

Graph algorithms in their many shapes and sizes

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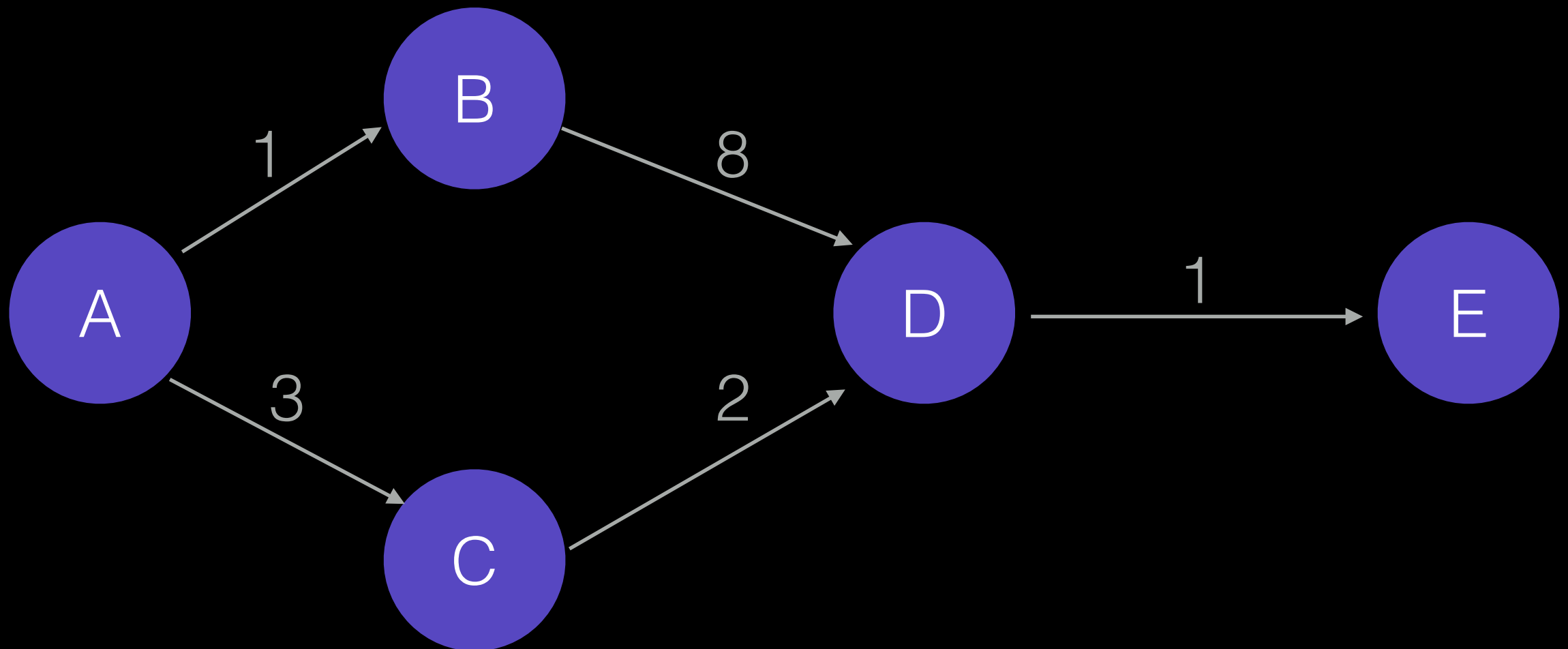
<https://github.com/depstein/programming-competitions>

In **mathematics** and **computer science**, **graph theory** is the study of *graphs*, which are mathematical structures used to model pairwise relations between objects. A "graph" in this context is made up of "**vertices**" or "nodes" and lines called *edges* that connect them. A graph may be *undirected*,

In mathematics and computer science, **graph theory** is the study of *graphs*, which are mathematical structures used to model pairwise relations between objects. A "graph" in this context is made up of "vertices" or "nodes" and lines called *edges* that connect them. A graph may be *undirected*,

Nodes and Edges!

