

CS/ECE/ISyE 524 - Fall 2023 - HW 10 - Starter Code

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1. Hexagon construction

In [5]: *# Question 1 starter*

```
using Random, JuMP, Ipopt

m = Model(Ipopt.Optimizer)

# locations of the six vertices.
@variable(m, x[1:6])
@variable(m, y[1:6])

# your code here
n = 6

@constraint(m, x[1] == 0)
@constraint(m, y[1] == 0)

@NLobjective(m, Max, 0.5*sum( x[i]*y[i+1]-y[i]*x[i+1] for i=2:n-1))

# add ordering constraint to the vertices
for i = 2:n-1
    @NLconstraint(m, x[i]*y[i+1]-y[i]*x[i+1] >= 0 )
end

for i = 1:n
    for j = i:n
        @NLconstraint(m, (x[i]-x[j])^2 + (y[i]-y[j])^2 <= 1)
    end
end

Random.seed!(2367877)

set_start_value.(x,rand(n))
set_start_value.(y,rand(n))

# setvalue(x,rand(n))
# setvalue(y,rand(n))

optimize!(m)

# print optimal objective
println("area=",objective_value(m))

# plot solution from optimal values of (x,y) coordinates.
using PyPlot
X = [value.(x); 0]
Y = [value.(y); 0]
axis("equal")
```

```
plot(X,Y,"b.-")  
title("Solution");
```

This is Ipopt version 3.14.4, running with linear solver MUMPS 5.5.1.

Number of nonzeros in equality constraint Jacobian...: 2
 Number of nonzeros in inequality constraint Jacobian.: 88
 Number of nonzeros in Lagrangian Hessian.....: 144

Total number of variables.....: 12
 variables with only lower bounds: 0
 variables with lower and upper bounds: 0
 variables with only upper bounds: 0
 Total number of equality constraints.....: 2
 Total number of inequality constraints.....: 25
 inequality constraints with only lower bounds: 4
 inequality constraints with lower and upper bounds: 0
 inequality constraints with only upper bounds: 21

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	l
s									
0	2.5267500e-02	9.56e-01	1.11e+00	-1.0	0.00e+00	-	0.00e+00	0.00e+00	
1	7.2142785e-02	1.86e-01	7.08e-01	-1.0	9.56e-01	-	9.79e-01	8.06e-01h	
2	1.3685851e-01	0.00e+00	1.07e+00	-1.7	1.86e-01	0.0	5.92e-01	1.00e+00h	
3	1.4563864e-01	0.00e+00	1.85e-01	-1.7	6.95e-02	0.4	1.00e+00	1.00e+00h	
4	1.9215749e-01	1.82e-33	1.45e-01	-2.5	8.88e-02	-0.1	8.87e-01	1.00e+00h	
5	3.8952427e-01	9.70e-33	1.09e-01	-2.5	3.67e-01	-0.5	1.00e+00	1.00e+00h	
6	4.1162541e-01	1.38e-33	1.04e-01	-2.5	1.32e-01	-0.1	1.00e+00	1.00e+00h	
7	5.0121782e-01	8.67e-03	7.81e-02	-2.5	2.98e-01	-0.6	1.00e+00	5.73e-01f	
8	6.2013002e-01	4.94e-02	5.92e-02	-2.5	1.54e+00	-1.1	6.05e-01	2.02e-01f	
9	6.3333894e-01	2.49e-31	5.58e-02	-2.5	2.38e-01	-0.6	1.00e+00	1.00e+00h	
iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	l
s									
10	6.5763856e-01	1.37e-02	3.83e-02	-2.5	3.82e-01	-1.1	1.00e+00	3.09e-01h	
11	6.5771439e-01	3.27e-27	7.05e-03	-2.5	6.48e-02	-1.6	1.00e+00	1.00e+00f	
12	6.7377186e-01	6.21e-04	7.27e-04	-3.8	7.43e-02	-2.1	9.48e-01	9.54e-01h	
13	6.7499784e-01	1.75e-04	8.43e-05	-5.7	1.26e-02	-	1.00e+00	9.68e-01h	
14	6.7497054e-01	3.61e-28	2.58e-06	-5.7	8.91e-04	-2.5	1.00e+00	1.00e+00h	
15	6.7498144e-01	5.08e-26	5.65e-10	-8.6	4.42e-05	-	1.00e+00	1.00e+00h	

