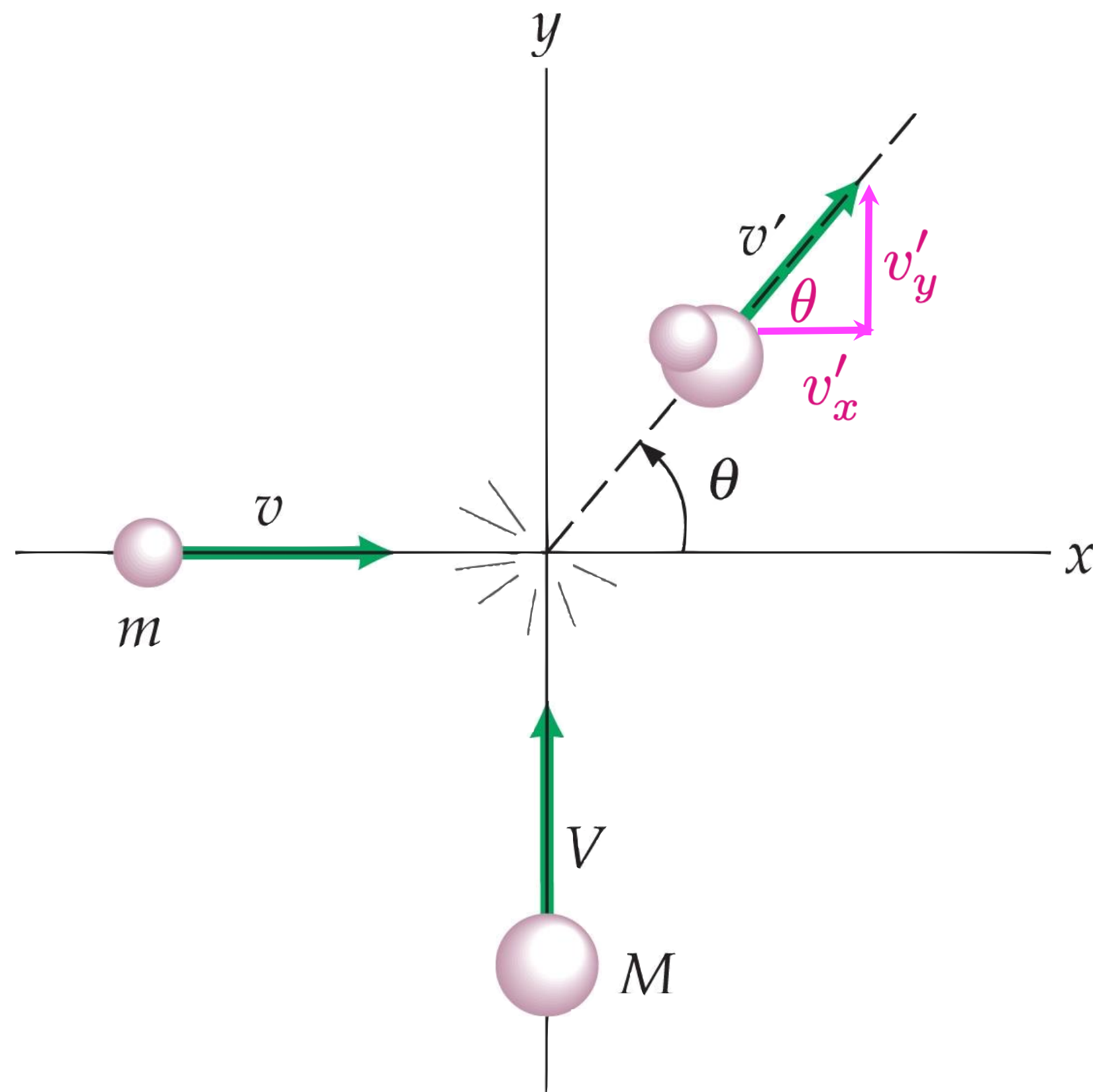
B $v_{fx} = V$

C $v_{fx} = \frac{mv}{m+M}$

Step 1:
 $\vec{P}_{xi, tot} = \vec{P}_{xf, tot}$
 $m v \hat{i} + M \cdot 0 = (m+M) \vec{v}_{fx}$
 $\rightarrow \vec{v}_{fx} = \frac{mv}{m+M} \hat{i}$

Clicker question 7

Given: **totally inelastic collision**



Mass	Before collision	After collision
m	$\vec{v}_{10} = v\hat{i}$	$\vec{v}_{1f} = \vec{v}_f = ?$
M	$\vec{v}_{20} = V\hat{j}$	$\vec{v}_{2f} = \vec{v}_f = ?$

Goal: **Final velocity, \vec{v}_{fy}**

Question: What is the y component of final velocity, v_{fy} ?

A $v_{fy} = v$

B $v_{fy} = V$

C $v_{fy} = \frac{MV}{m+M}$

$$P_{yi, \text{tot}} = P_{yf, \text{tot}}$$

$$m \cdot 0 + M \cdot V\hat{j} = (m+M)\vec{v}_{fy}$$

$$\rightarrow \vec{v}_{fy} = \frac{MV}{m+M}\hat{j}$$

Strategy: Collision

- 1. Read problem carefully
- 2. Sketches (before, after)
- 3. Given? Goal?
- 4. Principles and equations
 - **Collision?** Then the total momentum is conserved during the collision
 - ❖ Totally inelastic collision? Then all objects share the same final velocity, but $K_{tot,f} \neq K_{tot,i}$
 - ❖ **Elastic collision?** The sum of the kinetic energy is also conserved, $K_{tot,f} = K_{tot,i}$.

Summary of chapter 9

- Learning objectives

- Concepts:

- Center of mass, for point masses: $\vec{r}_{com} = \frac{\sum_i m_i \vec{r}_i}{\sum_i m_i}$

\vec{v}_{com} , \vec{a}_{com}

- Linear momentum: $\vec{P} = m\vec{v}$;

- Impulse: $\vec{I} = \int \vec{F} dt$; Linear momentum and impulse: $\vec{P}_f - \vec{P}_i = \vec{I}_{net}$

- Newton's 2nd law for a system: $\sum_i \vec{F}_{external,i} = \sum_i \frac{d\vec{P}_i}{dt}$, $\vec{F}_{net,external} = M_{tot} \vec{a}_{com}$

- ~~Conservation of linear momentum~~: If $\sum_i \vec{F}_{external,i} = 0$, then $\sum_i \vec{P}_i = const$

Conditional

- Practice:

- Collision problems: Elastic collision, inelastic collision, totally inelastic collision

Homework 9.5

- Due in a week.

Prelecture 10.1

- Before the next class.