Graph Representation

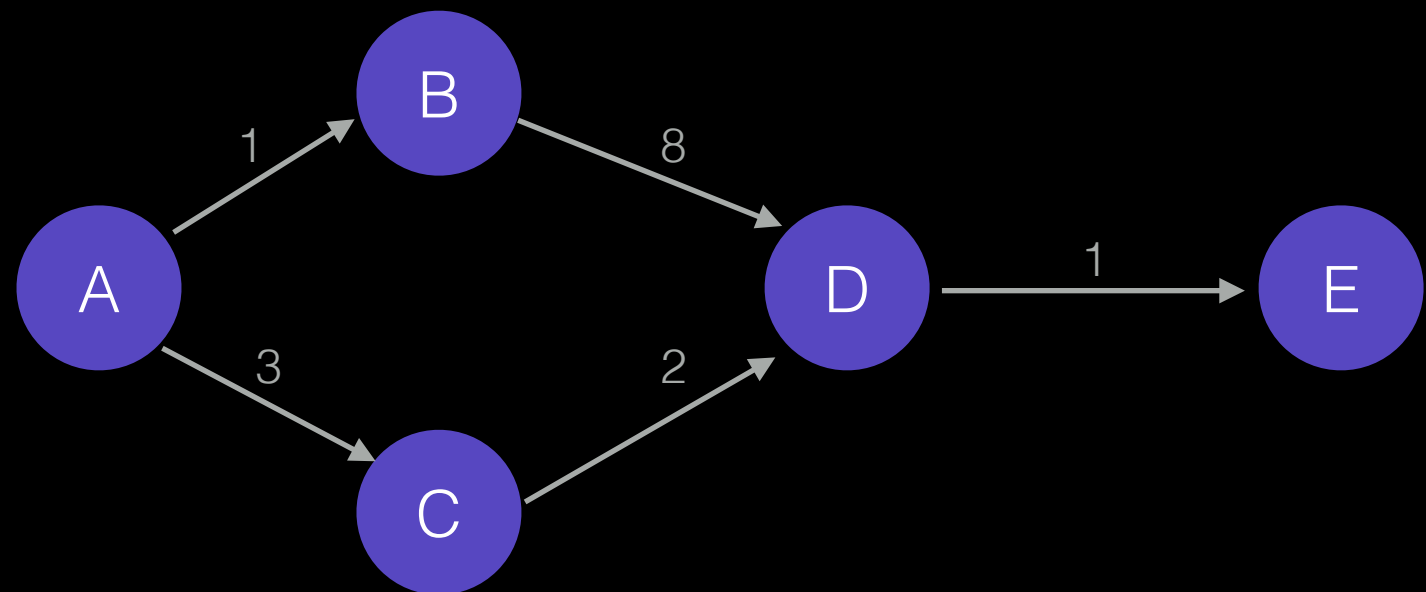


Arrays

```
import java.io.*;
import java.util.*;

public class arrays {
    public static int[][] dist = new int[5][5];

    public static void main(String[] args) {
        for(int i=0;i<5;i++)
            for(int j=0;j<5;j++) {
                if(i != j)
                    dist[i][j] = 1000; // Not using Integer.MAX_VALUE to avoid integer overflowing
            }
        //Initialize graph as described
        dist[0][1] = 1;
        dist[0][2] = 3;
        dist[1][3] = 8;
        dist[2][3] = 2;
        dist[3][4] = 1;
    }
}
```



Arrays

```
import java.io.*;
import java.util.*;
```

- Know the max number of nodes

```
public class arrays {
    public static int[][] dist = new int[5][5];
```

```
    public static void main(String[] args) {
```

- Adjacency Matrix

```
        for(int i=0;i<5;i++) {
            for(int j=0;j<5;j++) {
                if(i != j)
```

```
                    dist[i][j] = 1000; // Not using Integer.MAX_VALUE to avoid integer overflowing
```

- Easy to look up edge weight/edge existence

```
        //Initialize graph as described
```

```
        dist[0][1] = 1;
```

```
        dist[0][2] = 3;
```

```
        dist[1][3] = 8;
```