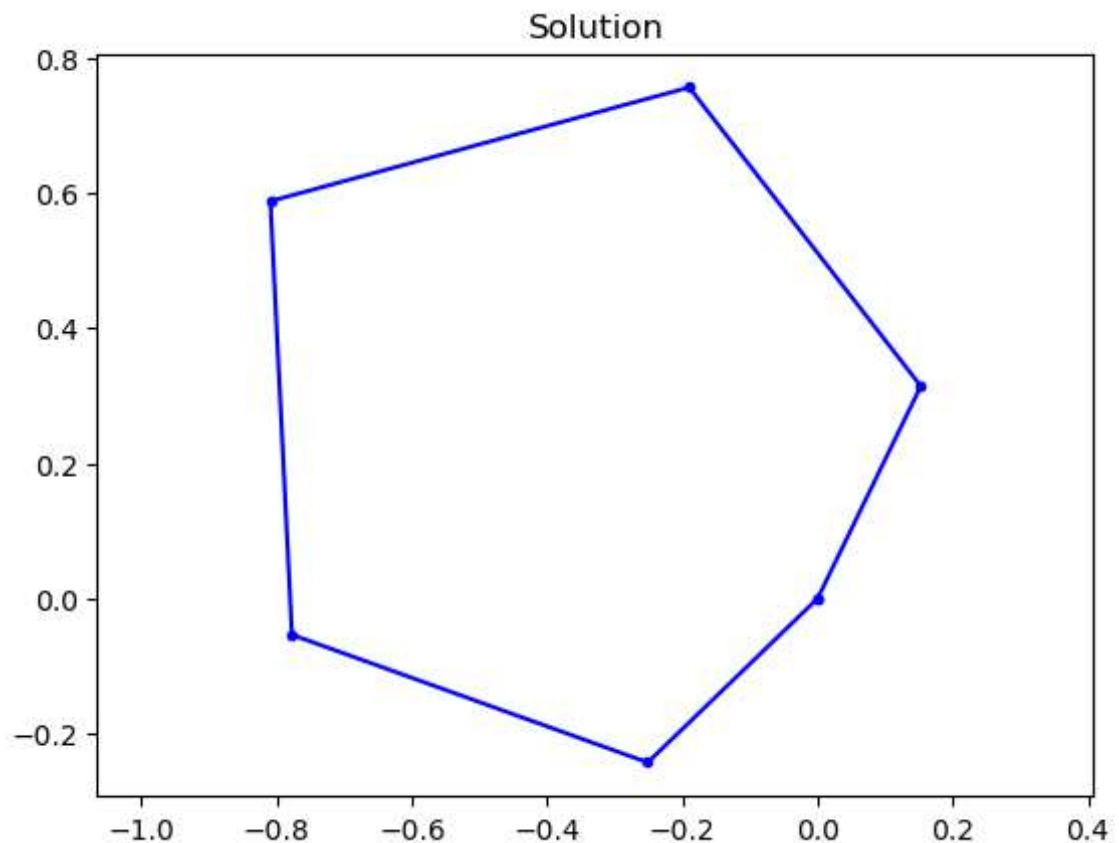
Number of Iterations.....: 15

	(scaled)	(unscaled)
Objective.....:	-6.7498143500990837e-01	6.7498143500990837e-01
Dual infeasibility.....:	5.6541463178128026e-10	5.6541463178128026e-10
Constraint violation....:	5.0830639782791767e-26	5.0830639782791767e-26
Variable bound violation:	0.0000000000000000e+00	0.0000000000000000e+00

Complementarity.....:	2.8313618569865823e-09	2.8313618569865823e-09
Overall NLP error.....:	2.8313618569865823e-09	2.8313618569865823e-09

Number of objective function evaluations	= 16
Number of objective gradient evaluations	= 16
Number of equality constraint evaluations	= 16
Number of inequality constraint evaluations	= 16
Number of equality constraint Jacobian evaluations	= 16
Number of inequality constraint Jacobian evaluations	= 16
Number of Lagrangian Hessian evaluations	= 15
Total seconds in IPOPT	= 0.013

EXIT: Optimal Solution Found.
area=0.6749814350099084



2. Fertilizer influence model

```
In [12]: # Question 2 starter

using JuMP, Ipopt

x =      [ -5  -3  -1   1   3   5]
ymeas = [127 151 379 421 460 426]
N = length(x)

# your code here
m = Model(Ipopt.Optimizer)

@variable(m, k[1:3])
expected_k = [500 -200 -1]
```

```

set_start_value.(k, expected_k)

@NLexpression(m, y[i in 1:N], k[1] + k[2] * exp(k[3] * x[i]))

@NLobjective(m, Min, sum((y[i] - ymeas[i])^2 for i in 1:N))

optimize!(m)
println(value.(k))

# Plot the data and the best-fit curve
using PyPlot

xv = range(-5, stop=5, length=100)
# plot some silly curve (replace this with the real thing)
yv = value.(k)[1] .+ value.(k)[2] .* exp.(value.(k)[3] .* xv)

scatter(x, ymeas, label="data points")
plot(xv, yv, "r-", label="best fit")
grid()
legend(loc="best"); title("Best fit for the data")

;

```

This is Ipopt version 3.14.4, running with linear solver MUMPS 5.5.1.

Number of nonzeros in equality constraint Jacobian...: 0
 Number of nonzeros in inequality constraint Jacobian.: 0
 Number of nonzeros in Lagrangian Hessian.....: 6

Total number of variables.....: 3
 variables with only lower bounds: 0
 variables with lower and upper bounds: 0
 variables with only upper bounds: 0
 Total number of equality constraints.....: 0
 Total number of inequality constraints.....: 0
 inequality constraints with only lower bounds: 0
 inequality constraints with lower and upper bounds: 0
 inequality constraints with only upper bounds: 0

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	1
s									
0	8.2578724e+05	0.00e+00	1.00e+02	-1.0	0.00e+00	-	0.00e+00	0.00e+00	
1	7.9098305e+05	0.00e+00	4.31e+01	-1.0	1.11e-01	2.0	1.00e+00	1.00e+00f	
2	7.7368507e+05	0.00e+00	1.84e+01	-1.0	1.22e-01	1.5	1.00e+00	1.00e+00f	
3	7.6462135e+05	0.00e+00	7.52e+00	-1.0	1.43e-01	1.0	1.00e+00	1.00e+00f	
4	7.5669591e+05	0.00e+00	2.34e+00	-1.0	6.22e-01	0.6	1.00e+00	1.00e+00f	
5	7.5214915e+05	0.00e+00	3.36e+00	-1.0	3.25e-01	1.0	1.00e+00	1.00e+00f	
6	7.3630462e+05	0.00e+00	2.55e+01	-1.0	4.44e-01	1.4	1.00e+00	1.00e+00f	
7	7.3348859e+05	0.00e+00	7.86e+00	-1.0	4.13e-02	1.8	1.00e+00	1.00e+00f	
8	7.3268256e+05	0.00e+00	1.60e+00	-1.0	4.79e-02	1.4	1.00e+00	1.00e+00f	
9	7.3160820e+05	0.00e+00	1.27e+00	-1.0	1.36e-01	0.9	1.00e+00	1.00e+00f	
iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	1
s									
10	1.0987204e+05	0.00e+00	2.99e+02	-1.0	3.81e+02	-	1.00e+00	1.00e+00f	
11	5.6246423e+04	0.00e+00	8.34e+01	-1.0	3.78e-01	1.3	1.00e+00	1.00e+00f	
12	4.6991507e+04	0.00e+00	1.86e+01	-1.0	1.78e-01	0.8	1.00e+00	1.00e+00f	
13	4.5480730e+04	0.00e+00	5.13e-01	-1.0	3.26e-01	0.4	1.00e+00	1.00e+00f	
14	4.4525878e+04	0.00e+00	3.00e+01	-1.7	1.08e+01	-	1.00e+00	5.00e-01f	
15	4.0430426e+04	0.00e+00	2.12e+01	-1.7	6.55e+00	-	1.00e+00	1.00e+00f	
16	3.9007772e+04	0.00e+00	1.63e+00	-1.7	4.62e-01	-0.1	1.00e+00	1.00e+00f	
17	3.7663598e+04	0.00e+00	3.73e+01	-1.7	1.36e+01	-	1.00e+00	5.00e-01f	
18	3.2613903e+04	0.00e+00	3.23e+01	-1.7	7.37e+00	-	1.00e+00	1.00e+00f	
19	3.0652798e+04	0.00e+00	3.77e+00	-1.7	6.75e-01	-0.6	1.00e+00	1.00e+00f	

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	1
s									
20	2.9040108e+04	0.00e+00	4.44e+01	-1.7	2.83e+01	-	1.00e+00	5.00e-01f	
21	2.3552089e+04	0.00e+00	3.64e+01	-1.7	9.88e+00	-	1.00e+00	1.00e+00f	
22	2.1706354e+04	0.00e+00	4.18e+00	-1.7	8.62e-01	-1.1	1.00e+00	1.00e+00f	
23	1.8903288e+04	0.00e+00	2.83e+01	-1.7	4.26e+01	-	1.00e+00	5.00e-01f	
24	1.6006615e+04	0.00e+00	4.59e-01	-1.7	1.42e+01	-	1.00e+00	1.00e+00f	
25	1.5213482e+04	0.00e+00	3.23e+01	-1.7	3.69e+01	-	1.00e+00	1.00e+00f	
26	1.3697207e+04	0.00e+00	5.82e+00	-1.7	1.22e+01	-	1.00e+00	1.00e+00f	
27	1.3434765e+04	0.00e+00	2.30e+00	-1.7	3.88e+01	-	1.00e+00	5.00e-01f	
28	1.3393324e+04	0.00e+00	9.80e-01	-1.7	1.01e+01	-	1.00e+00	1.00e+00f	
29	1.3390124e+04	0.00e+00	7.86e-02	-1.7	3.13e+00	-	1.00e+00	1.00e+00f	
iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	1
s									
30	1.3390093e+04	0.00e+00	1.12e-03	-2.5	3.65e-01	-	1.00e+00	1.00e+00f	
31	1.3390093e+04	0.00e+00	1.14e-07	-5.7	3.80e-03	-	1.00e+00	1.00e+00f	
32	1.3390093e+04	0.00e+00	4.37e-14	-8.6	5.00e-07	-	1.00e+00	1.00e+00f	