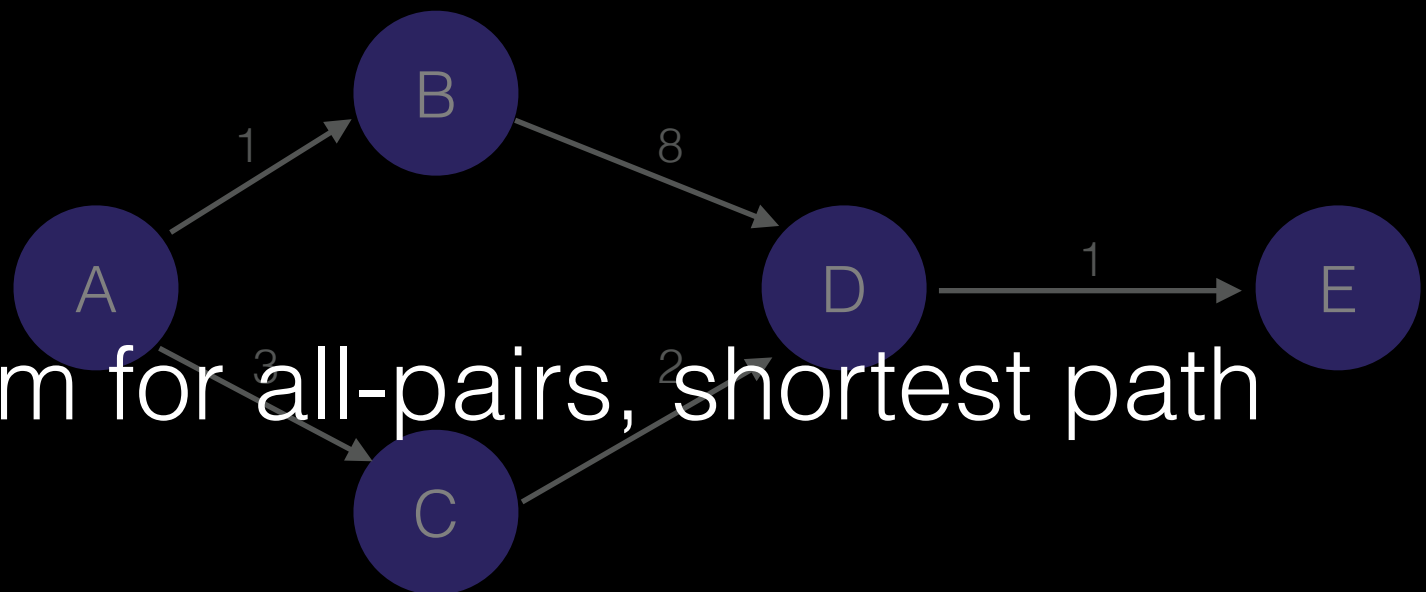
```
        dist[2][3] = 2;
```

```
        dist[3][4] = 1;
```

- Slow to get all edges out of a node

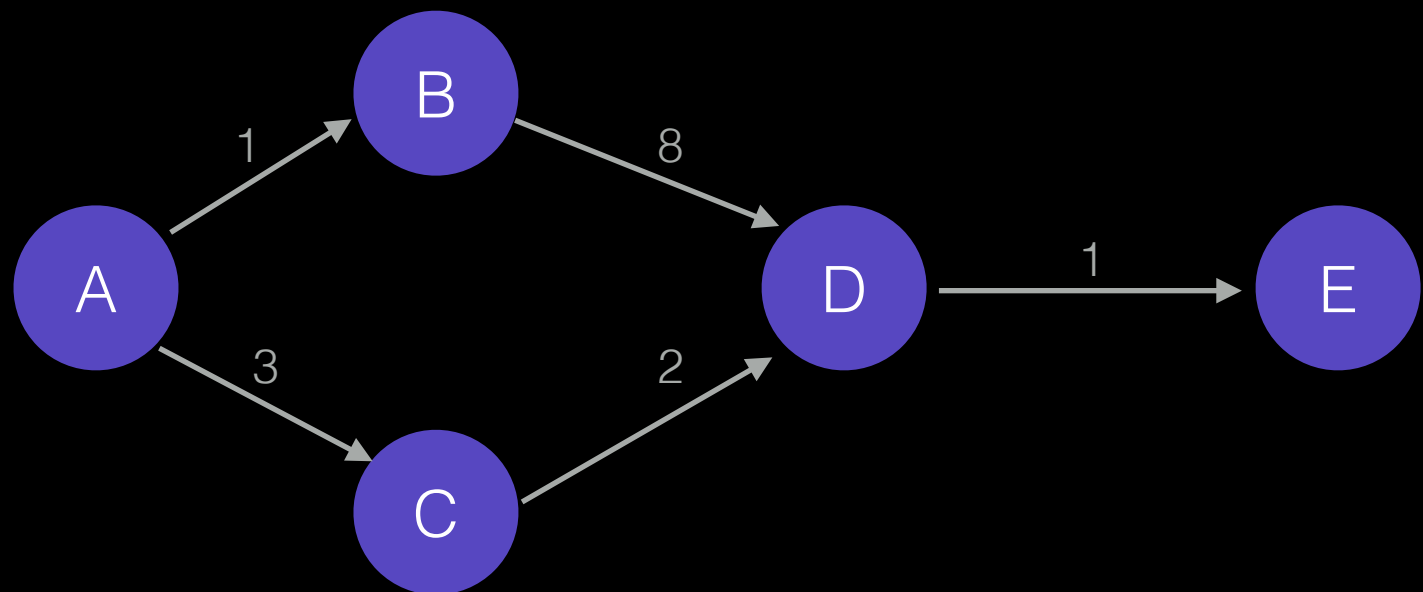
- Uses N^2 memory

- I tend to only use them for all-pairs, shortest path



Dedicated classes

```
class Node {  
    public ArrayList<Edge> neighbors = new ArrayList<Edge>();  
}  
  
class Edge {  
    public Node dest;  
    public int distance;  
  
    public Edge(Node dest, Node source, int distance) {  
        this.dest = dest;  
        this.distance = distance;  
        source.neighbors.add(this);  
    }  
}
```



Dedicated classes

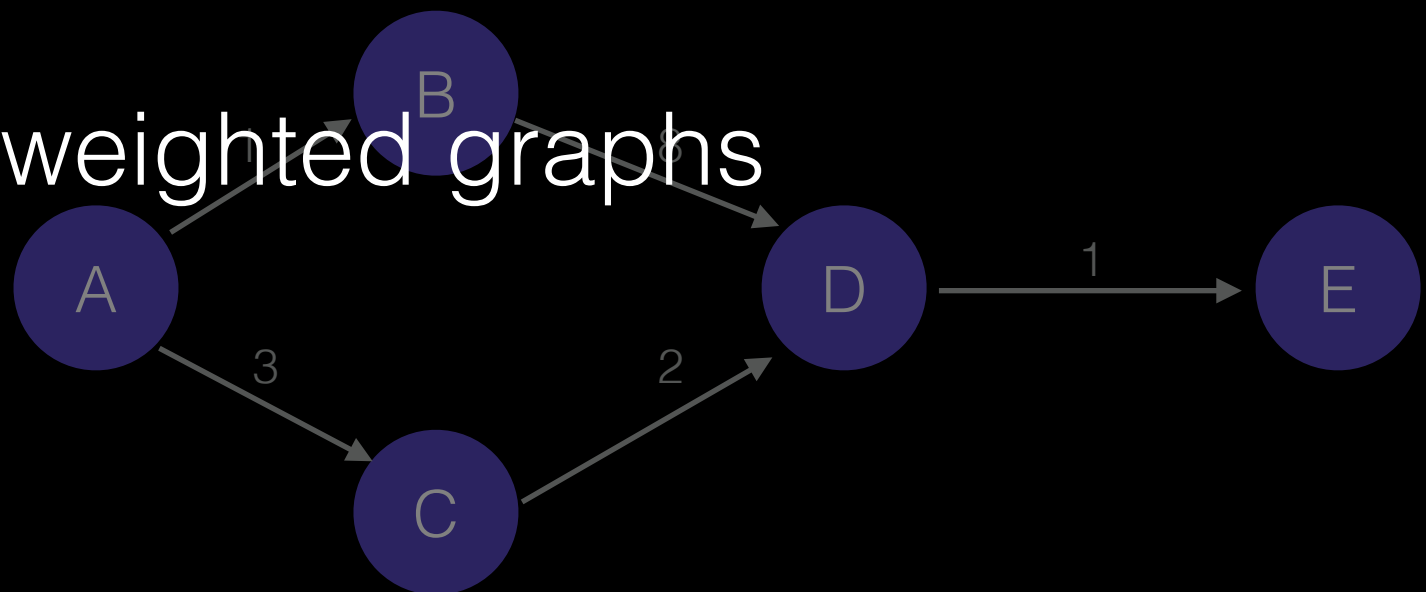
- Well-organized

```
class Node {  
    public ArrayList<Edge> neighbors = new ArrayList<Edge>();  
}
```

```
class Edge {  
    public Node dest;  
    public int distance;
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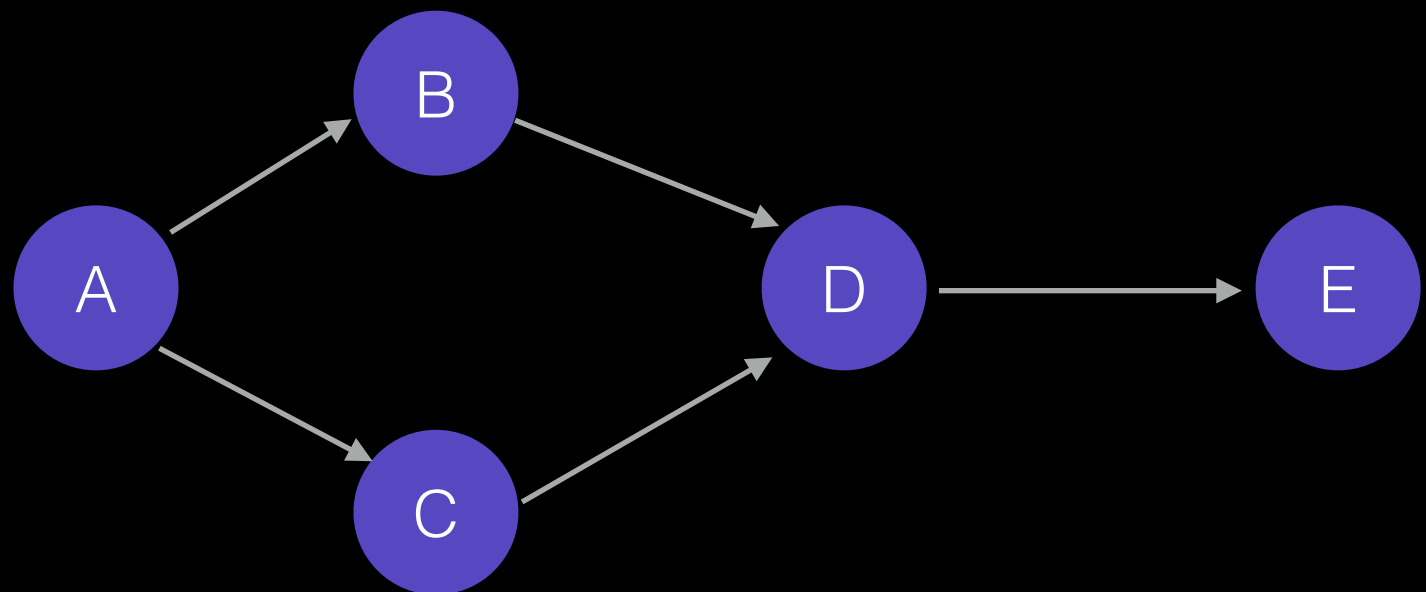
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    public Edge(Node dest, Node source, int distance) {  
        this.dest = dest;  
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        source.neighbors.add(this);  
    }  
}
```

- Easy to get all edges out of a node
- Difficult to find a particular edge
- This is what I use for weighted graphs



Unweighted Graphs

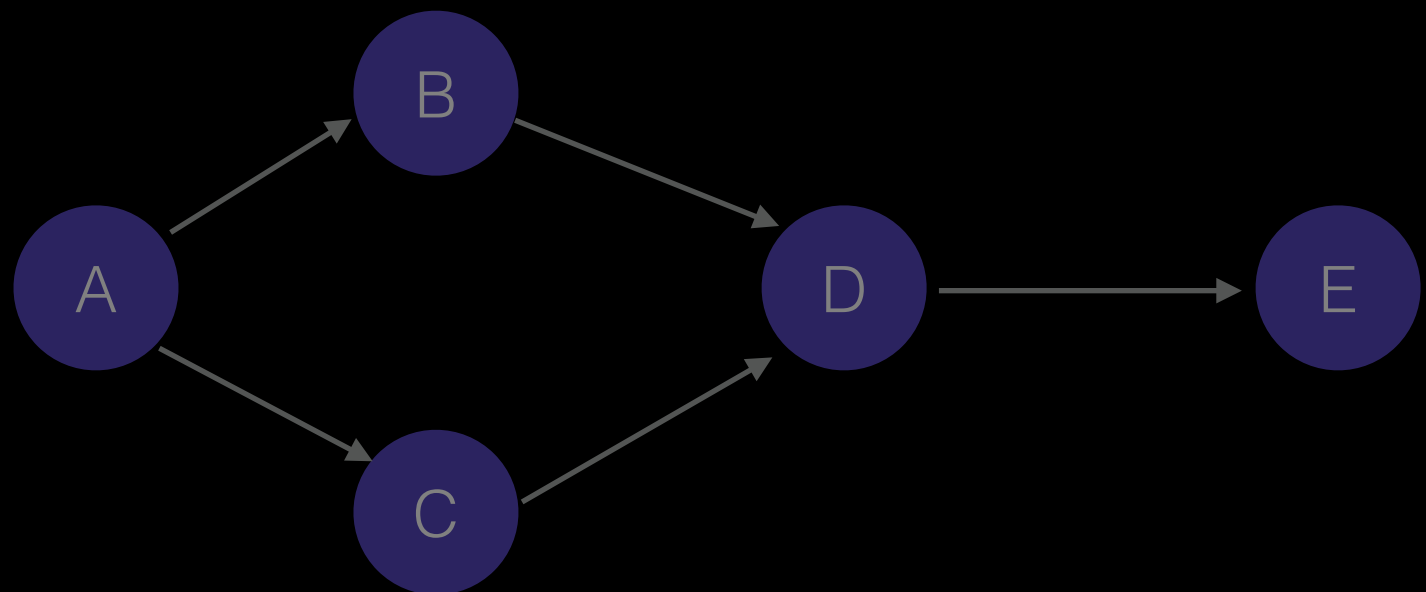
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class Node {  
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}
```



Unweighted Graphs

- Easy. You don't need an edge class!

```
class Node {  
    public ArrayList<Node> neighbors = new ArrayList<Node>();  
}
```



HashMaps

//For a weighted graph

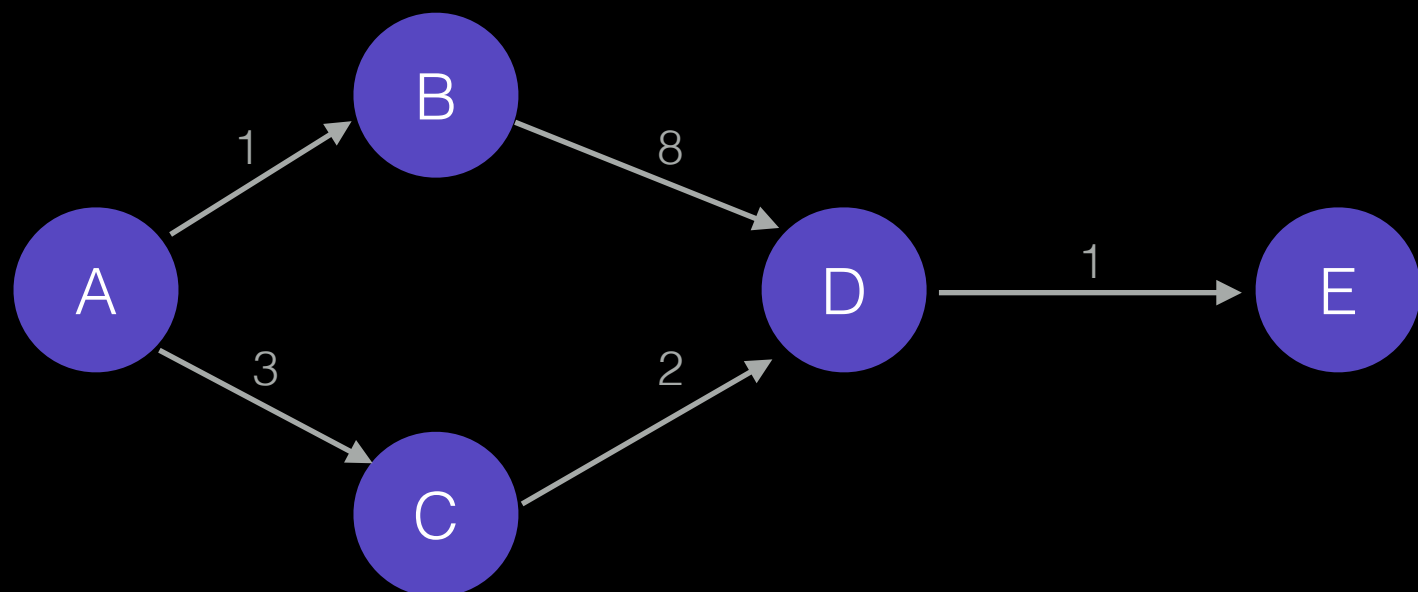
```
class Node {  
    public HashMap<Node, ArrayList<Node, Integer>> neighbors = new HashMap<Node,  
ArrayList<Node, Integer>>();  
}
```

//For a weighted graph, naming the nodes with Strings

```
public HashMap<String, HashMap<String, Integer>> neighbors = new HashMap<String,  
HashMap<String, Integer>>();
```

//For an unweighted graph, naming the nodes with Strings

```
public HashMap<String, ArrayList<String>> neighbors = new HashMap<String,  
ArrayList<String>>();
```



HashMaps

- A little harder to organize, debug

```
//For a weighted graph
```

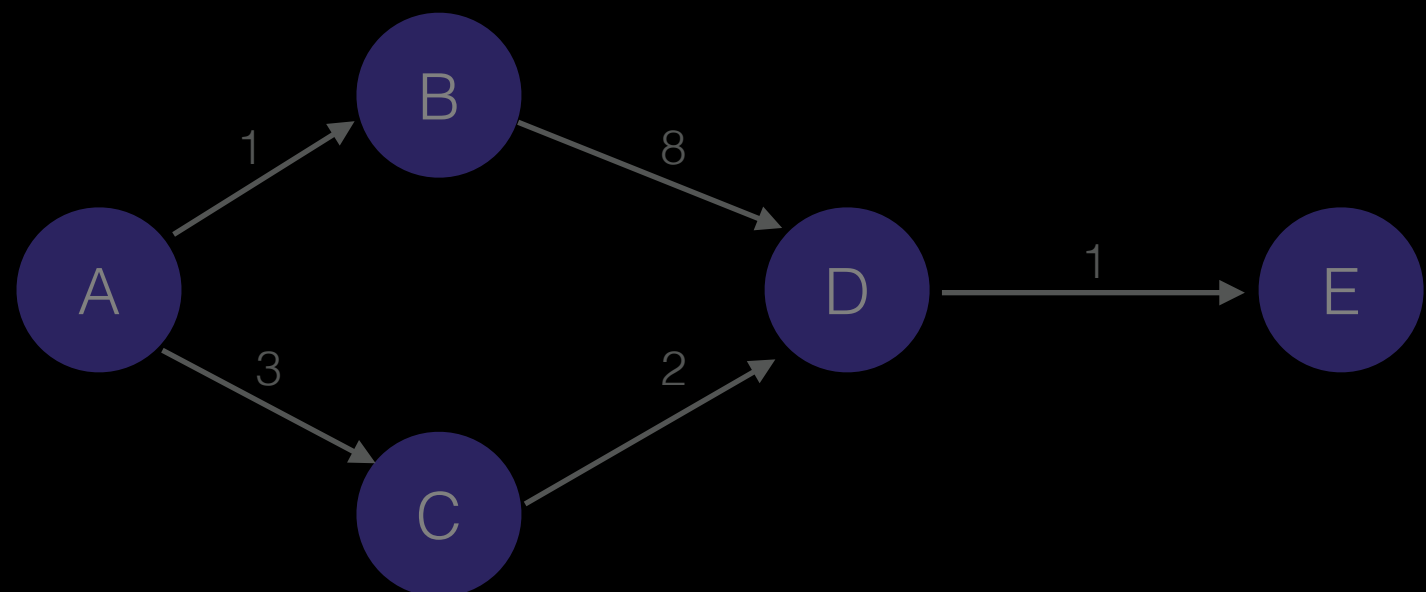
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//For an unweighted graph, naming the nodes with Strings
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Graph Algorithms

- Searches (Breadth-First, Depth-First)
- Shortest Path (Dijkstra's)
- Minimum Spanning Tree (Prim's, Kruskal's)
- Topological Sort
- Negative-Edge Shortest Path (Bellman-Ford)
- All-Pairs, Shortest Path (Floyd-Warshall)
- Max Flow (Ford-Fulkerson, Edmonds-Karp, Preflow Push)
- Minimum-Cost Flow

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