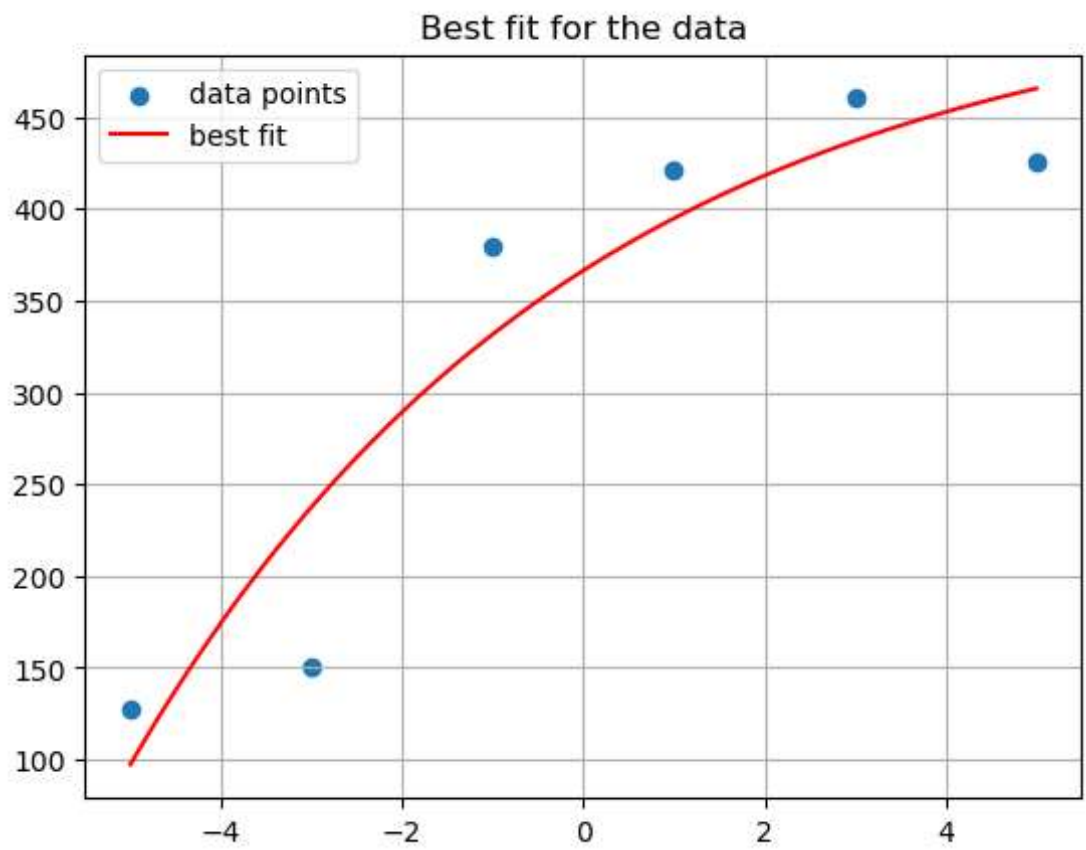
Number of Iterations.....: 32

	(scaled)	(unscaled)
Objective.....:	3.0954349427064827e+00	1.3390093119479570e+04
Dual infeasibility.....:	4.3732226821005179e-14	1.8917489796876907e-10
Constraint violation.....:	0.0000000000000000e+00	0.0000000000000000e+00
Variable bound violation:	0.0000000000000000e+00	0.0000000000000000e+00
Complementarity.....:	0.0000000000000000e+00	0.0000000000000000e+00
Overall NLP error.....:	4.3732226821005179e-14	1.8917489796876907e-10

Number of objective function evaluations	= 58
Number of objective gradient evaluations	= 33
Number of equality constraint evaluations	= 0
Number of inequality constraint evaluations	= 0
Number of equality constraint Jacobian evaluations	= 0
Number of inequality constraint Jacobian evaluations	= 0
Number of Lagrangian Hessian evaluations	= 32
Total seconds in IPOPT	= 0.019

EXIT: Optimal Solution Found.

[523.3055386212443, -156.94784350151693, -0.19966456906074545]



In []: